## **Dependent Normalized Random Measures**

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#### Joint work with Wray Buntine & Nan Ding June 9, 2012



Changyou Chen Dependent Normalized Random Measures

# Outline

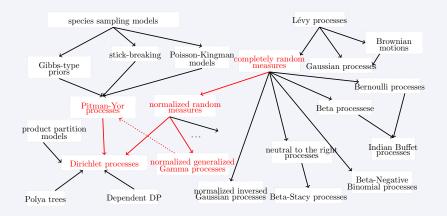


### Introduction

- 2 Normalized random measures
  - Background
  - Posterior analysis
  - Dependent NRMs
- 3 Applications in dynamic topic modeling
  - Model construction
  - Sampling
- 4 Experiments
- 5 Conclusion & future work

Introduction

## Nonparametric Bayesian family



#### Introduction

#### Dynamic topic models

- Dynamic topic models try to model topic evolution over time.
- There are several related dynamic topic models, *e.g.*, Blei&Lafferty's DTM [BL06], Ahmed&Xing's iDTM [AX10].

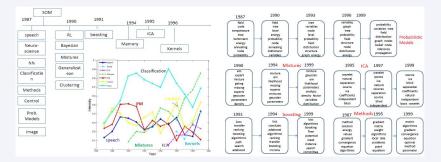


Figure: Topic evolution in NIPS, taken from [AX10].

### Main contributions

- Posterior analysis for normalized random measures.
- Develop dependent normalized random measures.
- Apply dependent normalized random measures to dynamic topic modeling to model *birth-death processes*, *dependency* and *power-law* phenomena in topic distributions over time.

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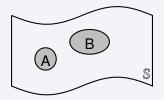
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- Basic idea:
  - measurable space:
  - disjoint subsets:  $A, B \in \mathbb{S}$ .
  - random function:

 $A, B \in \mathbb{S}.$  $\Phi: \mathbb{S} \longmapsto \mathbb{R}^+.$ 

S.

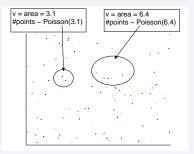


$$\Phi(A) \perp \Phi(B)$$

 It is shown that completely random measures can be constructed from Poisson processes.

#### Definition (Poisson Processes: )

A *Poisson process* on  $\mathbb{S}$  is a random subset  $\Pi \in \mathbb{S}$  such that if N(A) is the number of points of  $\Pi$  in  $A \subseteq \mathbb{S}$ , then N(A) is a Poisson random variable with mean v(A), and  $N(A_1), \dots, N(A_n)$  are independent if  $A_1, \dots, A_n$  are disjoint.

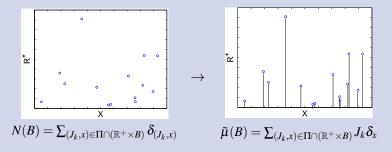


- Space: S
- Positive measure:  $v : \mathbb{S} \mapsto \mathbb{R}^+$
- Poisson random measure:
  - $N: \mathbb{S} \longmapsto \mathsf{integers}$
- $N(A) \sim \mathsf{Poisson}(v(A))$

#### Definition (Construction from Poisson processes)

Let N(dt, dx) being a Poisson random measure on a product space  $S = R^+ \times X$  with mean measure v(dt, dx). Construct a random measure  $\tilde{\mu}$  to be a linear functional of N(dt, dx) as

$$\tilde{\mu}(B) = \int_{\mathbb{R}^+ \times B} tN(\mathrm{d} t, \mathrm{d} x), \forall B \in \mathscr{B}(\mathbb{X}).$$



$$\tilde{\mu}(B) = \int_{\mathbb{R}^+ \times B} t N(\mathrm{d}t, \mathrm{d}x) = \sum_{(J_k, x) \in \Pi \cap (\mathbb{R}^+ \times B)} J_k \delta_x$$

#### Proposition

 $\tilde{\mu}$  is a completely random measure on X.

- Call  $v(dt, dx) = \rho(dt|x)H(dx)$  the *Lévy measure* of  $\tilde{\mu}$ .
- Taking different Lévy measures v(dt, dx) we get different CRMs.

