

Third Order Maneuvering Track Filter

Design and Simulations

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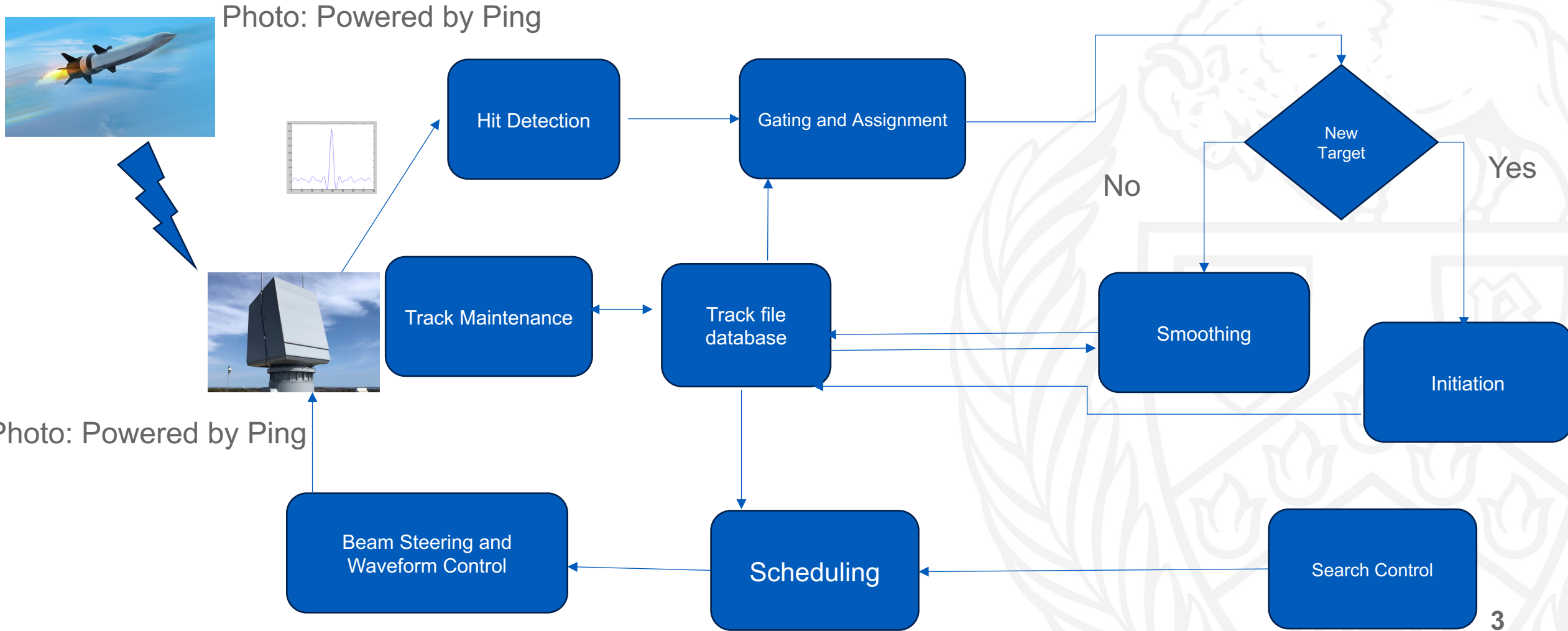
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Definition Of A Third Order Track Filter

- ❖ An algorithm that combines previous and current data pertaining to the target position(range), velocity and acceleration to estimate the current and future target position (range), velocity and acceleration.
- ❖ Filters can be evaluated by several parameters such as:
 - The accuracy of the estimate given a particular target motion and measurement accuracy
 - The responsiveness of the estimate to changes in target dynamics
 - The ability of the algorithm to characterize its own accuracy
 - The computational complexity of the algorithm
 - The robustness of the algorithm

Track Filter Algorithm System Diagram



Kalman Filter and Separate Filter

- ❖ For both filters, the state update equation is

$$R_s = (1 - \alpha) R_p + \alpha R_m$$

Given the same value of α , the same results are achieved regardless of the model chosen

- ❖ The more standard Kalman filter approach of choosing process noise can result in the same results
 - The optimum process noise is non-trivial to compute in real time
 - The standard approach of using a constant process noise does not result in optimal noise
 - No bias estimate is easily available
- ❖ For the reason above, Optimal Reduced State Estimator (ORSE) is extensively use

Higher Order Filter

- ❖ To improve the system performance, the filter order should be increased
- ❖ The system model is expressed in matrix form

- For a second order track filter, the long form system model is defined as follows:

The state equation, $x_{k+1} = Fx_k + G\lambda_k$

$R_{k+1} = R_k + T V_k + 0.5T^2\lambda_k$; the range(position)

$V_{k+1} = V_k + T \lambda_k$; the velocity

and the measurement model in matrix form is expressed as

- $R_m = Hx + n_k$
- where $H = [1 \ 0]$ and $n = N(0, sR_m^2)$, Measurement Noise Long Form: $R_m = R_k + n_k$

