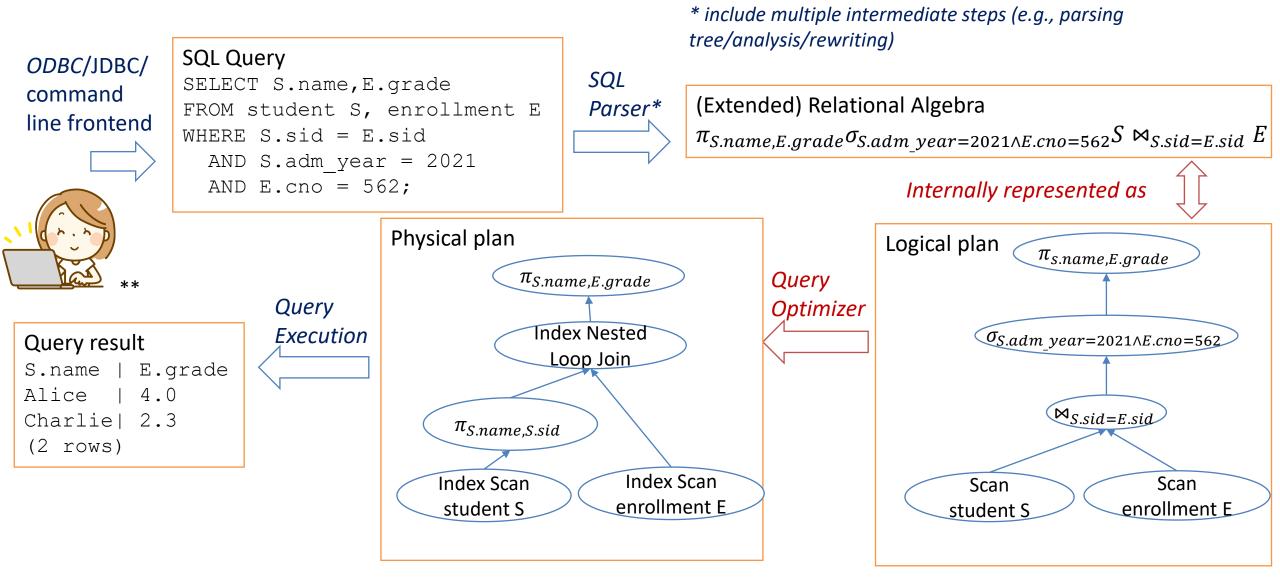
CSE462/562: Database Systems (Spring 23) Lecture 18: Query Optimization Overview 4/20/2023



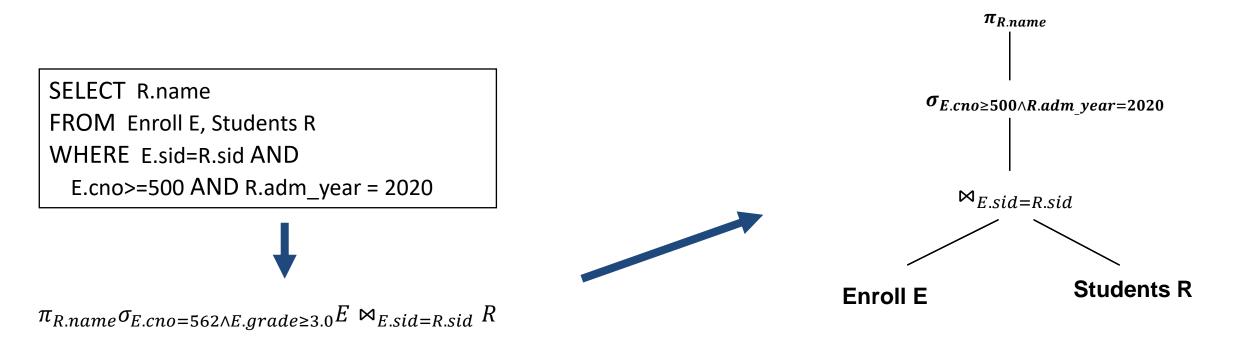
Query processing overview



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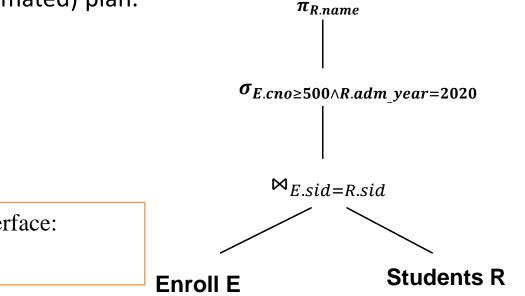
Query optimization overview

- Query can be converted to relational algebra
- Relational Algebra converted to tree, joins as branches
- Each operator has implementation choices
- Operators can also be applied in different order!



