

Solving System of Linear Equations

CSE 633 Course Project (Spring 2014)

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Equation Form

$$\begin{array}{cccc} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 & & & \\ \vdots & \vdots & \vdots & \vdots \\ a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n = b_i & & & \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n = b_n & & & \end{array}$$

$$Ax = b$$

where $A \in \mathbb{R}^{n \times n}$ is an $n \times n$ matrix of real numbers, $b \in \mathbb{R}^n$ is a vector of size n , and $x \in \mathbb{R}^n$ is an unknown solution vector of size n .

Solution exists only when there exists a matrix A^{-1} such that $A \cdot A^{-1} = I$

Methods of Implementation

- Direct Method – *Gaussian Elimination*
Exact solution except rounding errors
- Iterative Method – *Jacobi Method*
Determination of an approximate solution
than exact one

Gaussian Elimination

Gaussian Elimination

- Forward Elimination and Backward Substitution
- Upper Triangular form

$$A^{(k)} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1,k-1} & a_{1k} & \cdots & a_{1n} \\ 0 & a_{22}^{(2)} & \cdots & a_{2,k-1}^{(2)} & a_{2k}^{(2)} & \cdots & a_{2n}^{(2)} \\ \vdots & \ddots & \ddots & \vdots & \vdots & & \vdots \\ \vdots & & \ddots & a_{k-1,k-1}^{(k-1)} & a_{k-1,k}^{(k-1)} & \cdots & a_{k-1,n}^{(k-1)} \\ \vdots & & & 0 & a_{kk}^{(k)} & \cdots & a_{kn}^{(k)} \\ \vdots & & & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & \cdots & 0 & a_{nk}^{(k)} & \cdots & a_{nn}^{(k)} \end{bmatrix} .$$

Parallel Implementation Details

- Block distribution
 - Processor with rank 0 scatters data
 - n rows, p processors – each processor has n/p rows
- Forward elimination
 - For first processor,
 - For first row
 - Make pivot element 1 by doing row operations
 - For lower ranked rows in the same processor, make the corresponding elements 0 by row operations
 - Do this for other rows one by one
 - Send the data to other processors ranked higher
 - Do this for other processors (from low to high) one by one
- Backward substitution
 - The matrix is now in upper triangular form (i.e all the elements before pivot element in each row are zero and pivot element is 1)
 - From last to first processor,
 - For last to first row
 - For higher ranked rows in same processor, make the elements in the same column 0 by doing row operations
 - Do this for other rows from bottom to top
 - Send the data to other processors ranked lower
 - Do this for other processors (from high to low) one by one
- Processor with rank 0 gathers the data from all other processors which is the output vector

Parallel Implementation using Example

$$\begin{bmatrix} 2 & 2 & 4 & 2 \\ 2 & 3 & 3 & 2 \\ 1 & 2 & 3 & 3 \\ 1 & 2 & 3 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2 \\ 6 \\ 3 \\ 2 \end{bmatrix}$$

$$Ax = b$$

Demonstrated in class

Jacobi Method

Jacobi Method

Given a square system of n linear equations:

$$A\mathbf{x} = \mathbf{b}$$

where:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

Then A can be decomposed into a diagonal component D , and the remainder R :

$$A = D + R \quad \text{where} \quad D = \begin{bmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} \end{bmatrix} \quad \text{and} \quad R = \begin{bmatrix} 0 & a_{12} & \cdots & a_{1n} \\ a_{21} & 0 & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & 0 \end{bmatrix}.$$

The solution is then obtained iteratively via

$$\mathbf{x}^{(k+1)} = D^{-1}(\mathbf{b} - R\mathbf{x}^{(k)}).$$

The element-based formula is thus:

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left(b_i - \sum_{j \neq i} a_{ij} x_j^{(k)} \right), \quad i = 1, 2, \dots, n.$$


Calculating X

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left(b_i - \sum_{j \neq i} a_{ij} x_j^{(k)} \right), \quad i = 1, 2, \dots, n.$$

$$\begin{aligned} x_1 &= \frac{1}{a_{11}} (b_1 - a_{12}x_2 - a_{13}x_3 - \dots - a_{1n}x_n) \\ x_2 &= \frac{1}{a_{22}} (b_2 - a_{21}x_1 - a_{23}x_3 - \dots - a_{2n}x_n) \\ &\vdots \end{aligned}$$