ORSE Equations For Prediction In Matrix Form

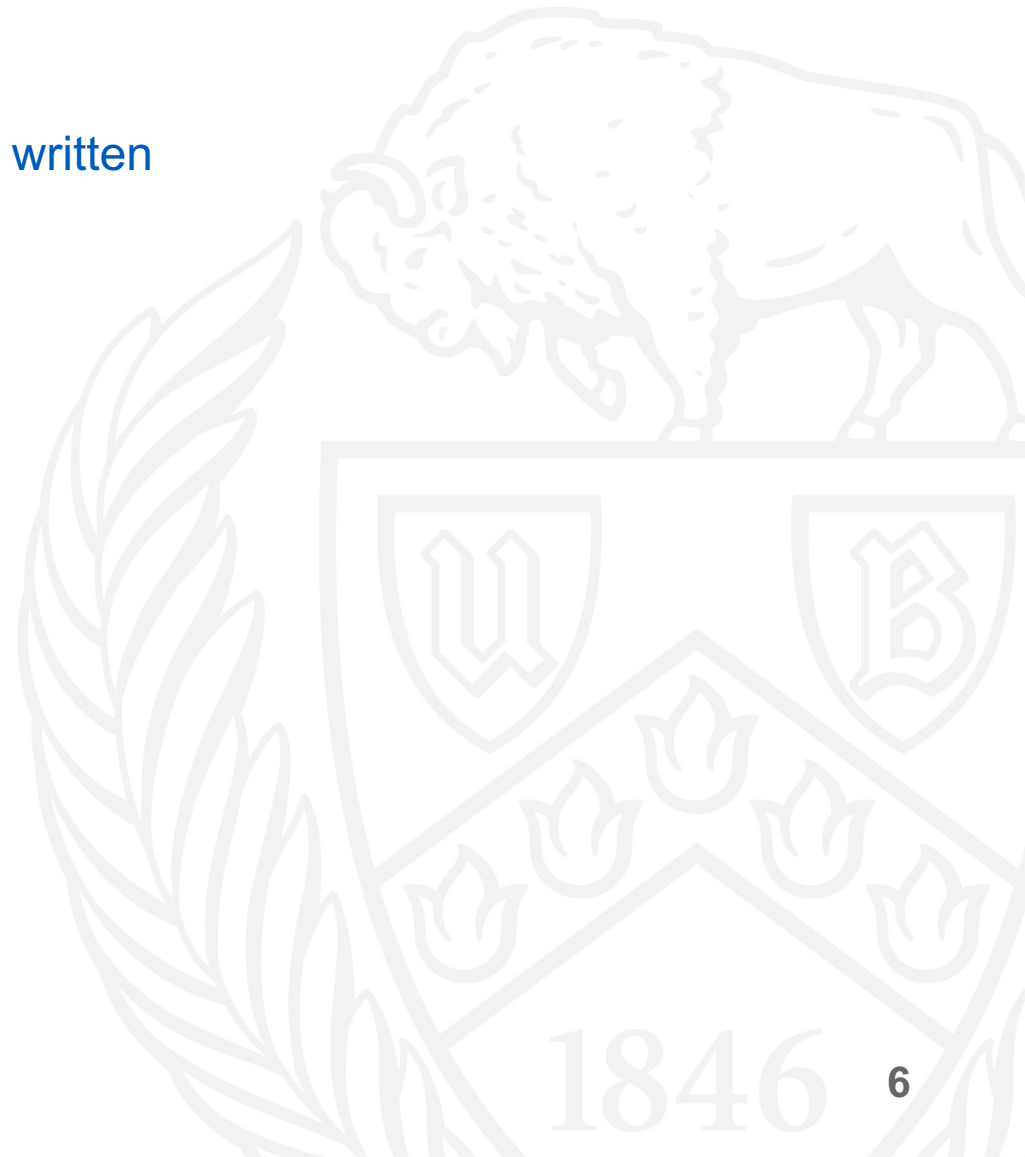
- ❖ The equation to predict a state estimate forward in time can be written

$$x_p = F x_s$$

- ❖ Note that the unknown acceleration component is not added.

The covariance of the predicted state can be written

- $M_p = F M_s F^T$
- $D_p = F D_s + G$
- $S_p = M_p + D_p \Lambda D_p^T$
- ❖ Note new terminology (from ORSE papers)
 - M: Covariance of track state
 - D: Bias scaling matrix
 - S: RSS of covariance and bias
 - L: Maximum maneuver (squared), in each dimension



ORSE Equations For Prediction In Matrix Form Cont'd

- ❖ λ is the maximum uncertainty in the model
- ❖ D describes how a maneuver creates a bias ($D\lambda$)
- ❖ M is the random, unbiased variance in the track state
- ❖ When reporting the total covariance, it is usually intended to represent a $(1-\sigma)$ representation of the data
- ❖ $\text{Cov} = M + D\Lambda D'$
- ❖ In this case, Λ represents the 'variance' of the maneuver –not technically correct