#### Example (Gamma CRM (Gamma processes))

A Gamma process on X is obtained by setting

$$\mathbf{v}(\mathrm{d} t, \mathrm{d} x) = \frac{e^{-t}}{t} \mathrm{d} t H(\mathrm{d} x).$$

# Sampling a CRM

$$ilde{\mu}(B) = \sum_{(J_k,x)\in\Pi\cap(\mathbb{R}^+ imes B)} J_k \delta_x$$

• Cannot directly sample from the Lévy measure  $v(dx, dt) = \rho(dt|x)H(x)$  because it is improper.

Size biased sampling starting from the largest jump, then the second largest largest jump ..., given by Ferguson and Klass [FK72].

- Draw *i.i.d.* samples  $x_i$  from the base measure H(dx).
- The *k*-th largest jump has cumulative distribution function:

$$P(J_k \leq j_k | J_{k-1} = j_{k-1}) = \exp\left\{-\int_{\mathbb{X}} \int_{j_k}^{j_{k-1}} v(\mathrm{d}t, \mathrm{d}x)\right\}$$
.

#### Background

### Normalized random measures

Definition (Normalized Random Measures (NRM))

An NRM is obtained by normalizing the CRM  $\tilde{\mu}$  as:

$$\mu = rac{ ilde{\mu}}{ ilde{\mu}(\mathbb{X})} = \sum_k rac{J_k}{\sum_{k'} J_{k'}} \delta_{X_k^*} \; .$$

#### Definition (Normalized generalized Gamma processes (NGG))

A normalized generalized Gamma process is an NRM with Lévy measure being  $v(dt, dx) = M \frac{e^{-t}}{d+a} H(dx), (0 < a < 1)^a$ .

<sup>*a*</sup>The general form is  $v(dt, dx) = M \frac{e^{-bt}}{t^{1+a}} H(dx) (0 < a < 1, b > 0)$ , but *b* can be absorbed into M, thus we use b = 1.

• We denote a NRM with parameters a, M and base measure  $H(\cdot)$  as NRM $(a, M, H(\cdot))$ .

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## Posterior analysis for the NGG

 General form for the posteriors of the NRM is developed in [JLP09], here we focus on NGG<sup>1</sup>.

#### Theorem (Posterior of the NGG)

Consider the NGG(a,M, $H(\cdot)$ ). For a data vector  $\vec{X}$  of length N there are K distinct values  $X_1^*, ..., X_K^*$  with counts  $n_1, ..., n_K$  respectively. The posterior marginal is given by

$$p\left(\vec{X}|NGG(a,M,H(\cdot))\right) = \frac{e^{M}a^{K-1}T_{a,M}^{N,K}}{\Gamma(N)}\prod_{k=1}^{K}(1-a)_{n_{k}-1}h(X_{k}^{*}).$$
 (1)

where

$$T_{a,M}^{N,K} = a \frac{M^K}{e^M} \int_{\mathbb{R}^+} \frac{u^{N-1}}{(1+u)^{N-Ka}} e^{M-M(1+u)^a} du .$$
 (2)

<sup>1</sup>[FT12] also derives some similar results.

## Posterior analysis for the NGG

Compare NGG with PYP (Pitman-Yor process)

$$p(\vec{X}|\mathsf{NGG},\cdots) = \frac{e^{M}a^{K-1}T_{a,M}^{N,K}}{\Gamma(N)} \prod_{k=1}^{K} (1-a)_{n_{k}-1}h(X_{k}^{*}) .$$
$$p(\vec{X}|\mathsf{PYP},\cdots) = \frac{(b|a)_{K}}{(b)_{N}} \prod_{k=1}^{K} (1-a)_{n_{k}-1}h(X_{k}^{*}) .$$

#### Corollary (NGG $\leftrightarrow$ PYP)

Let  $\vec{\mu} \sim \text{NGG}(a, M, H(\cdot))$  and suppose  $M \sim \Gamma(b/a, 1)$  then it follows that  $\vec{\mu} \sim \text{PYP}(a, b, H(\cdot))$ 

• If we also sample *M* using the prior  $\Gamma(b/a, 1)$  for NGG, then we are sampling from a PYP.