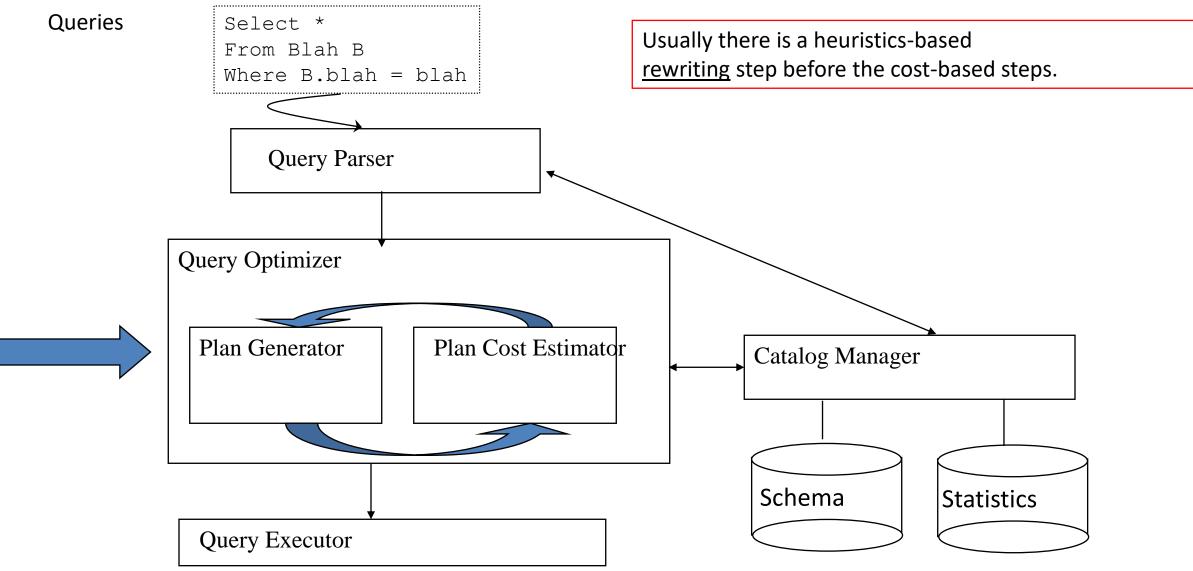
Query optimization overview

- <u>Plan:</u> Tree of R.A. ops (and some others) with choice of algorithm for each op.
 - Each operator typically implemented using a `pull' interface: when an operator is `pulled' for the next output tuples, it `pulls' on its inputs and computes them.
- Two main issues:
 - For a given query, what plans are considered?
 - Algorithm to search plan space for cheapest (estimated) plan.
 - How is the cost of a plan estimated?
- Ideally: Want to find best plan.
- Reality: Avoid worst plans!



Relational operators have a uniform *iterator* interface: *open(), get_next(), close()*

Cost-based query optimizer



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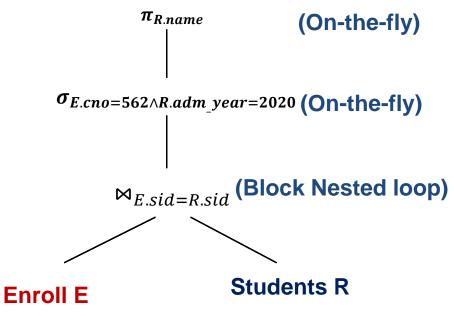
Running example

