

# CSE 331: Algorithms & Complexity

## “BFS”

Prof. Charlie Anne Carlson (She/Her)

**Lecture 11**

Monday September 22nd, 2025



**University at Buffalo®**

# Schedule

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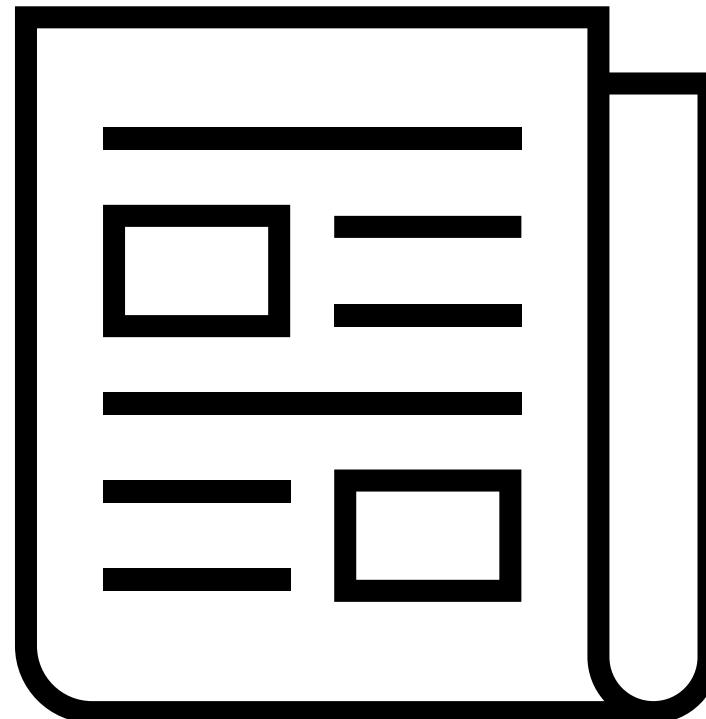
1. Course Updates
2. Graph Connectivity
3. Graph Traversal
  1. BFS
  2. DFS
  3. WFS



# Course Updates

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- HW 1 Grading Out Tomorrow
- HW 2 Due Tomorrow
- HW 3 Out Tomorrow
- Group Project
  - Team Emails Soon
  - No Autolab Registration
- First Quiz NEXT Monday!



# Connectivity Problem(s)

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## **s-t Connectivity Problem:**

**Input:** Graph  $G = (V, E)$ , source  $s$ , and destination  $t$ .

**Output:** True if there exists a path and False otherwise.

## **s-t Shortest Path Problem:**

**Input:** Graph  $G = (V, E)$ , source  $s$ , and destination  $t$ .

**Output:** The length of the shortest path from  $s$  to  $t$  ( $\infty$  if there is no path).

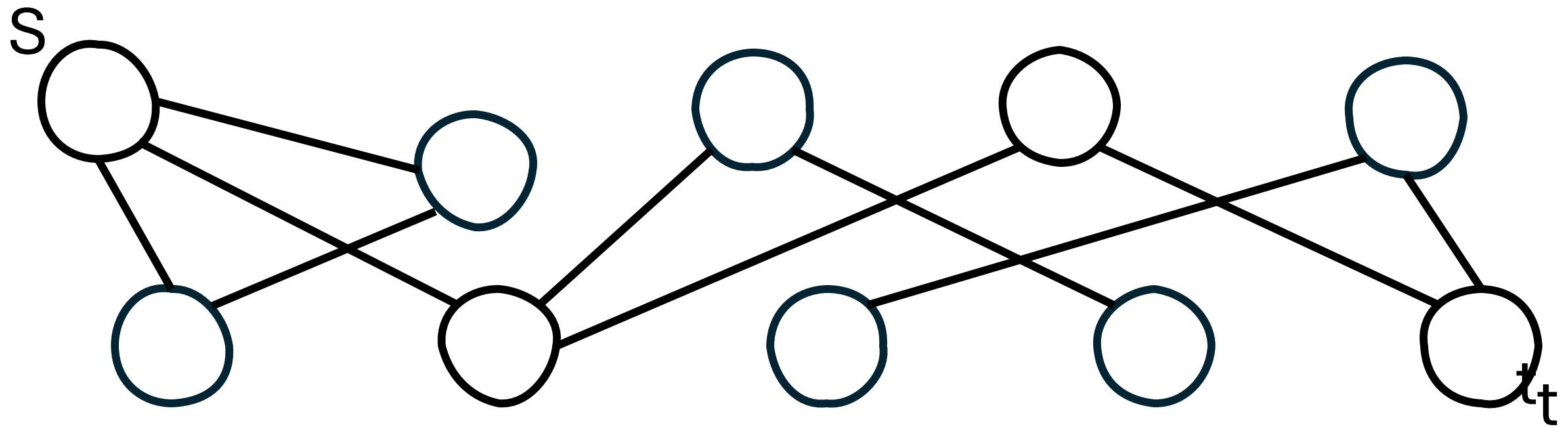
# Another Connectivity Problem

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## Graph Connectivity:

**Input:**  $G = (V, E)$  and  $s \in V$

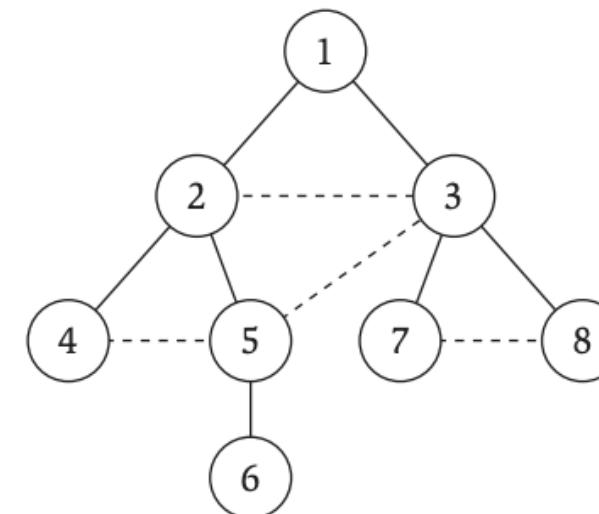
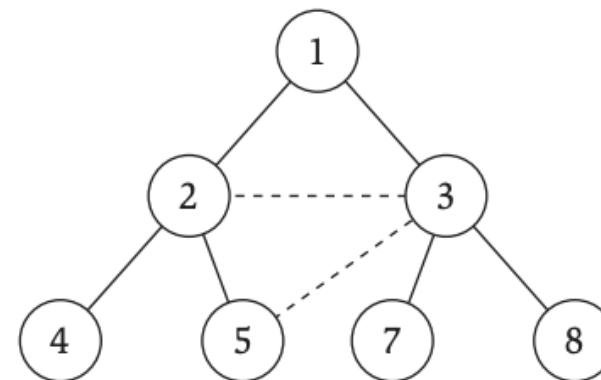
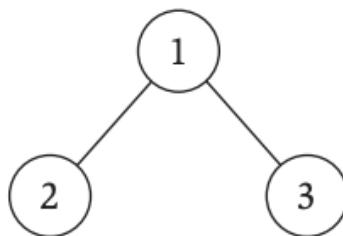
**Output:**  $T = \{u \in T: \text{there exists a path from } s \text{ to } u \text{ in } G\}$



# Breadth First Search (Layers)

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- $L_0 = s$
- $L_1 = \text{neighbors of } L_0.$
- $L_2 = \text{neighbors of } L_1 \text{ that are not in } L_0.$
- $L_i = \text{neighbors of } L_{i-1} \text{ that are not in previous layer.}$



# Breadth First Search (“Algorithm”)

---

- Input:  $G = (V, E)$  and  $s \in V$
- Let  $L_0 = \{s\}$
- Assume  $L_0, \dots, L_i$  have been constructed:
  - Let  $L_{i+1}$  be nodes do not appear in  $L_0, \dots, L_i$  and have an edge to  $L_i$ .
  - If  $L_{i+1}$  is empty, stop.
- Return all layers.

# Breadth First Search (Properties)

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- For each  $j \geq 0$ , layer  $L_j$  produced by BFS consists of all nodes at distance  $j$  from  $s$ .
- There is a path from  $s$  to  $t$  if and only if  $t$  appears in some layer.
- For any  $\{u, v\} \in E$ , if  $u \in L_i$  and  $v \in L_j$  then  $i$  and  $j$  differ by at most 1.
- You can think of the output as a tree! We call this the **BFS (discovery) Tree**.

# Breadth First Search (Properties)

---

**Claim:** For any  $\{u, v\} \in E$ , if  $u \in L_i$  and  $v \in L_j$  then  $i$  and  $j$  differ by at most 1.

# Breadth First Search (Properties)

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**Claim:** For any  $\{u, v\} \in E$ , if  $u \in L_i$  and  $v \in L_j$  then  $i$  and  $j$  differ by at most 1.

## Proof Outline:

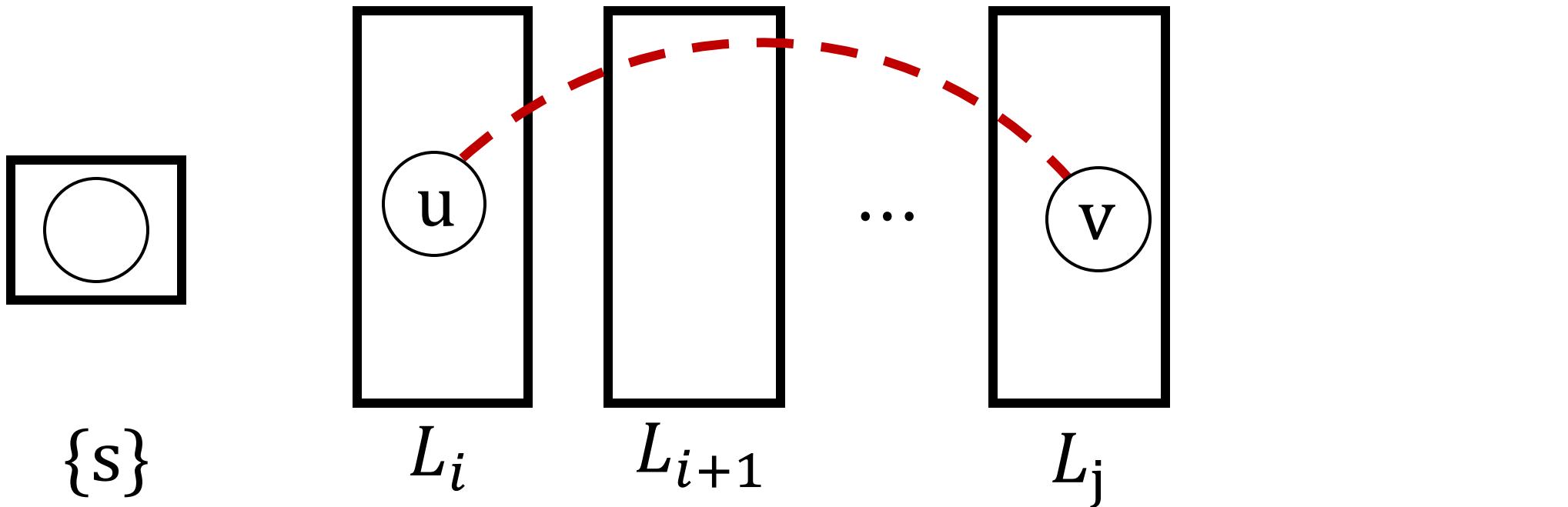
- Without loss of generality, we assume that  $i \leq j$ .
- Suppose for the sake of contradiction that  $d(i, j) > 1$ .