 P_0

$$x_n = \frac{1}{a_{nn}} (b_n - a_{n1}x_1 - a_{n2}x_2 - \dots - a_{n,n-1}x_{n-1})$$

 P_{k-1}

Distribution at each Process

$$A = \left(\begin{array}{|c|} \hline \begin{array}{cccccc} a_{11} & a_{12} & a_{13} & \cdots & a_{1n-1} & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n-1} & a_{2n} \end{array} \\ \hline \begin{array}{|c|} \hline \begin{array}{cccccc} a_{31} & a_{32} & a_{33} & \cdots & a_{3n-1} & a_{3n} \end{array} \\ \hline \begin{array}{c} \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{array} \\ \hline \begin{array}{|c|} \hline \begin{array}{cccccc} a_{n-11} & a_{n-12} & a_{n-13} & \cdots & a_{n-1n-1} & a_{n-1n} \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn-1} & a_{nn} \end{array} \\ \hline \end{array} \right) \begin{array}{l} \Rightarrow P_0 \\ \Rightarrow P_1 \\ \Rightarrow P_{k-1} \end{array}$$

$$\mathbf{b} = \left(\begin{array}{|c|} \hline \begin{array}{c} b_1 \\ b_2 \\ \vdots \\ b_n \end{array} \\ \hline \end{array} \right) \begin{array}{l} \Rightarrow P_0 \\ \Rightarrow P_{k-1} \end{array} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

Algorithm

```
Choose an initial  $X^{\text{new}} = b$ .
int iteration = 0;
int k = num of rows per process;
do {
     $X^{\text{old}} = X^{\text{new}}$ ;
    for i=1...k, do
         $\sigma = 0$ ;
        for j=1...n, do
            if (i != j), then
                 $\sigma = \sigma + a_{ij}x_j^{\text{old}}$ ;
            end-if.
        end-for.
         $x_i^{\text{new}} = (b_i - \sigma)/a_{ii}$ ;
    end-for.
    MPI_Allgather( $X^{\text{new}}$ );
    iteration++;
} while ((!converged) && (iteration < MAX_ITERATIONS));
```

Input

- A = Diagonally dominant square matrix

```
//      Generating random Diagonally Dominant matrix A  //
for (irow = 0; irow < n; irow++) {
    A[irow] = (double *) malloc(n*sizeof(double));
    for (jcol = 0; jcol < n; jcol++) {
        if (irow == jcol) {
            A[irow][jcol] = (((double) rand())/((double) (RAND_MAX))) * (MAX_LIMIT * cols);
        } else {
            A[irow][jcol] = (((double) rand())/((double) (RAND_MAX)));
        }
    }
}
```

MPI Functions Used

```
// Broadcast the number of rows and columns from root //
```

```
MPI_Bcast( &rows, 1, MPI_INT, ROOT, MPI_COMM_WORLD);  
MPI_Bcast( &cols, 1, MPI_INT, ROOT, MPI_COMM_WORLD);
```

```
/* Scatter the input data from 1-D array to all the processes....  
 * Each Process captures its share of the data  
 *  
 */
```

```
MPI_Scatter(arrayA, rows_process*n, MPI_DOUBLE,  
           ARecv, rows_process*n, MPI_DOUBLE,  
           ROOT, MPI_COMM_WORLD);
```