- Notations: for relation *R*
 - T_R : number of records, N_R : number of pages in its heap file, B_R : (average) number of tuples per page
 - h_I : height of a B-tree index I over the file
 - *M*: private workspace size in pages
- Running example
 - Student: R(sid: int, name: varchar(19), login: varchar(19), major: char(2), adm_year: int)
 - 50 bytes/tuple, $B_R = 80$, $T_R = 40,000$, $N_R = 500$
 - Assume the student records in the table span 10 years (between 2012 and 2022)
 - Enrollment: E(<u>sid: int, semester: char(4), cno: int</u>, grade: double)
 - 20 bytes/tuple, $B_E = 200$, $T_E = 200,000$, $N_E = 1000$
 - Assume 50% of the enrollment records belong to the graduate level (>=500) courses
- Consider a simplified cost model: *cost = #page_transfers (i.e., ignoring the random seeks)*
 - Often good enough for approximating the trend of the cost relative to data size
 - Correct size estimation is key to a correct comparison of costs
- Assume we have 5 pages in the buffer CSE462/562 (Spring 2023): Lecture 18

Motivating example

SELECT R.name FROM Enroll E, Students R WHERE E.sid=R.sid AND

E.cno=562 AND R.adm_year = 2020



Cost = 1000 + 1000 * 500 = 501,000 I/Os

- By no means the worst plan!
- Misses several opportunities: selections could have been
 `pushed' earlier, no use is made of any available indexes, etc.
- *Goal of optimization:* To find more efficient plans that compute the same answer.

Relational algebra equivalence

- Rules that allow the optimizer to transform a logical plan into an equivalent plan with the same output over any database instance
- <u>Selections</u>:
 - Cascade: $\sigma_{\theta_1 \land \theta_2} E \equiv \sigma_{\theta_1} \sigma_{\theta_2} E$
 - Commutative: $\sigma_{\theta_1}\sigma_{\theta_2}E\equiv\sigma_{\theta_2}\sigma_{\theta_1}E$
- Projections:
 - Cascade: $\pi_{A_1}\pi_{A_2} \dots \pi_{A_n}E \equiv \pi_{A_1}(E)$ where $A_1 \subseteq A_2 \subseteq \dots \subseteq A_n$
 - Only need to perform the final projection in a sequence of projections
- (Inner) Joins or Cartesian product:
 - Commutative: $E_1 \Join_{\theta} E_2 \equiv E_2 \bowtie_{\theta} E_1$ (allows switching the inner and outer)
 - Associative
 - Special case natural join: $(E_1 \bowtie E_2) \bowtie E_3 \equiv E_1 \bowtie (E_2 \bowtie E_3)$
 - General theta join: $(E_1 \bowtie_{\theta_1} E_2) \bowtie_{\theta_2 \land \theta_3} E_3 \equiv E_1 \bowtie_{\theta_1 \land \theta_3} (E_2 \bowtie_{\theta_2} E_3)$
 - Implication: inner joins can be done in any order!
 - Join reordering: an important optimization step in DBMS CSE462/562 (Spring 2023): Lecture 18

Assuming θ_2 only involves fields in E_2 and E_3

Relational algebra equivalence

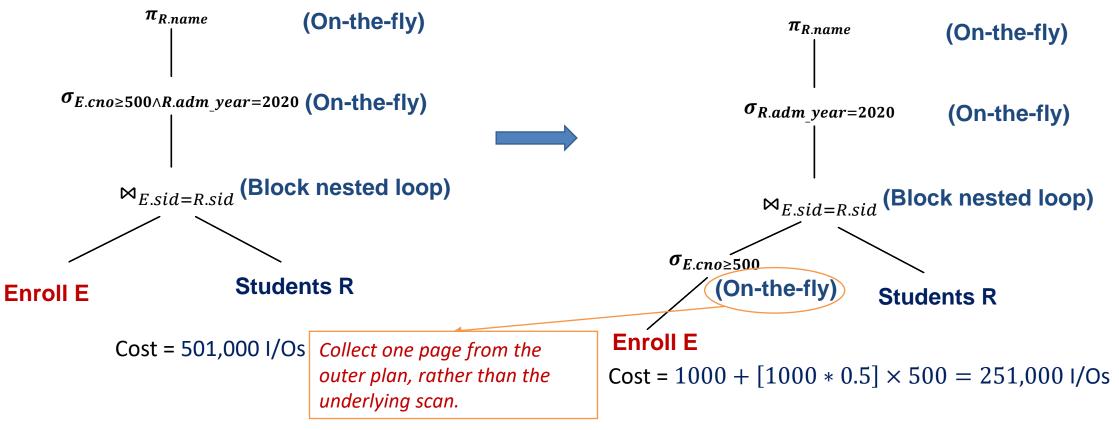
- Rules for more than one operator
 - Selection can be combined with inner join/cartesian product