# Breadth First Search (Properties)

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## Proof Outline:

- Without loss of generality, we assume that  $i < j$ .
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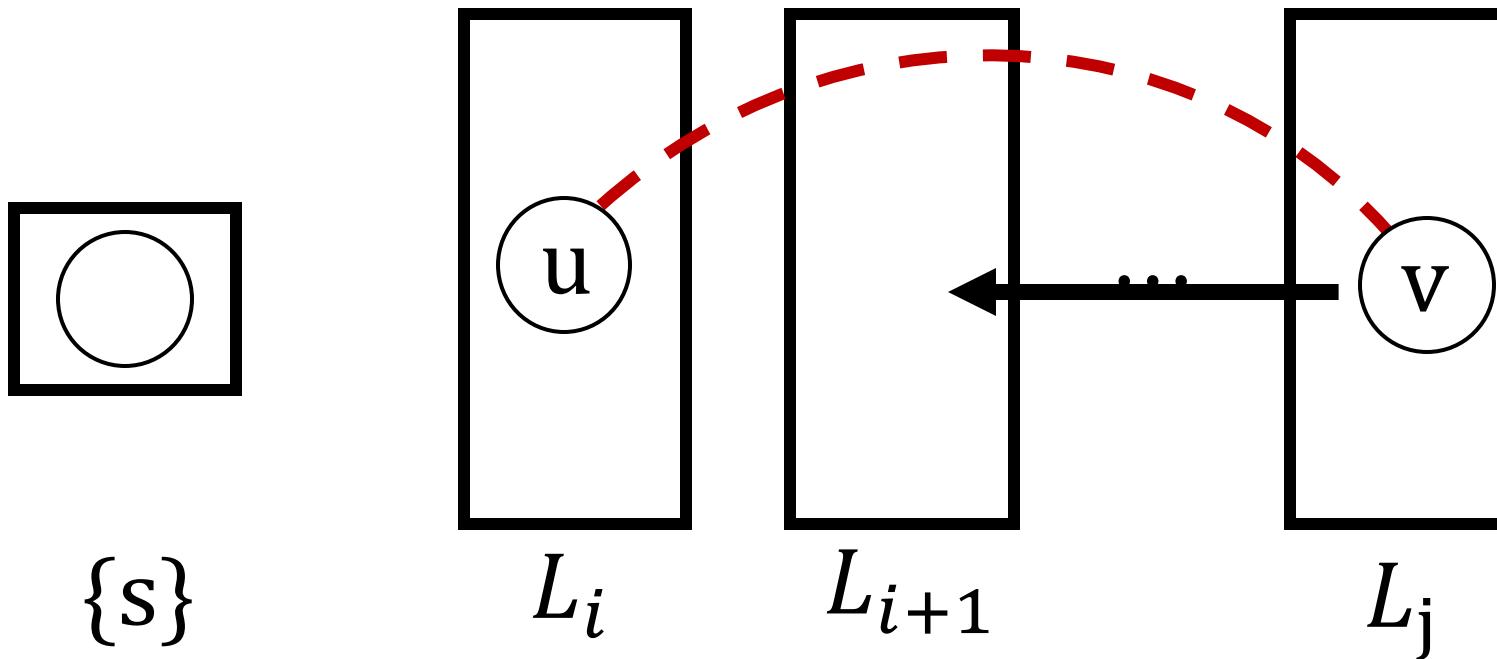


# Breadth First Search (Properties)

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# Breadth First Search (Properties)

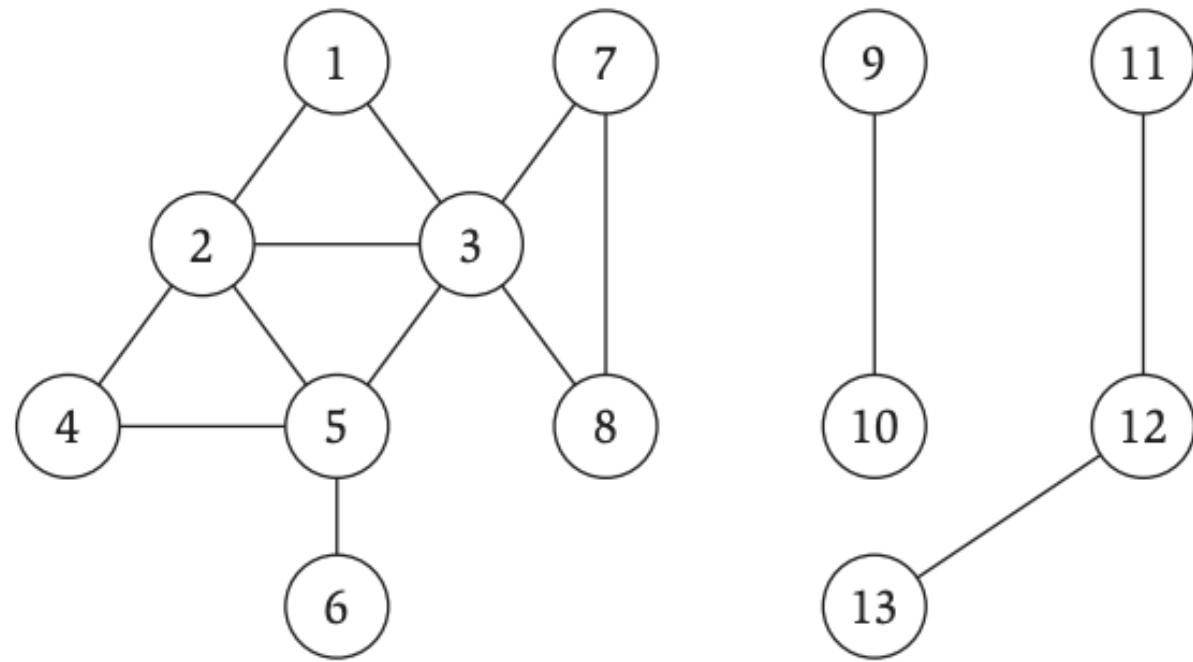
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## Proof:

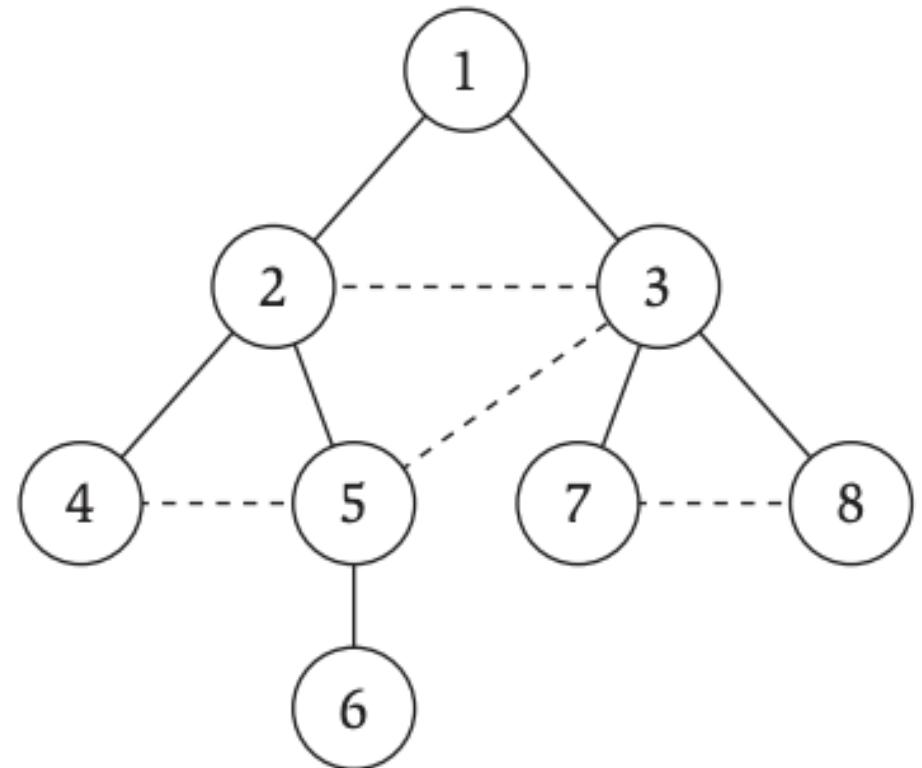
- Without loss of generality, we assume that  $i < j$ .
- Suppose for the sake of contradiction that  $d(i, j) > 1$ .
  - This implies  $i + 1 < j$ .
  - Then  $u \in L_i, v \notin L_0, L_1, \dots, L_i$ , and  $\{u, v\} \in E$ .
    - Hence, BFS would have put  $v \in L_{i+1}$ .
    - This contradicts initial assumption that  $v \in L_j$  and  $j > i + 1$ .

# Breadth First Search (Tree)

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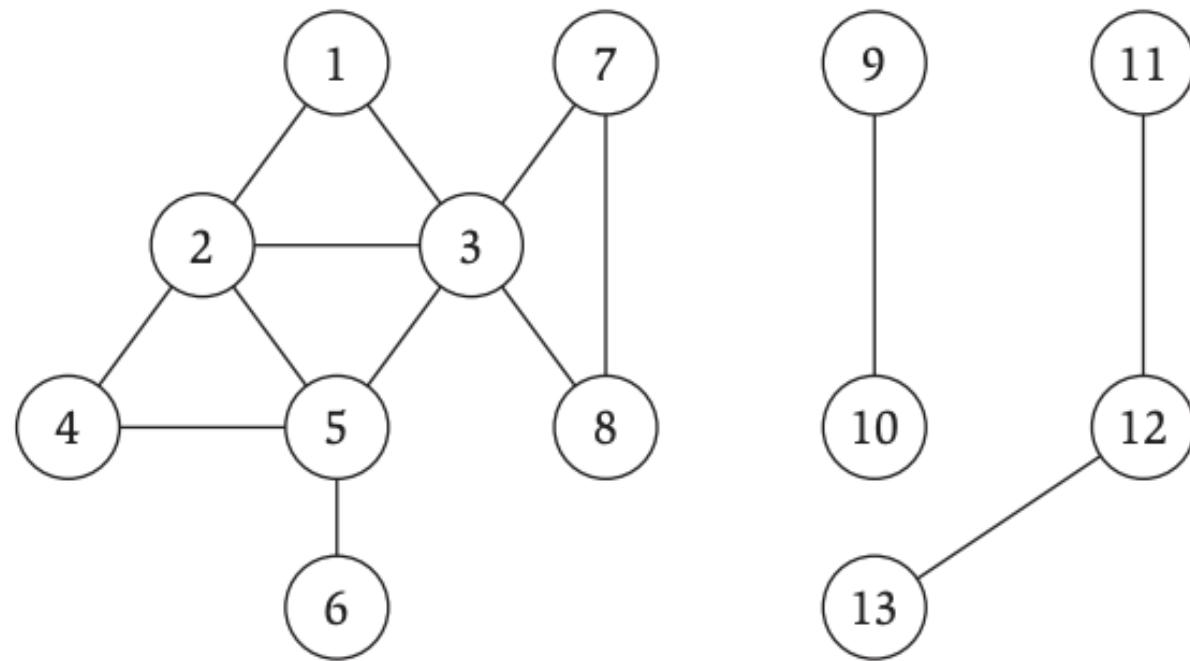