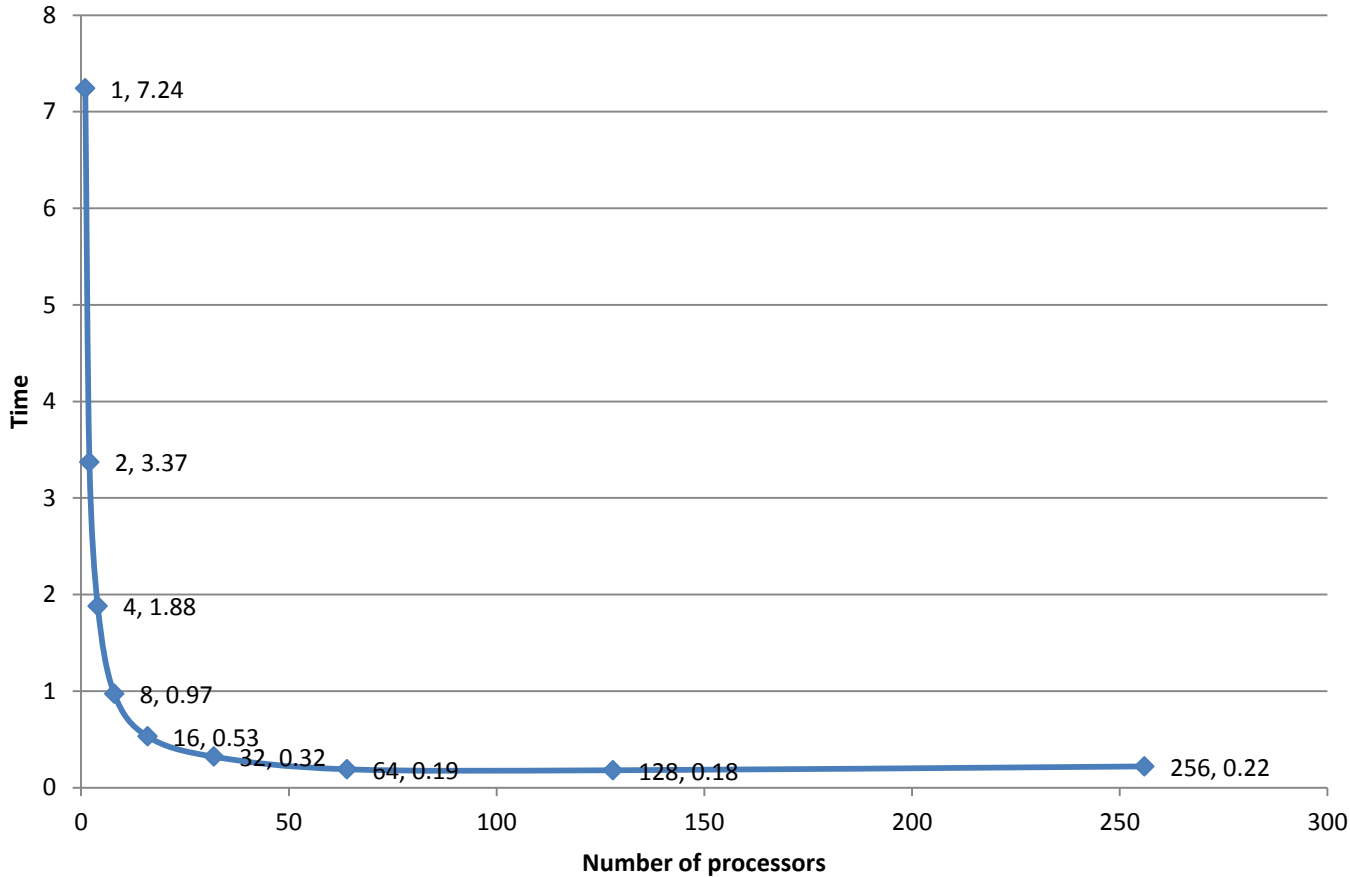
```
MPI_Scatter(B, rows_process, MPI_DOUBLE,  
           BRecv, rows_process, MPI_DOUBLE,  
           ROOT, MPI_COMM_WORLD);
```

```
// Collecting all the values of x from 1...n into X_new //
```

```
MPI_Allgather(process_X, rows_process, MPI_DOUBLE,  
             X_new, rows_process, MPI_DOUBLE,  
             MPI_COMM_WORLD);
```