$$\sigma_{\theta_1}(E_1 \bowtie_{\theta_2} E_2) \equiv E_1 \bowtie_{\theta_1 \land \theta_2} E_2$$

- <u>Projection push-down</u>: select/join and projection commutes (provided that the predicate only involves the projected fields) $\pi_A \sigma_{\theta} E \equiv \sigma_{\theta} \pi_A E$ when $Var(\theta) \subseteq A$ $\pi_{A_1 \cup A_2}(E_1 \bowtie_{\theta} E_2) \equiv \pi_{A_1} E_1 \bowtie_{\theta} \pi_{A_2} E_2$ when $Var(\theta) \subseteq A_1 \cup A_2$ and A_1, A_2 only involve fields from E_1, E_2 , resp.
- <u>Selection push-down</u>: join and select commutes (provided that the selection predicate only involves attributes from one side) $\sigma_{\theta_1}(E_1 \Join_{\theta} E_2) \equiv (\sigma_{\theta_1} E_1) \Join_{\theta} E_2$ when $Var(\theta_1) \subseteq A(E_1)$ (set of fields in E_1)
- More rules about other operators, e.g., aggregation, set operations, sort, ...
- Note: rules involving outer joins may be different
 - Exercise: Can we always push selection through outer joins? What about projections?

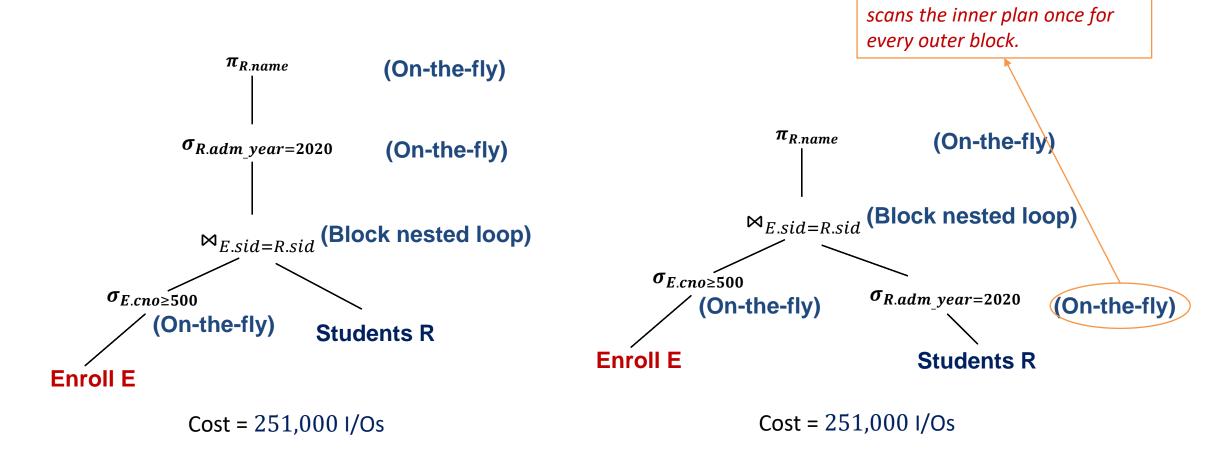
Selection push-down (no index)

- Heuristics 1: perform selections as early as possible
 - Selection is often very cheap or "free" (in I/O only cost model)
 - reduces intermediate size



Selection push-down (no index)