# Posterior analysis for the NGG

- This relationship is different from the Poisson-Kingman construction of the PYP, where it is constructed by exponentially tilting an σ-stable process, but we believe they are closely related.
- One problem of the above posterior sampling is the evaluation of  $T_{a,M}^{N,K}$ , which is computationally expensive and cannot easily be tabulated.

# Conditional posterior for the NGG

- Likelihood of NGG:  $\frac{\prod_{k=1}^{K} J_k^{n_k}}{\left(\sum_{k'=1}^{\infty} J_k'\right)^{\sum_{k=1}^{K} n_k}}.$
- A well studied auxiliary variable is introduced to eliminate this power term in the denominator. We call it *latent relative mass*.

#### Definition (Latent relative mass)

The latent relative mass is an auxiliary variable  $U_N$  defined as

$$U_N = \Gamma_N/(\sum_{k=1}^\infty J_k), ext{ where } \Gamma_N \sim \gamma(1,N)$$

• After a change of variable, we then have:

$$\frac{1}{(\sum_{k=1}^{\infty}J_k)^N}p(\Gamma_N)\mathrm{d}\Gamma_N=\exp\left\{-U_N\sum_{k=1}^{\infty}J_k\right\}\mathrm{d}U_N.$$

## Conditional posterior for the NGG

#### Theorem (Conditional posterior)

Given  $NGG(a, M, H(\cdot))$  and *N* observed data  $\vec{X}$ , assume there are *K* jumps such that  $n_k > 0$ , then (marginalize out jumps)

$$p\left(\vec{X}, U_N = u, K | N, \mathsf{NGG}(a, M, H(\cdot))\right)$$
  
=  $\frac{u^{N-1}}{(1+u)^{N-Ka}} (Ma)^K e^{M-M(1+u)^a} \prod_{k=1}^K (1-a)_{n_k-1} h(X_k^*)$ . (3)

Moreover (retain jumps),

$$p\left(\vec{X}, U_N = u, K, J_1, ..., J_K | N, \mathsf{NGG}(a, M, H(\cdot))\right)$$
  
=  $u^{N-1} \left(\frac{Ma}{\Gamma(1-a)}\right)^K e^{M-M(1+u)^a} \prod_{k=1}^K J_k^{n_k-a-1} e^{-(1+u)J_k} h(X_k^*)$  (4)

# Posterior sampling for the NGG

$$Q = \sum_k J_k \delta_{X_k^a}$$

- Conditional posterior sampling for the NGG:
  - Sample the auxiliary variable:

$$p(U_N|\cdot) \propto \frac{U_N^{N-1}}{(1+U_N)^{N-Ka}} e^{-M(1+U_N)^a}$$

• For the jumps  $J_k$  with data attached:

$$J_k \sim \operatorname{Gamma}(U_N+1, n_k-\frac{1}{2}).$$

The rest of jumps form another NGG with an updated Lévy measure

$$e^{-U_N t} \mathbf{v}(\mathrm{d} t, \mathrm{d} x),$$

which is essentially  $\sum_{k:n_k=0} J_k \delta_{X_k^*}$ 



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# **Dependent NRMs**

- There are several ways to construct dependent nonparametric Bayesian models.
- We use the standard dependency operations on Poisson processes to construct dependent NRMs, *e.g.*, *superposition*, *subsampling* and *point transition*.
- This has been used in dependent Dirichlet processes by Lin, Grimson and Fisher [LGF10].

### Dependency operations

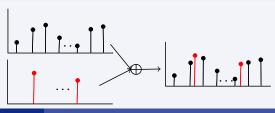
#### Definition (Superposition of NRMs)

Given *n* independent NRMs  $\mu_1, \dots, \mu_n$  on  $\mathbb{X}$ , the superposition  $(\oplus)$  is:

$$\mu_1 \oplus \mu_2 \oplus \cdots \oplus \mu_n := c_1 \mu_1 + c_2 \mu_2 + \cdots + c_n \mu_n .$$

where the weights<sup>*a*</sup>  $c_m = \frac{\tilde{\mu}_m(\mathbb{X})}{\sum_j \tilde{\mu}_j(\mathbb{X})}$  and  $\tilde{\mu}_m$  is the unnormalized random measures corresponding to  $\mu_m$ .