Original Graph

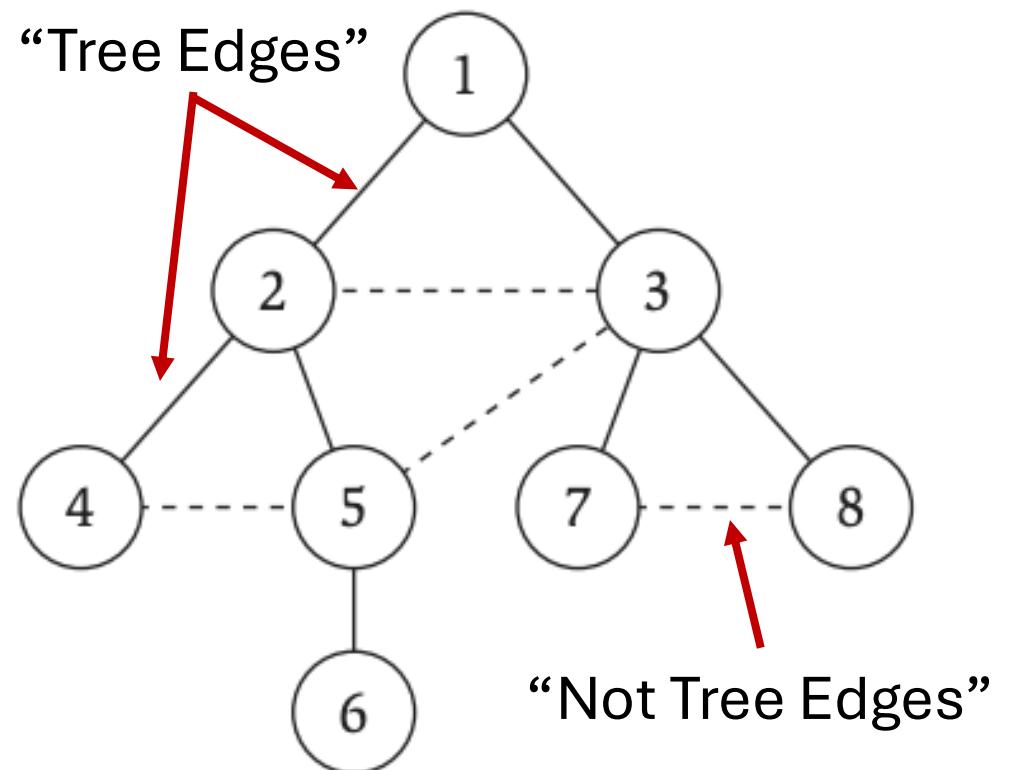


Search Tree

# Breadth First Search (Tree)



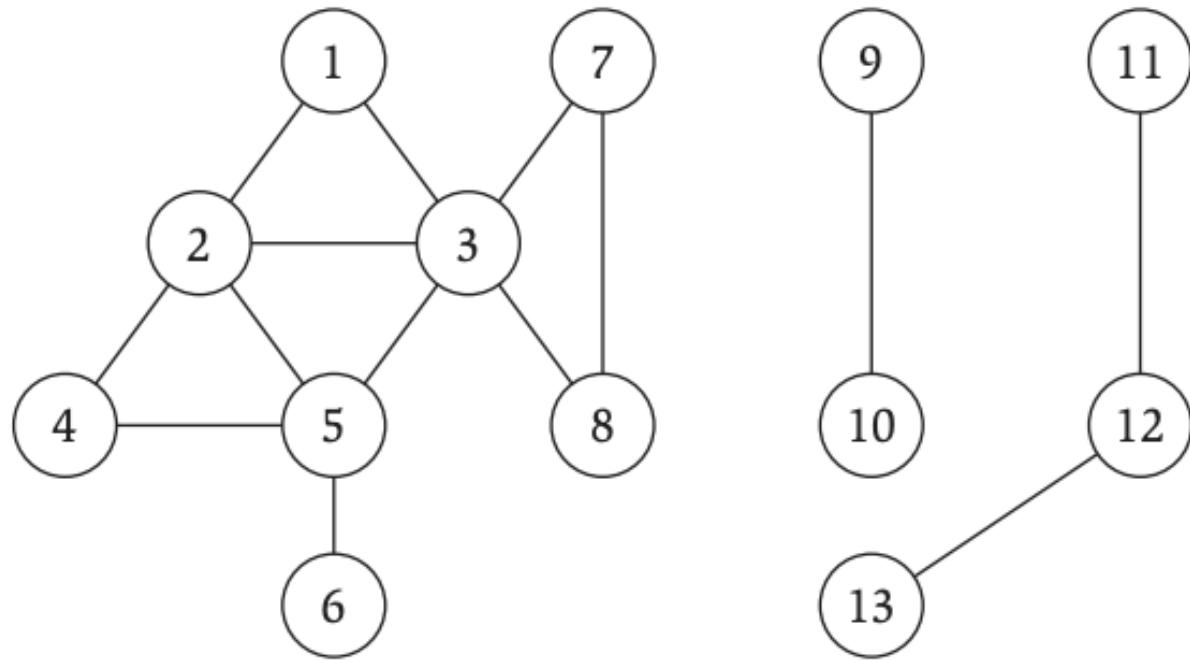
Original Graph



Search Tree

# Connected Component of (s) (CC(s))

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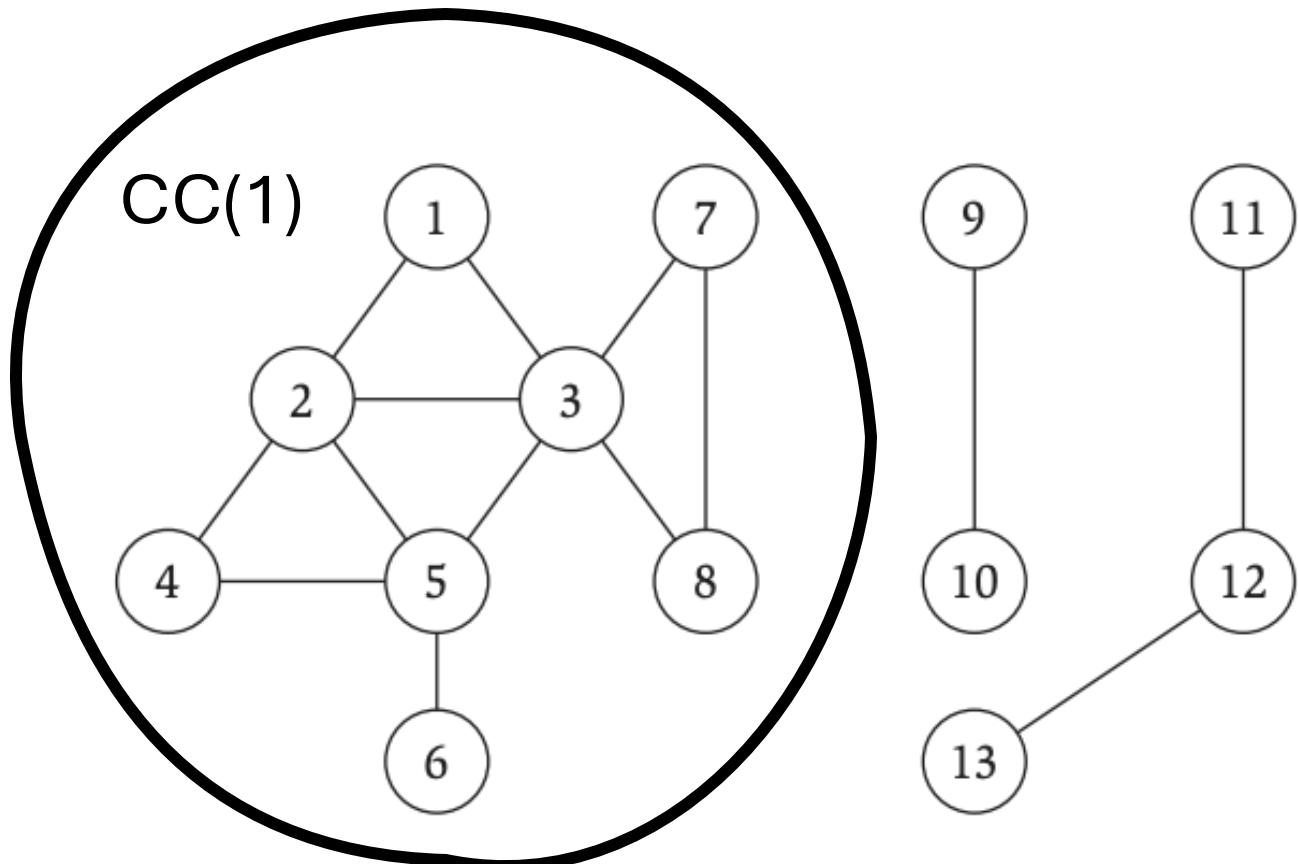


The CC(s) is the set of all vertices that are connected to s by a path.

“The set of vertices that you can reach from s using a simple path.”

# Connected Component of (s) (CC(s))

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The  $CC(s)$  is the set of all vertices that are connected to  $s$  by a path.

“The set of vertices that you can reach from  $s$  using a simple path.”

# Explore Algorithm

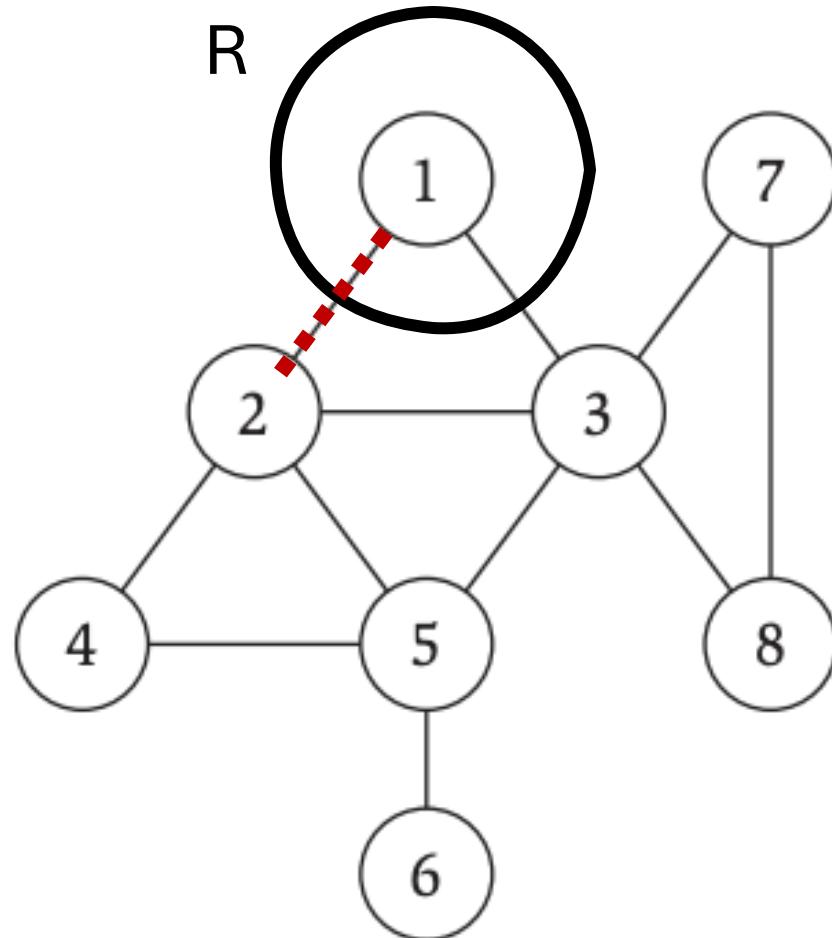
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- Input:  $G = (V, E)$  and  $s \in V$
- Output:  $\text{CC}(s)$
- Let  $R = \{s\}$
- While there exists  $\{u, v\} \in E$  such that  $u \in R$  and  $v \notin R$ :
  - Add  $v$  to  $R$
- Return  $R$