Results – Gaussian Elimination

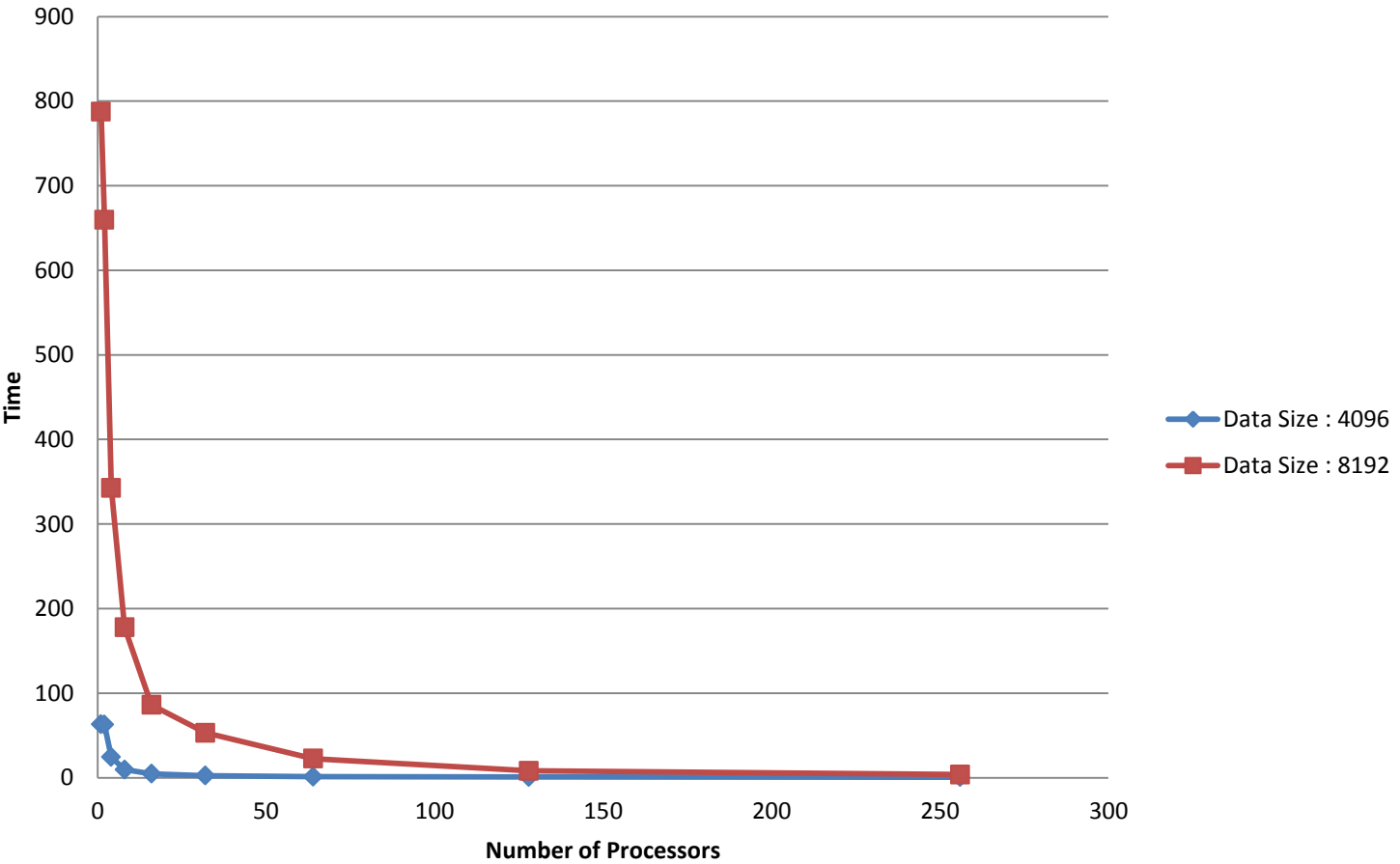
Time vs Number of processors (Data Size 2048)



#processors	time taken
1	7.24
2	3.37
4	1.88
8	0.97
16	0.53
32	0.32
64	0.19
128	0.18
256	0.22