Gain and ORSE Smoothing Equations In Matrix Form

- ❖ The gain equation can be written

$$K = Sp H^T (\sigma R_m 2 + H Sp H^T)^{-1}$$

- ❖ This is the gain to minimize the smoothed covariance

- ❖ Compare this to

$$\alpha = Pp / (Pp + Pm)$$

- ❖ The components of the gain of a second order filter are often labeled

$$K = \begin{bmatrix} \alpha \\ \beta / T \end{bmatrix}$$



Gain And ORSE Smoothing Equations In Matrix Form Cont'd

- ❖ The equation to smooth a state prediction with a measurement can be written

$$x_s = x_p + K(Rm - Hx_p) ;$$

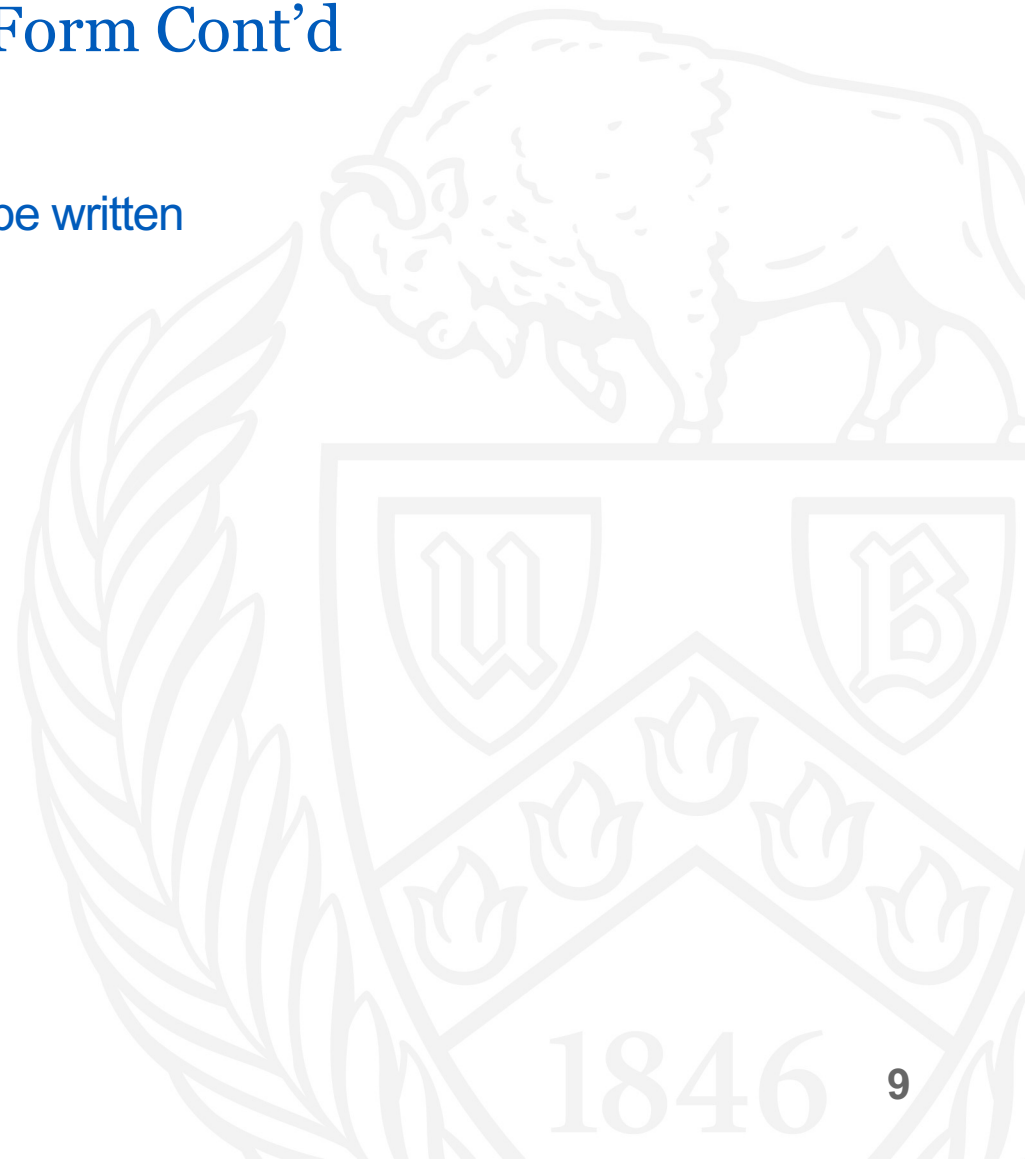
Compare this to $R_s = R_p + \alpha(Rm - R_p)$