# Explore Algorithm

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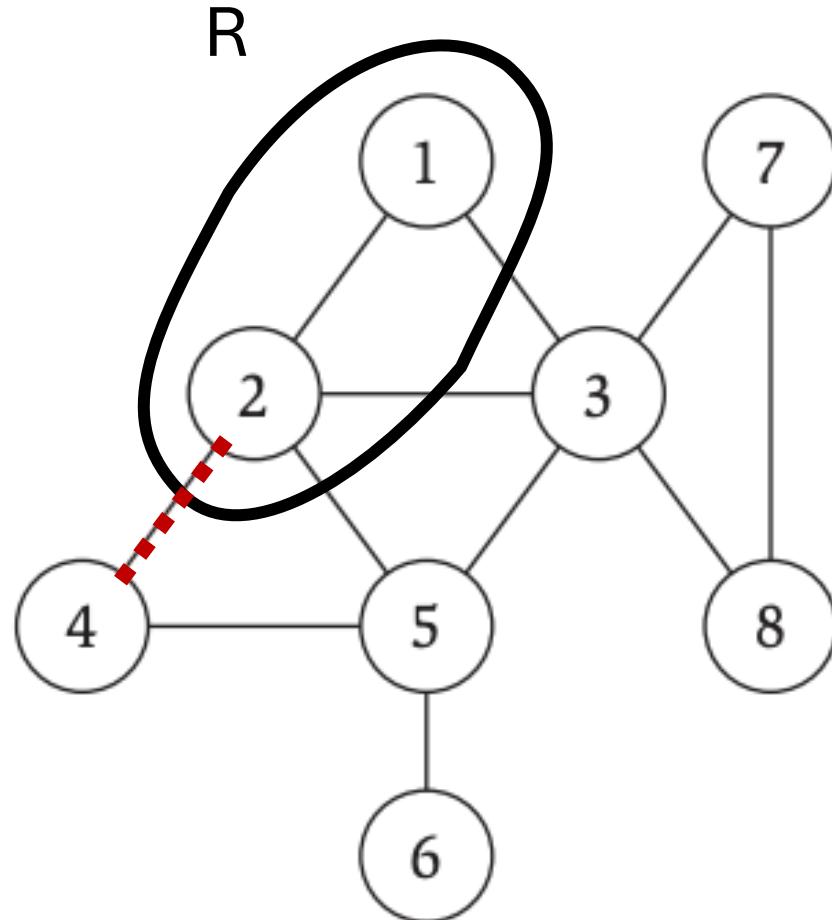
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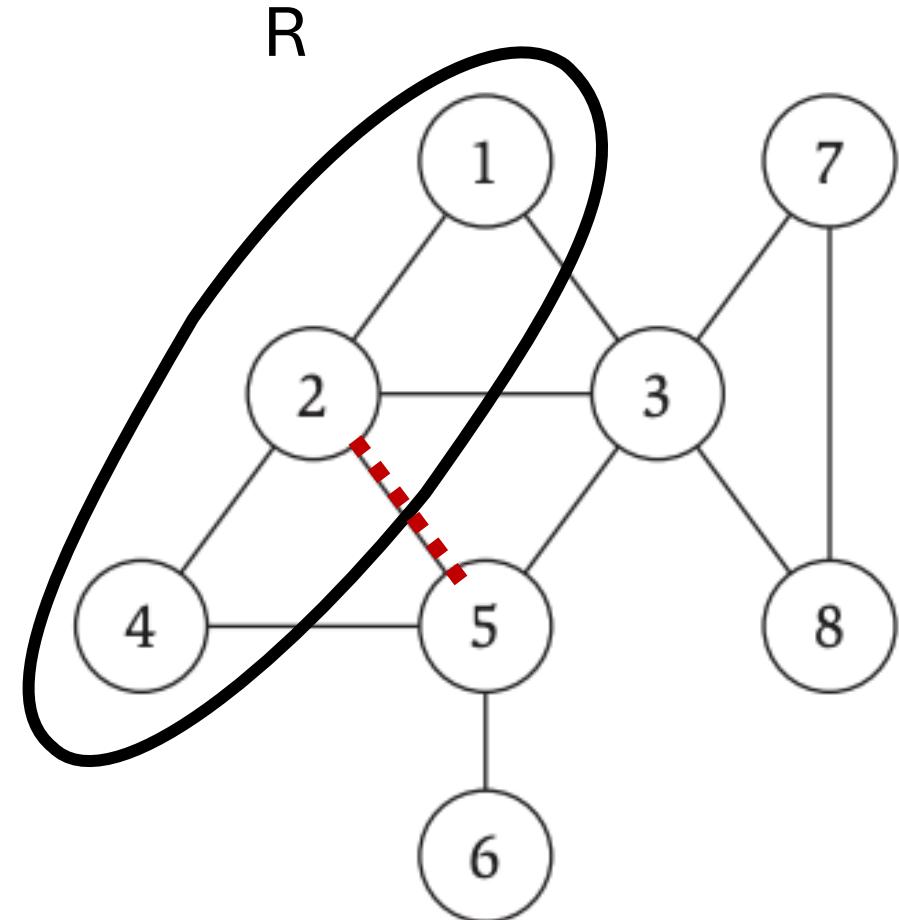
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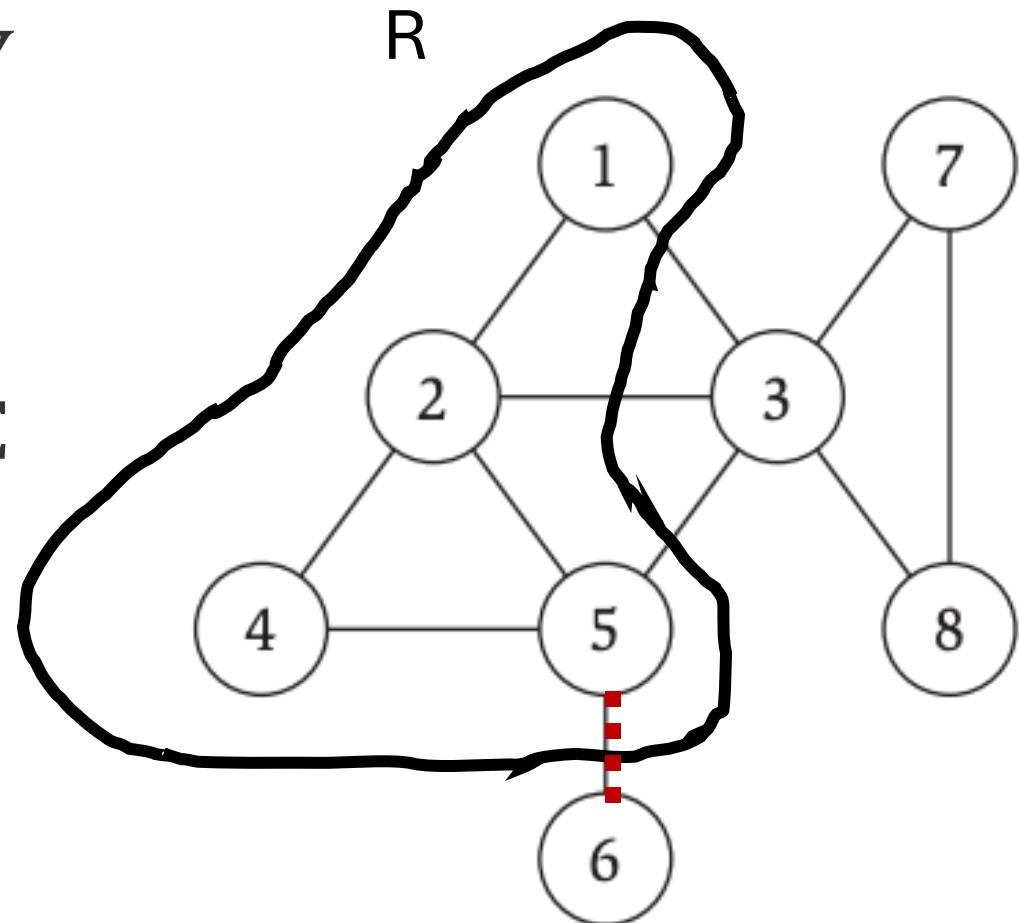
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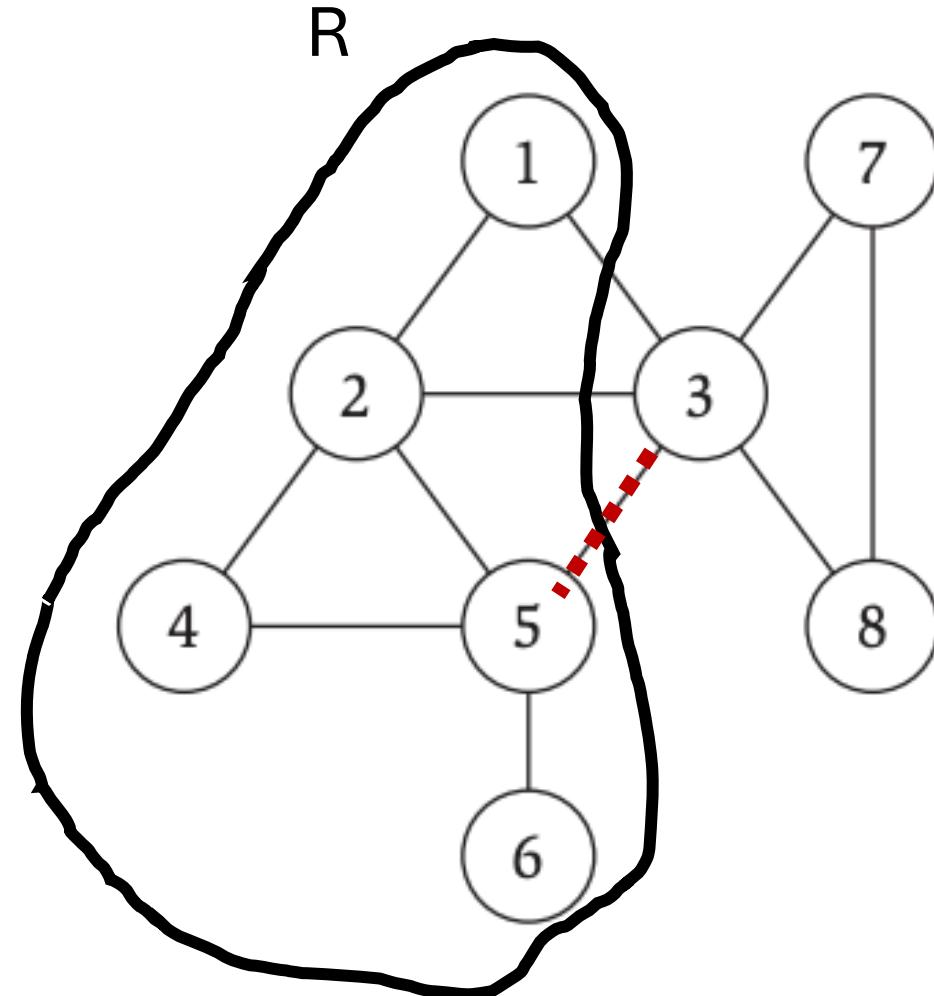
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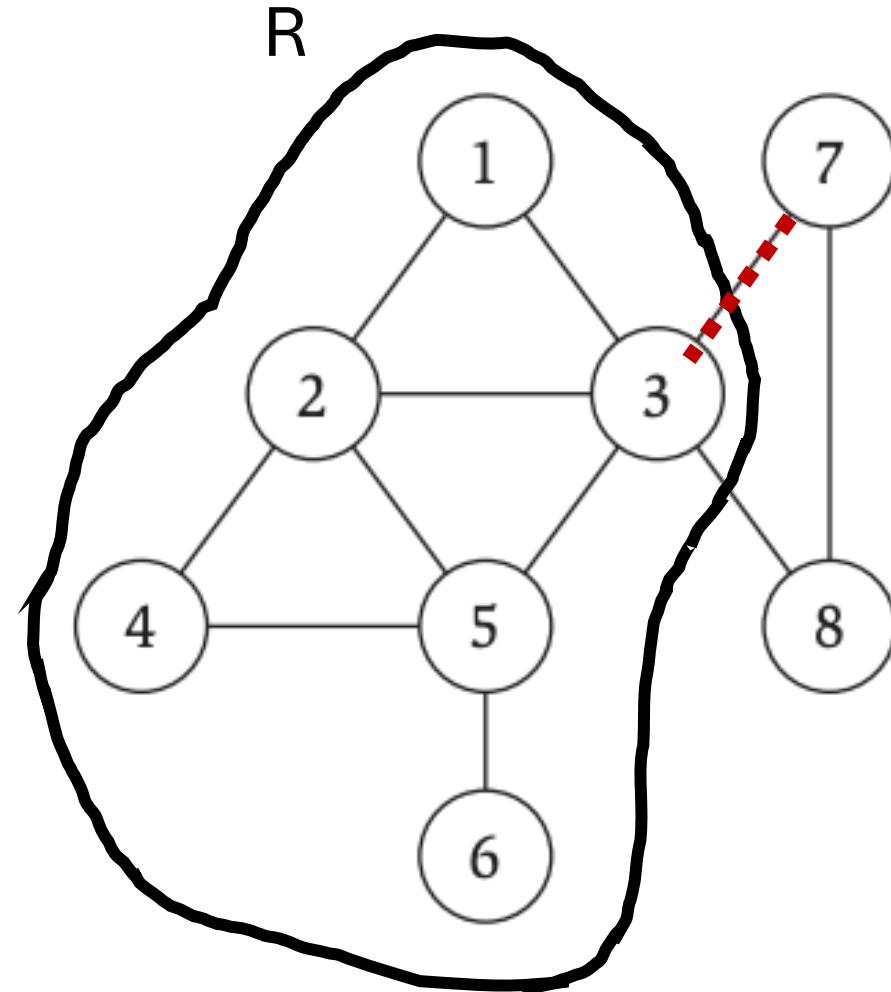
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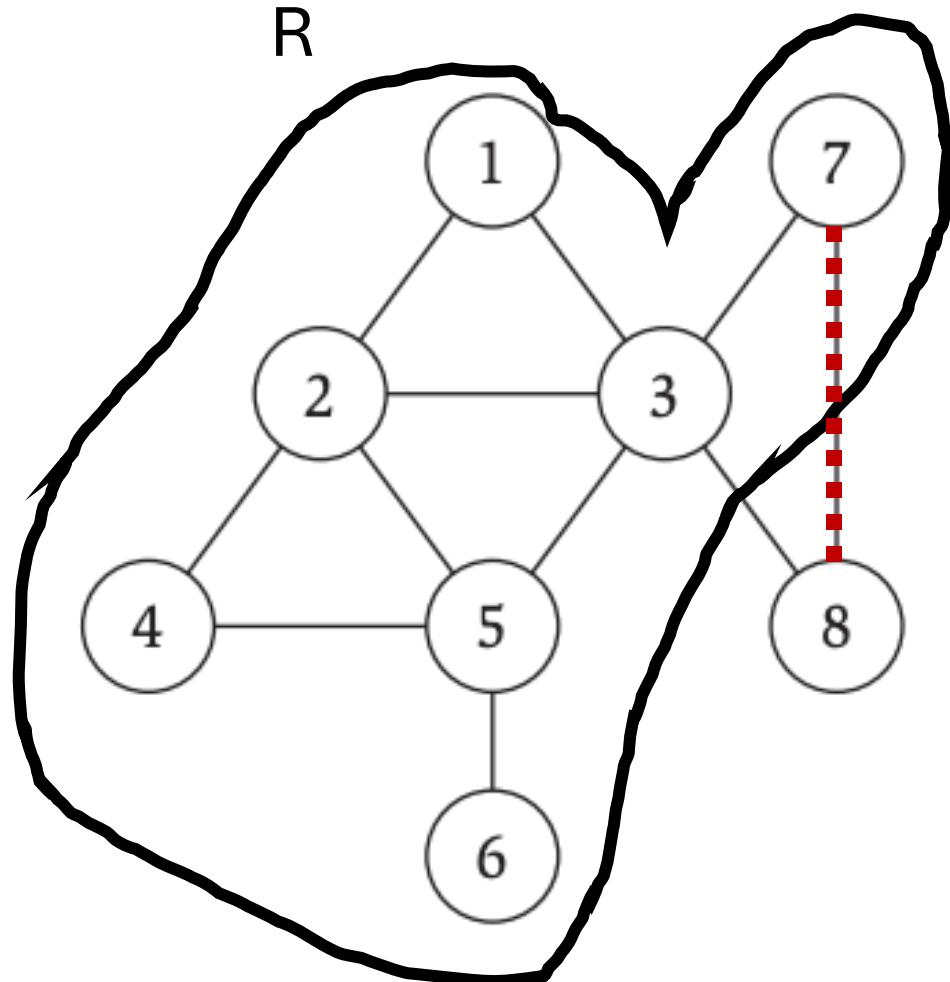
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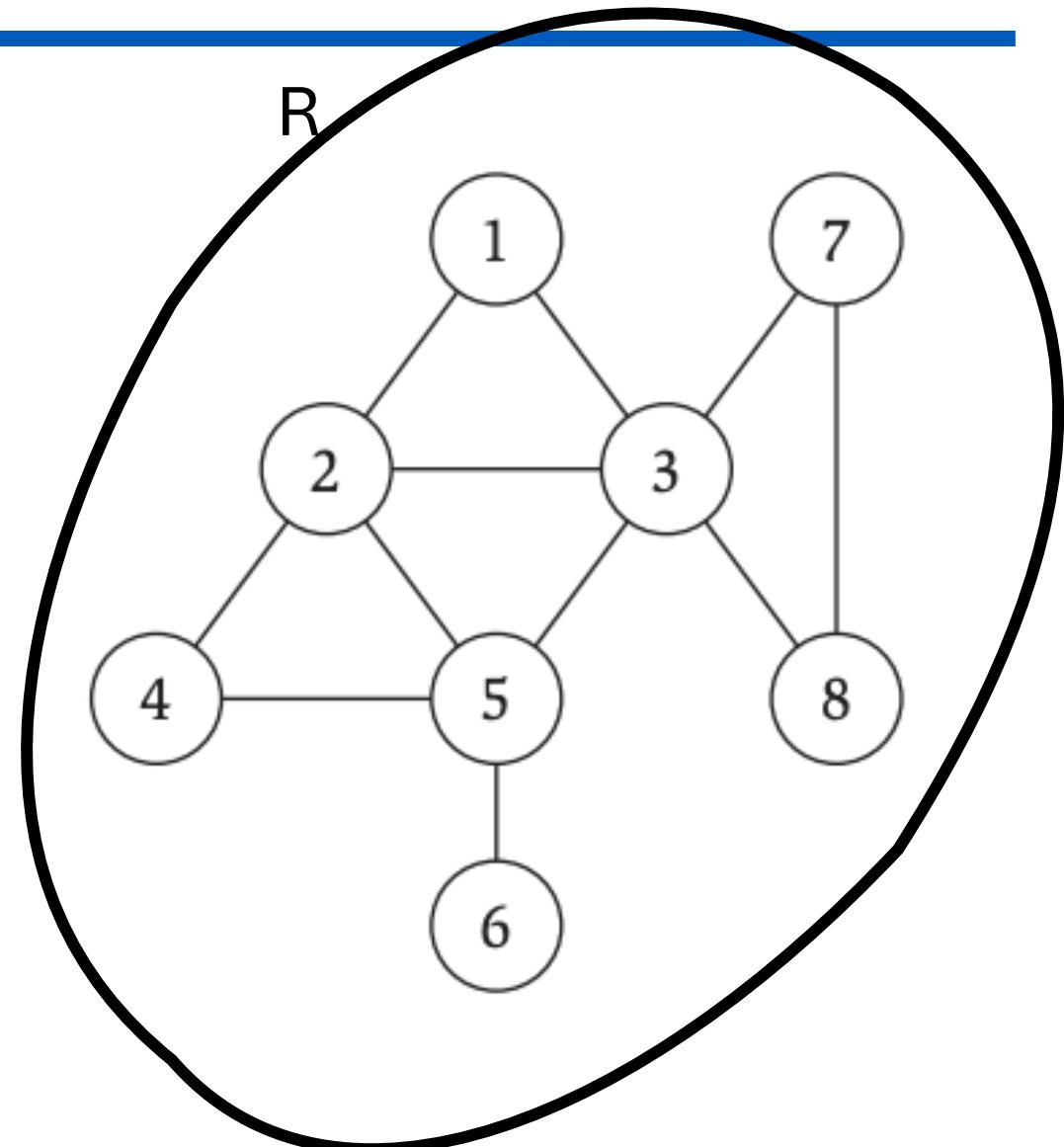
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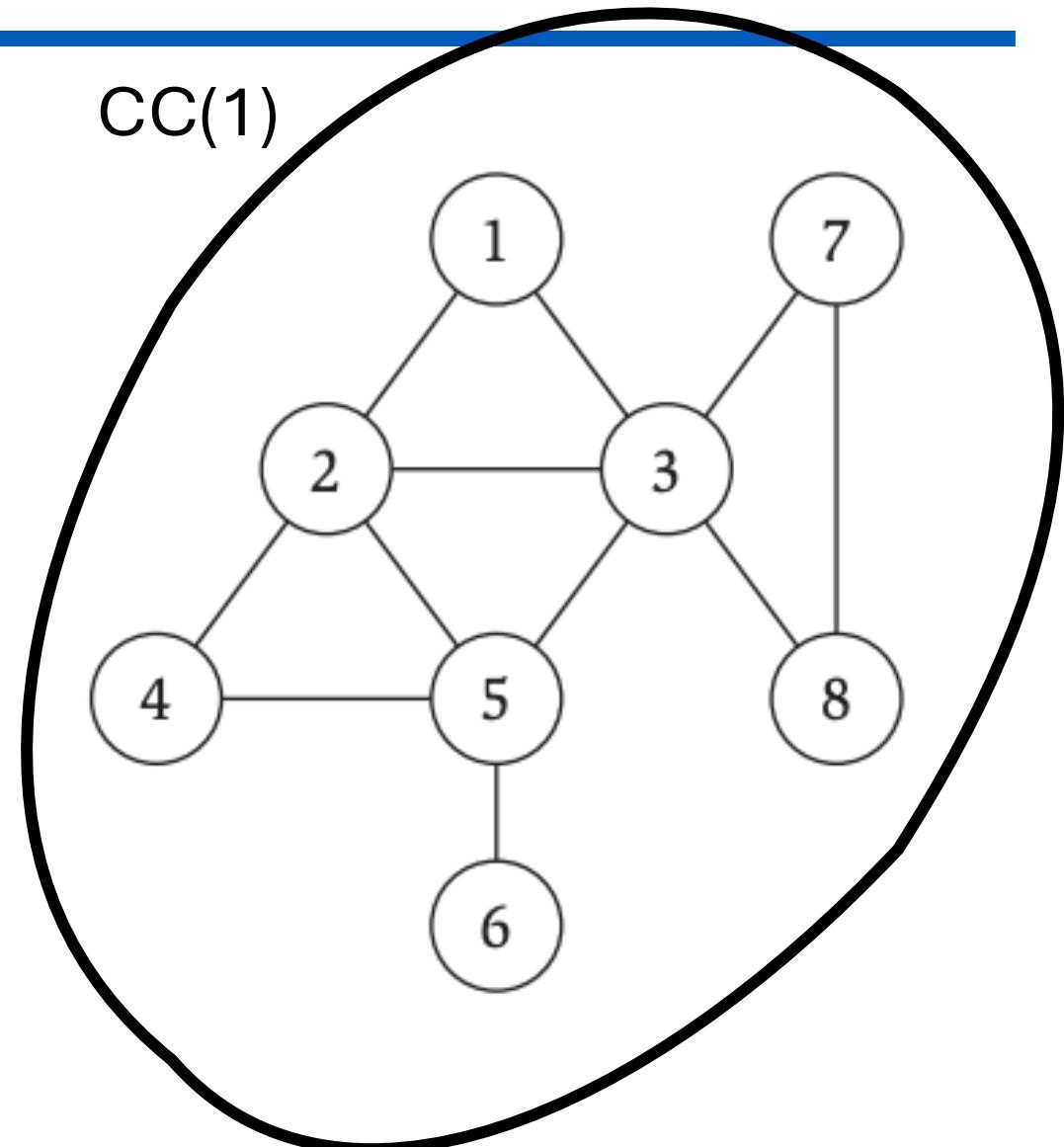
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# Q: What is the difference? (BFS vs Explore)