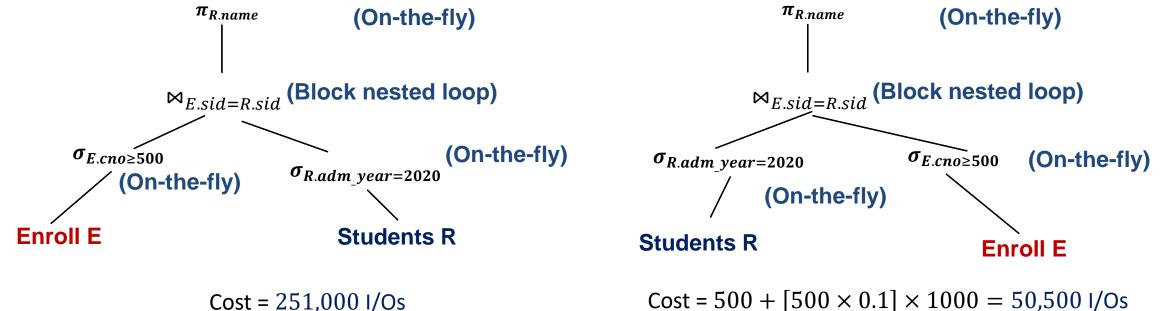
• Can also push-down on the other side



No impact on I/O because BNL

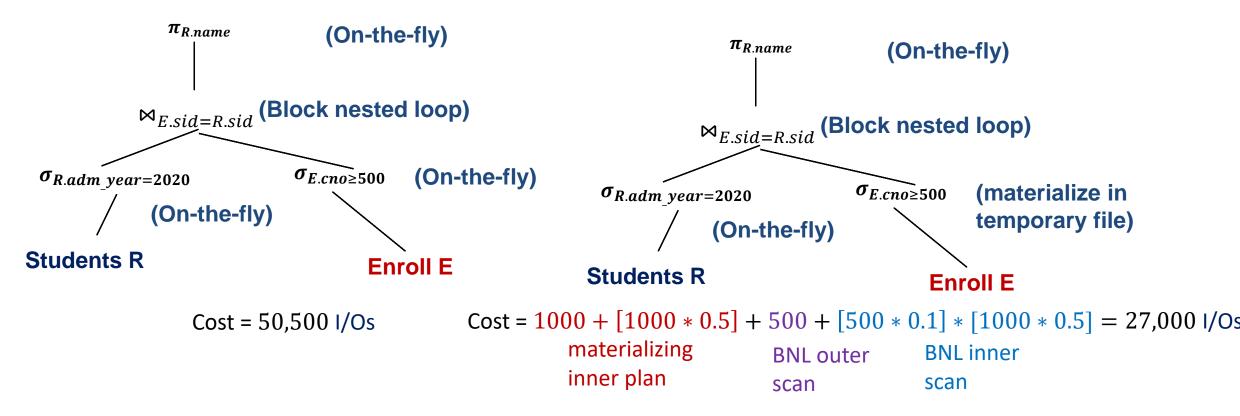
Join reordering

- Different join ordering may result in different cost
 - even if we use the same join algorithm
 - Generally, the outer plan should have a smaller output in BNL
 - what about hash join/sort merge join?



