



CSE 331: Algorithms & Complexity “BFS”

Prof. Charlie Anne Carlson (She/Her)

Lecture 11

Monday September 22nd, 2025



University at Buffalo®



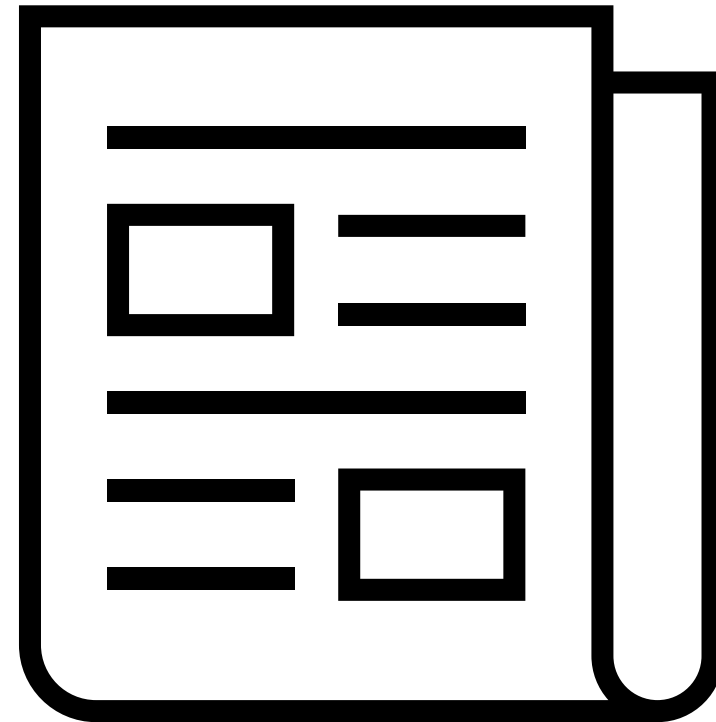
Schedule

1. Course Updates
2. Graph Connectivity
3. Graph Traversal
 1. BFS
 2. DFS
 3. WFS



Course Updates

- HW 1 Grading Out Tomorrow
- HW 2 Due Tomorrow
- HW 3 Out Tomorrow
- Group Project
 - Team Emails Soon
 - No Autolab Registration
- First Quiz NEXT Monday!



Connectivity Problem(s)

s-t Connectivity Problem:

Input: Graph $G = (V, E)$, source s , and destination t .

Output: True if there exists a path and False otherwise.

s-t Shortest Path Problem:

Input: Graph $G = (V, E)$, source s , and destination t .

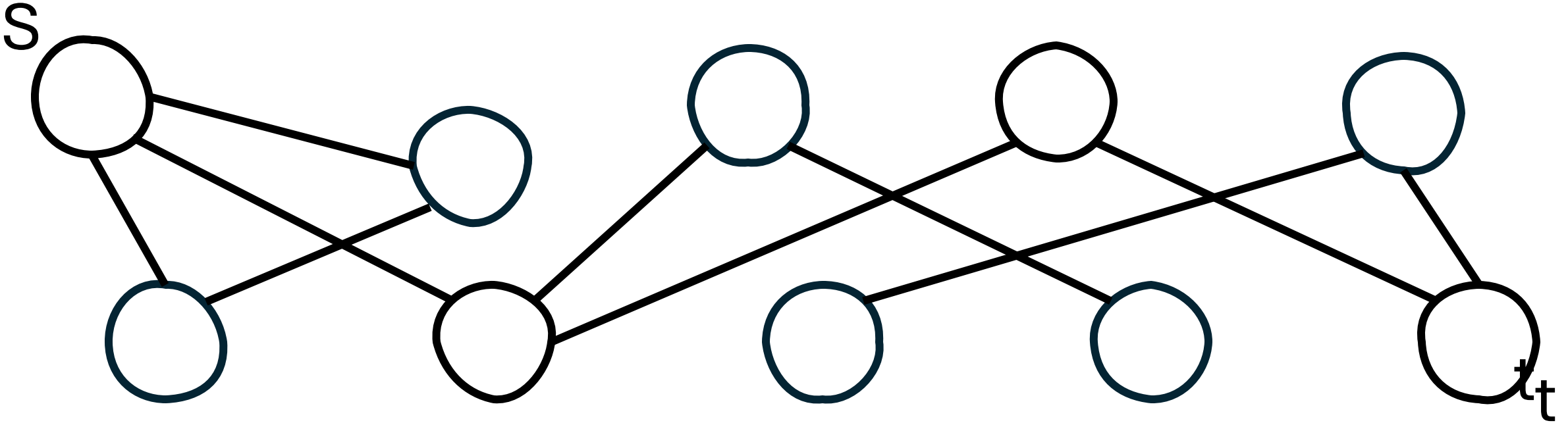
Output: The length of the shortest path from s to t (∞ if there is no path).

Another Connectivity Problem

Graph Connectivity:

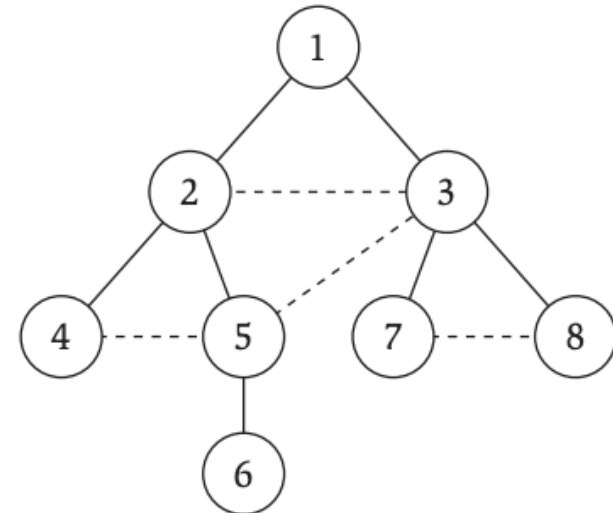
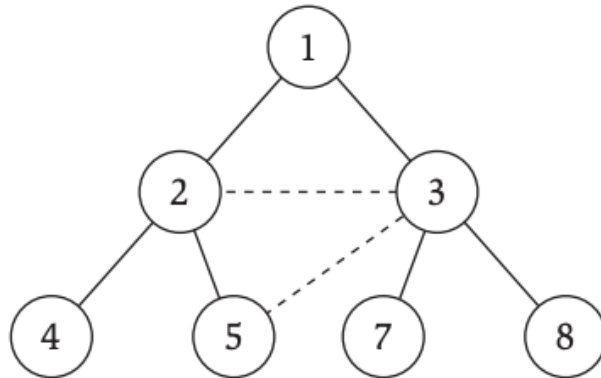
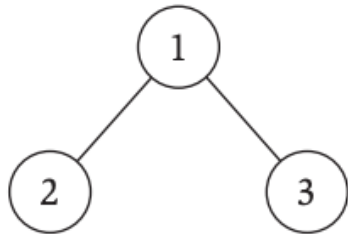
Input: $G = (V, E)$ and $s \in V$

Output: $T = \{u \in V : \text{there exists a path from } s \text{ to } u \text{ in } G\}$



Breadth First Search (Layers)

- $L_0 = s$
- $L_1 =$ neighbors of L_0 .
- $L_2 =$ neighbors of L_1 that are not in L_0 .
- $L_i =$ neighbors of L_{i-1} that are not in previous layer.



Breadth First Search (“Algorithm”)

- Input: $G = (V, E)$ and $s \in V$
- Let $L_0 = \{s\}$
- Assume L_0, \dots, L_i have been constructed:
 - Let L_{i+1} be nodes do not appear in L_0, \dots, L_i and have an edge to L_i .
 - If L_{i+1} is empty, stop.
- Return all layers.

Breadth First Search (Properties)

- For each $j \geq 0$, layer L_j produced by BFS consists of all nodes at distance j from s .
- There is a path from s to t if and only if t appears in some layer.
- For any $\{u, v\} \in E$, if $u \in L_i$ and $v \in L_j$ then i and j differ by at most 1.
- You can think of the output as a tree! We call this the **BFS (discovery) Tree**.

Breadth First Search (Properties)

Claim: For any $\{u, v\} \in E$, if $u \in L_i$ and $v \in L_j$ then i and j differ by at most 1.

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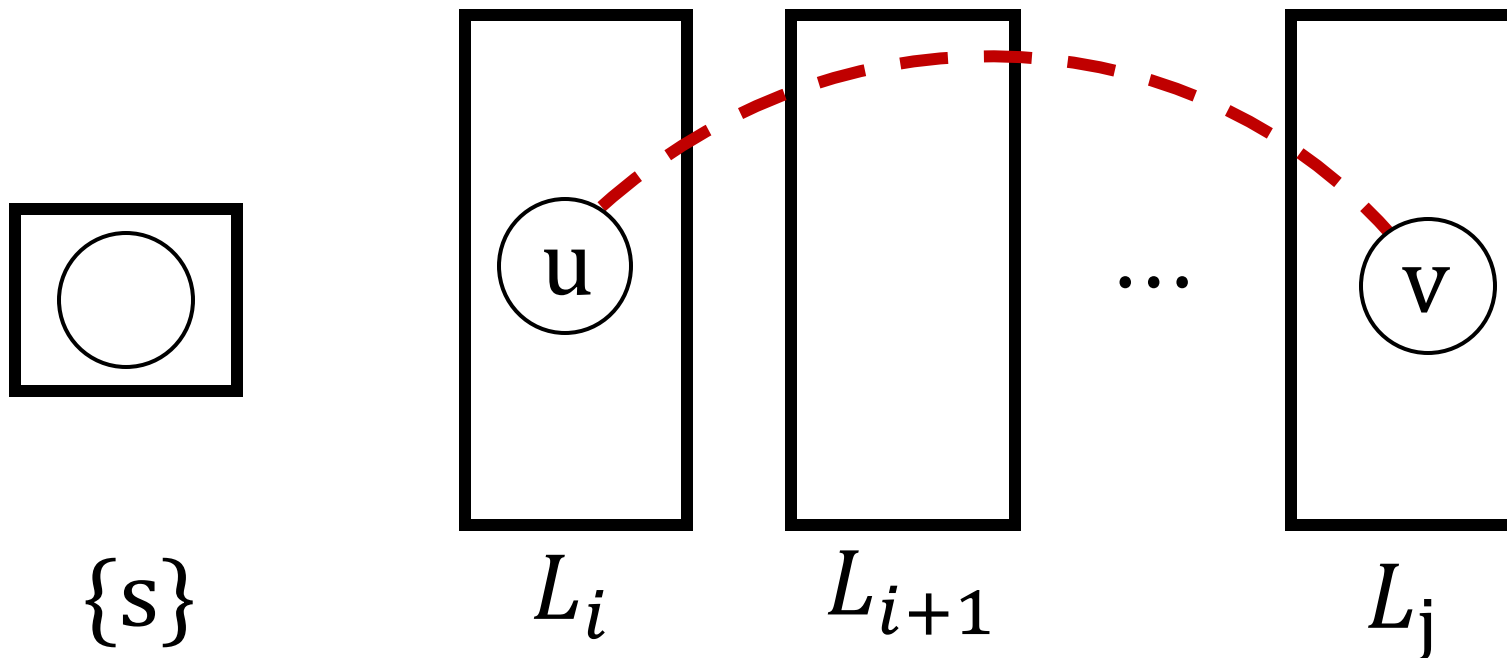
Proof Outline:

- Without loss of generality, we assume that $i \leq j$.
- Suppose for the sake of contradiction that $d(i, j) > 1$.

