Dependent Normalized Random Measures

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Joint work with Wray Buntine & Nan Ding June 9, 2012

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Introduction \mathbb{R}^n Sampling the Shadow Poisson-Dirichlet Process \mathbb{R}^n

Nonparametric Bayesian family

Dynamic topic models

- Dynamic topic models try to model topic evolution over time.
- There are several related dynamic topic models, *e.g.*, Blei&Lafferty's DTM [\[BL06\]](#page-45-0), Ahmed&Xing's iDTM [\[AX10\]](#page-45-1).

Figure: Topic evolution in NIPS, taken from [\[AX10\]](#page-45-1).

Main contributions

- **Posterior analysis for normalized random measures.**
- Develop dependent normalized random measures.
- Apply dependent normalized random measures to dynamic topic modeling to model *birth-death processes*, *dependency* and *power-law* phenomena in topic distributions over time.

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- **·** Basic idea:
	- measurable space: S.
	- \bullet disjoint subsets: $A, B \in \mathbb{S}$.
	- random function:

 $\Phi: \mathbb{S} \longmapsto \mathbb{R}^+$.

$$
\Phi(A) \perp \!\!\! \perp \Phi(B)
$$

• It is shown that completely random measures can be constructed from Poisson processes.

Definition (Poisson Processes:)

A *Poisson process* on $\mathbb S$ is a random subset $\Pi \in \mathbb S$ such that if *N*(*A*) is the number of points of Π in $A \subseteq \mathbb{S}$, then *N*(*A*) is a Poisson random variable with mean $v(A)$, and $N(A_1), \cdots, N(A_n)$ are independent if A_1, \dots, A_n are disjoint.

- Space: S
- **Positive measure:**

 $v : \mathbb{S} \longmapsto \mathbb{R}^+$

- Poisson random measure:
	- *N* : \mathbb{S} → integers
- \bullet *N*(*A*) ∼ Poisson($v(A)$)

Definition (Construction from Poisson processes)

Let *N*(d*t*,d*x*) being a Poisson random measure on a product space $\mathbb{S} = R^+ \times \mathbb{X}$ with mean measure $v(\mathrm{d}t,\mathrm{d}x)$. Construct a random measure $\tilde{\mu}$ to be a linear functional of $N(dt, dx)$ as

$$
\tilde{\mu}(B) = \int_{\mathbb{R}^+\times B} tN(\mathrm{d}t, \mathrm{d}x), \forall B \in \mathscr{B}(\mathbb{X}).
$$

$$
\tilde{\mu}(B) = \int_{\mathbb{R}^+ \times B} t N(\mathrm{d}t, \mathrm{d}x) = \sum_{(J_k, x) \in \Pi \cap (\mathbb{R}^+ \times B)} J_k \delta_x
$$

Proposition

 $\tilde{\mu}$ is a completely random measure on X.

- Call $v(dt, dx) = \rho(dt|x)H(dx)$ the Lévy measure of $\tilde{\mu}$.
- Taking different Lévy measures $v(dt,dx)$ we get different CRMs.

Example (Gamma CRM (Gamma processes))

A Gamma process on X is obtained by setting

$$
v(\mathrm{d}t, \mathrm{d}x) = \frac{e^{-t}}{t} \mathrm{d}t H(\mathrm{d}x).
$$

Sampling a CRM

$$
\tilde{\mu}(B)=\sum_{(J_k,\mathrm{x})\in \Pi\cap(\mathbb{R}^+\times B)}J_k\delta_{\mathrm{x}}
$$

• Cannot directly sample from the Lévy measure $v(\mathrm{d}x,\mathrm{d}t) = \rho(\mathrm{d}t|x)H(x)$ because it is improper.

Size biased sampling starting from the largest jump, then the second largest largest jump \cdots , given by Ferguson and Klass [\[FK72\]](#page-45-2).

- Draw *i.i.d.* samples x_i from the base measure $H(dx)$.
- The *k*-th largest jump has cumulative distribution function:

$$
P(J_k \leq j_k | J_{k-1} = j_{k-1}) = \exp \left\{-\int_{\mathbb{X}} \int_{j_k}^{j_{k-1}} v(\mathrm{d}t, \mathrm{d}x)\right\}.
$$

Normalized random measures

Definition (Normalized Random Measures (NRM))

An NRM is obtained by normalizing the CRM $\tilde{\mu}$ as:

$$
\mu = \frac{\tilde{\mu}}{\tilde{\mu}(\mathbb{X})} = \sum_{k} \frac{J_k}{\sum_{k'} J_{k'}} \delta_{X_k^*} \; .
$$

Definition (Normalized generalized Gamma processes (NGG))

A normalized generalized Gamma process is an NRM with *Lévy measure* being $v(dt,dx) = M \frac{e^{-t}}{t^{1+d}}$ $\frac{e^{-t}}{t^{1+a}}H(\mathrm{d}x), (0 < a < 1)^a.$

*a*The general form is $v(dt,dx) = M \frac{e^{-bt}}{t^{1+a}}$ $\frac{e^{-bt}}{t^{1+a}}H(\mathrm{d} x)(0 < a < 1, b > 0)$, but *b* can be absorbed into M , thus we use $b = 1$.