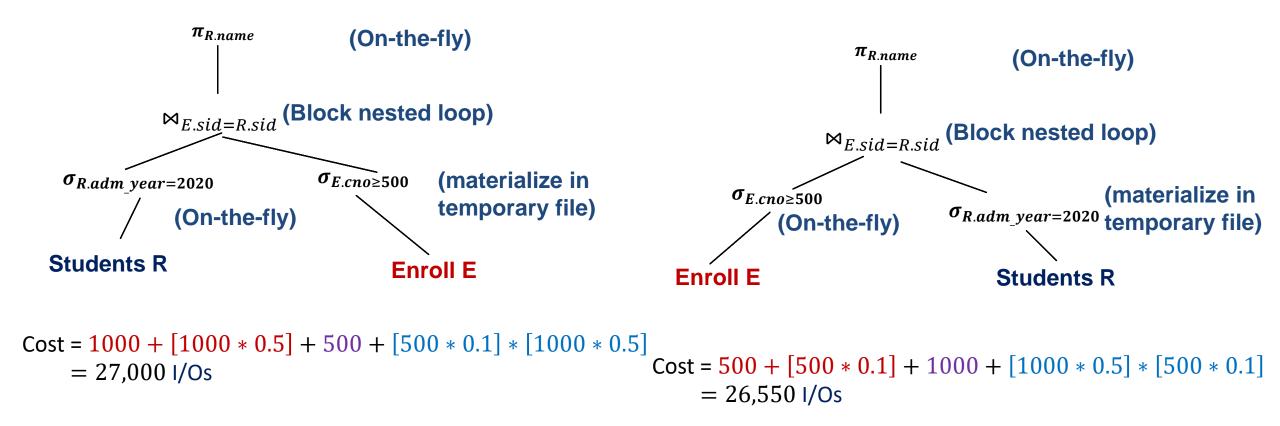
Materialization of inner plan

• We can also choose to materialize the inner plan for BNL to save repeated scan on the original relation



Materialization of inner plan

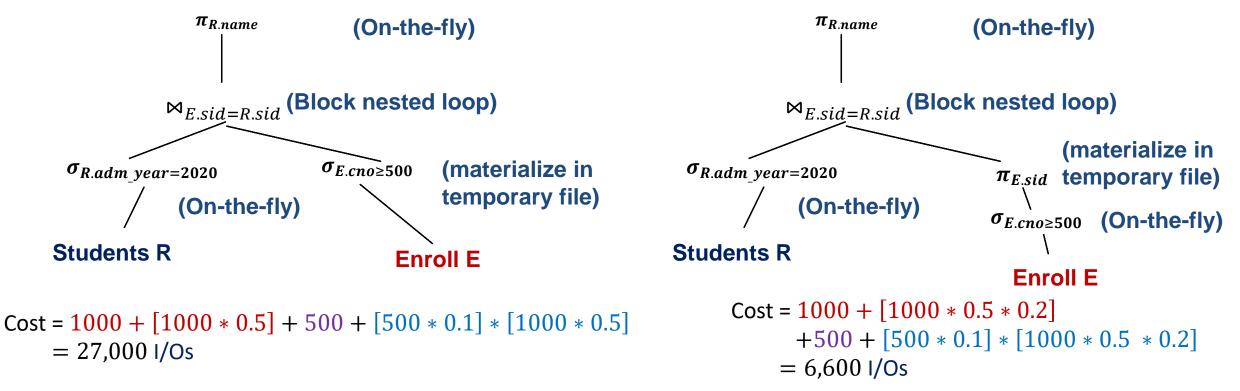
• Sometimes with materialization, it might be cheaper to use the larger plan as the outer