- ❖ The covariance of the smoothed state can be written

$$M_s = (I - KH) M_p (I - KH)^T + KPm K^T$$

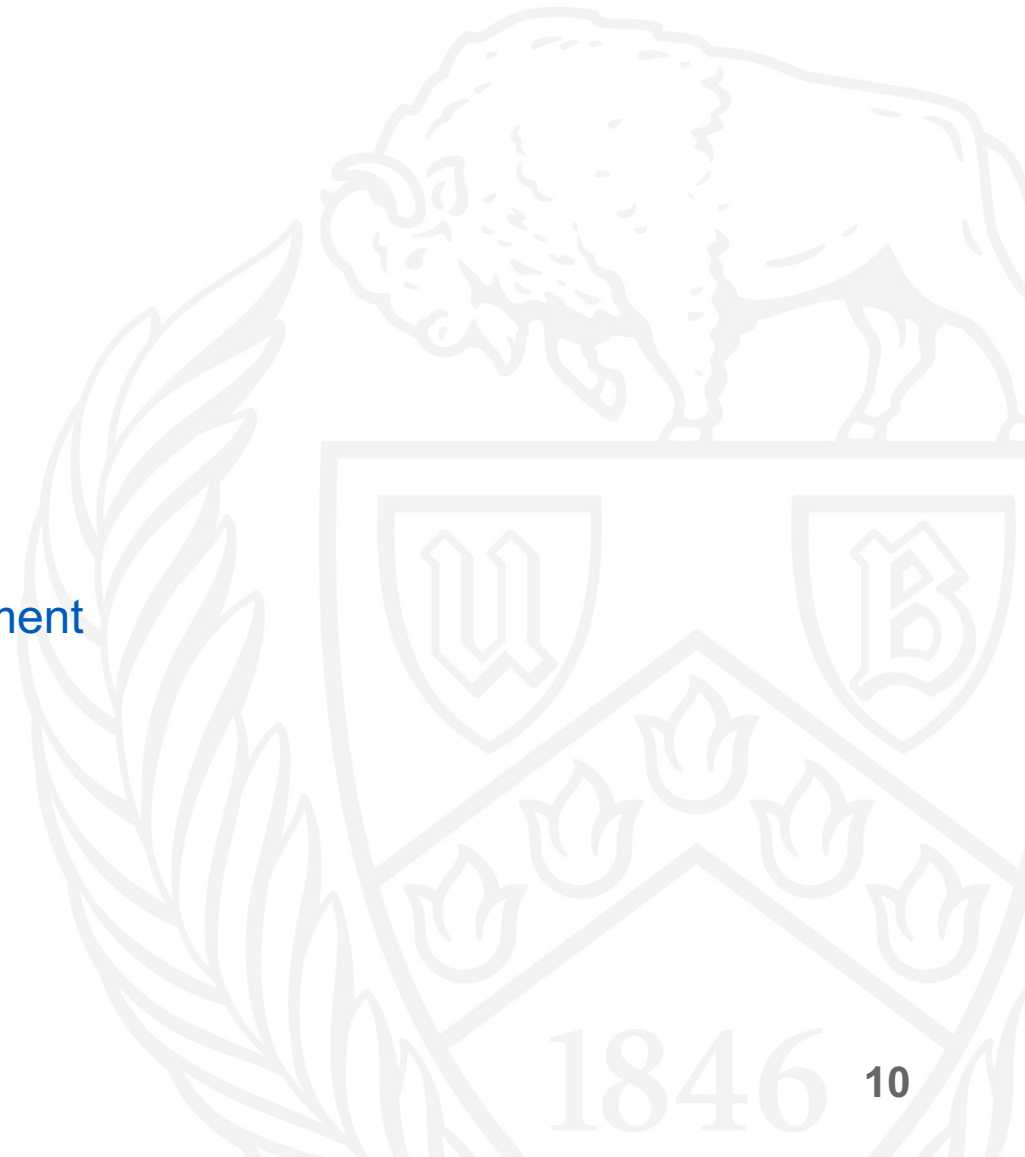
$$D_s = (I - KH) D_p$$

$$S_s = M_s + D_s \Lambda D_s^T$$



Track Initialization and Reinitialization

- ❖ At first measurements
 - $X_1 = \begin{bmatrix} R_{m1} \\ 0 \end{bmatrix}$,
 - $M_{1|1} = \begin{bmatrix} \sigma_n^2 & 0 \\ 0 & \infty \end{bmatrix}$ and $D_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$,
- ❖ Infinite value is difficult to enter into software
 - Never look at value until reinitialized at second measurement
 - Use reasonable large value,
- ❖ At second update, two measurements are available



Track Initialization and Reinitialization Cont'd

❖ At second update, two measurements are available

- $X_2 = \begin{bmatrix} R_{m2} \\ (R_{m2} - R_{m1})/\Delta T \end{bmatrix},$

- $M_{2|2} = \begin{bmatrix} \sigma_n^2 & \sigma_{n/\Delta T}^2 \\ \sigma_{n/\Delta T}^2 & \sigma_{n/\Delta T^2}^2 \end{bmatrix}$ and $D_2 = \begin{bmatrix} 0 \\ \Delta T/2 \end{bmatrix},$



Third order Filter System Modeling

- ❖ The system model is expressed in matrix form as

$$x_{k+1} = F x_k + G \lambda_k$$

Where $G = \begin{bmatrix} \frac{1}{6} T^3 \\ \frac{1}{2} T^2 \\ 1 \end{bmatrix}$

$\lambda =$ maneuver (acceleration, now)

$$F = \begin{bmatrix} 1 & T & 0.5T^2 \\ 0 & 1 & T \\ 0 & 0 & 1 \end{bmatrix} \text{ is the transition matrix}$$



Third order Filter System Modeling Cont'd

- ❖ The measurement model is expressed in matrix form

$$Rm = Hx + nk$$

where

$$H = [1 \ 0 \ 0]$$

$n = N(0, \sigma_{Rm}^2)$ is the measurement noise



Third order Filter System Modeling Cont'd

- ❖ The third order track filtering consists of :
 - A third order track initialization module: initializes track detection, track time, next track, track state and track update
 - A third order track reinitialization module: Update the track state and detection
 - A third order target module: define target state parameters, time and update time
 - A third order prediction module: Predict track state and time
 - A third order detection module: defines detected track parameters with added detection noise
 - A third order filter module: defines track state and detection filter
 - A Driver module: runs the models and plotting
 - A plotting module: plots track simulations parameters

Known Motion Compensation

- ❖ Knowing additional information can help in improving system performance
- ❖ Ballistic targets have predictable acceleration due to gravity
 - In the prediction model, known acceleration can be added into the model
 - Approximately known forces, such as forces due to drag, can be added into the model, and the errors can also be taken into consideration
- ❖ Target tracking in a relative coordinate frame will have motion components due to sensor platform motion, and these can be compensated