<sup>a</sup>This is different from Lin et al.'s [LGF10]



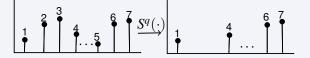
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### **Dependency operations**

#### Definition (Subsampling of NRMs)

Given a NRM  $\mu = \sum_{k=1}^{\infty} r_k \delta_{\theta_k}$  on  $\mathbb{X}$ , and a measurable function  $q: \mathbb{X} \to [0,1]$ . If we independently draw  $z(\theta) \in \{0,1\}$  for each  $\theta \in \mathbb{X}$  with  $p(z(\theta) = 1) = q(\theta)$ , the subsampling of  $\mu$ , is defined as

$$S^{q}(\mu) := \sum_{k: z(\theta_{k})=1} \frac{r_{k}}{\sum_{j} z(\theta_{j}) r_{j}} \delta_{\theta_{k}},$$
(5)

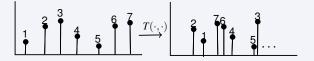


### Dependency operations

#### Definition (Point transition of NRMs)

Given a NRM  $\mu = \sum_{k=1}^{\infty} r_k \delta_{\theta_k}$  on  $\mathbb{X}$ , the point transition of  $\mu$ , is to draw atoms  $\theta'_k$  from a transformed base measure to yield a new NRM as

$$T(\boldsymbol{\mu}) := \sum_{k=1}^{\infty} r_k \delta_{\boldsymbol{\theta}'_k} \; .$$



# Properties of operations

#### Theorem (Posterior under superposition)

Let  $\tilde{\mu}_1, \tilde{\mu}_2, \dots, \tilde{\mu}_n$  be *n* independent CRMs on  $\mathbb{X}$  with Lévy measures  $v_i(dt, dx), \tilde{\mu} = \bigoplus_{i=1}^n \tilde{\mu}_i$ . The posterior of  $\tilde{\mu}$  given observed data { $(X_k^*, n_k)$ } is given by

$$\tilde{\mu}_n + \sum_{k=1}^K J_k \delta_{X_k^*},$$

- $\tilde{\mu}_n$ : a CRM with  $v(dt, dx) = e^{-ut} (\sum_{i=1}^n v_i(dt, dx));$
- 2  $X_k^*$ :fixed points;
- 3  $J_k$ : jumps with densities proportional to  $t^{n_k}e^{-ut}(\sum_{i=1}^n v_i(dt, dx)).$

## Properties of operations

#### Theorem (Lévy measure under subsampling)

Let  $\tilde{\mu} = \sum_{k=1}^{\infty} J_k \delta_{X_k^*}$  be a CRM on  $\mathbb{X}$  with Lévy measure v(dt, dx),  $S^q(\tilde{\mu})$  be its subsampling version with acceptance rate  $q(\cdot)$ , then  $S^q(\tilde{\mu})$  has the Lévy measure of

#### $q(\mathrm{d} x) \mathbf{v}(\mathrm{d} t, \mathrm{d} x)$ .

# Properties of operations

#### Lemma (Applied on graphs)

• Subsampling is commutative:

$$S^{q'}(S^q(\tilde{\mu})) = S^q(S^{q'}(\tilde{\mu})) = S^{q'q}(\tilde{\mu}))$$

• Transitions commute under constant subsampling rates:

$$S^q(T(\tilde{\mu})) = T(S^q(\tilde{\mu}))$$

• Subsampling and transition distribute over superposition:

 $S^q( ilde{\mu}\oplus ilde{\mu}')=S^q( ilde{\mu})\oplus S^q( ilde{\mu}')\,,\qquad T( ilde{\mu}\oplus ilde{\mu}')=T( ilde{\mu})\oplus T( ilde{\mu}')\,.$ 

• Superposition is commutative and associative:

$$ilde{\mu} \oplus ilde{\mu}' = ilde{\mu}' \oplus ilde{\mu}, \qquad ( ilde{\mu} \oplus ilde{\mu}') \oplus ilde{\mu}'' = ilde{\mu} \oplus ( ilde{\mu}' \oplus ilde{\mu}'')$$

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#### Model construction

### Applications: Dynamic topic models

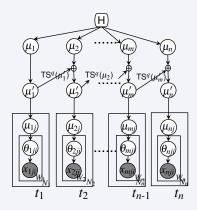
We want to model the following phenomenas in dynamic topic models:

- Birth-death processes.
- Dependency of topics between time frames (partially exchangeable).
- Power-law phenomena.