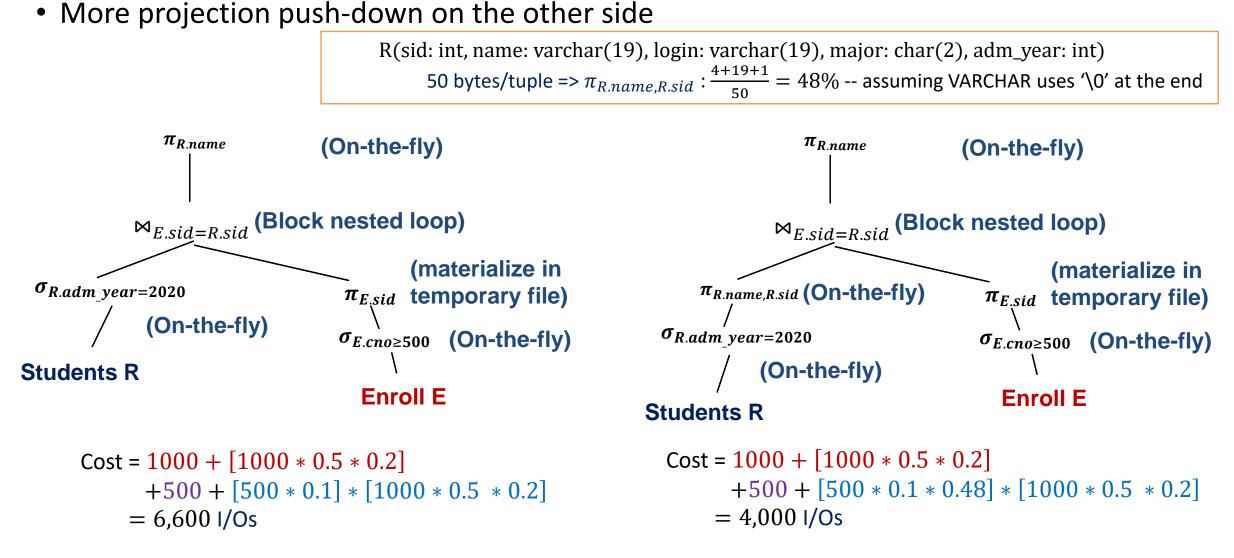
Projection push-down

- Heuristics 2: apply projection as early as possible
 - helps if materializing plan output

Enrollment: E(<u>sid: int, semester: char(3), cno: int</u>, grade: double) 20 bytes/tuple => $\pi_{E.sid}$: $\frac{4}{20}$ = 20% in size after projection

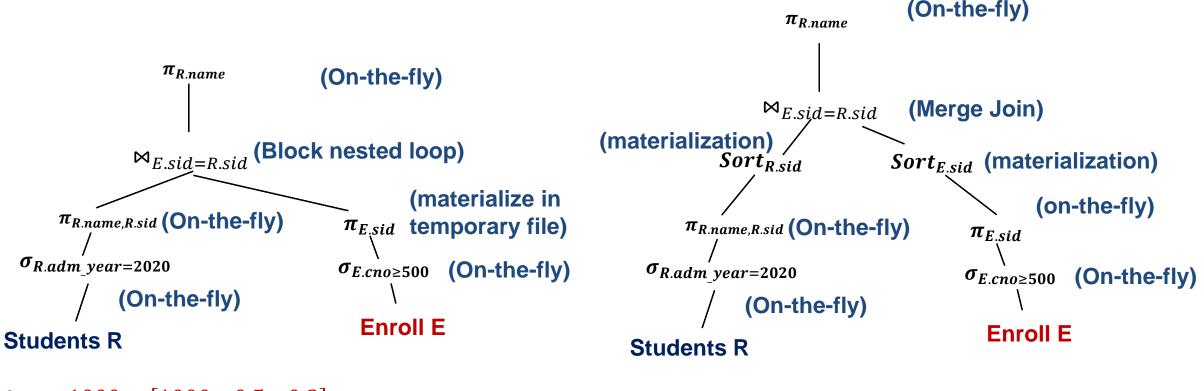


Projection push-down



Choice of join algorithms

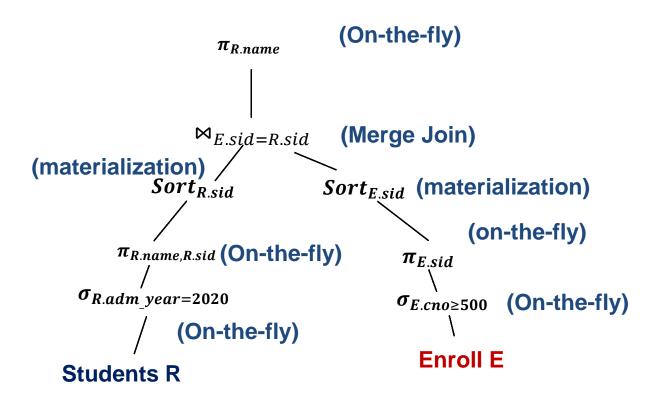
• If we switch to sort-merge join with 5 buffers



```
Cost = 1000 + [1000 * 0.5 * 0.2]
+500 + [500 * 0.1 * 0.48] * [1000 * 0.5 * 0.2] Cost = ?
= 4,000 I/Os
```