Code Repository

- `/user/jeandedi/Desktop/FinalProjectCodes`

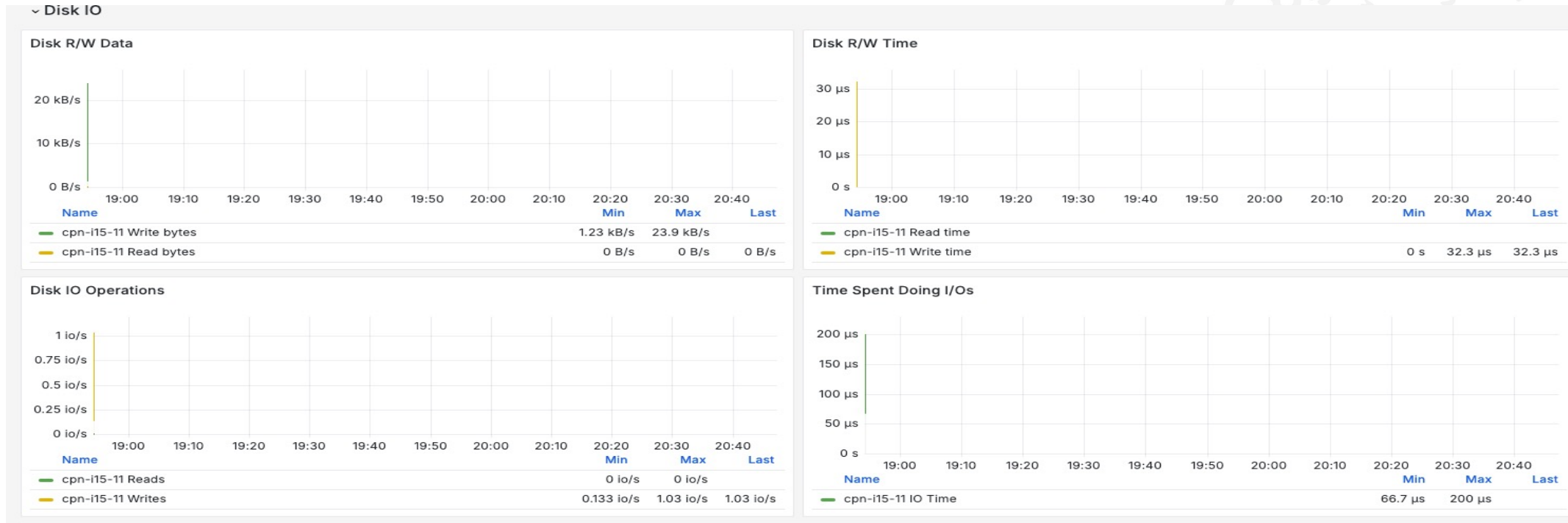


Job Submission Script

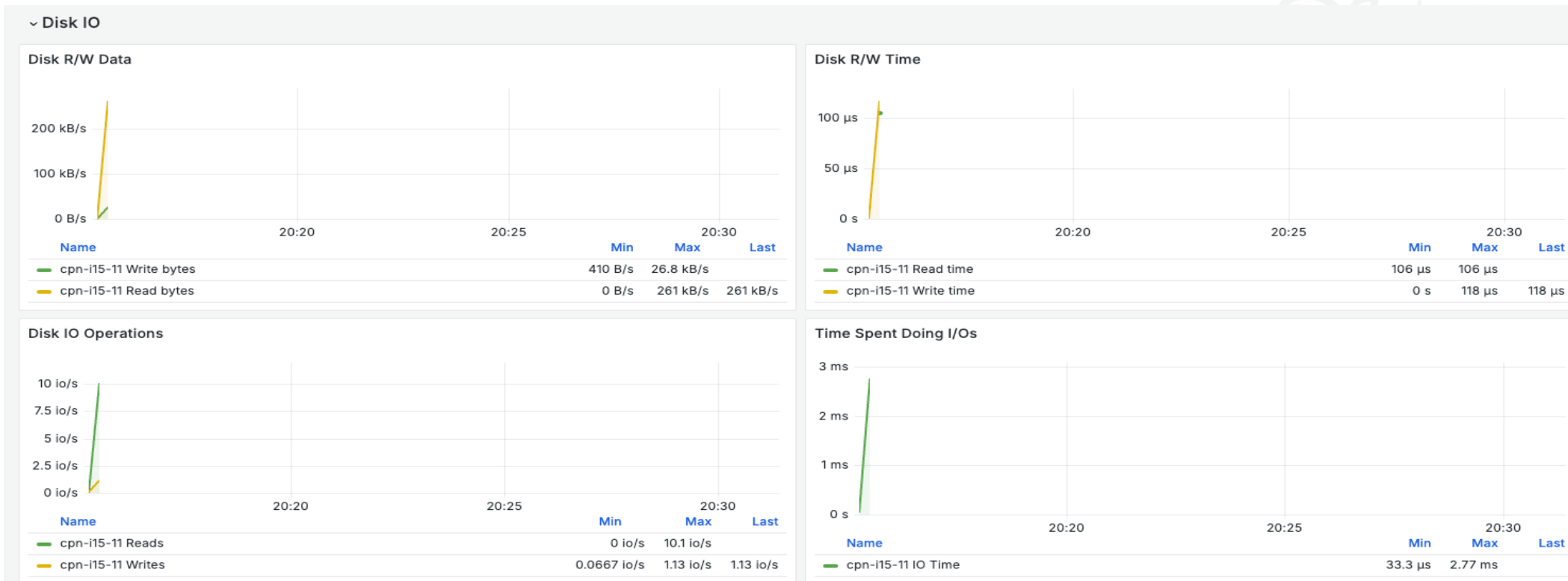
```
#!/bin/bash -l
#SBATCH --ntasks=2
#SBATCH --cpus-per-task=2
#SBATCH --time=00:10:00
#SBATCH --nodes=16
#SBATCH --mem=10000
#SBATCH --job-name=TrackFilter
#SBATCH --output=TrackFilter.out
#SBATCH --ntasks-per-node=32
#SBATCH --partition=general-compute
#SBATCH --qos=general-compute
#SBATCH --cluster=ub-hpc
#SBATCH --account=cse633
#SBATCH --mail-type=ALL
#SBATCH --mail-user=jeandedi@buffalo.edu
srun ./driver.exe
module load gcc
module load openmpi
module load gcc/11.2.0 openmpi/4.1.1
export OMP_NUM_THREADS=$SLURM_CPUS_PER_TASK
```