---

- Input:  $G = (V, E)$  and  $s \in V$
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- Input:  $G = (V, E)$  and  $s \in V$
- Let  $L_0 = \{s\}$
- Assume  $L_0, \dots, L_i$  have been constructed:
  - Let  $L_{i+1}$  be nodes do not appear in  $L_0, \dots, L_i$  and have an edge to  $L_i$ .
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  - Return all layers.

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  - If  $L_{i+1}$  is empty, stop.
  - Return all layers.

**BFS is Explore but Explore isn't necessarily BFS!**

# Q: How do we show this solves Connectivity?

---

- Input:  $G = (V, E)$  and  $s \in V$
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- Return  $R$
- Argue that  $R = \text{CC}(s)!$
- Q: How do we do this?

# Q: How do we show this solves Connectivity?

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  - Add  $v$  to  $R$
- Return  $R$
- Argue that  $R = \text{CC}(s)!$ 
  - Show  $R \subseteq \text{CC}(s)$
  - Show  $\text{CC}(s) \subseteq R$

# Breadth First Search (Properties)

---

**Claim:**  $R \subseteq CC(s)$

**Proof Idea:**

- This wants us to show that everything reached by Explore is in the connected component of  $s$ .
- Let's do induction on iteration of the algorithm.
  - Do you believe the first iteration.
  - Given any iteration is true, how do you feel about the next iteration?

# Q: Does this always terminate?

---

- Input:  $G = (V, E)$  and  $s \in V$
- Output:  $\text{CC}(s)$
- Let  $R = \{s\}$
- While there exists  $\{u, v\} \in E$  such that  $u \in R$  and  $v \notin R$ :
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- Return  $R$
- Well, we must be adding a vertex in each iteration and there are only so many vertices, right?

# Q: Does this always terminate?

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# Explore Proofs

---

**Claim:**  $CC(s) \subseteq R$

**Proof:**

- This is saying that every vertex in the connected component is added to  $R$  by `Explore`.
- This is saying that for every vertex  $v$  such that there is a path from  $s$  to  $v$ ,  $v$  is added to  $R$  by `Explore`.