We denote a NRM with parameters *a*,*M* and base measure $H(\cdot)$ as $NRM(a,M,H(\cdot))$.

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Posterior analysis for the NGG

General form for the posteriors of the NRM is developed in [\[JLP09\]](#page-45-3), here we focus on $\mathsf{NGG^1}.$

Theorem (Posterior of the NGG)

Consider the NGG $(a, M, H(\cdot))$ *. For a data vector* \vec{X} *of length N* i *there are K distinct values* $X^*_1,...,X^*_K$ *with counts* $n_1,...,n_K$ *respectively. The posterior marginal is given by*

$$
p\left(\vec{X}|\mathsf{NGG}(a,M,H(\cdot)\right) \;=\; \frac{e^M a^{K-1} T_{a,M}^{N,K}}{\Gamma(N)} \prod_{k=1}^K (1-a)_{n_k-1} h(X_k^*) \;.\tag{1}
$$

where

$$
T_{a,M}^{N,K} = a \frac{M^K}{e^M} \int_{\mathbb{R}^+} \frac{u^{N-1}}{(1+u)^{N-Ka}} e^{M-M(1+u)^a} du \ . \tag{2}
$$

1 [\[FT12\]](#page-46-0) also derives some similar results.

Posterior analysis for the NGG

• Compare NGG with PYP (Pitman-Yor process)

$$
p(\vec{X}|\text{NGG},\cdots) = \frac{e^M a^{K-1} T_{a,M}^{N,K}}{\Gamma(N)} \prod_{k=1}^K (1-a)_{n_k-1} h(X_k^*) .
$$

$$
p(\vec{X}|\text{PYP},\cdots) = \frac{(b|a)_K}{(b)_N} \prod_{k=1}^K (1-a)_{n_k-1} h(X_k^*) .
$$

Corollary (NGG←→PYP)

 \mathcal{L} *et* $\vec{\mu} \sim \mathcal{N}$ *GG*(*a,M,H*(·)) *and suppose* $M \sim \Gamma(b/a, 1)$ *then it follows that* $\vec{\mu} \sim PYP(a, b, H(\cdot))$

If we also sample *M* using the prior $\Gamma(b/a,1)$ for NGG, then we are sampling from a PYP.

Posterior analysis for the NGG

- This relationship is different from the Poisson-Kingman construction of the PYP, where it is constructed by exponentially tilting an σ -stable process, but we believe they are closely related.
- One problem of the above posterior sampling is the evaluation of $T^{N,K}_{a,M}$, which is computationally expensive and cannot easily be tabulated.

Conditional posterior for the NGG

- $\frac{\prod_{k=1}^K J_k^{n_k}}{\sum_{k=1}^K J_k^{n_k}}$ $\frac{\prod_{k=1}^{k} J_k}{\left(\sum_{k'=1}^{\infty} J_{k'}\right)^{\sum_{k=1}^{K} n_k}}$.
- A well studied auxiliary variable is introduced to eliminate this power term in the denominator. We call it *latent relative mass*.

Definition (Latent relative mass)

The latent relative mass is an auxiliary variable U_N defined as

$$
U_N = \Gamma_N / (\sum_{k=1}^{\infty} J_k), \text{ where } \Gamma_N \sim \gamma(1, N)
$$

After a change of variable, we then have:

$$
\frac{1}{(\sum_{k=1}^{\infty} J_k)^N} p(\Gamma_N) d\Gamma_N = \exp \left\{-U_N \sum_{k=1}^{\infty} J_k\right\} dU_N.
$$

Conditional posterior for the NGG

Theorem (Conditional posterior)

Given NGG $(a, M, H(\cdot))$ *and N observed data* \vec{X} *, assume there are K* jumps such that $n_k > 0$, then (marginalize out jumps)

$$
p\left(\vec{X}, U_N = u, K | N, \text{NGG}(a, M, H(\cdot))\right)
$$

=
$$
\frac{u^{N-1}}{(1+u)^{N-Ka}} (Ma)^K e^{M-M(1+u)^a} \prod_{k=1}^K (1-a)_{n_k-1} h(X_k^*)
$$
. (3)

Moreover (retain jumps),

$$
p\left(\vec{X}, U_N = u, K, J_1, ..., J_K | N, NGG(a, M, H(\cdot))\right)
$$

= $u^{N-1} \left(\frac{Ma}{\Gamma(1-a)}\right)^K e^{M-M(1+u)^a} \prod_{k=1}^K J_k^{n_k-a-1} e^{-(1+u)J_k} h(X_k^*)$ (4)