Nodes = 4, Total CPUs = 128



Nodes = 2, Total CPUs = 64



Slurm Job Runs Settings and Performance

```

jeandedi@login1:~$ sacct --jobs=15758151 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
AlBe2H8_1+  1      1      16    10:53:36  masashik  00:00:02  00:40:51  cpn-h22-06
batch      1      1      16    10:53:36  00:00:00  00:40:51  cpn-h22-06
extern     1      1      16    10:53:36  00:00:00  00:40:51  cpn-h22-06
vasp_std   16     1      16    10:52:32  00:40:34  00:40:47  cpn-h22-06
jeandedi@login1:~$ sacct --jobs=15758150 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
AlBe2H8_1+  1      1      16    11:39:44  masashik  00:00:02  00:43:44  cpn-h22-10
batch      1      1      16    11:39:44  00:00:00  00:43:44  cpn-h22-10
extern     1      1      16    11:39:44  00:00:00  00:43:44  cpn-h22-10
vasp_std   16     1      16    11:38:40  00:43:26  00:43:40  cpn-h22-10
jeandedi@login1:~$ sacct --jobs=15757817 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
download.+  1      1      8     00:00:08  kendrasc  00:00:00  00:00:01  cpn-h22-15
batch      1      1      8     00:00:08  00:00:00  00:00:01  cpn-h22-15
extern     1      1      8     00:00:08  00:00:00  00:00:01  cpn-h22-15
jeandedi@login1:~$ sacct --jobs=15768205 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      64    00:03:12  jeandedi  00:00:01  00:00:03  cpn-i15-11
batch      1      1      64    00:03:12  00:00:00  00:00:03  cpn-i15-11
extern     1      1      64    00:03:12  00:00:00  00:00:03  cpn-i15-11
driver.exe  2      1      64    00:00:00  00:00:00  00:00:00  cpn-i15-11
jeandedi@login1:~$ sacct --jobs=15768207 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      64    00:02:08  jeandedi  00:00:01  00:00:02  cpn-i15-11
batch      1      1      64    00:02:08  00:00:00  00:00:02  cpn-i15-11
extern     1      1      64    00:02:08  00:00:00  00:00:02  cpn-i15-11
driver.exe  2      1      64    00:00:00  00:00:00  00:00:00  cpn-i15-11
jeandedi@login1:~$ sacct --jobs=15770779 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      4     00:00:20  jeandedi  00:00:02  00:00:05  cpn-h22-15
batch      1      1      4     00:00:20  00:00:00  00:00:05  cpn-h22-15
extern     1      1      4     00:00:20  00:00:00  00:00:05  cpn-h22-15
driver.exe  2      1      4     00:00:00  00:00:00  00:00:00  cpn-h22-15
jeandedi@login1:~$ sacct --jobs=15770776 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      32    00:02:08  jeandedi  00:00:01  00:00:04  cpn-h22-33
batch      1      1      32    00:02:08  00:00:00  00:00:04  cpn-h22-33
extern     1      1      32    00:02:08  00:00:00  00:00:04  cpn-h22-33
driver.exe  16     1      32    00:00:32  00:00:00  00:00:01  cpn-h22-33
jeandedi@login1:~$ sacct --jobs=15768949 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      32    00:01:36  jeandedi  00:00:01  00:00:03  cpn-i15-11
batch      1      1      32    00:01:36  00:00:00  00:00:03  cpn-i15-11
extern     1      1      32    00:01:36  00:00:00  00:00:03  cpn-i15-11
driver.exe  16     1      32    00:00:32  00:00:00  00:00:01  cpn-i15-11

```

```

jeandedi@login1:~/Desktop/FinalProjectCodes$ sacct --jobs=15793688 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      32    00:03:12  jeandedi  00:00:01  00:00:06  cpn-i15-17
batch      1      1      32    00:03:12  00:00:00  00:00:06  cpn-i15-17
extern     1      1      32    00:03:12  00:00:00  00:00:06  cpn-i15-17
driver.exe  4      1      32    00:00:00  00:00:00  00:00:00  cpn-i15-17
jeandedi@login1:~/Desktop/FinalProjectCodes$ sacct --jobs=15793553 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      16    00:01:20  jeandedi  00:00:01  00:00:05  cpn-i15-21
batch      1      1      16    00:01:20  00:00:00  00:00:05  cpn-i15-21
extern     1      1      16    00:01:20  00:00:00  00:00:05  cpn-i15-21
driver.exe  2      1      16    00:00:00  00:00:00  00:00:00  cpn-i15-21
jeandedi@login1:~/Desktop/FinalProjectCodes$ sbatch trackFilter.sh
Submitted batch job 15793843 on cluster ub-hpc
jeandedi@login1:~/Desktop/FinalProjectCodes$ sacct --jobs=15793843 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      16    00:01:52  jeandedi  00:00:02  00:00:07  cpn-h22-15
batch      1      1      16    00:01:52  00:00:00  00:00:07  cpn-h22-15
extern     1      1      16    00:01:52  00:00:00  00:00:07  cpn-h22-15
driver.exe  4      1      16    00:00:16  00:00:00  00:00:01  cpn-h22-15
jeandedi@login1:~/Desktop/FinalProjectCodes$ sbatch trackFilter.sh
Submitted batch job 15793844 on cluster ub-hpc
jeandedi@login1:~/Desktop/FinalProjectCodes$ sacct --jobs=15793844 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,nodelist
JobName  NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+  1      1      64    00:00:00  jeandedi  00:00:00  00:00:00  None assigned
jeandedi@login1:~/Desktop/FinalProjectCodes$