Breadth First Search (Properties)

Proof Outline:

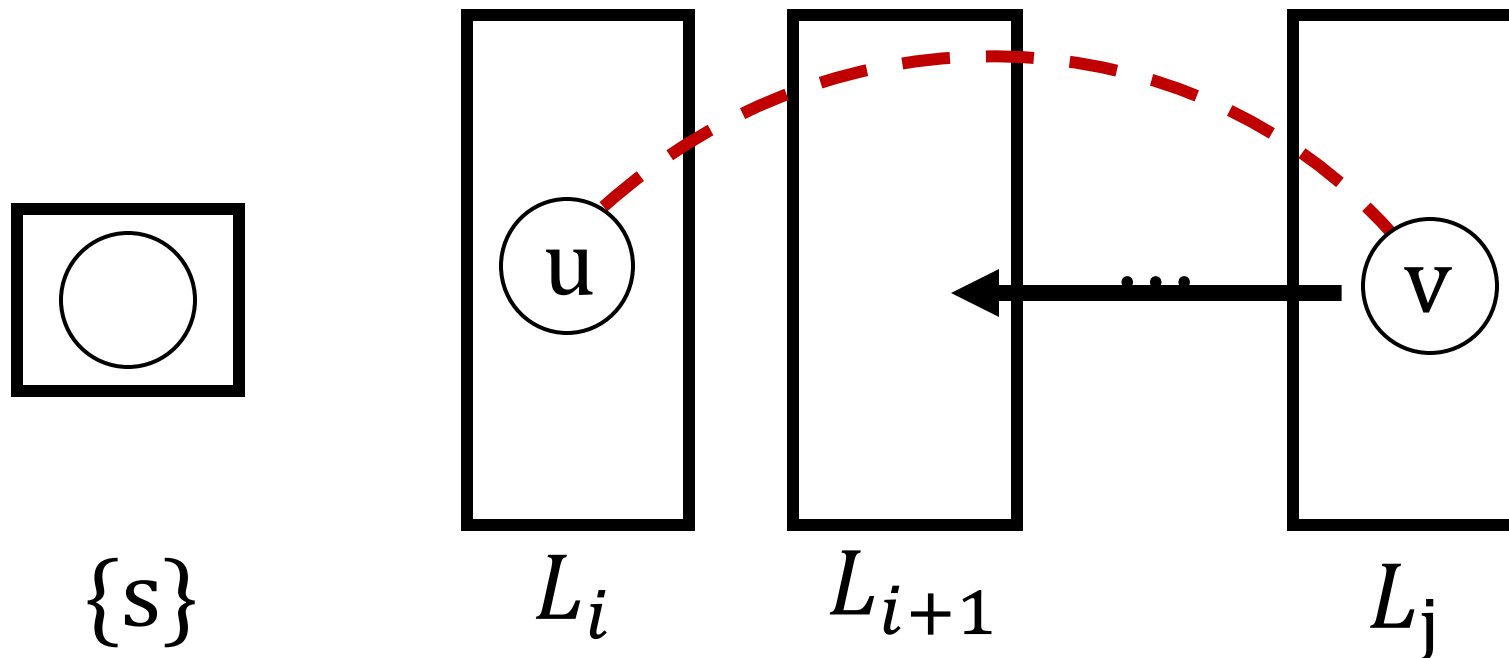
- Without loss of generality, we assume that $i < j$.
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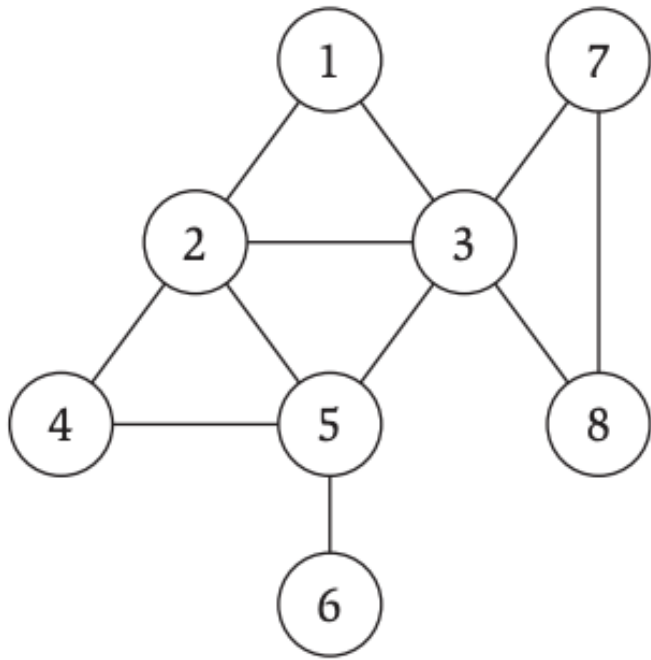


Breadth First Search (Properties)

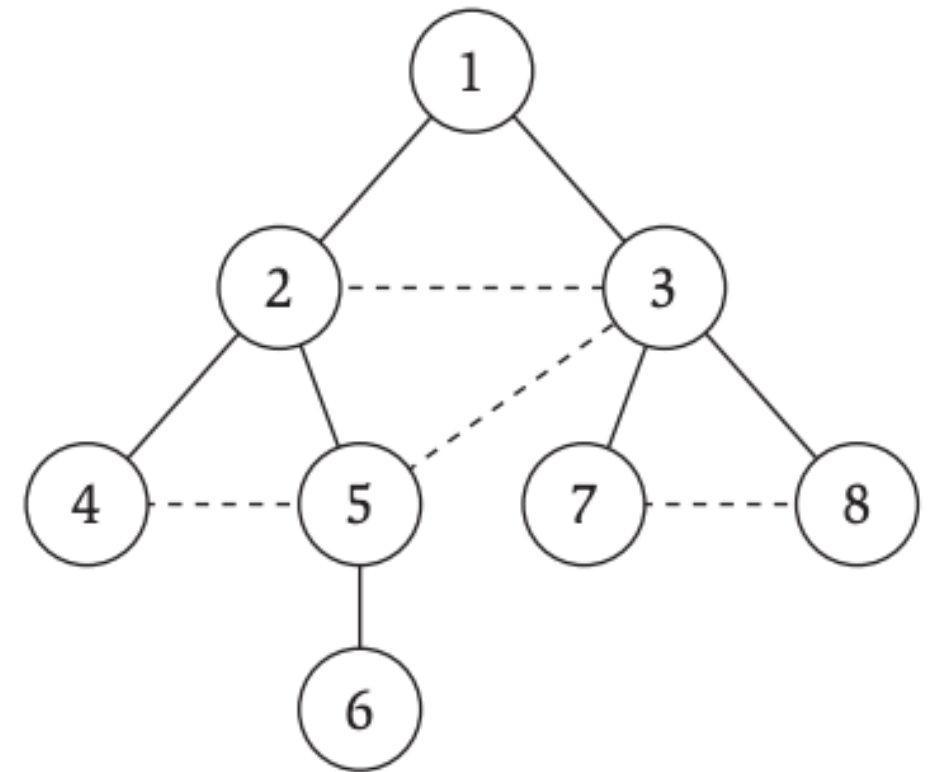
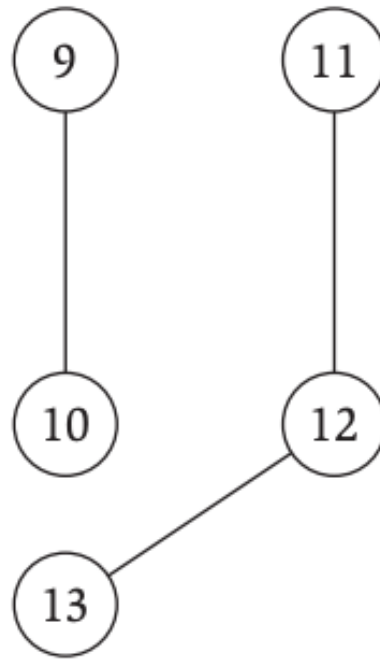
Proof:

- Without loss of generality, we assume that $i < j$.
- Suppose for the sake of contradiction that $d(i, j) > 1$.
 - This implies $i + 1 < j$.
- Then $u \in L_i, v \notin L_0, L_1, \dots, L_i$, and $\{u, v\} \in E$.
 - Hence, BFS would have put $v \in L_{i+1}$.
 - This contradicts initial assumption that $v \in L_j$ and $j > i + 1$.

Breadth First Search (Tree)

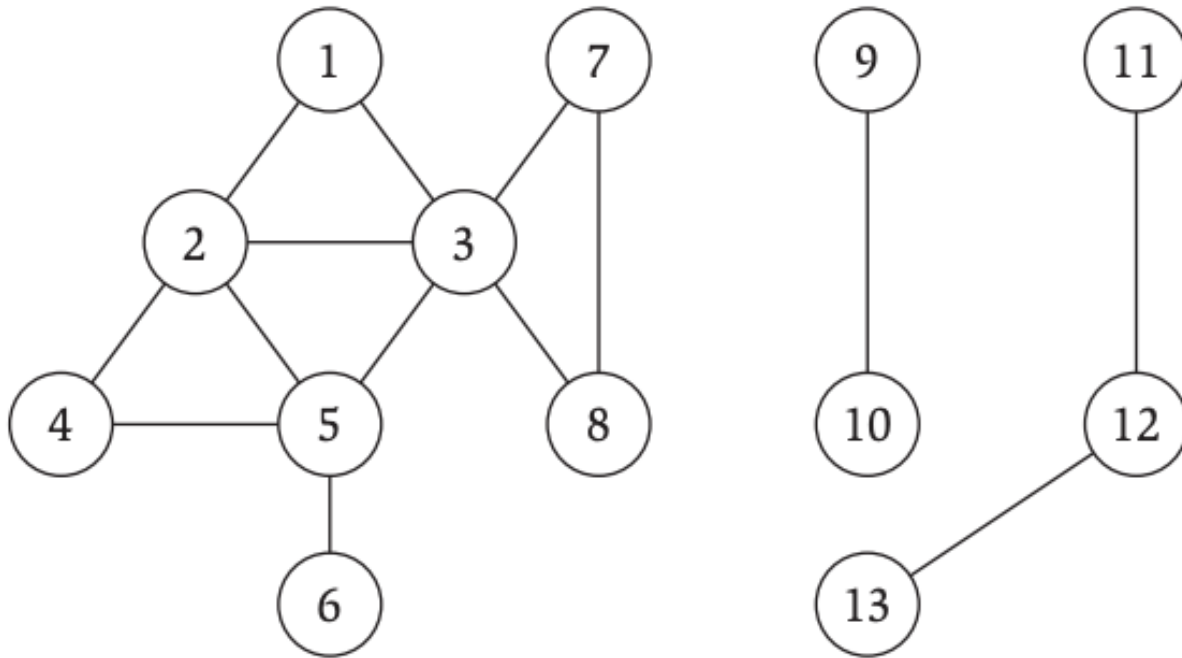


Original Graph

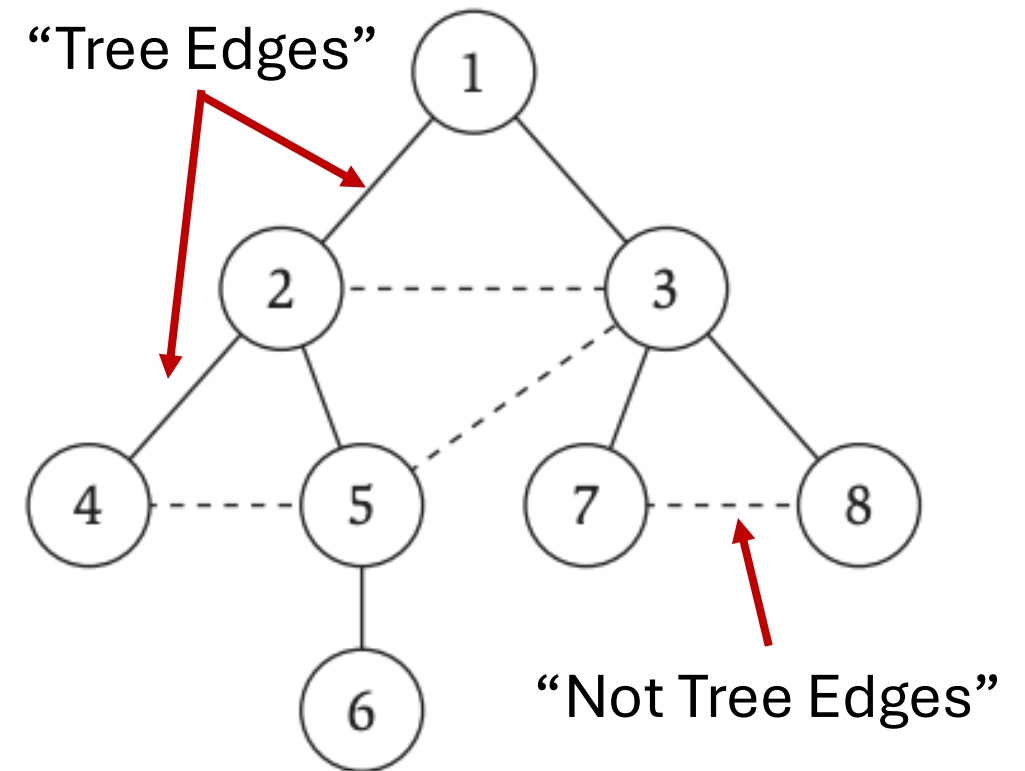


Search Tree

Breadth First Search (Tree)