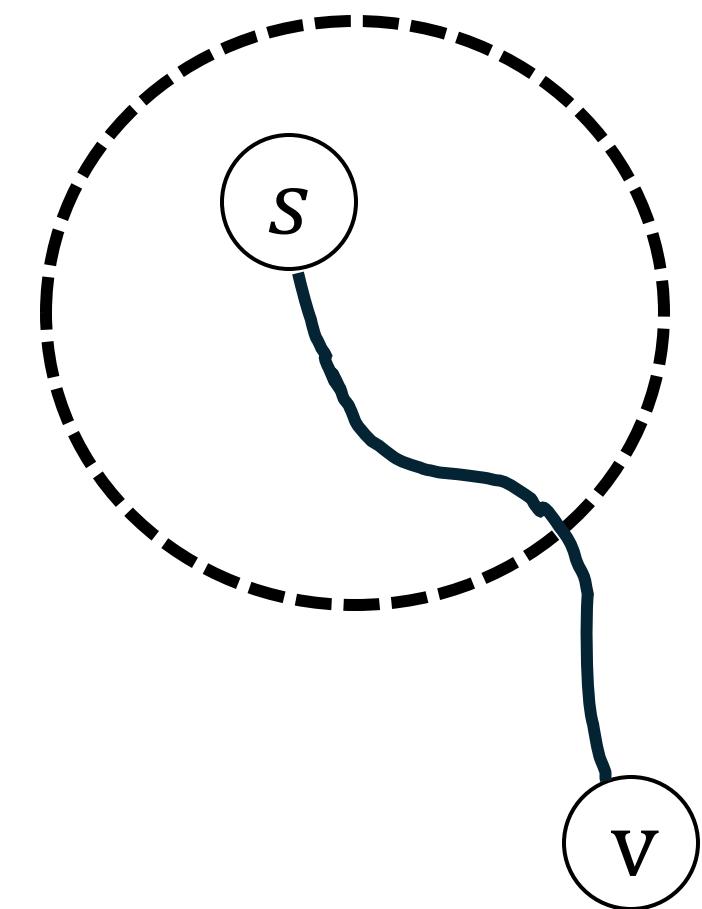
# Explore Proofs

---

**Claim:**  $CC(s) \subseteq R$

**Proof:**

- Suppose to the contrary that there exists  $v \in CC(s)$  such that  $v \notin R$ .
  - Then there must exist a path that starts at  $s$  (inside  $R$ ) and ends at  $v$  (outside  $R$ ).



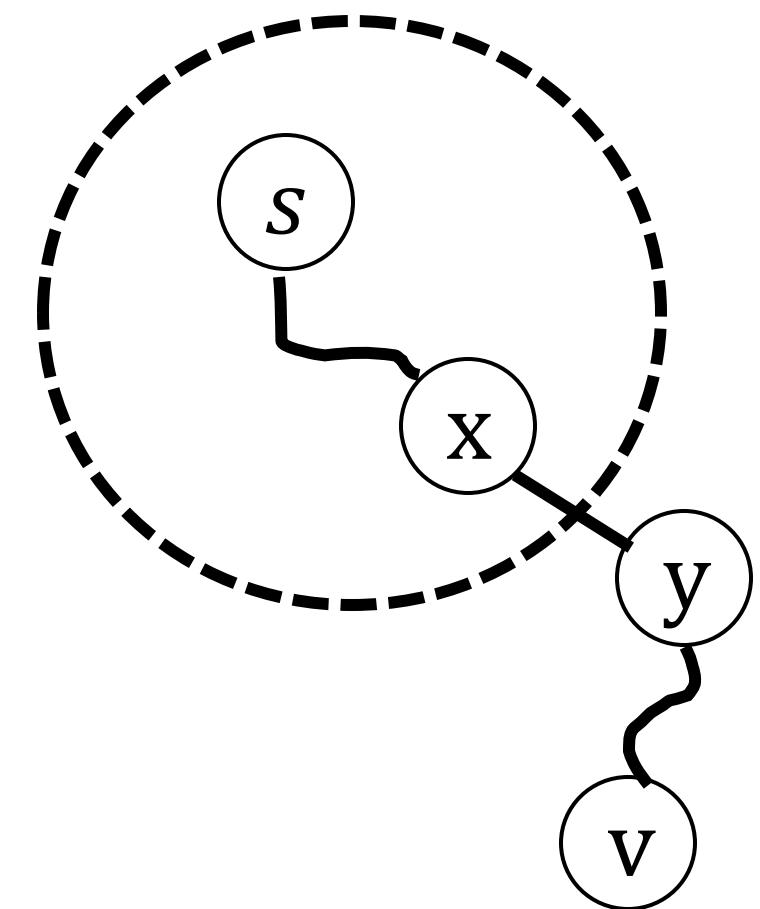
# Explore Proofs

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**Claim:**  $CC(s) \subseteq R$

**Proof:**

- There then must exist  $\{x, y\} \in E$  such that  $x \in R$  and  $y \notin R$ .



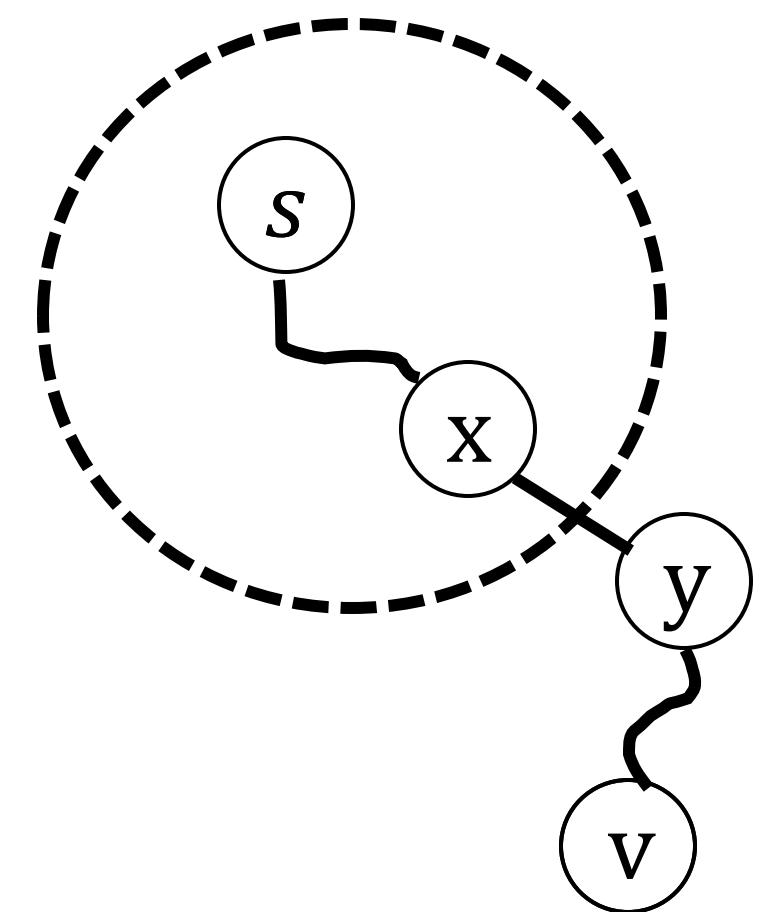
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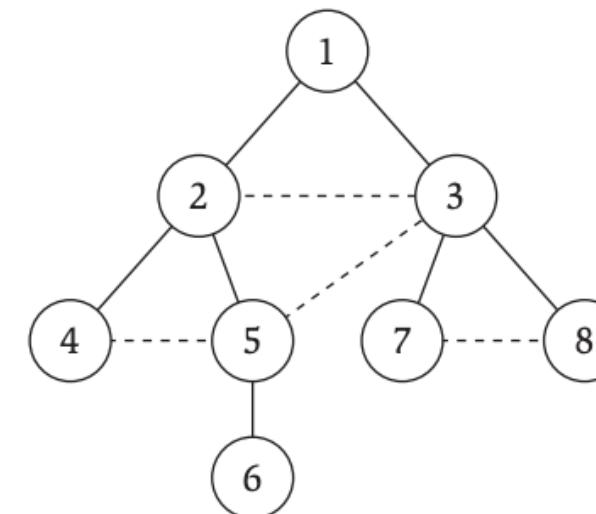
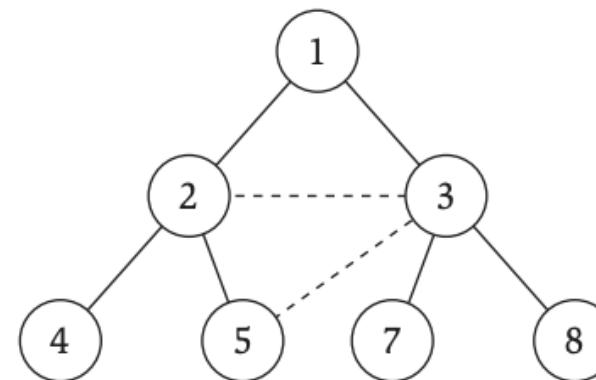
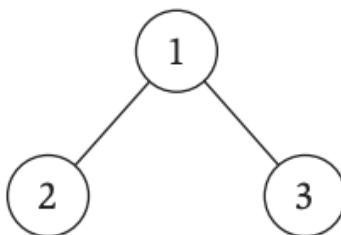
- There then must exist  $\{x, y\} \in E$  such that  $x \in R$  and  $y \notin R$ .
- If this the case, then the algorithm wouldn't have terminated and would have instead added  $y$ .  $=><=$



# Q: How would you describe BFS?

---

- $L_0 = s$
- $L_1 = \text{neighbors of } L_0.$
- $L_2 = \text{neighbors of } L_1 \text{ that are not in } L_0.$
- $L_i = \text{neighbors of } L_{i-1} \text{ that are not in previous layer.}$



# Depth First Search

---

- **Input:** The current vertex  $u \in V$
- **Global:** An array of exploration  $A \in \{0,1\}^V$
- Mark current vertex as explored ( $A[u] = 1$ ).
- For each  $\{u, v\} \in E$ :
  - If  $v$  is not explored ( $A[v] == 0$ ):
    - $\text{DFS}(v, A)$

# Depth First Search

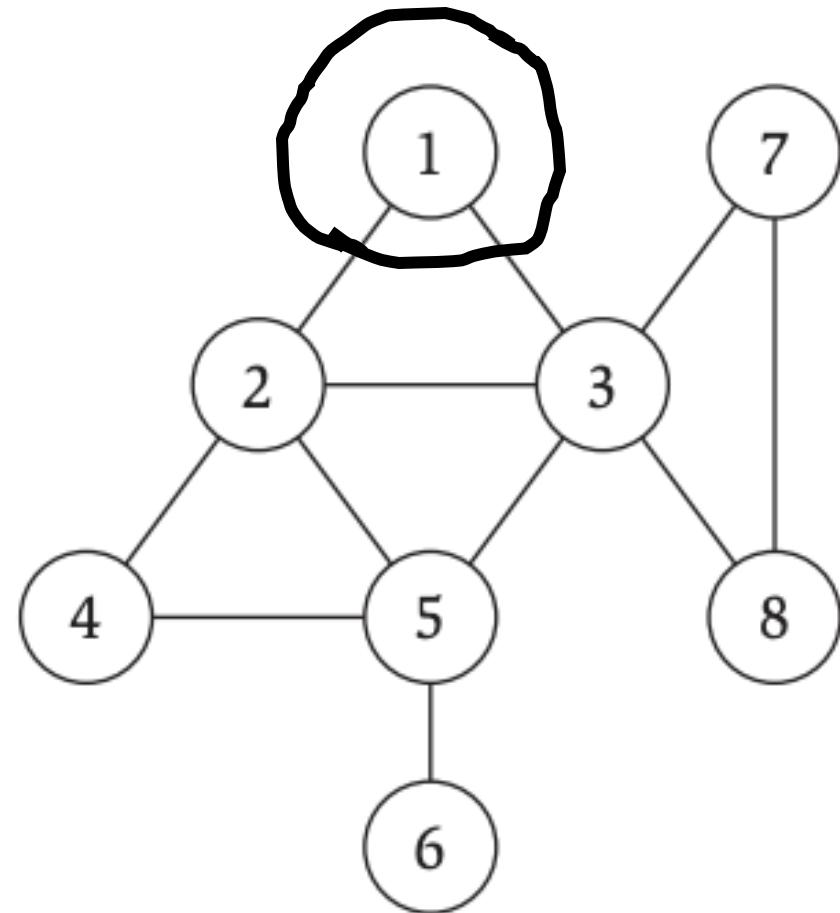
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- For each  $\{u, v\} \in E$ :
  - If  $v$  is not explored ( $A[v] == 0$ ):
    - $\text{DFS}(v, A)$
- **Idea:** You are recursing or “drilling down”. If you get stuck, you go up a step and try the next choice.