```


Slurm Job Runs Settings and Performance

```

jeandedi@login1:~$ sacct --jobs=15768204 --format=jobname,ncpus,cputime,nnodes,ntasks,user,avecpu,elapsed,node,time
JobName      NCPUS  CPUTime  NNodes  NTasks  User      AveCPU  Elapsed  NodeList  TimeLimit
-----
TrackFilt+   32     00:01:36  1        1        jeandedi  00:00:03  00:00:03  cpn-i15-11  00:10:00
batch        32     00:01:36  1        1        00:00:01  00:00:03  cpn-i15-11
extern       32     00:01:36  1        1        00:00:00  00:00:03  cpn-i15-11
driver.exe   32     00:00:32  1        4        00:00:00  00:00:01  cpn-i15-11
jeandedi@login1:~$ sacct --jobs=15768204 --format=jobname,ncpus,cputime,nnodes,ntasks,user,avecpu,elapsed,node
JobName      NCPUS  CPUTime  NNodes  NTasks  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   32     00:01:36  1        1        jeandedi  00:00:03  00:00:03  cpn-i15-11
batch        32     00:01:36  1        1        00:00:01  00:00:03  cpn-i15-11
extern       32     00:01:36  1        1        00:00:00  00:00:03  cpn-i15-11
driver.exe   32     00:00:32  1        4        00:00:00  00:00:01  cpn-i15-11
jeandedi@login1:~$ sacct --jobs=15767188 --format=jobname,ncpus,cputime,nnodes,ntasks,user,avecpu,elapsed,node
JobName      NCPUS  CPUTime  NNodes  NTasks  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   64     00:02:08  2        2        jeandedi  00:00:02  00:00:02  cpn-i15-[11,13]
batch        32     00:01:04  1        1        00:00:01  00:00:02  cpn-i15-11
extern       64     00:02:08  2        2        00:00:00  00:00:02  cpn-i15-[11,13]
driver.exe   64     00:00:00  2        4        00:00:00  00:00:00  cpn-i15-[11,13]
jeandedi@login1:~$ sacct --jobs=15768204 --format=jobname,ncpus,cputime,nnodes,ntasks,user,avecpu,elapsed,node
JobName      NCPUS  CPUTime  NNodes  NTasks  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   32     00:01:36  1        1        jeandedi  00:00:03  00:00:03  cpn-i15-11
batch        32     00:01:36  1        1        00:00:01  00:00:03  cpn-i15-11
extern       32     00:01:36  1        1        00:00:00  00:00:03  cpn-i15-11
driver.exe   32     00:00:32  1        4        00:00:00  00:00:01  cpn-i15-11
jeandedi@login1:~$ sacct --jobs=15768451 --format=jobname,ncpus,cputime,nnodes,ntasks,user,avecpu,elapsed,node
JobName      NCPUS  CPUTime  NNodes  NTasks  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   32     00:01:36  2        2        jeandedi  00:00:03  00:00:03  cpn-i15-[05,07]
batch        16     00:00:48  1        1        00:00:01  00:00:03  cpn-i15-05
extern       32     00:01:36  2        2        00:00:00  00:00:03  cpn-i15-[05,07]
driver.exe   32     00:00:00  2        16       00:00:00  00:00:00  cpn-i15-[05,07]
jeandedi@login1:~$ sacct --jobs=15767182 --format=jobname,ncpus,cputime,nnodes,ntasks,user,avecpu,elapsed,node
JobName      NCPUS  CPUTime  NNodes  NTasks  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   128    00:12:48  4        4        jeandedi  00:00:06  00:00:06  cpn-q07-24,cpn+
batch        32     00:03:12  1        1        00:00:03  00:00:06  cpn-q07-24
extern       128    00:12:48  4        4        00:00:00  00:00:06  cpn-q07-24,cpn+
driver.exe   128    00:00:00  4        16       00:00:00  00:00:00  cpn-q07-24,cpn+
jeandedi@login1:~$ sacct --jobs=15767169 --format=jobname,ncpus,cputime,nnodes,ntasks,user,avecpu,elapsed,node
JobName      NCPUS  CPUTime  NNodes  NTasks  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   48     00:03:12  4        4        jeandedi  00:00:04  00:00:04  cpn-i14-35,cpn+
batch        12     00:00:48  1        1        00:00:01  00:00:04  cpn-i14-35
extern       48     00:03:12  4        4        00:00:00  00:00:04  cpn-i14-35,cpn+
driver.exe   48     00:00:00  4        6        00:00:00  00:00:00  cpn-i14-35,cpn+
  
```

```

jeandedi@login1:~$ sacct --jobs=15768205 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed
-----
TrackFilt+   1        1        64     00:03:12  jeandedi  00:00:01  00:00:03
batch        1        1        64     00:03:12  00:00:00  00:00:03
extern       1        1        64     00:03:12  00:00:00  00:00:03
driver.exe   2        1        64     00:00:00  00:00:00  00:00:00
jeandedi@login1:~$ sacct --jobs=15752043 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   2        2        16     00:01:20  jeandedi  00:00:05  00:00:05  cpn-i14-[33,35]
batch        1        1        8      00:00:40  00:00:03  00:00:05  cpn-i14-33
extern       2        2        16     00:01:20  00:00:00  00:00:05  cpn-i14-[33,35]
driver.exe   4        2        16     00:00:00  00:00:00  00:00:00  cpn-i14-[33,35]
jeandedi@login1:~$ sacct --jobs=15752044 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   1        1        4      00:00:20  jeandedi  00:00:05  00:00:05  cpn-i14-33
batch        1        1        4      00:00:20  00:00:03  00:00:05  cpn-i14-33
extern       1        1        4      00:00:20  00:00:00  00:00:05  cpn-i14-33
driver.exe   1        1        4      00:00:20  00:00:00  00:00:00  cpn-i14-33
jeandedi@login1:~$ sacct --jobs=15752046 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   2        2        16     00:01:20  jeandedi  00:00:05  00:00:05  cpn-i14-[33,35]
batch        1        1        8      00:00:40  00:00:03  00:00:05  cpn-i14-33
extern       2        2        16     00:01:20  00:00:00  00:00:05  cpn-i14-[33,35]
driver.exe   2        2        16     00:00:00  00:00:00  00:00:00  cpn-i14-[33,35]
jeandedi@login1:~$ sacct --jobs=15752047 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   2        2        8      00:00:40  jeandedi  00:00:05  00:00:05  cpn-i14-[33,35]
batch        1        1        4      00:00:20  00:00:03  00:00:05  cpn-i14-33
extern       2        2        8      00:00:40  00:00:00  00:00:05  cpn-i14-[33,35]
driver.exe   2        2        8      00:00:00  00:00:00  00:00:00  cpn-i14-[33,35]
jeandedi@login1:~$ sacct --jobs=15752049 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   2        2        24     00:02:24  jeandedi  00:00:06  00:00:06  cpn-i14-[33,35]
batch        1        1        12     00:01:12  00:00:03  00:00:06  cpn-i14-33
extern       2        2        24     00:02:24  00:00:00  00:00:06  cpn-i14-[33,35]
driver.exe   2        2        24     00:00:00  00:00:00  00:00:00  cpn-i14-[33,35]
jeandedi@login1:~$ sacct --jobs=15752049 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   2        2        24     00:02:24  jeandedi  00:00:06  00:00:06  cpn-i14-[33,35]
batch        1        1        12     00:01:12  00:00:03  00:00:06  cpn-i14-33
extern       2        2        24     00:02:24  00:00:00  00:00:06  cpn-i14-[33,35]
driver.exe   2        2        24     00:00:00  00:00:00  00:00:00  cpn-i14-[33,35]
jeandedi@login1:~$ sacct --jobs=15752052 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   2        2        128    00:08:32  jeandedi  00:00:04  00:00:04  cpn-i15-[07,23]
batch        1        1        64     00:04:16  00:00:03  00:00:04  cpn-i15-07
extern       2        2        128    00:08:32  00:00:00  00:00:04  cpn-i15-[07,23]
driver.exe   2        2        128    00:00:00  00:00:00  00:00:00  cpn-i15-[07,23]
jeandedi@login1:~$ sacct --jobs=15752060 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   1        1        64     00:05:20  jeandedi  00:00:05  00:00:05  cpn-i15-30
batch        1        1        64     00:05:20  00:00:03  00:00:05  cpn-i15-30
extern       8        1        64     00:00:00  00:00:00  00:00:00  cpn-i15-30
driver.exe   8        1        64     00:00:00  00:00:00  00:00:00  cpn-i15-30
jeandedi@login1:~$ sacct --jobs=15752061 --format=jobname,ntasks,nnodes,ncpus,cputime,user,avecpu,elapsed,node
JobName      NTasks  NNodes  NCPUS  CPUTime  User      AveCPU  Elapsed  NodeList
-----
TrackFilt+   1        1        64     00:05:20  jeandedi  00:00:05  00:00:05  cpn-i16-09
batch        1        1        64     00:05:20  00:00:03  00:00:05  cpn-i16-09
extern       1        1        64     00:05:20  00:00:00  00:00:05  cpn-i16-09
driver.exe   32       1        64     00:00:00  00:00:00  00:00:00  cpn-i16-09
  