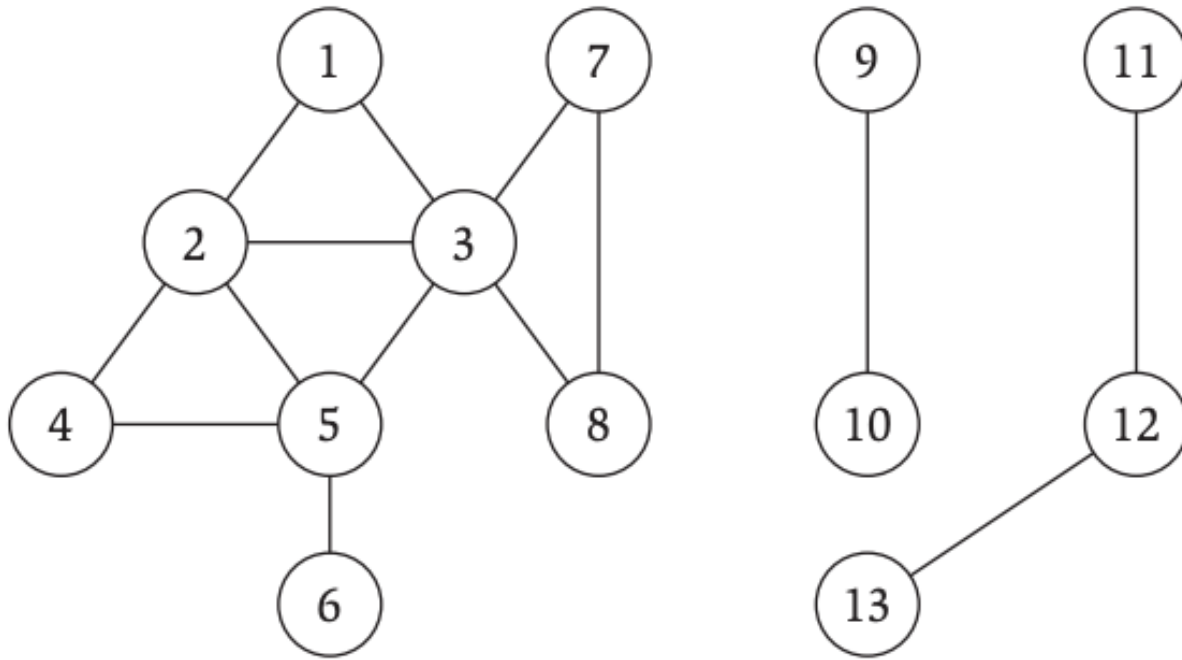


Original Graph



Search Tree

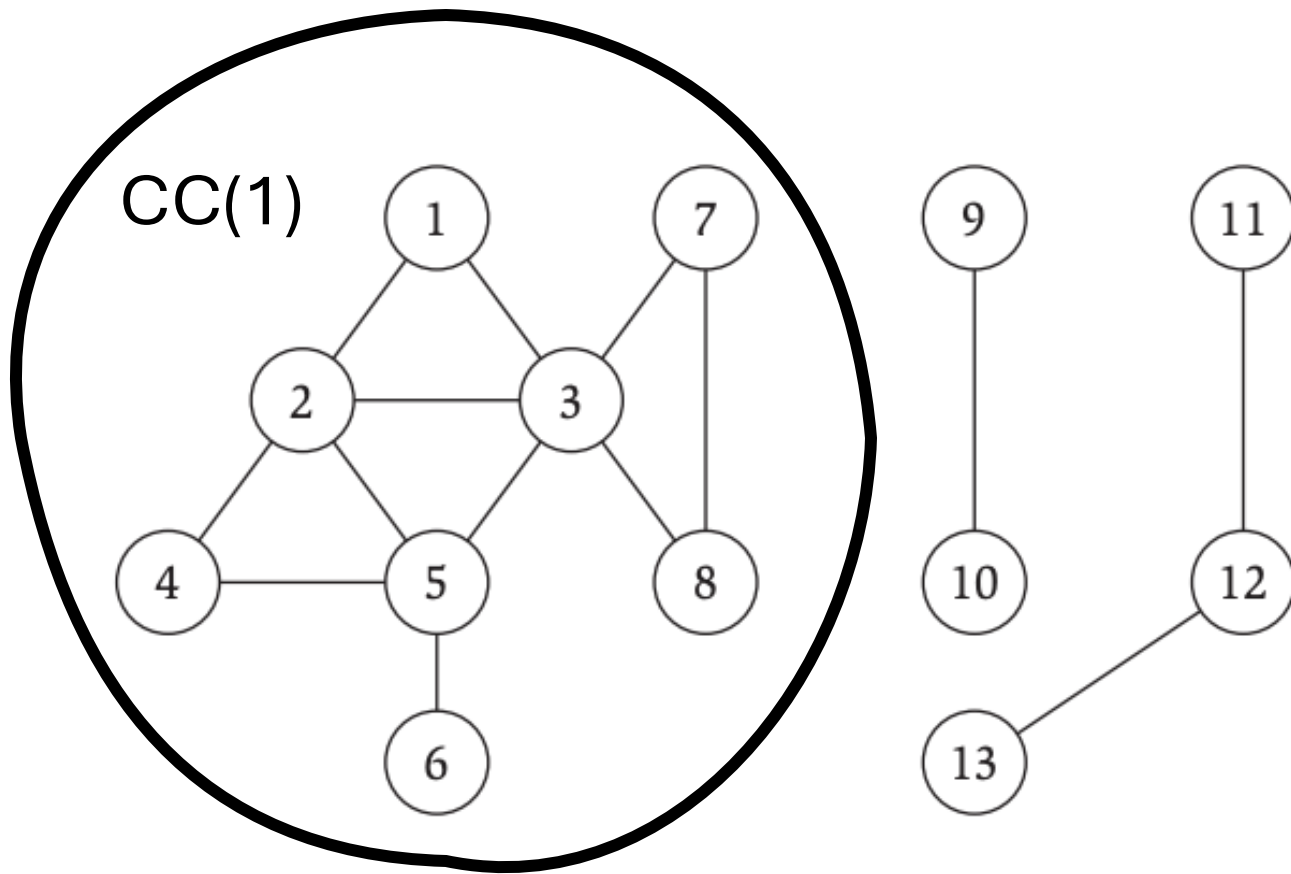
Connected Component of (s) (CC(s))



The $CC(s)$ is the set of all vertices that are connected to s by a path.

“The set of vertices that you can reach from s using a simple path.”

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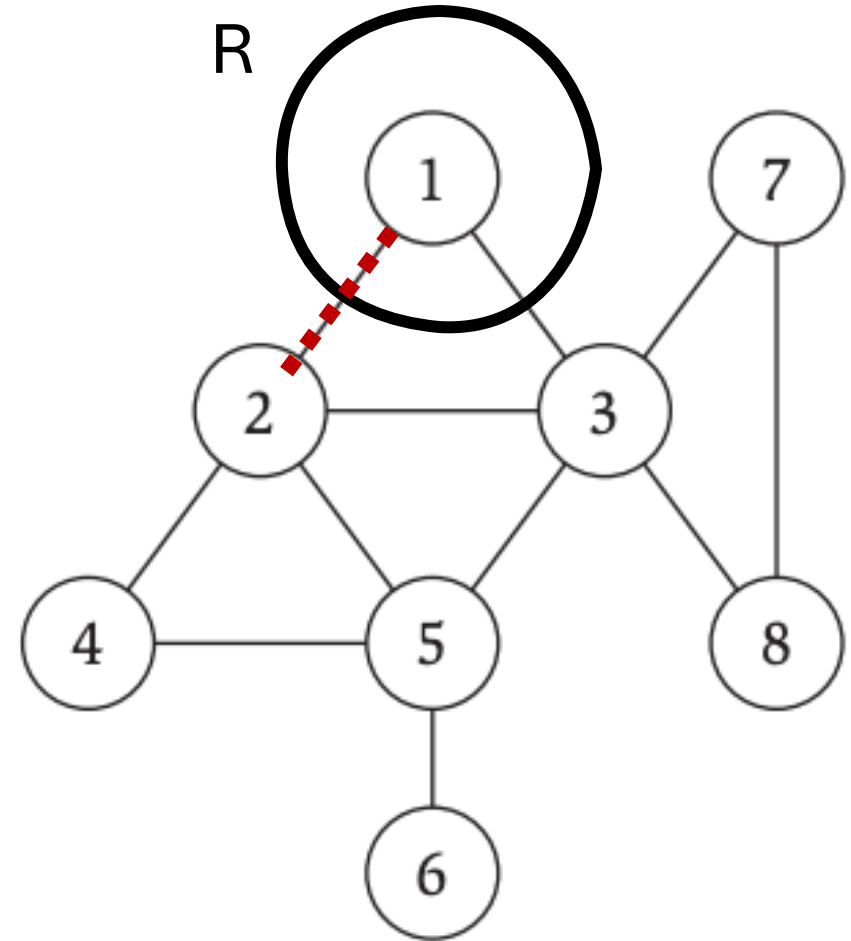
“The set of vertices that you can reach from s using a simple path.”

Explore Algorithm

- Input: $G = (V, E)$ and $s \in V$
- Output: $CC(s)$
- Let $R = \{s\}$
- While there exists $\{u, v\} \in E$ such that $u \in R$ and $v \notin R$:
 - Add v to R
- Return R