These objectives are well tackled by the dependent NRMs framework.

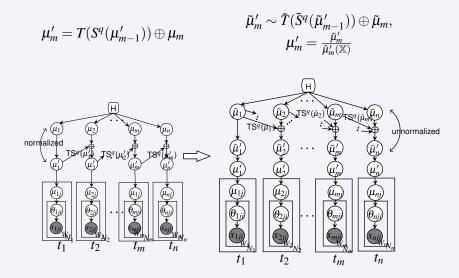
# Model construction

$$\mu'_m = T(S^q(\mu'_{m-1})) \oplus \mu_m$$



- $t_i$ : epochs.
- 2  $\mu_i$ : new topics at epoch *i*.
- $\mu_i'$ : topic distribution for epoch *i*.
- Each epoch has a hierarchical NRM structure.

### Model construction



### Relation between NRMs and CRMs

#### Theorem

The following two generative processes are equivalent:

• Manipulate the normalized random measures:

$$\mu_m' \sim T(S^q(\mu_{m-1}')) \oplus \mu_m,$$
 for  $m > 1$ .

• Manipulate the completely random measures:

$$\tilde{\mu}'_m \sim \tilde{T}(\tilde{S}^q(\tilde{\mu}'_{m-1})) \oplus \tilde{\mu}_m, \quad \mu'_m = rac{\tilde{\mu}'_m}{\tilde{\mu}'_m(\mathbb{X})} \quad \text{for } m > 1.$$

The resultant NRMs  $\mu'_m$ 's correspond to:

$$\mu_m' = \sum_{j=1}^m \frac{\left(q^{m-j}\tilde{\mu}_j\right)(\mathbb{X})}{\sum_{j'=1}^m \left(q^{m-j'}\tilde{\mu}_{j'}\right)(\mathbb{X})} T^{m-j}(\mu_j), \qquad \qquad \text{for } m > 1$$

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# Sampling

At each time frame *m*, we do:

- **Top level**: slice sample  $J_{mk}$  (ends up finite jumps).
- Second Level: subsample  $J'_{mk}$  by inheriting from  $J_{m'k}$  (top level),  $m' \le m$  with Bernoulli trials.
- Third level: construct  $\mu'_m$  by normalizing  $J'_{mk}$ .

#### Hierarchical NRMs:

- sample topic assignments s<sub>mji</sub> using a generalized Blackwell-MacQueen sampling scheme for the hierarchical NRM.
- Sample #customers for the parent restaurant  $n'_{mk}$  by simulating a generalized Chinese restaurant process for the NRM.

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### Datasets

• Academic, news, Twitter, blog datasets.

| dataset              | vocab | docs | words | epochs      |
|----------------------|-------|------|-------|-------------|
| ICML                 | 2k    | 765  | 44k   | 2007–2011   |
| JMLR                 | 2.4k  | 818  | 60k   | 12 vols     |
| TPAMI                | 3k    | 1108 | 91k   | 2006–2011   |
| NIPS                 | 14k   | 2483 | 3.28M | 1987-2003   |
| Person               | 60k   | 8616 | 1.55M | 08/96-08/97 |
| Twitter <sub>1</sub> | 6k    | 3200 | 16k   | 14 months   |
| Twitter <sub>2</sub> | 6k    | 3200 | 31k   | 16 months   |
| Twitter <sub>3</sub> | 6k    | 3200 | 25k   | 29 months   |
| BDT                  | 8k    | 2649 | 234k  | 11/07–04/08 |
|                      |       |      |       |             |