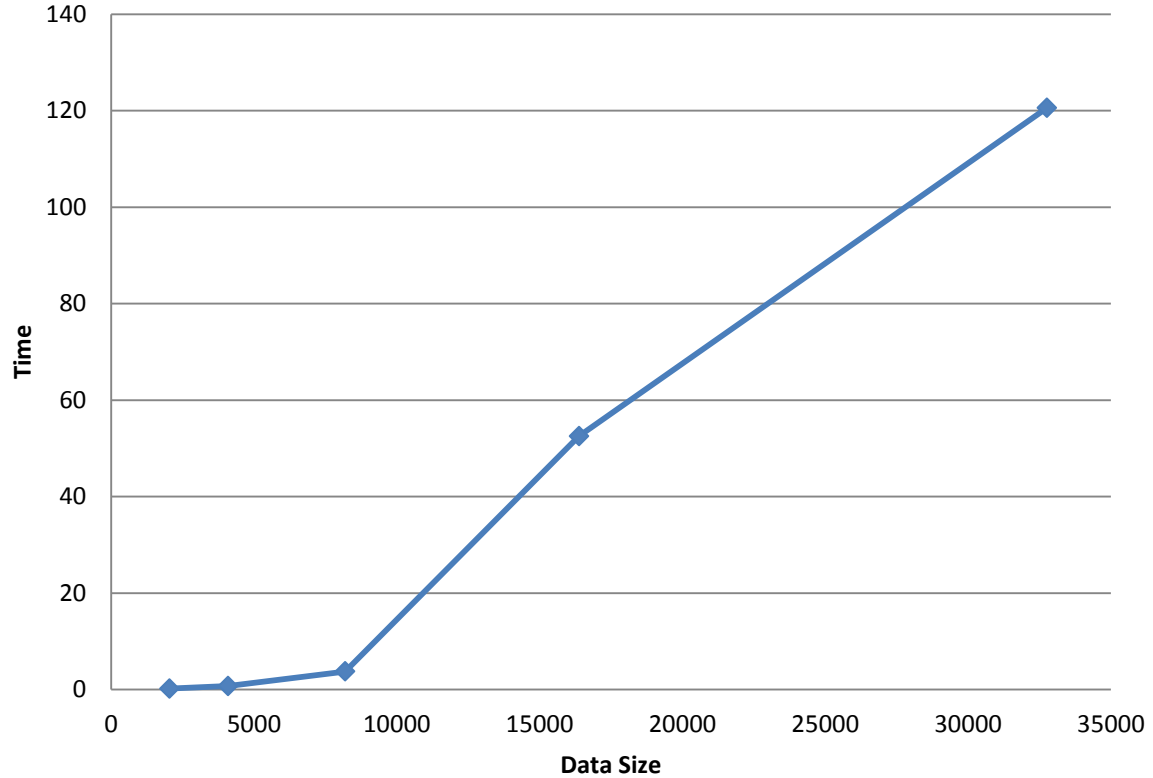
Results – Gaussian Elimination

Time vs Number of Processors



Results – Gaussian Elimination

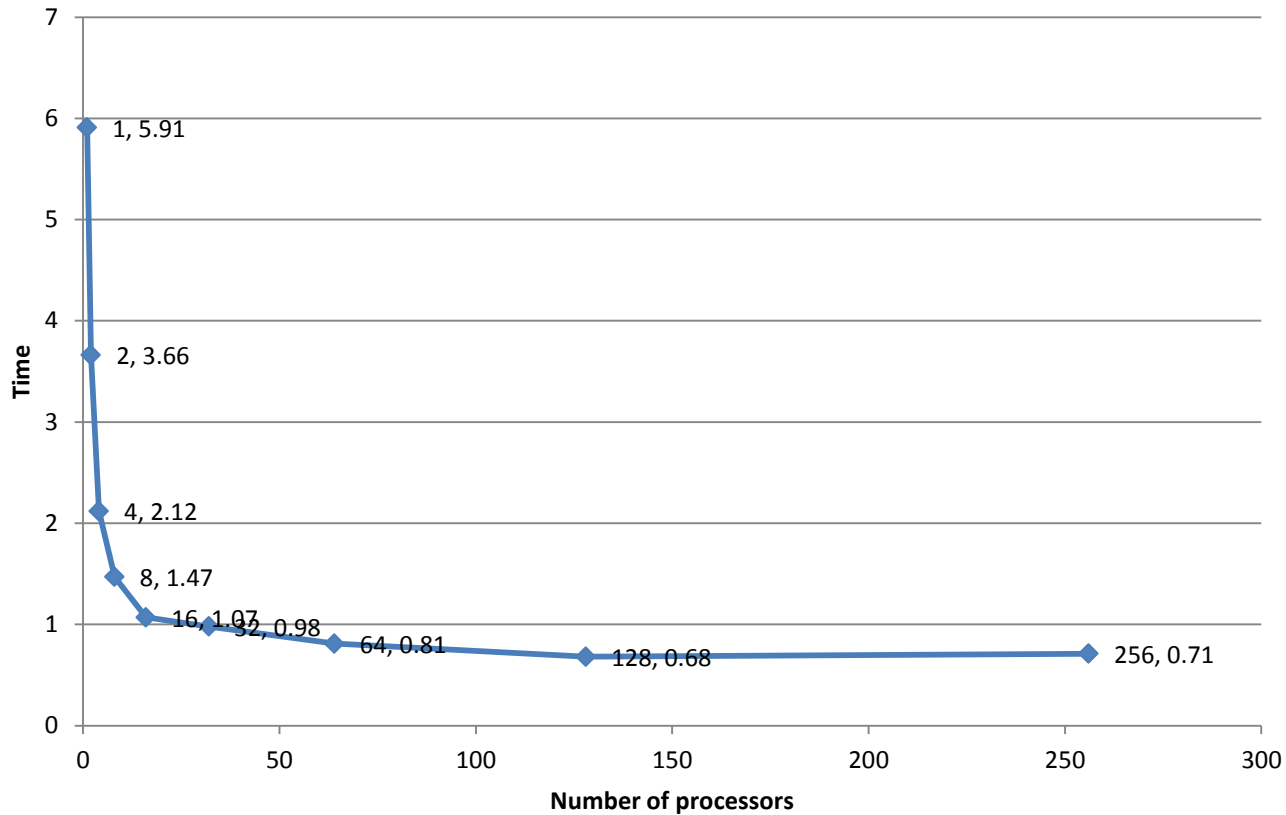
Time vs Data Size (256 Processors)