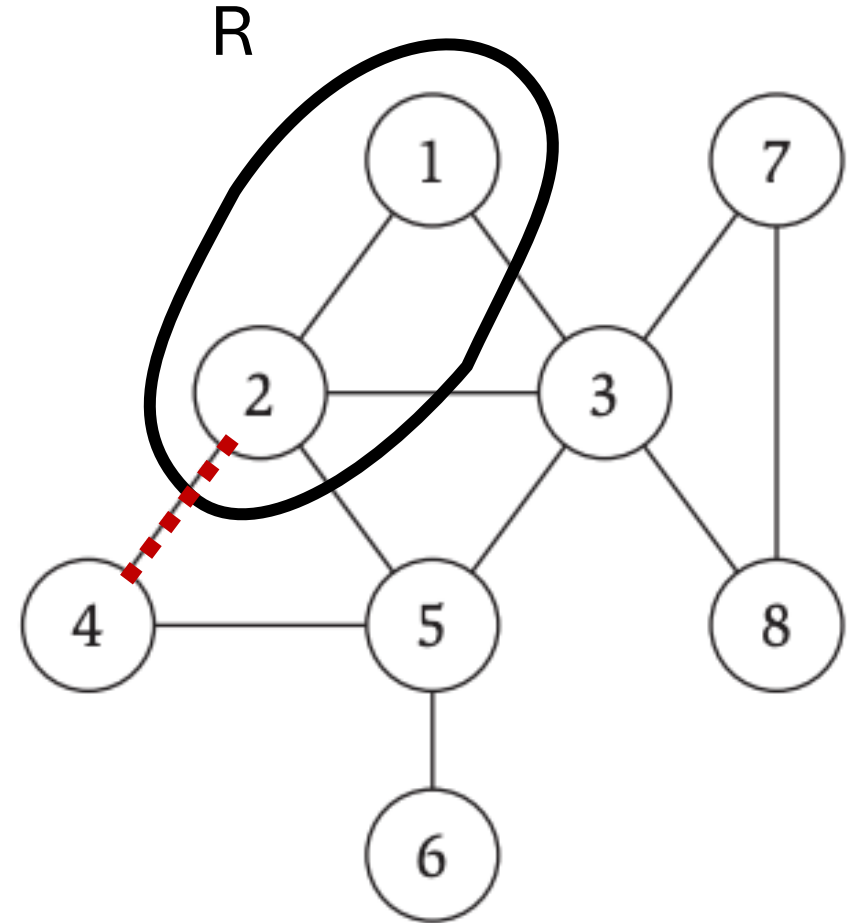
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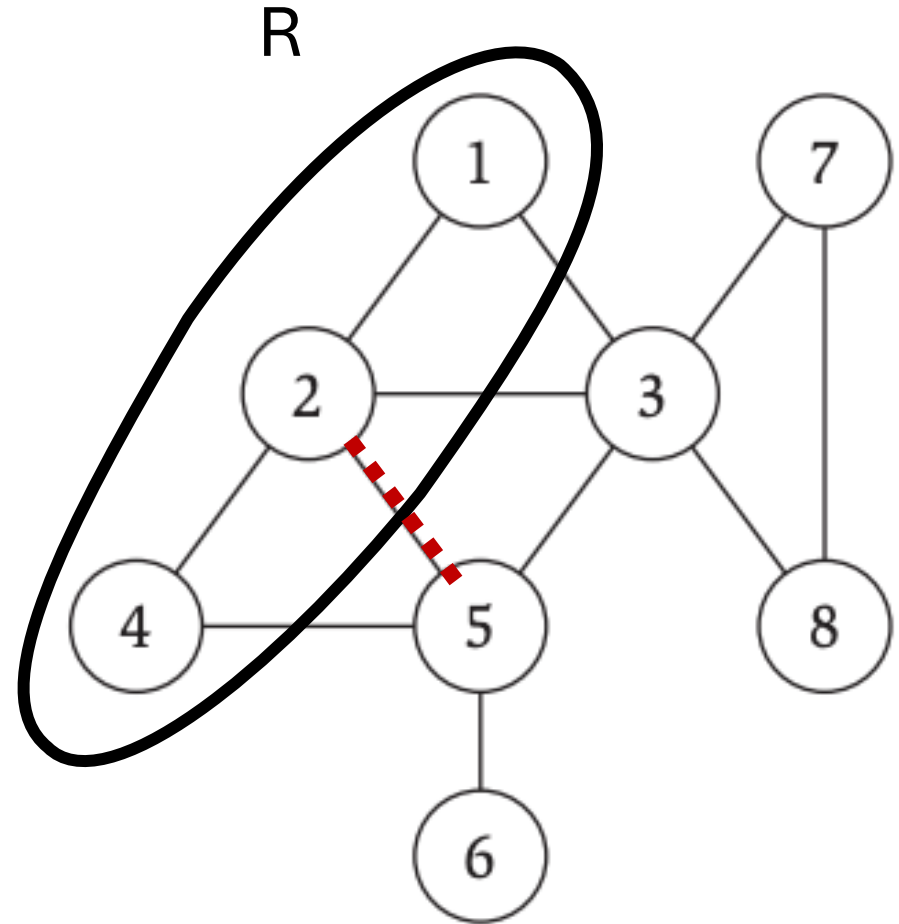
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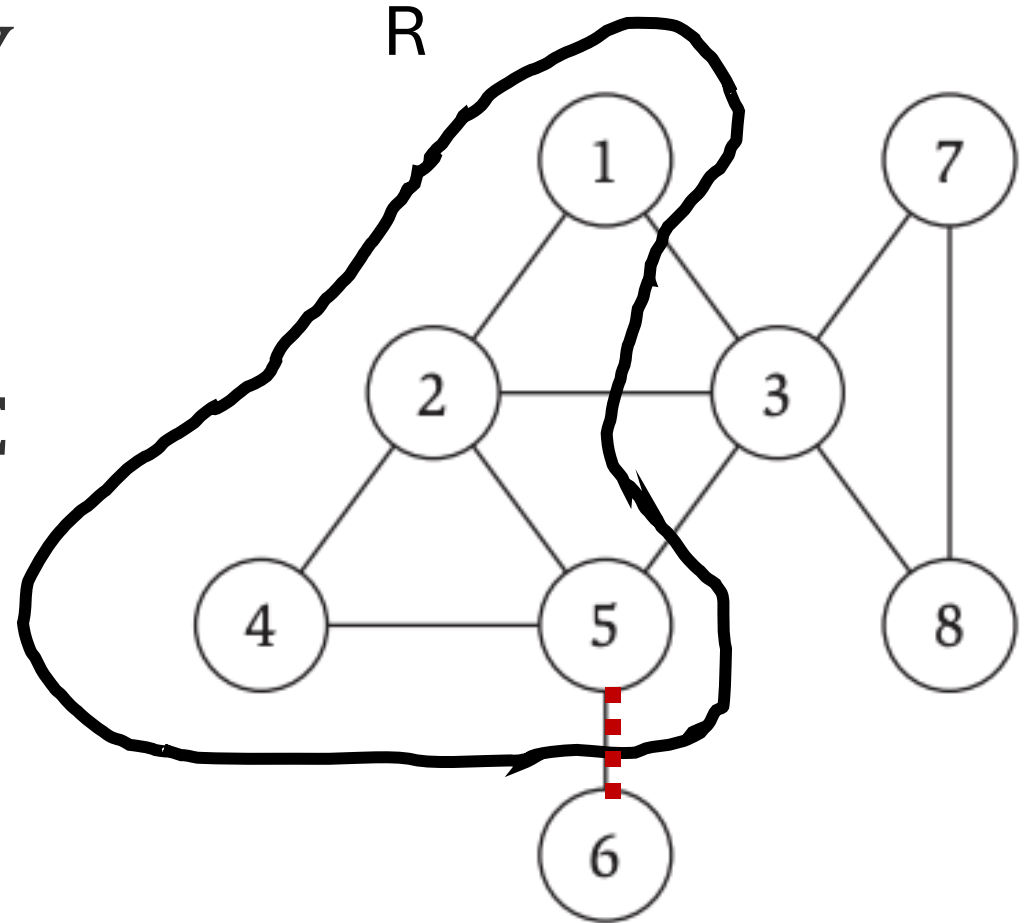
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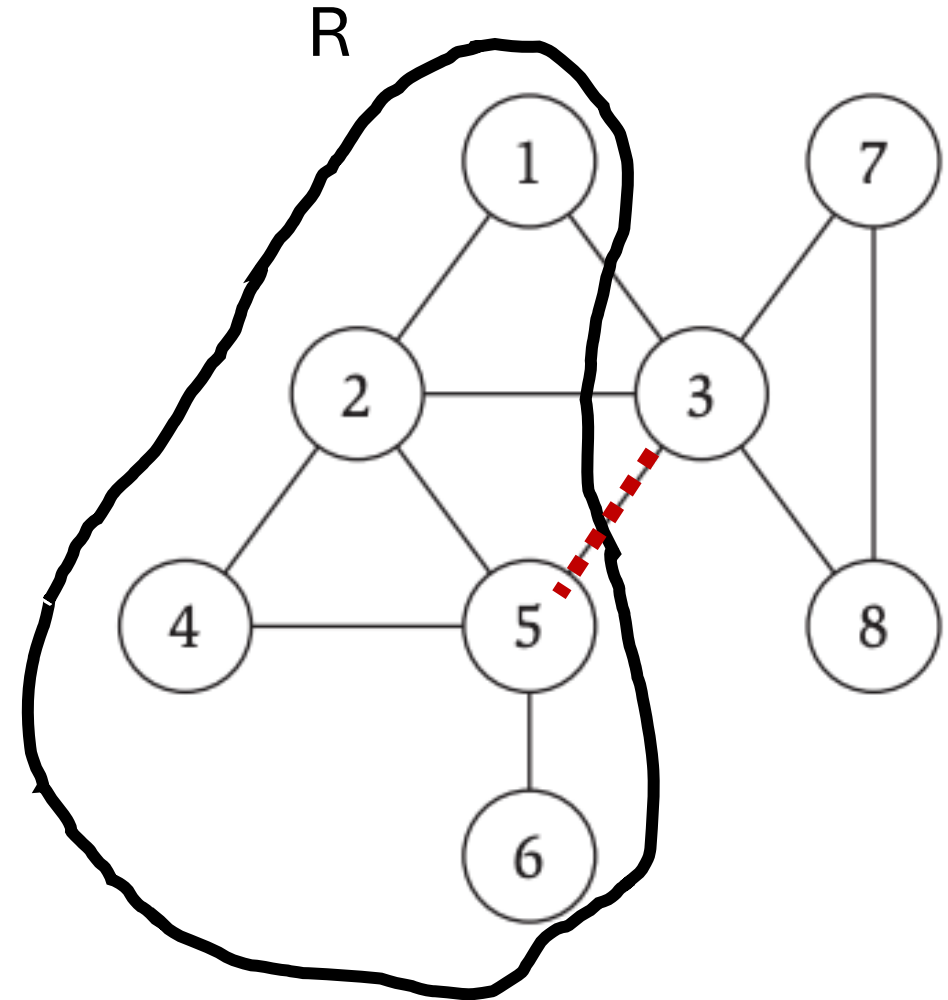
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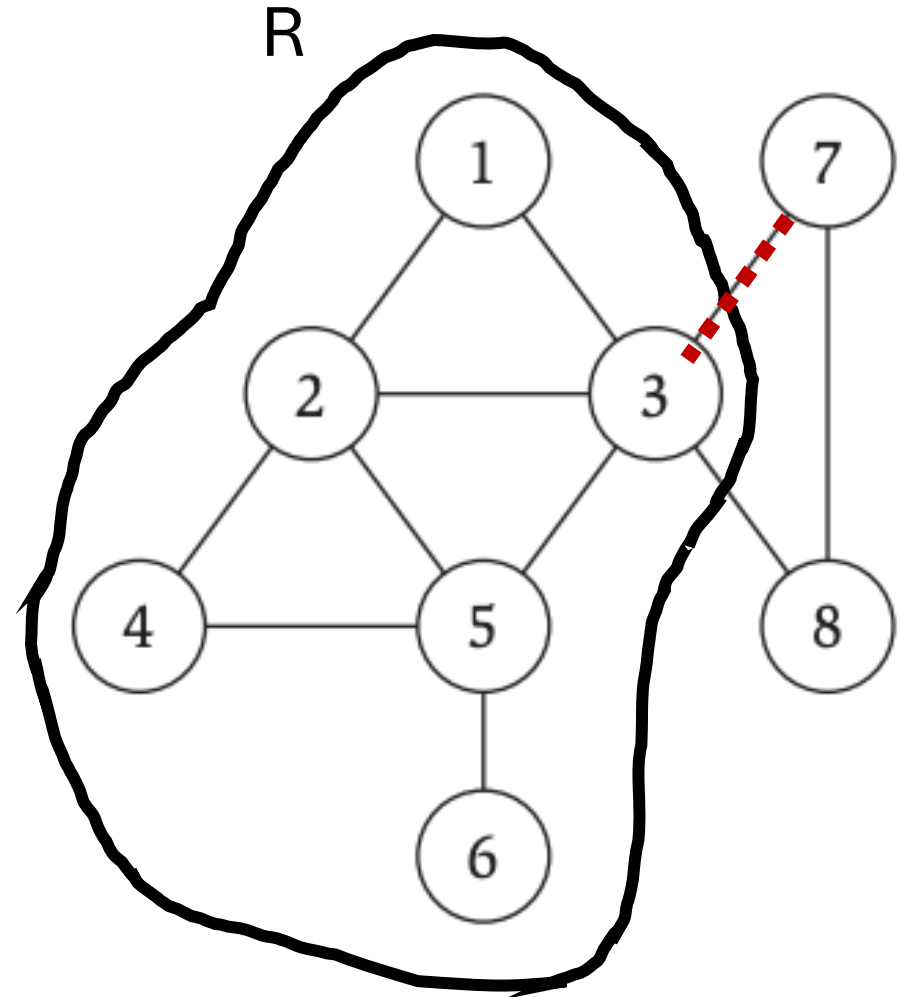