# Depth First Search

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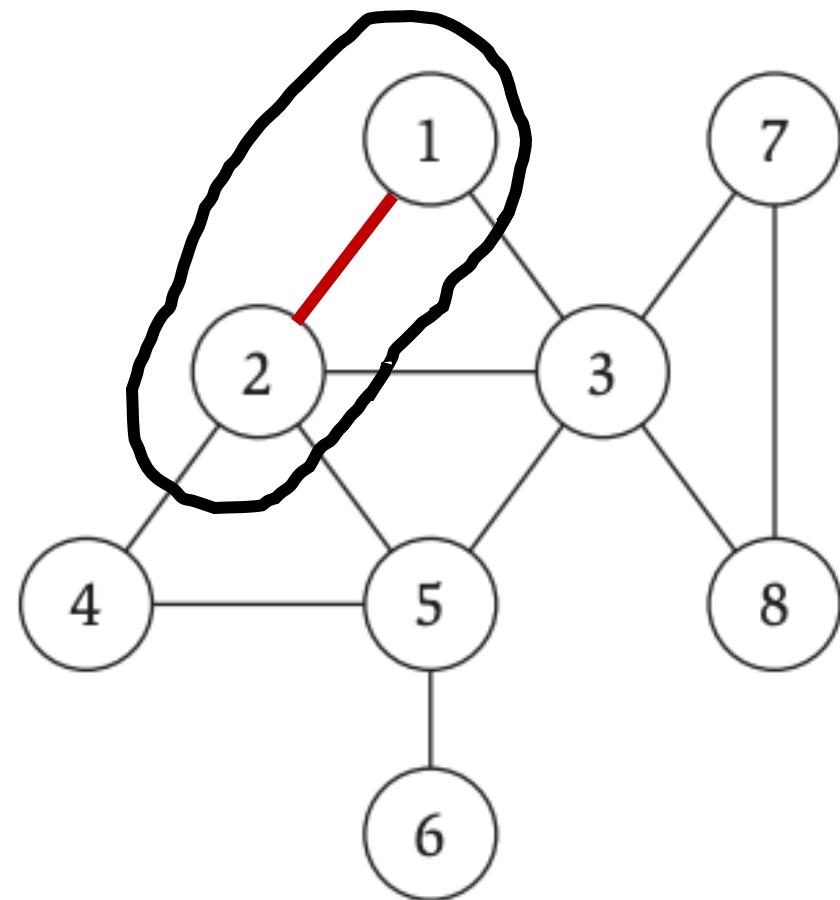
$A = \{1\}$



# Depth First Search

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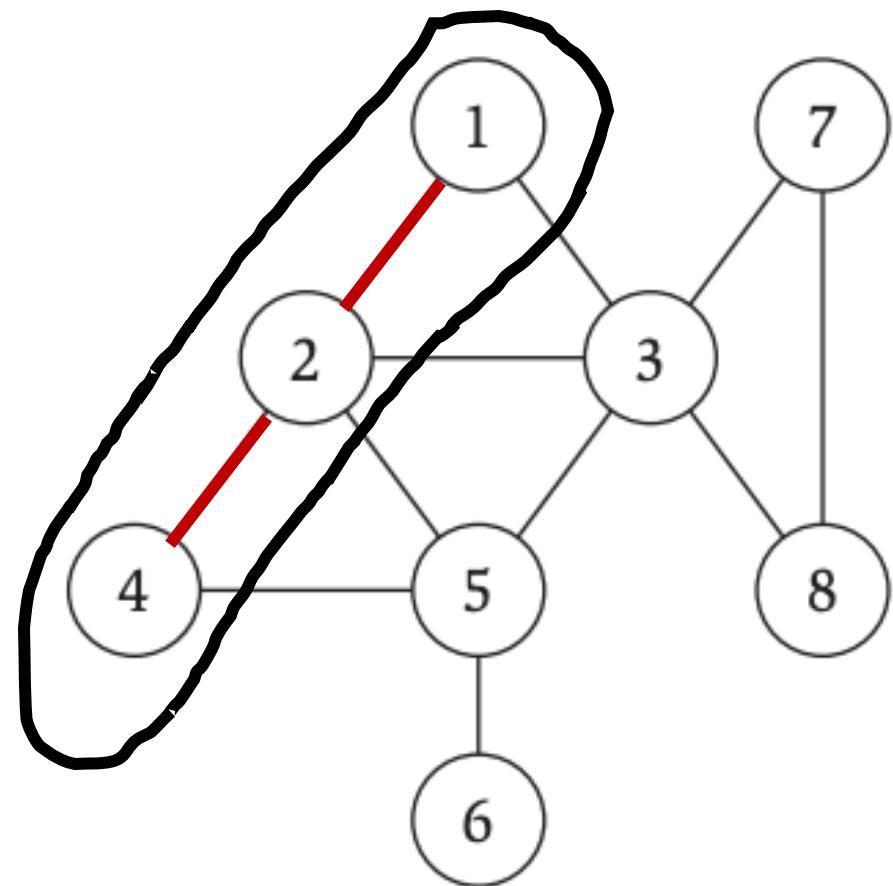
$$A = \{1, 2\}$$



# Depth First Search

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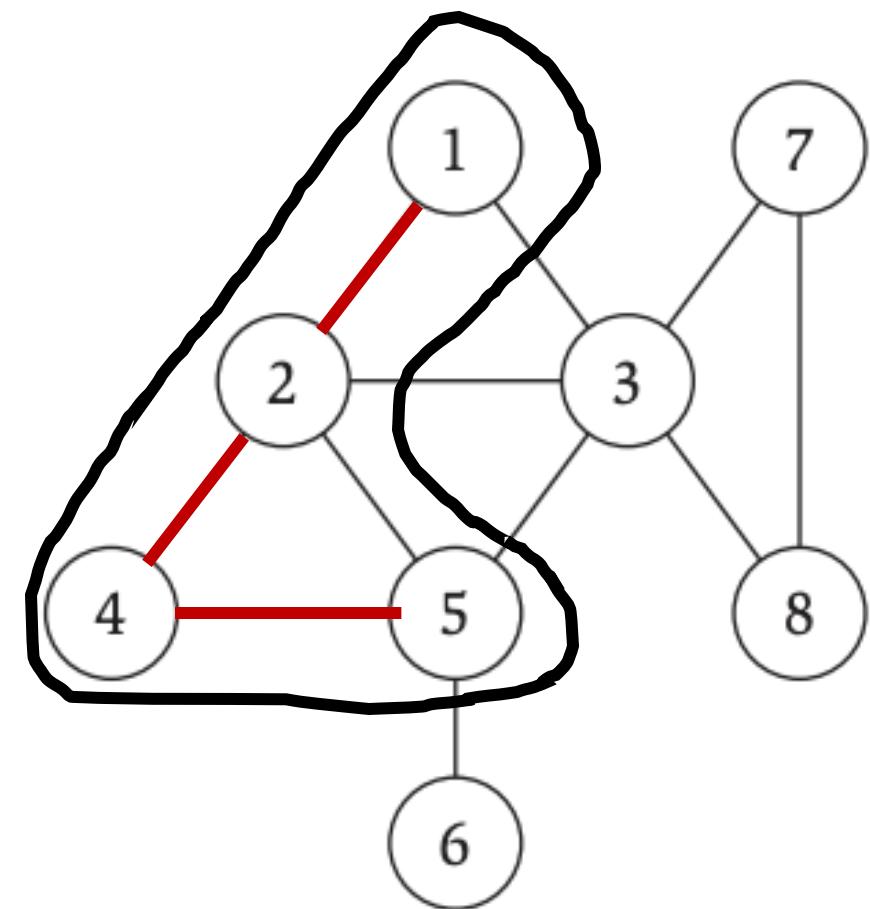
$A = \{1, 2, 4\}$



# Depth First Search

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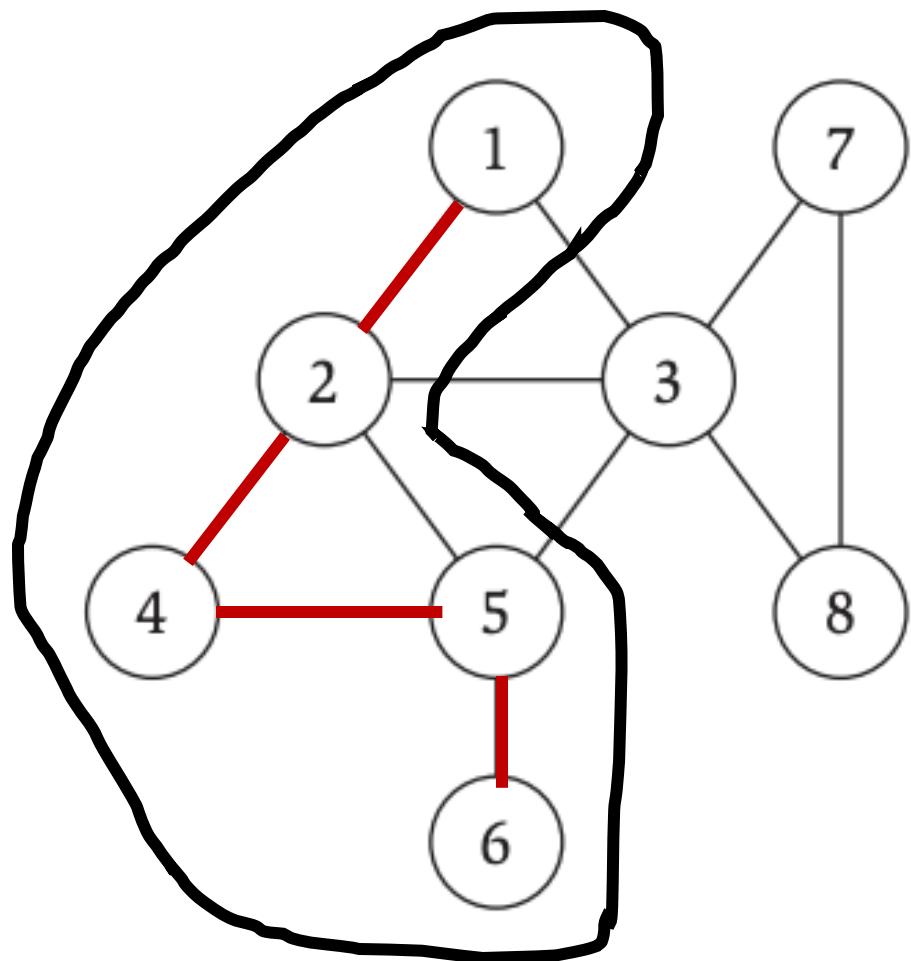
$A = \{1, 2, 4, 5\}$



# Depth First Search

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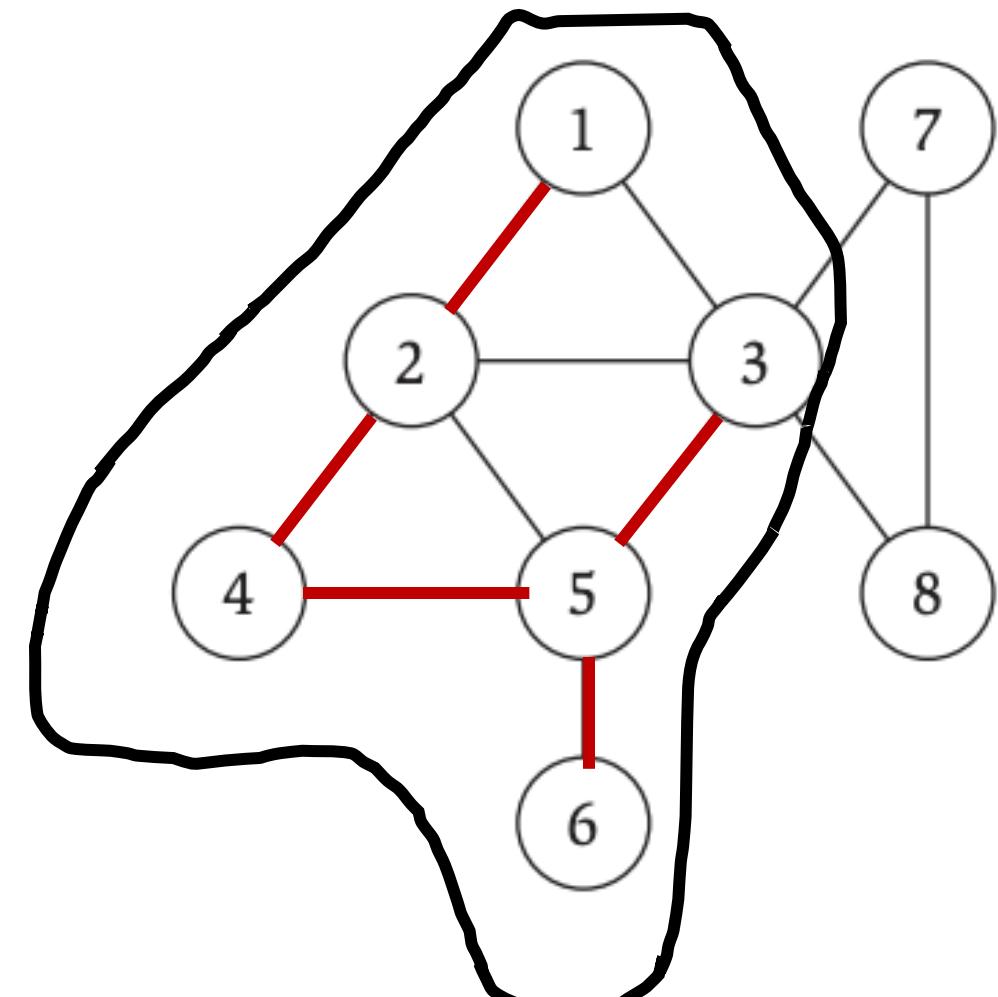
$A = \{1, 2, 4, 5, 6\}$