Posterior sampling for the NGG

$$
Q=\sum_k J_k \delta_{\!X_k^*}
$$

- Conditional posterior sampling for the NGG:
	- Sample the auxiliary variable:

$$
p(U_N|\cdot) \propto \frac{U_N^{N-1}}{(1+U_N)^{N-Ka}} e^{-M(1+U_N)^a}.
$$

• For the jumps J_k with data attached:

$$
J_k \sim \text{Gamma}(U_N + 1, n_k - \frac{1}{2}).
$$

• The rest of jumps form another NGG with an updated Lévy measure

$$
e^{-U_N t}v(\mathrm{d} t,\mathrm{d} x),
$$

which is essentially $\sum_{k: n_k=0} J_k \delta_{\!X^*_k}$

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Dependent NRMs

- There are several ways to construct dependent nonparametric Bayesian models.
- We use the standard dependency operations on Poisson processes to construct dependent NRMs, *e.g.*, *superposition*, *subsampling* and *point transition*.
- This has been used in dependent Dirichlet processes by Lin, Grimson and Fisher [\[LGF10\]](#page-45-4).

Dependency operations

Definition (Superposition of NRMs)

Given *n* independent NRMs μ_1, \cdots, μ_n on \mathbb{X} , the superposition (⊕) is:

$$
\mu_1\oplus\mu_2\oplus\cdots\oplus\mu_n:=c_1\mu_1+c_2\mu_2+\cdots+c_n\mu_n.
$$

where the weights $^a \, c_m = \frac{\tilde{\mu}_m(\mathbb{X})}{\sum_i \tilde{\mu}_i(\mathbb{X})}$ $\frac{\mu_m(\mathbb{A})}{\Sigma_j \tilde \mu_j(\mathbb{X})}$ and $\tilde \mu_m$ is the unnormalized random measures corresponding to µ*m*.

*^a*This is different from Lin *et al.*'s [\[LGF10\]](#page-45-4)

Dependency operations

Definition (Subsampling of NRMs)

Given a NRM $\mu = \sum_{k=1}^\infty r_k \delta_{\theta_k}$ on $\mathbb{X},$ and a measurable function $q: \mathbb{X} \to [0,1]$. If we independently draw $z(\theta) \in \{0,1\}$ for each $\theta \in \mathbb{X}$ with $p(z(\theta) = 1) = q(\theta)$, the subsampling of μ , is defined as

$$
S^{q}(\mu) := \sum_{k:z(\theta_k)=1} \frac{r_k}{\sum_j z(\theta_j) r_j} \delta_{\theta_k},
$$
\n(5)

Dependency operations

Definition (Point transition of NRMs)

Given a NRM $\mu = \sum_{k=1}^{\infty} r_k \delta_{\theta_k}$ on \mathbb{X} , the point transition of μ , is to draw atoms $\theta _{k}^{\prime }$ from a transformed base measure to yield a new NRM as

$$
T(\mu):=\sum_{k=1}^\infty r_k\delta_{\theta_k'}\ .
$$

Properties of operations

Theorem (Posterior under superposition)

Let $\tilde{\mu}_1, \tilde{\mu}_2, \cdots, \tilde{\mu}_n$ be *n* independent CRMs on $\mathbb X$ with Lévy *measures* $v_i(\mathrm{d}t,\mathrm{d}x)$, $\tilde{\mu} = \bigoplus_{i=1}^n \tilde{\mu}_i$. The posterior of $\tilde{\mu}$ given *observed data {*(*X* ∗ *k* ,*nk*)*} is given by*

$$
\tilde{\mu}_n + \sum_{k=1}^K J_k \delta_{\!X_k^*},
$$

- **1** $\tilde{\mu}_n$: *a CRM with* $v(dt, dx) = e^{-ut} (\sum_{i=1}^n v_i(dt, dx))$;
- ² *X* ∗ *k* :*fixed points;*
- ³ *J^k* : *jumps with densities proportional to* $t^{n_k} e^{-ut} (\sum_{i=1}^n v_i(dt, dx)).$

Properties of operations

Theorem (Lévy measure under subsampling)

Let $\tilde{\mu} = \sum_{k=1}^{\infty} J_k \delta_{X_k^*}$ be a CRM on \mathbb{X} with Lévy measure $v(\mathrm{d}t,\mathrm{d}x)$, $S^q(\tilde{\mu})$ *be its subsampling version with acceptance rate* $q(\cdot)$ *, then S q* (µ˜) *has the Lévy measure of*

 $q(dx)v(dt, dx)$.