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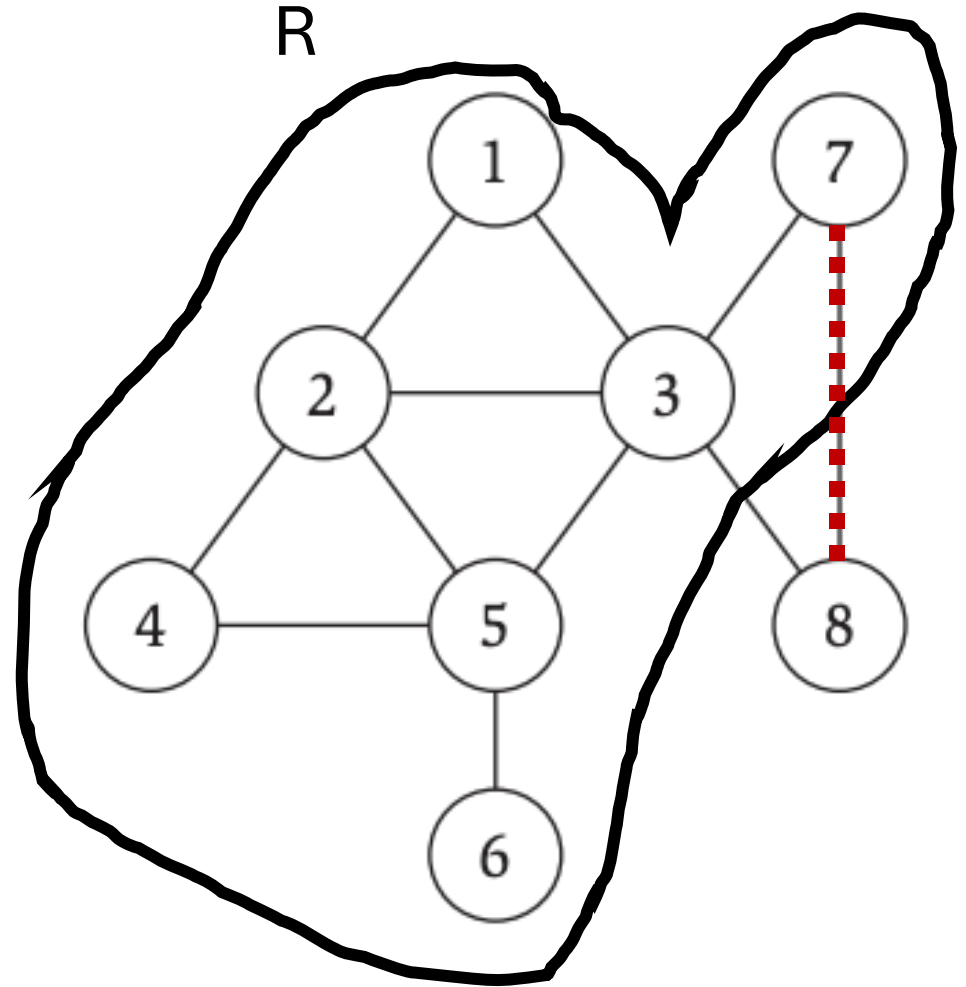
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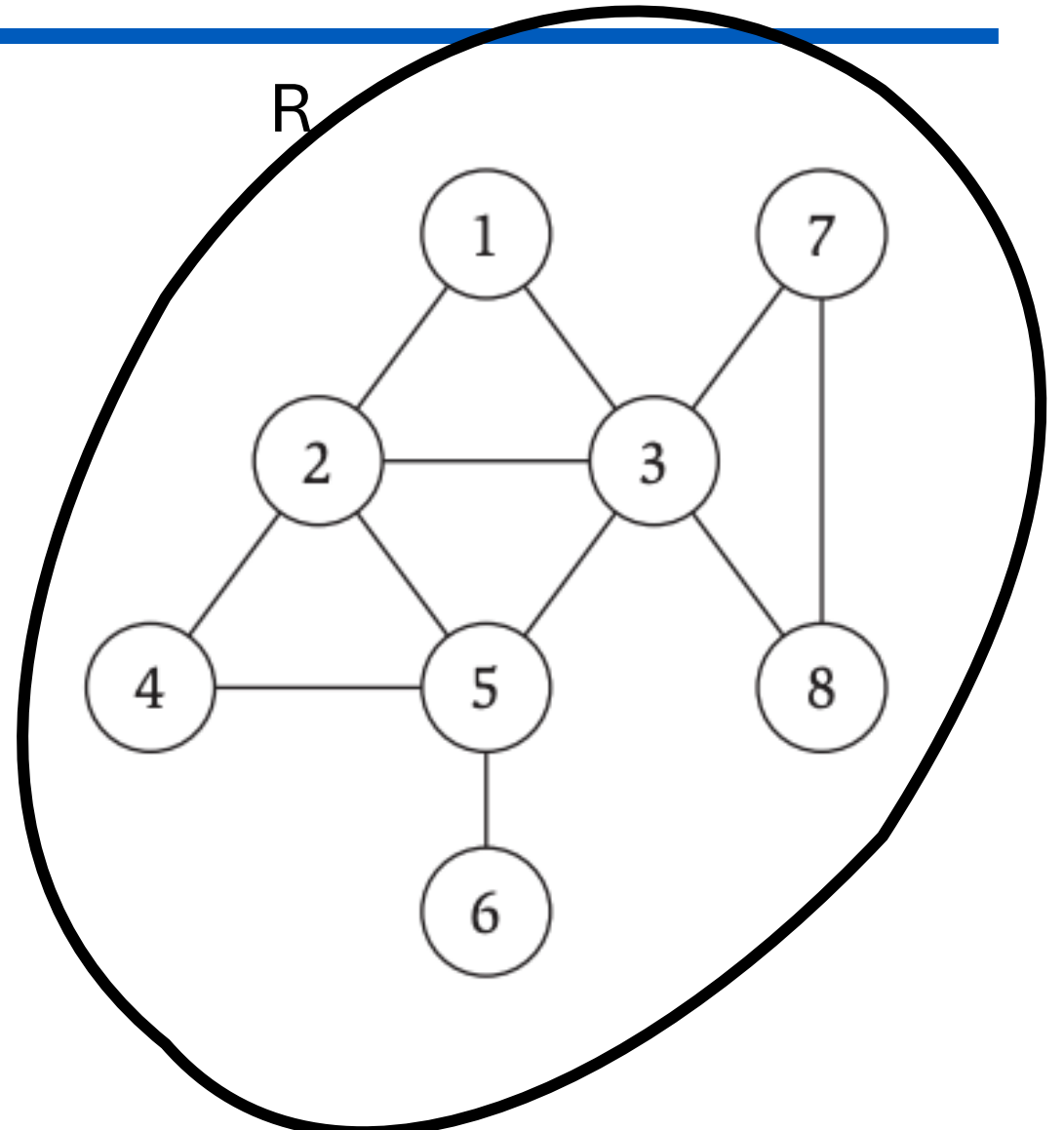
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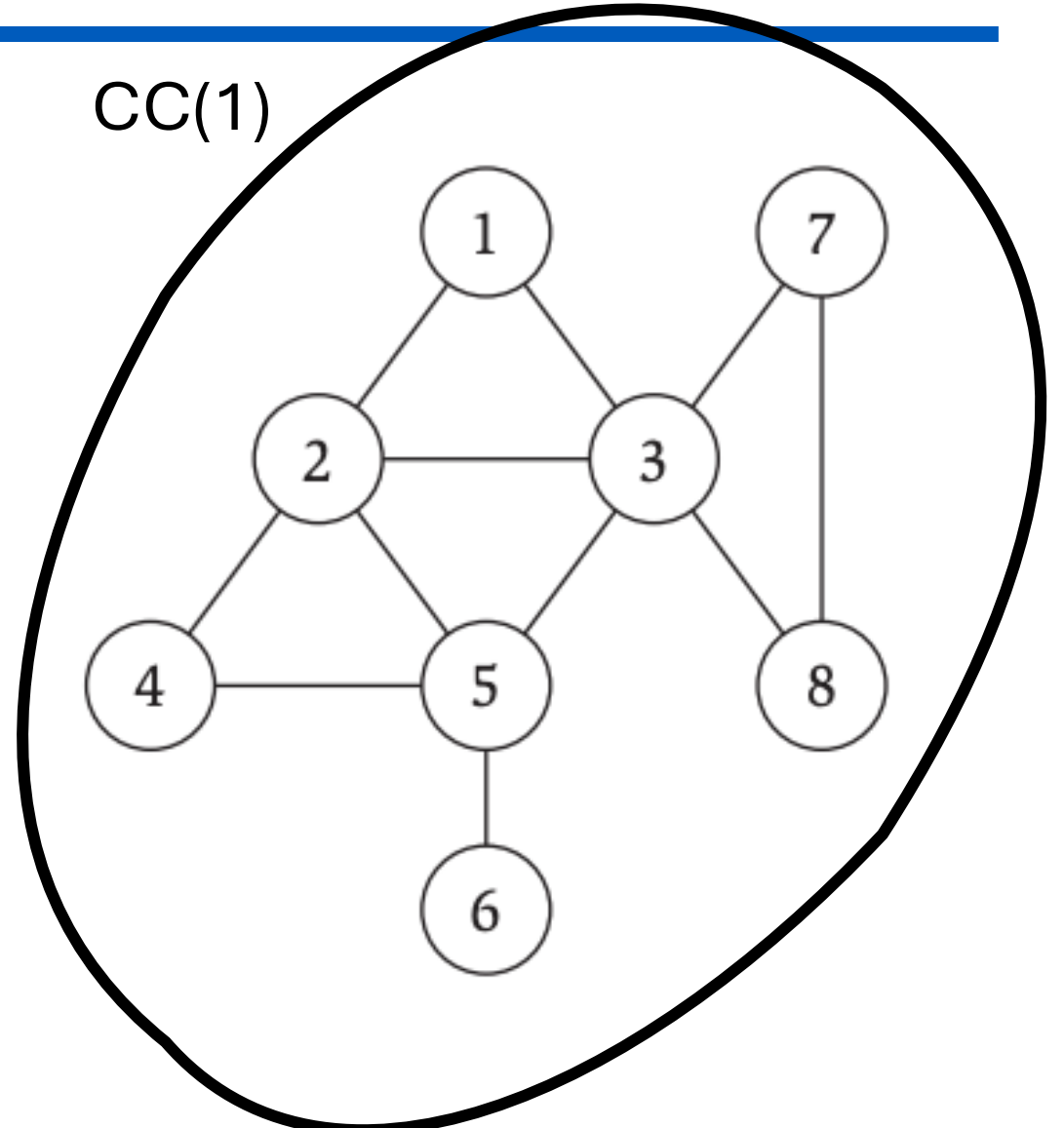
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CC(1)