# Depth First Search

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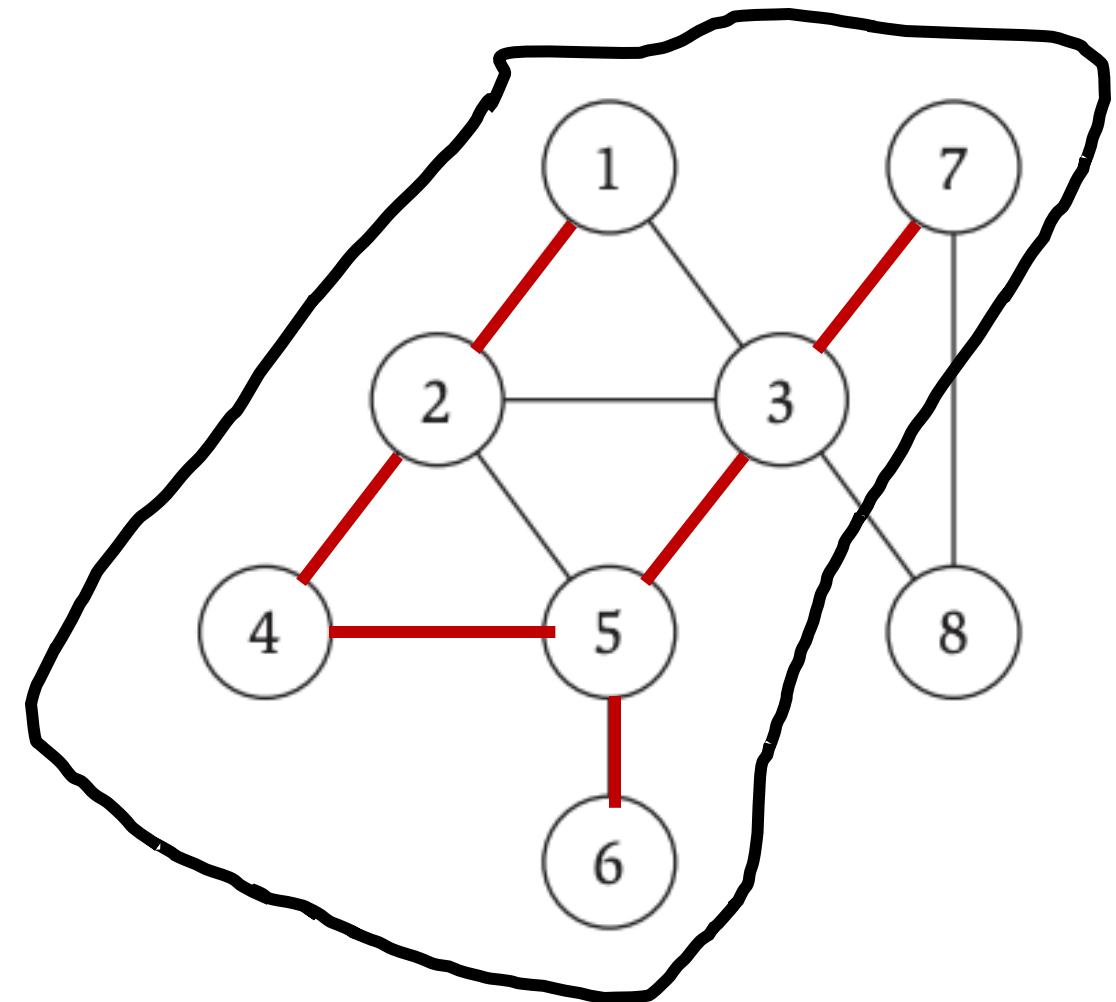
$A = \{1, 2, 4, 5, 6, 3\}$



# Depth First Search

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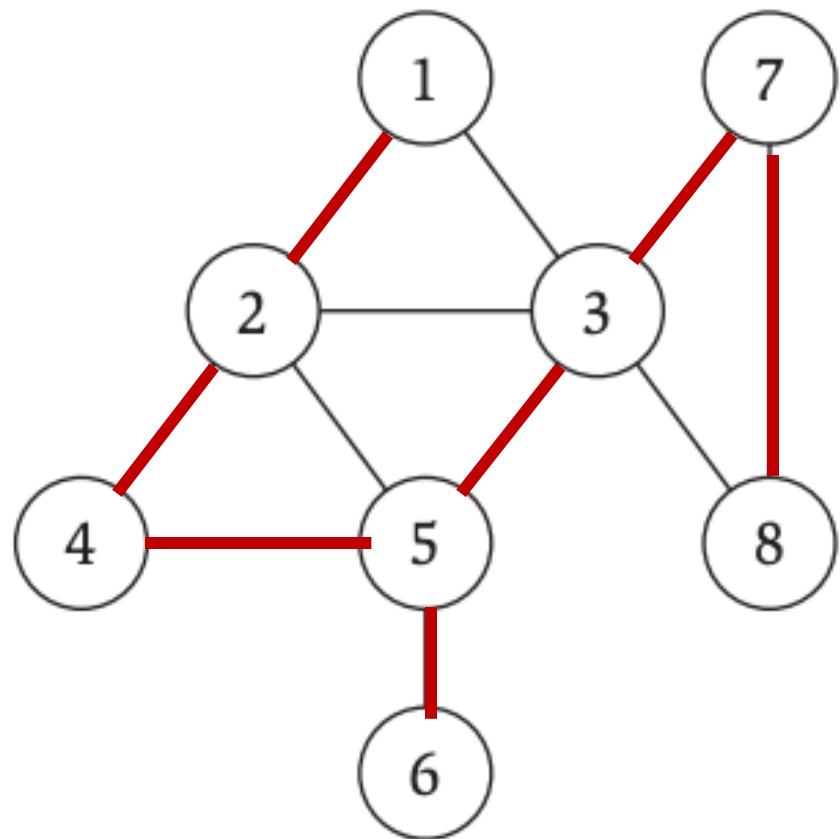
$A = \{1, 2, 4, 5, 6, 3, 7\}$



# Depth First Search

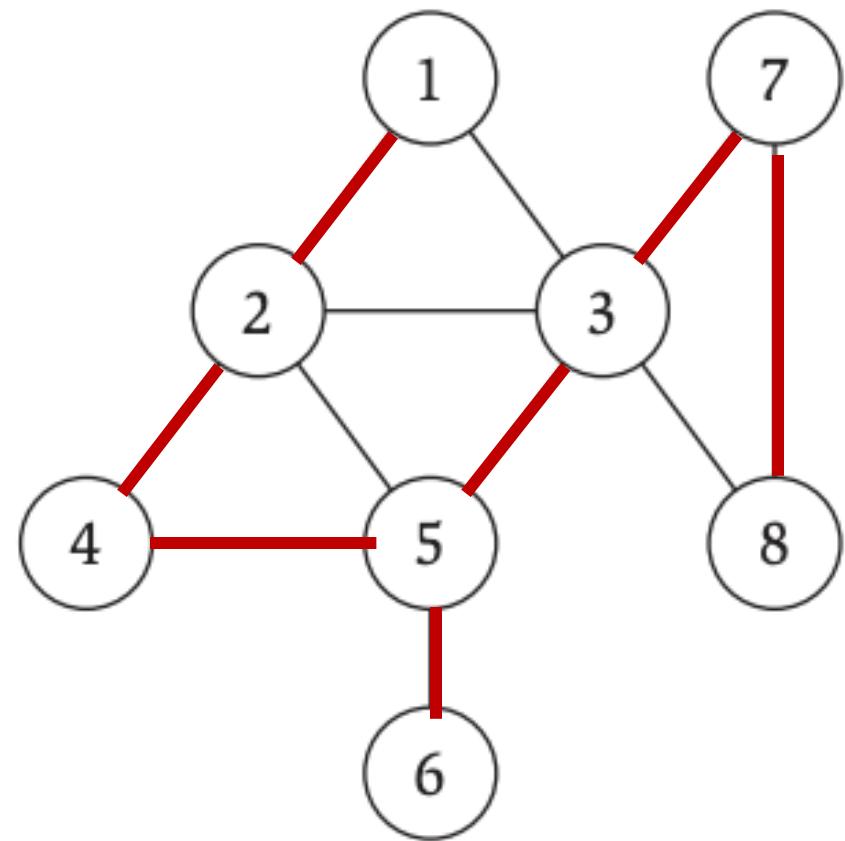
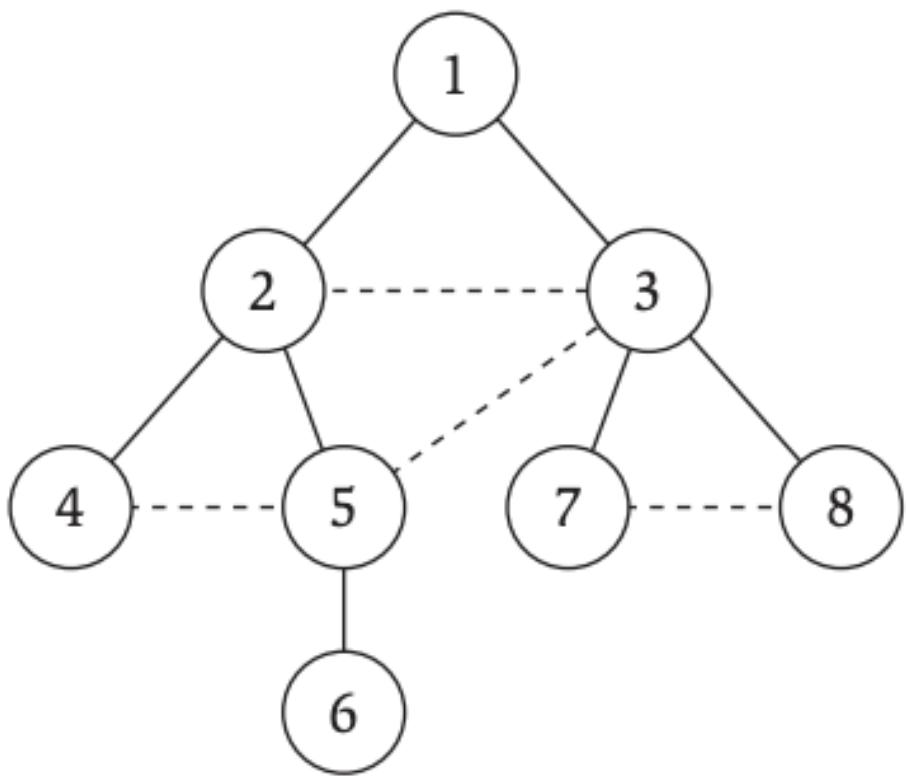
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$A = \{1, 2, 4, 5, 6, 3, 7, 8\}$



# DFS Trees vs BFS Trees

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Q: How can you compute all the connected components of a graph?

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