Properties of operations

Lemma (Applied on graphs)

Subsampling is commutative:

$$
S^{q'}(S^q(\tilde{\mu})) = S^q(S^{q'}(\tilde{\mu})) = S^{q'q}(\tilde{\mu}))
$$

Transitions commute under constant subsampling rates:

$$
S^q(T(\tilde{\mu})) = T(S^q(\tilde{\mu}))
$$

Subsampling and transition distribute over superposition:

 $S^q(\tilde{\mu} \oplus \tilde{\mu}') = S^q(\tilde{\mu}) \oplus S^q(\tilde{\mu}') \ , \qquad T(\tilde{\mu} \oplus \tilde{\mu}') = T(\tilde{\mu}) \oplus T(\tilde{\mu}') \ .$

Superposition is commutative and associative:

$$
\tilde{\mu} \oplus \tilde{\mu}' = \tilde{\mu}' \oplus \tilde{\mu}, \qquad (\tilde{\mu} \oplus \tilde{\mu}') \oplus \tilde{\mu}'' = \tilde{\mu} \oplus (\tilde{\mu}' \oplus \tilde{\mu}'')
$$

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Applications: Dynamic topic models

We want to model the following phenomenas in dynamic topic models:

- Birth-death processes.
- Dependency of topics between time frames (partially exchangeable).
- Power-law phenomena.

These objectives are well tackled by the dependent NRMs framework.

Model construction

$$
\mu'_m=T(S^q(\mu'_{m-1}))\oplus \mu_m
$$

- $\mathbf{1}$ t_i : epochs.
- ² µ*i* : new topics at epoch *i*.
- \mathbf{p}^{\prime} μ^{\prime}_i : topic distribution for epoch *i*.
- **4** Each epoch has a hierarchical NRM structure.

Model construction

Relation between NRMs and CRMs

Theorem

The following two generative processes are equivalent:

Manipulate the normalized random measures:

$$
\mu'_m \sim T(S^q(\mu'_{m-1})) \oplus \mu_m, \qquad \text{for } m > 1.
$$

Manipulate the completely random measures:

$$
\tilde{\mu}'_m \sim \tilde{T}(\tilde{S}^q(\tilde{\mu}'_{m-1})) \oplus \tilde{\mu}_m, \quad \mu'_m = \frac{\tilde{\mu}'_m}{\tilde{\mu}'_m(\mathbb{X})} \quad \text{for } m > 1.
$$

The resultant NRMs μ'_m *'s correspond to:*

$$
\mu'_{m} = \sum_{j=1}^{m} \frac{\left(q^{m-j}\tilde{\mu}_{j}\right)(\mathbb{X})}{\sum_{j'=1}^{m} \left(q^{m-j'}\tilde{\mu}_{j'}\right)(\mathbb{X})} T^{m-j}(\mu_{j}), \qquad \text{for } m > 1
$$

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Sampling

At each time frame *m*, we do:

- **Top level**: slice sample *Jmk* (ends up finite jumps).
- **Second Level**: subsample J'_{mk} by inheriting from $J_{m'k}$ (top level), $m' \leq m$ with Bernoulli trials.
- **Third level**: construct μ'_m by normalizing J'_{mk} .

Hierarchical NRMs:

- \bullet sample topic assignments s_{mii} using a generalized Blackwell-MacQueen sampling scheme for the hierarchical NRM.
- Sample #customers for the parent restaurant n'_{mk} by simulating a generalized Chinese restaurant process for the NRM.

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Datasets

• Academic, news, Twitter, blog datasets.

Table: Data statistics

Experiments: Quantitative evaluation

- *DHNGG*: dependent hierarchical normalized generalized Gamma processes
- *DHDP*: dependent hierarchical Dirichlet processes
- *HDP*: hierarchical Dirichlet processes
- *DTM:* dynamic topic model²

 $2D$ id not compare with Ahmed& Xing's iDTM [\[AX10\]](#page-45-1), but ours is expected to be better since iDTM is comparable to HDP.

Experiments: Topic evolutions on Twitter

Experiments: Topic evolutions on JMLR

• 12 vol. from JMLR.

Experiments: Topic evolutions on Reuters

• 1 year (1996) news from Reuters.

Experiments: Topic evolutions on blogs

6 month blog data from Daily Kos blogs.

I have increased)

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Conclusion

- Reviewed and developed theory of normalized random measures (NRM).
- Extended the Poisson based dependency operations to NRMs.
- Application on dynamic topic models.
- Developed a sampler for the proposed model.
- **•** Future work include:
	- Develop more efficient sampler for NGG, specifically, for the dependent NGG.
	- Explore other ways of constructing dependent NRMs, *e.g.*, Lijoi, Nipoti and Prüster's dependent NRMs [\[LNP12\]](#page-46-1), which is related but somehow different to ours.

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Thanks for your attention!!!