Data size (Number of Row)	Time Taken
2048	0.22
4096	0.73
8192	3.76
16384	52.53
32768	120.6

Results – Jacobi Method

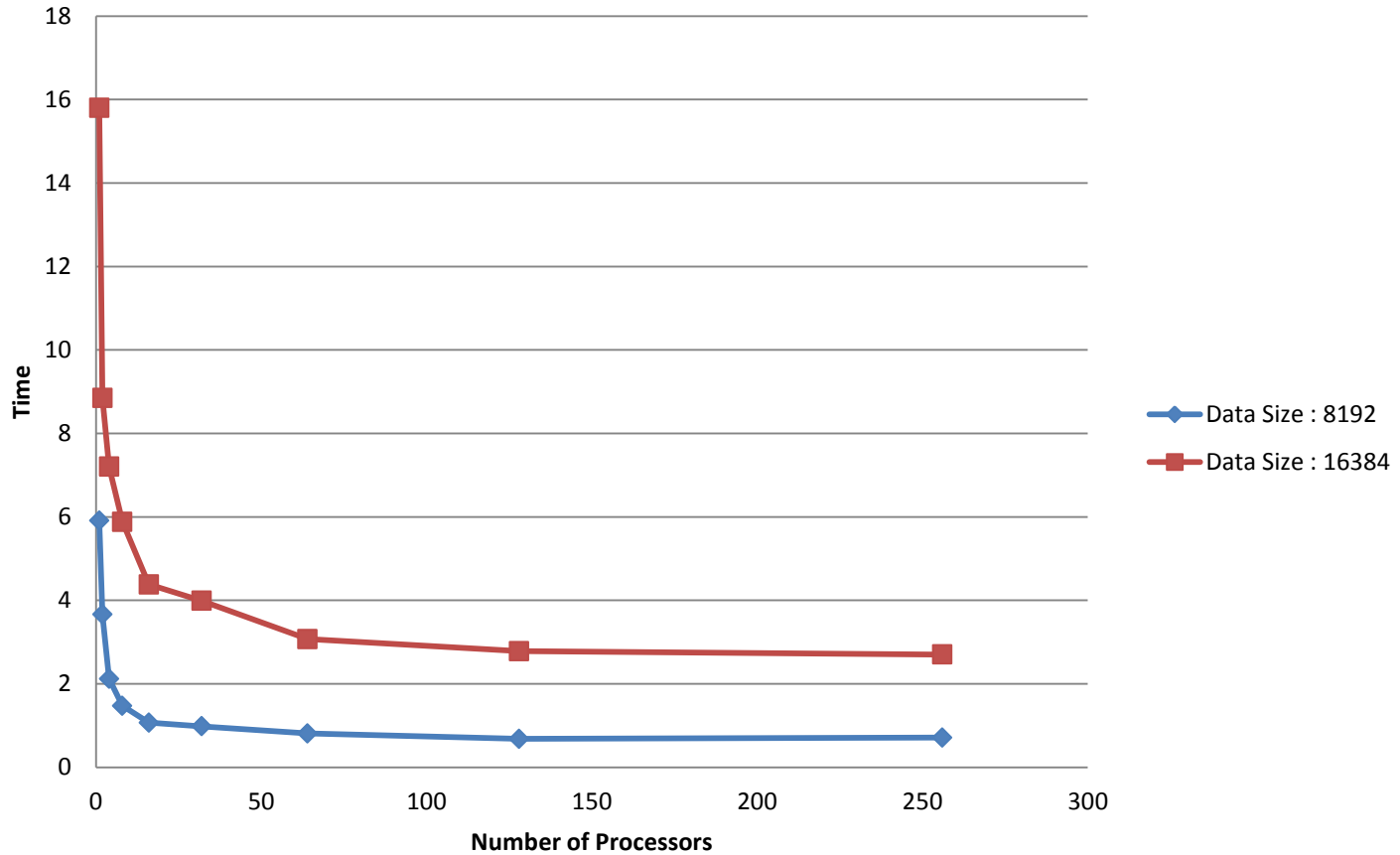
Time vs Number of Processors (Data Size 8192 Rows)