Q: What is the difference? (BFS vs Explore)

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- BFS is Explore but Explore isn't necessarily BFS!**
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- Argue that $R = CC(s)$!
 - Q: How do we do this?

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- While there exists $\{u, v\} \in E$ such that $u \in R$ and $v \notin R$:
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- Return R
- Argue that $R = CC(s)$!
 - Show $R \subseteq CC(s)$
 - Show $CC(s) \subseteq R$

Breadth First Search (Properties)

Claim: $R \subseteq CC(s)$

Proof Idea:

- This wants us to show that everything reached by Explore is in the connected component of s .
- Let's do induction on iteration of the algorithm.
 - Do you believe the first iteration.
 - Given any iteration is true, how do you feel about the next iteration?

Q: Does this always terminate?

- Input: $G = (V, E)$ and $s \in V$
- Output: $CC(s)$
- Let $R = \{s\}$
- While there exists $\{u, v\} \in E$ such that $u \in R$ and $v \notin R$:
 - Add v to R
- Return R
- Well, we must be adding a vertex in each iteration and there are only so many vertices, right?

Q: Does this always terminate?

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Explore Proofs

Claim: $CC(s) \subseteq R$

Proof:

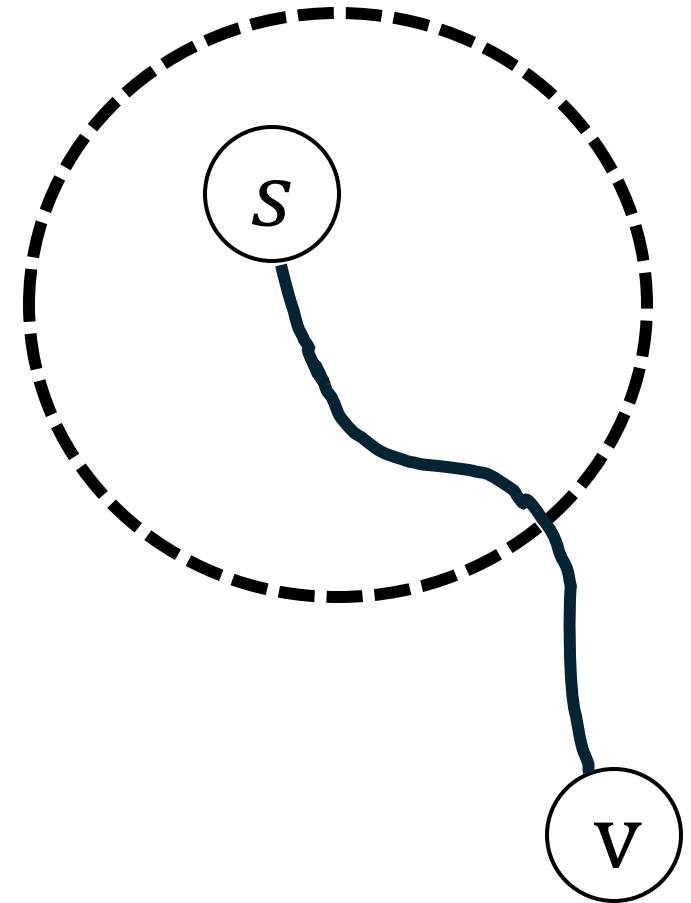
- This saying that every vertex in the connected component is added to R by Explore.
- This is saying that for every vertex v such that there is a path from s to v , v is added to R by Explore.

Explore Proofs

Claim: $CC(s) \subseteq R$

Proof:

- Suppose to the contrary that there exists $v \in CC(s)$ such that $v \notin R$.
- Then there must exist a path that starts at s (inside R) and ends at v (outside R).

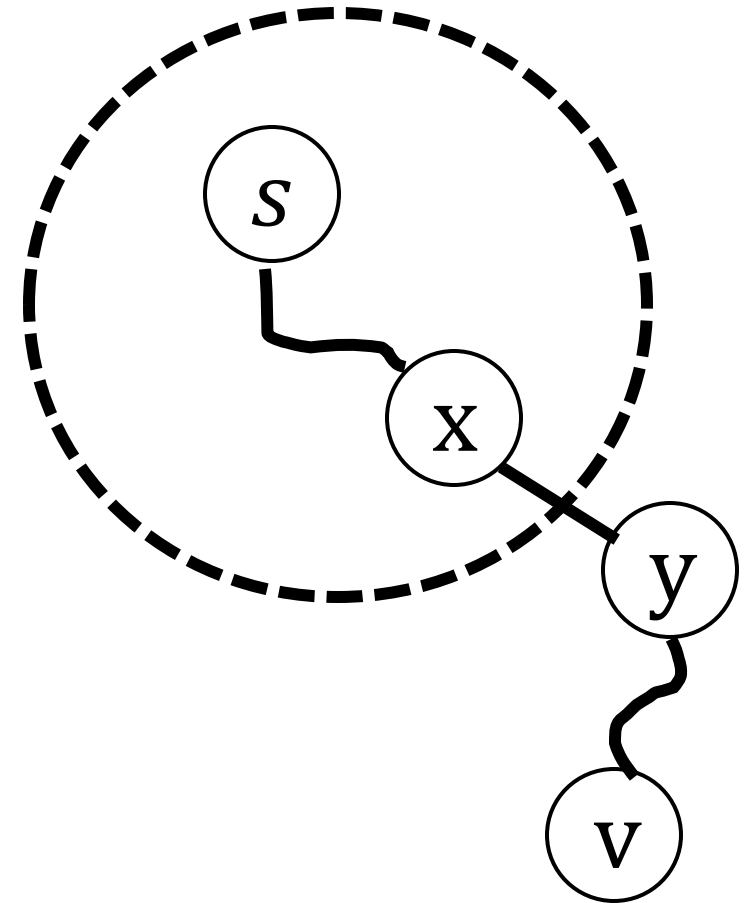


Explore Proofs

Claim: $CC(s) \subseteq R$

Proof:

- There then must exist $\{x, y\} \in E$ such that $x \in R$ and $y \notin R$.

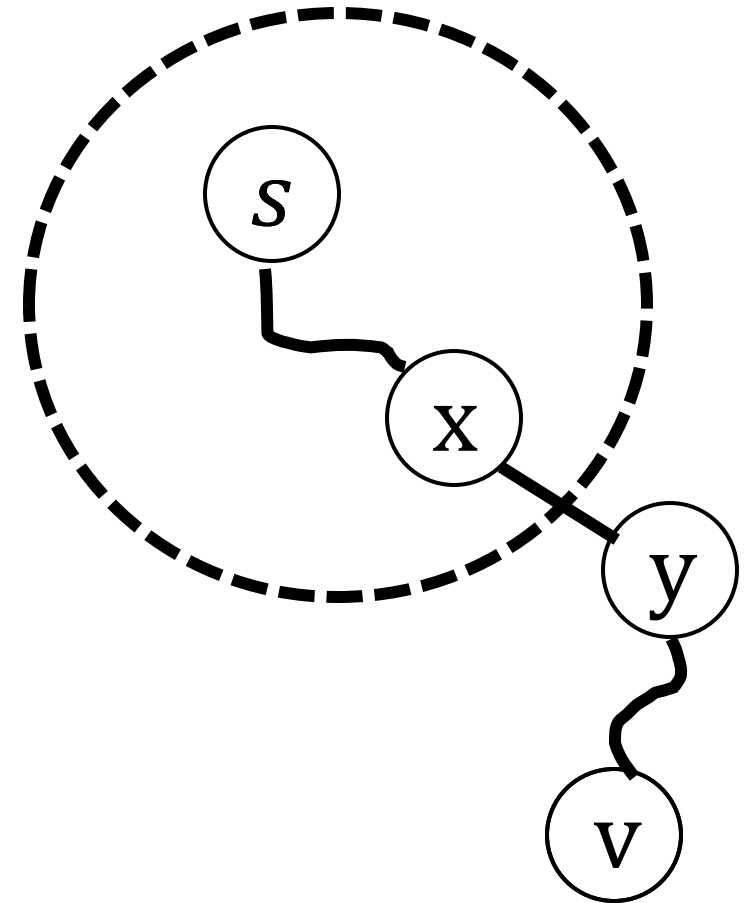


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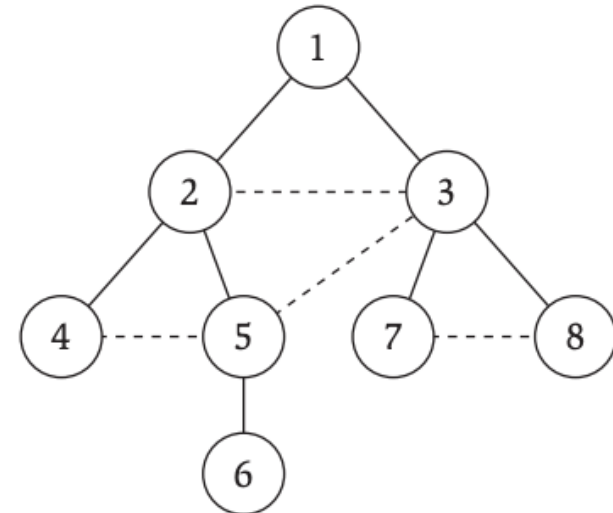
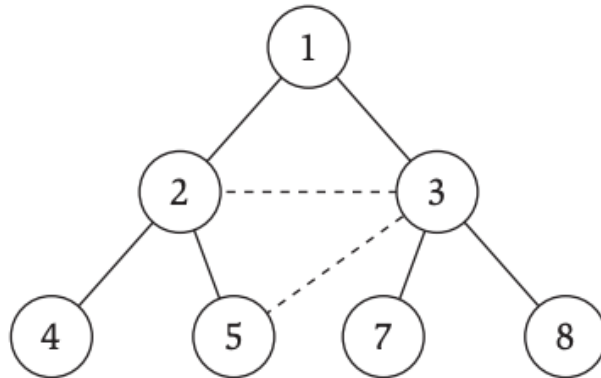
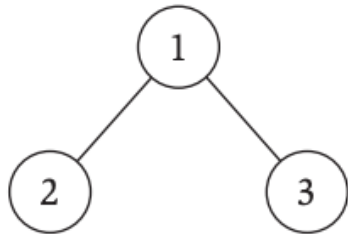
Proof:

- There then must exist $\{x, y\} \in E$ such that $x \in R$ and $y \notin R$.
- If this the case, then the algorithm wouldn't have terminated and would have instead added y . $\Rightarrow \Leftarrow$



Q: How would you describe BFS?

- $L_0 = s$
- $L_1 =$ neighbors of L_0 .
- $L_2 =$ neighbors of L_1 that are not in L_0 .
- $L_i =$ neighbors of L_{i-1} that are not in previous layer.



Depth First Search

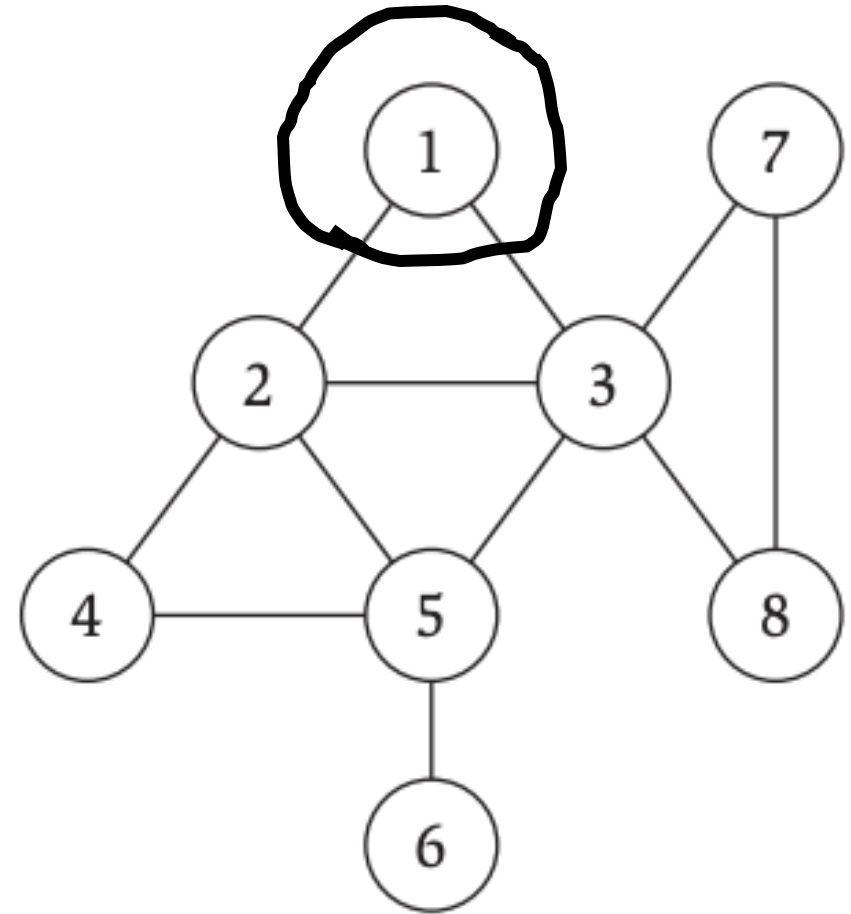
- **Input:** The current vertex $u \in V$
- **Global:** An array of exploration $A \in \{0,1\}^V$
- Mark current vertex as explored ($A[u] = 1$).
- For each $\{u, v\} \in E$:
 - If v is not explored ($A[v] == 0$):
 - DFS(v, A)

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- Mark current vertex as explored ($A[u] = 1$).
- For each $\{u, v\} \in E$:
 - If v is not explored ($A[v] == 0$):
 - DFS(v, A)
- **Idea:** You are recursing or “drilling down”. If you get stuck, you go up a step and try the next choice.