Choice of join algorithms

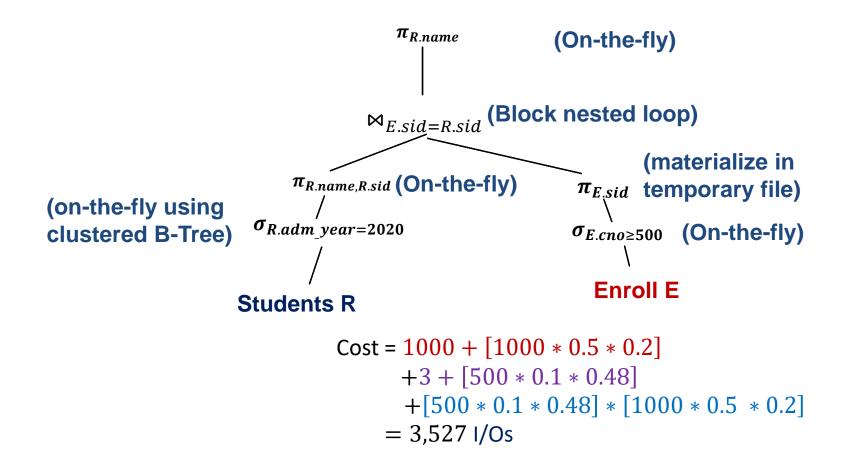
- Sort outer:
 - Size after pass 0: [500 * 0.1 * 0.48] = 24
 - 4 pages/run, 6 runs (need one input buffer for table scan)
 - # merge passes = $\lceil \log_4 6 \rceil = 2$
 - Total I/O: $500 + 24 + 2 \times 2 \times 24 = 620$
- Sort inner: # I/O = 1700
- Merge
 - assuming d = 5 and always fit in one page
 - 24 + 100 = 124
- Total cost = 620 + 1700 + 124 = 2,444 I/Os
 - vs BNL: 4,000 I/Os



Cost = ?

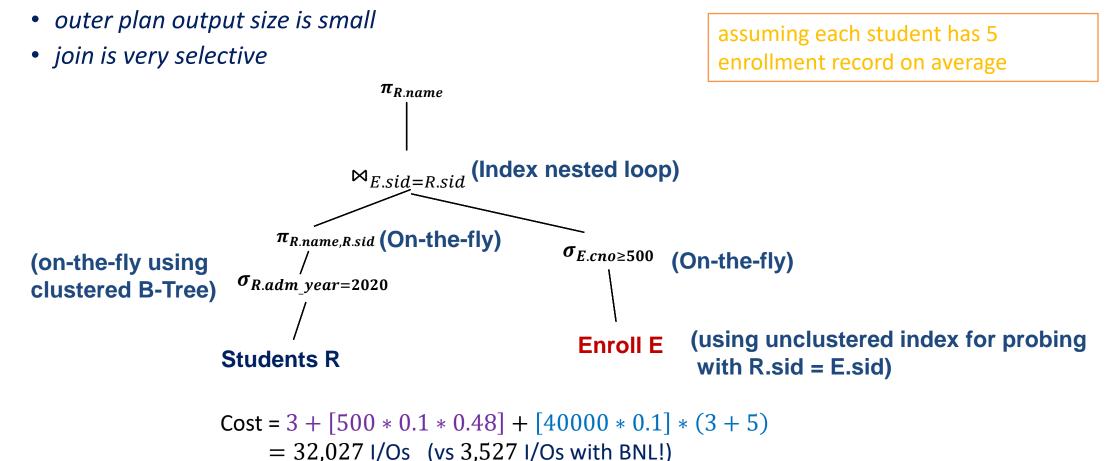
Using indexes

• If we have a clustered B-Tree index over $R(adm_yaer)$, h = 3



Using indexes

- If we have an unclustered B-Tree index over E(sid), h = 3
 - Generally, index nested loop is a bad choice unless both of the following is true



What's needed for query optimization?

- A closed set of operators
 - Relational ops (table in, table out)
 - Encapsulation based on iterators
- Plan space, based on
 - Based on relational equivalences
- Cost Estimation, based on
 - Cost formulas
 - Size estimation, based on
 - Catalog information on base tables
 - Selectivity (Reduction Factor) estimation
- A search algorithm
 - To sift through the plan space based on cost!

Summary

- Today's lecture
 - Query optimization overview
 - Relational algebra equivalence
 - Query optimization is needed to ensure not-too-bad performance if not the best
 - Need to understand the impact of cost model/physical data layout/indexing for a given query
- Next lecture(s)
 - Plan size and cost estimation
 - How to search in the optimization space
 - System R style query optimizer