```

Occurring Libraries Issues

```
jeandedi@login1:~$ module load gcc
jeandedi@login1:~$ module load openmpi
jeandedi@login1:~$ cd Desktop/
jeandedi@login1:~/Desktop$ cd FinalProjectCodes/
jeandedi@login1:~/Desktop/FinalProjectCodes$ ls -al
total 104
drwxr-xr-x 2 jeandedi jeandedi 4096 May 11 23:13 .
drwxr-xr-x 2 jeandedi jeandedi 4096 May 9 18:32 ..
-rwxrwxrwx 1 jeandedi jeandedi 14970 May 11 16:29 driver.cpp
-rwxrwxr-x 1 jeandedi jeandedi 88152 May 11 18:53 driver.exe
-rwxrwxrwx 1 jeandedi jeandedi 722 May 12 11:34 TrackFilter.out
-rwxrwxrwx 1 jeandedi jeandedi 578 May 12 00:40 trackFilter.sh
jeandedi@login1:~/Desktop/FinalProjectCodes$ g++ driver.cpp -o driver.exe -fopenmp -L/opt/openmpi/lib -lmpi -ldl -lm -Wl,--export-dynamic -lrt -lnsl -lutil -lm -ldl
jeandedi@login1:~/Desktop/FinalProjectCodes$ vi TrackFilter.out
jeandedi@login1:~/Desktop/FinalProjectCodes$ vi TrackFilter.out
```

```
/user/jeandedi/Desktop/FinalProjectCodes/./driver.exe: error while loading shared libraries: libmpi.so.40: cannot open shared object file: No such file or directory
/user/jeandedi/Desktop/FinalProjectCodes/./driver.exe: error while loading shared libraries: libmpi.so.40: cannot open shared object file: No such file or directory
srun: error: cpn-i15-11: task 0: Exited with exit code 127
srun: launch/slurm: _step_signal: Terminating StepId=15768151.0
srun: error: cpn-i15-37: task 1: Exited with exit code 127
The following modules were not unloaded:
  (Use "module --force purge" to unload all):
  1) ccrenv  2) gentoo/2023.01  3) ccrsoft/2023.01
Lmod is automatically replacing "gcc/11.2.0" with "intel/2022.00".
```


Conclusion

- ❖ A third order track filter for position, velocity and acceleration of a maneuvering target was implemented using C++; However, I could not plot the results due to C++ plotting limitations.
- ❖ The C++ Third Order Track Filter debugged using a GCC and openmpi compilers libraries
- ❖ An MPI adaption of the C++ Third Order Track Filter was implemented
- ❖ The C++ Third Order Track Filter was submitted to slurm using a batch script to test run timing performance using a variety of CCR cluster nodes, cpu per task and other ub-hpc setup resources configurations.
- ❖ Due to some Lockheed Martin PI reference materials, the associated MATLAB filter algorithm design with not be shared but can be demonstrated via a video reference to only U.S citizens, and cannot be shared in a personal email.
- ❖ Note that the variance estimation & smoothing algorithm was not implemented and simulated using C++ as well at this time
- ❖ Also, the gain calculations algorithm was not implemented and simulated using a C++ code as well at this time
- ❖ In the future, I would like to investigate more and simulate the optimal gain, variance estimation & smoothing algorithm to have a more robust tracking system

References

- ❖ Lockheed Martin RMS Employee Top Gun Track and Advanced Track Filtering Internal Courses: Unable to disclose the referenced resources due to unpublished Lockheed Martin Proprietary Information Contained
- ❖ Tracking Multiple Moving Objects Using Unscented Kalman Filtering Techniques by Xi Chen, Xiao Wang and Jianhua Xuan Bradley
- ❖ UB CCR Documentations and high- performance computing resources
- ❖ Extensive Google Research while debugging the C++ code and other associated issues.