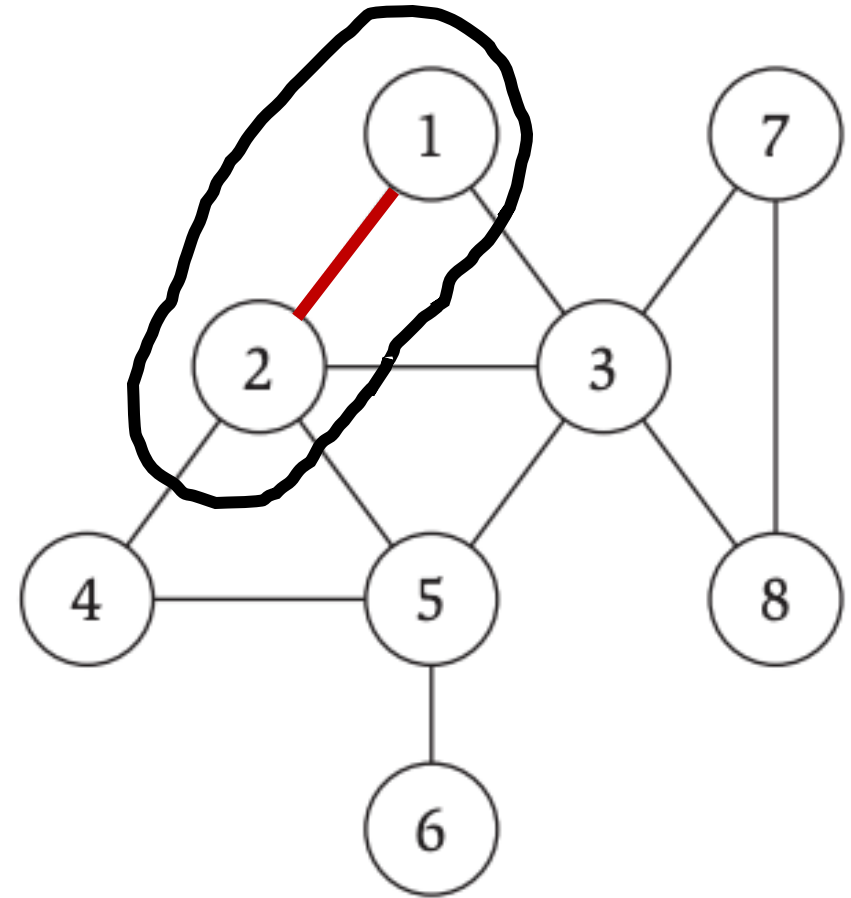
Depth First Search

$A = \{1\}$



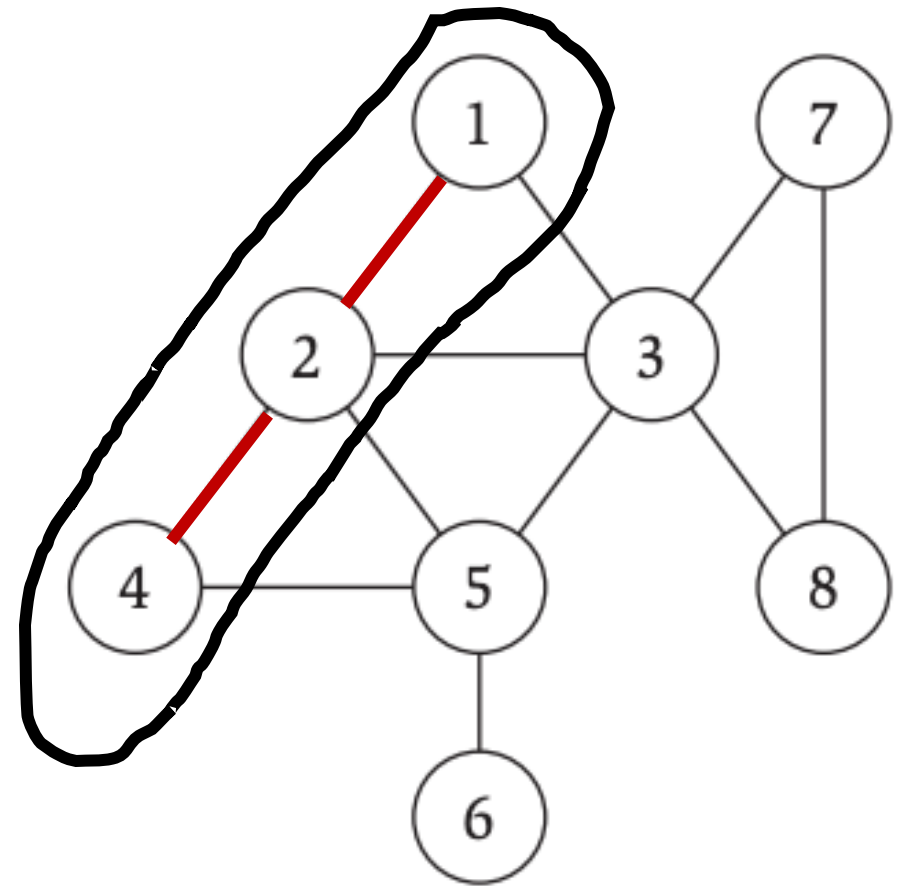
Depth First Search

$A = \{1, 2\}$



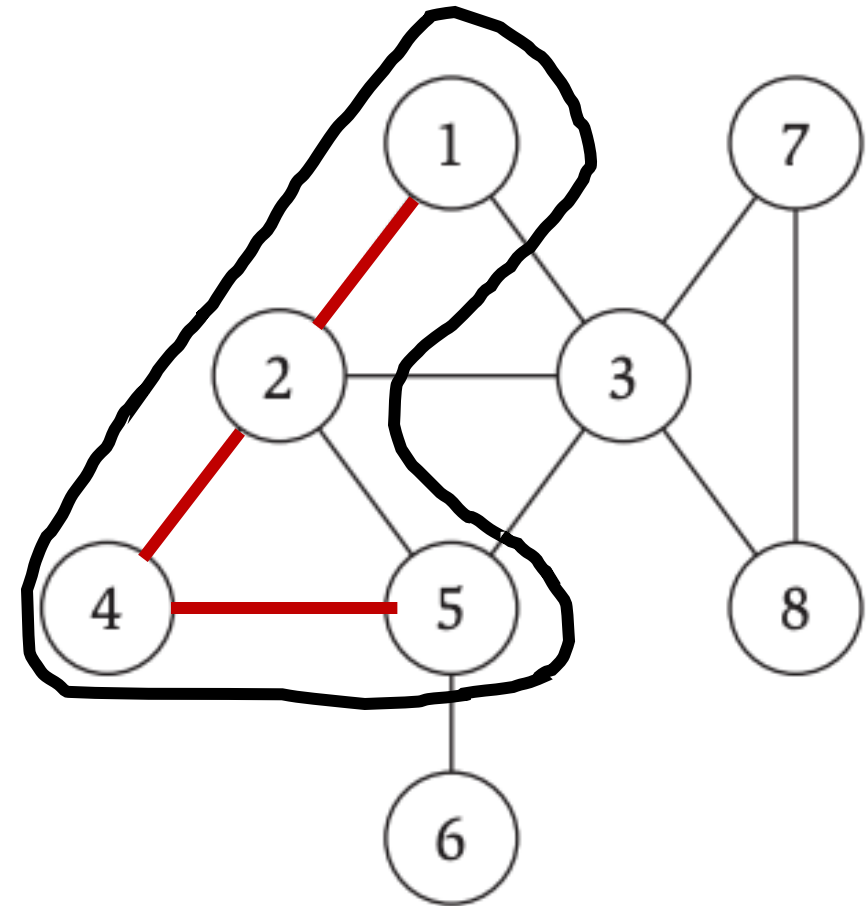
Depth First Search

$A = \{1, 2, 4\}$



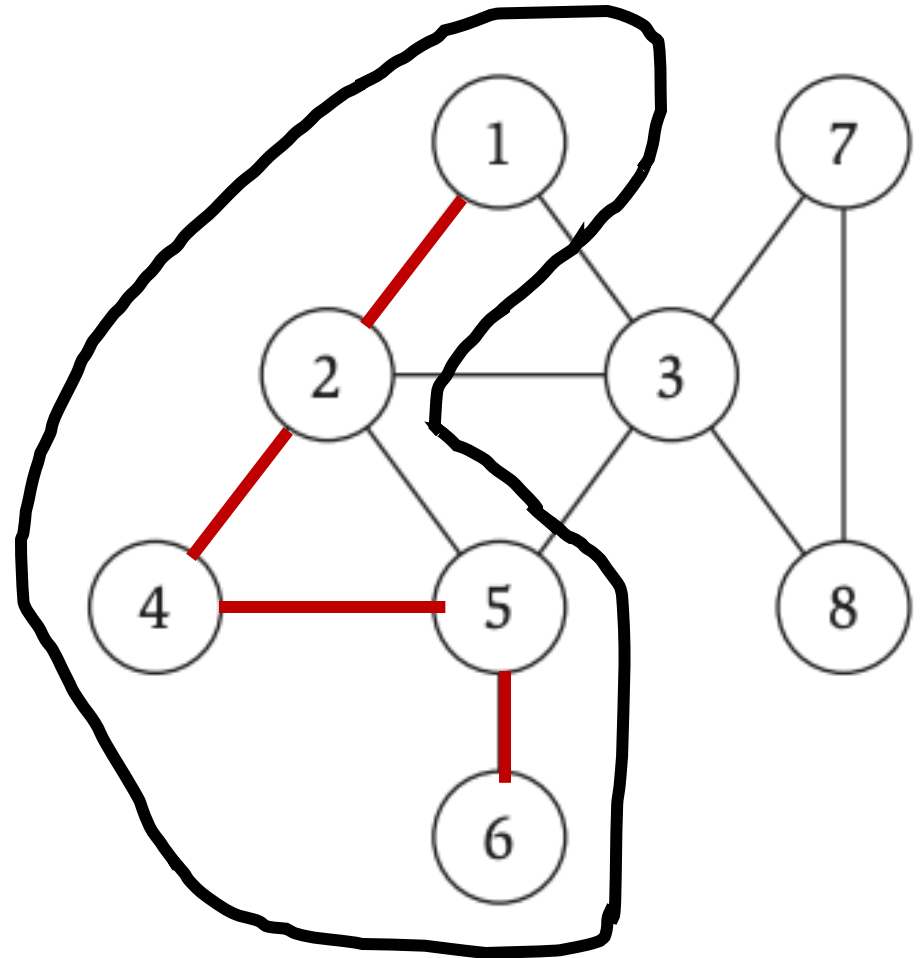
Depth First Search

$A = \{1, 2, 4, 5\}$



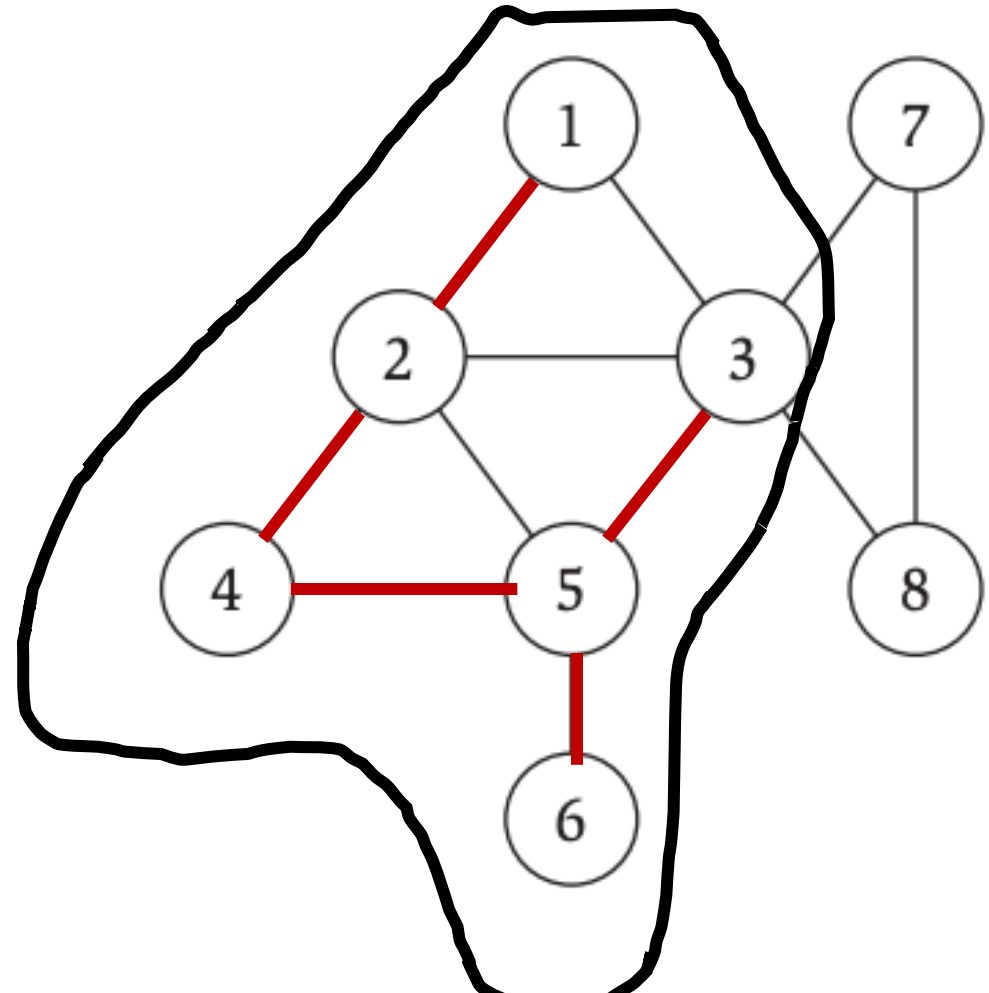
Depth First Search

$A = \{1, 2, 4, 5, 6\}$