Number of Processors	Time
1	5.91
2	3.66
4	2.12
8	1.47
16	1.07
32	0.98
64	0.81
128	0.68
256	0.71

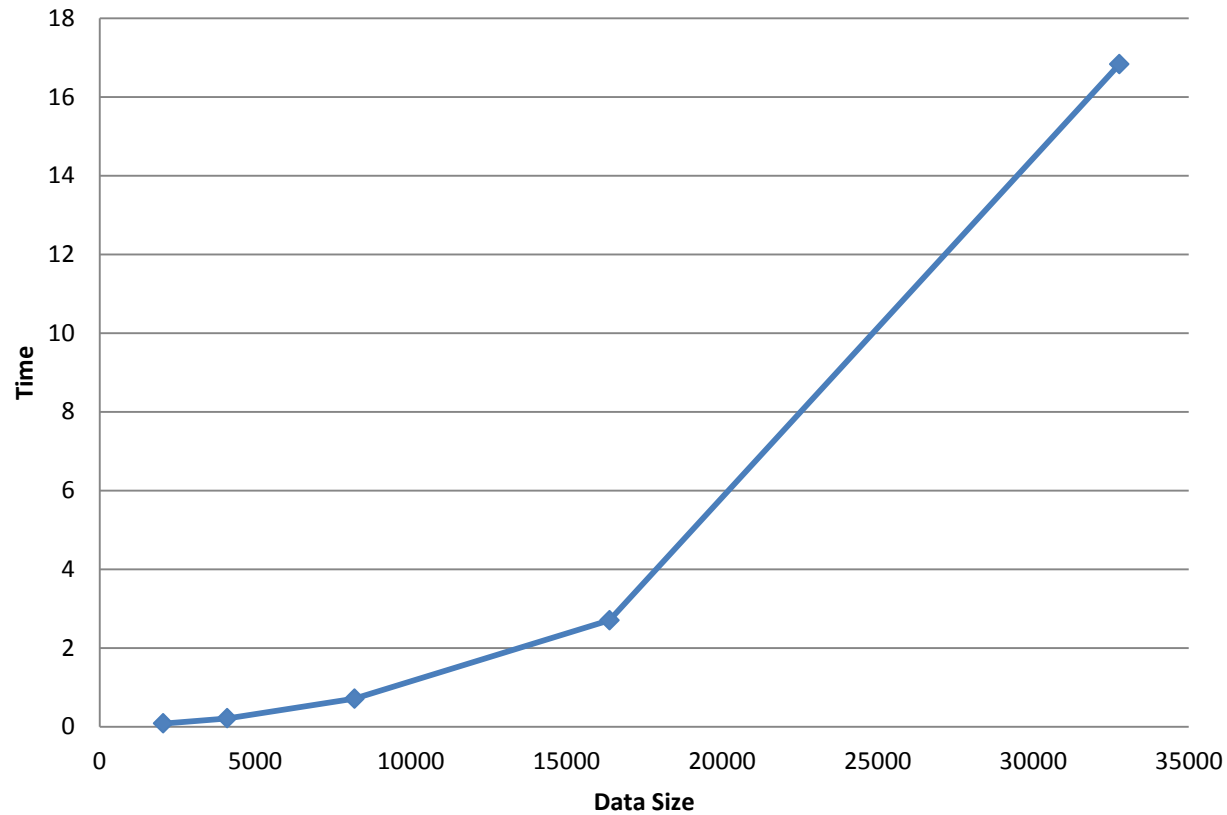
Results – Jacobi Method

Time vs Number of Processors



Results – Jacobi Method

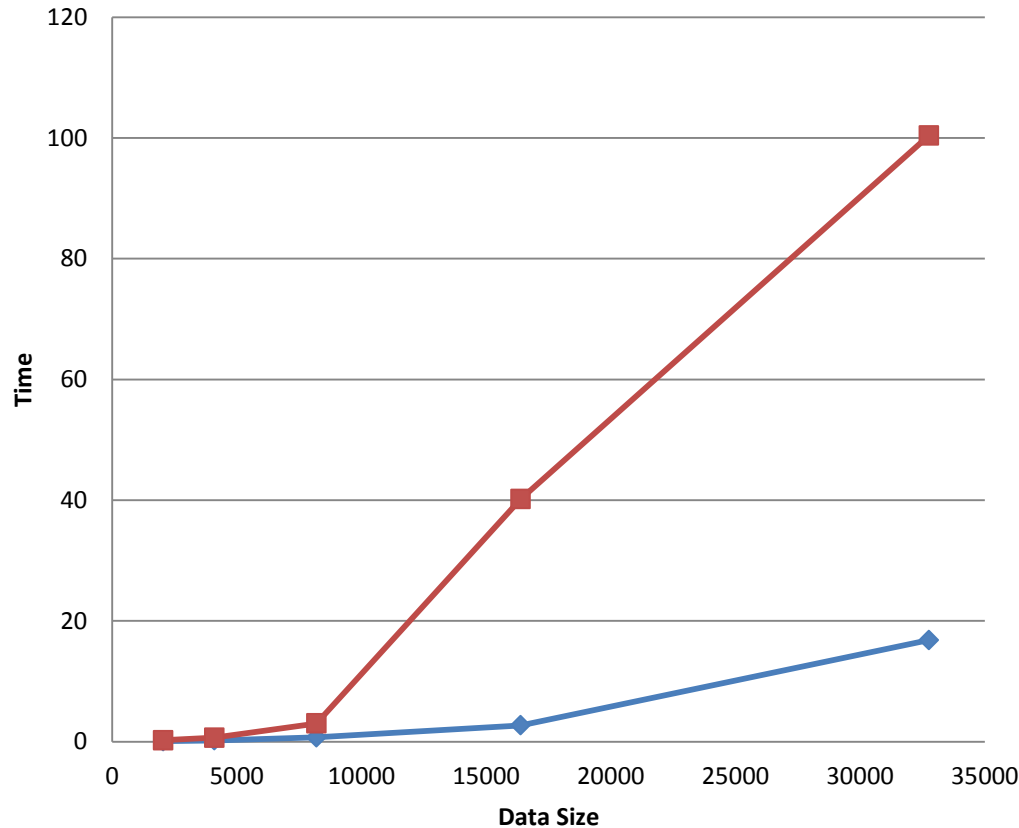
Time vs Data Size (Number of Processors 256)



Data Size	Time
2048	0.08
4096	0.21
8192	0.71
16384	2.7
32768	16.83

Results – Gaussian vs. Jacobi

Gaussian vs Jacobi (Number of Processors 256)



Data Size	Jacobi	Gaussian
2048	0.08	0.23
4096	0.21	0.65
8192	0.71	3
16384	2.7	40.18
32768	16.83	100.4

—◆— jacobi
—■— gaussian

Comparison between both methods for diagonally dominant data

Future Work

- Using Relaxation methods for Jacobi Method

$$x_i^{(k+1)} = \frac{\omega}{a_{ii}} \left(b_i - \sum_{j=1, j \neq i}^n a_{ij} x_j^{(k)} \right) + (1 - \omega) x_i^{(k)}, \quad i = 1, \dots, n .$$

- Gauss – Seidel for large sparse matrices
- Use cyclic distribution in Gaussian Elimination

References

- [Parallel Programming for Multicore and Cluster Systems](#) (Thomas Rauber and Gudula Runger)
- [Iterative Methods for Sparse Linear Systems, Second Edition](#) (Yousef Saad)
- Message Passing Interface (MPI) forum <http://www.mpi-forum.org>
- MPI Tutorial <http://mpitutorial.com/>

Thank You