Table: Data statistics

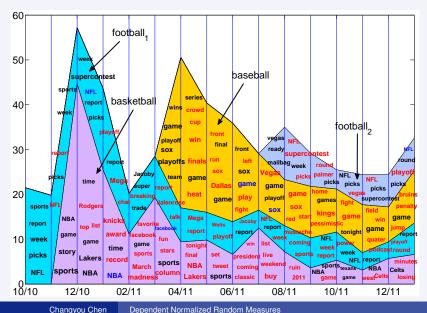
# Experiments: Quantitative evaluation

- *DHNGG*: dependent hierarchical normalized generalized Gamma processes
- DHDP: dependent hierarchical Dirichlet processes
- HDP: hierarchical Dirichlet processes
- DTM: dynamic topic model<sup>2</sup>

| Datasets | ICML                 | JMLR                 | TPAMI                | NIPS        | Person      |
|----------|----------------------|----------------------|----------------------|-------------|-------------|
| DHNGG    | -5.3123e+04          | -7.3318e+04          | -1.1841e+05          | -4.1866e+06 | -2.4718e+06 |
| DHDP     | -5.3366e+04          | -7.3661e+04          | -1.2006e+05          | -4.4055e+06 | -2.4763e+06 |
| HDP      | -5.4793e+04          | -7.7442e+04          | -1.2363e+05          | -4.4122e+06 | -2.6125e+06 |
| DTM      | -6.2982e+04          | -8.7226e+04          | -1.4021e+05          | -5.1590e+06 | -2.9023e+06 |
| Datasets | Twitter <sub>1</sub> | Twitter <sub>2</sub> | Twitter <sub>3</sub> | BDT         |             |
| DHNGG    | -1.0391e+05          | -2.1777e+05          | -1.5694e+05          | -3.3909e+05 |             |
| DHDP     | -1.0711e+05          | -2.2090e+05          | -1.5847e+05          | -3.4048e+05 |             |
|          |                      |                      |                      |             |             |
| HDP      | -1.0752e+05          | -2.1903e+05          | -1.6016e+05          | -3.4833e+05 |             |

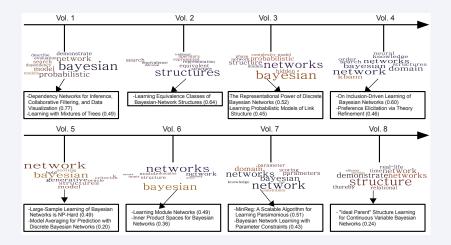
<sup>2</sup>Did not compare with Ahmed& Xing's iDTM [AX10], but ours is expected to be better since iDTM is comparable to HDP.

# Experiments: Topic evolutions on Twitter



### Experiments: Topic evolutions on JMLR

### • 12 vol. from JMLR.



# Experiments: Topic evolutions on Reuters

• 1 year (1996) news from Reuters.



# Experiments: Topic evolutions on blogs

### • 6 month blog data from Daily Kos blogs.



#### | have increased)

| 12/07   | 01/08   | 02/08  | 03/08   |  |  |
|---|---|--|---|--|--|
| 29.7%) course d ll m made<br>nedia point political l'E really<br>hings time want year years | (31.2%) candidates d john ll M<br>news re really thing things<br>time want world year years   | (26.2%) course d ll m political<br>president re really story thing<br>time want work year years                            | (25.4%) course d ll m made medi<br>news political press re really<br>things time want years                           |  |  |
|   | (11.8%) campaign caucus<br>Clinton democratic edwards<br>hampahire hillary Obama<br>primary results state update vote<br>voters won | (17.4%) campaign clinton delegates<br>democratic hillary Obama primary<br>state states where update vote voters<br>win won | (16.2%) campaign Clinton<br>delegate delegates wilkey Obama<br>onio polis race state states where<br>texas vote votes |  |  |
| 10.2%) candidate democratic<br>Memocrats district election                                  | (7.8%) blue candidate congress  | (6.5%) candidate democrat democratic   | (10.2%) ып blue candidate<br>democratic district election   |  |  |
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# Conclusion

- Reviewed and developed theory of normalized random measures (NRM).
- Extended the Poisson based dependency operations to NRMs.
- Application on dynamic topic models.
- Developed a sampler for the proposed model.
- Future work include:
  - Develop more efficient sampler for NGG, specifically, for the dependent NGG.
  - Explore other ways of constructing dependent NRMs, *e.g.*, Lijoi, Nipoti and Prüster's dependent NRMs [LNP12], which is related but somehow different to ours.

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# Thanks for your attention!!!