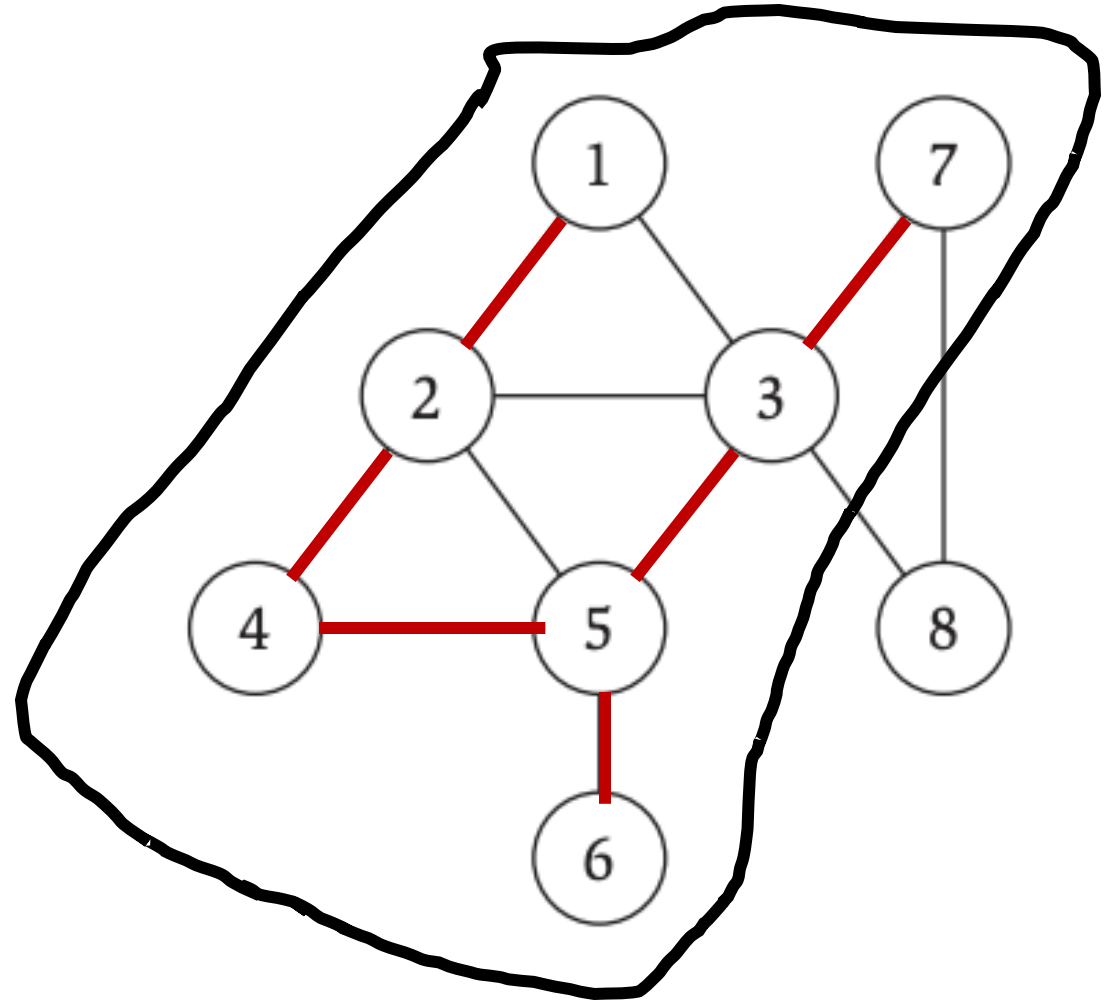
Depth First Search

$A = \{1, 2, 4, 5, 6, 3\}$



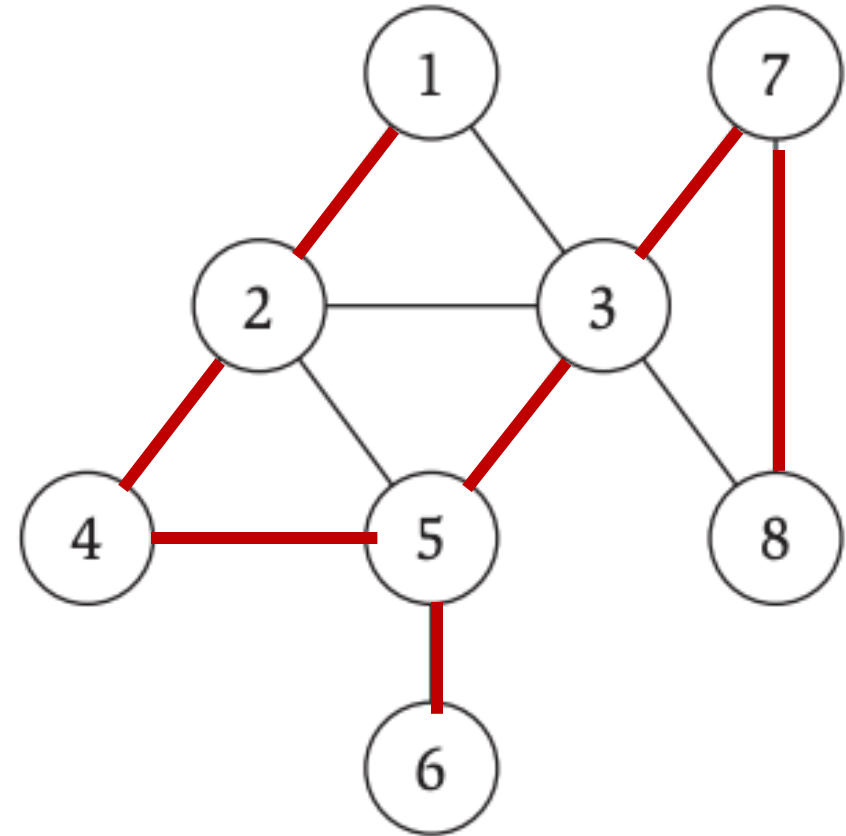
Depth First Search

$A = \{1, 2, 4, 5, 6, 3, 7\}$

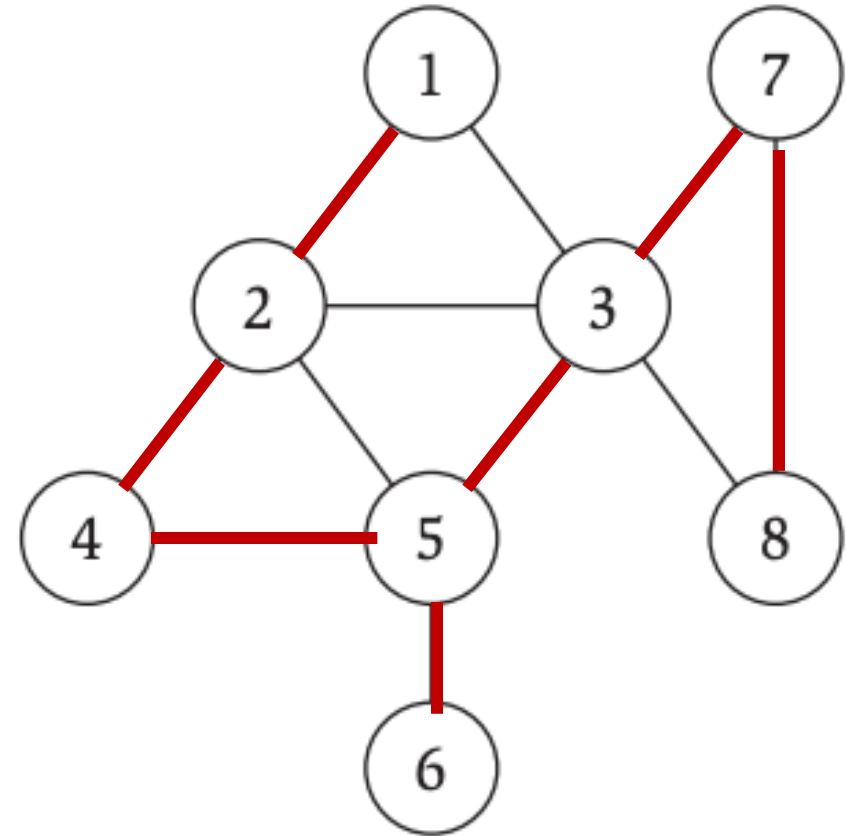
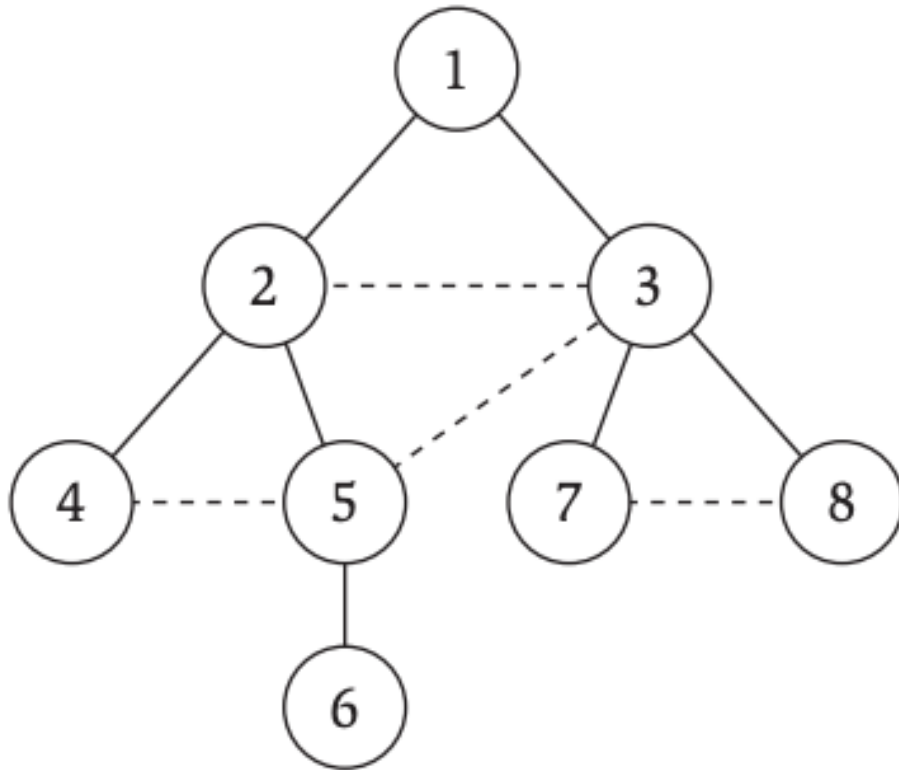


Depth First Search

$A = \{1, 2, 4, 5, 6, 3, 7, 8\}$



DFS Trees vs BFS Trees



Q: How can you compute all the connected components of a graph?

