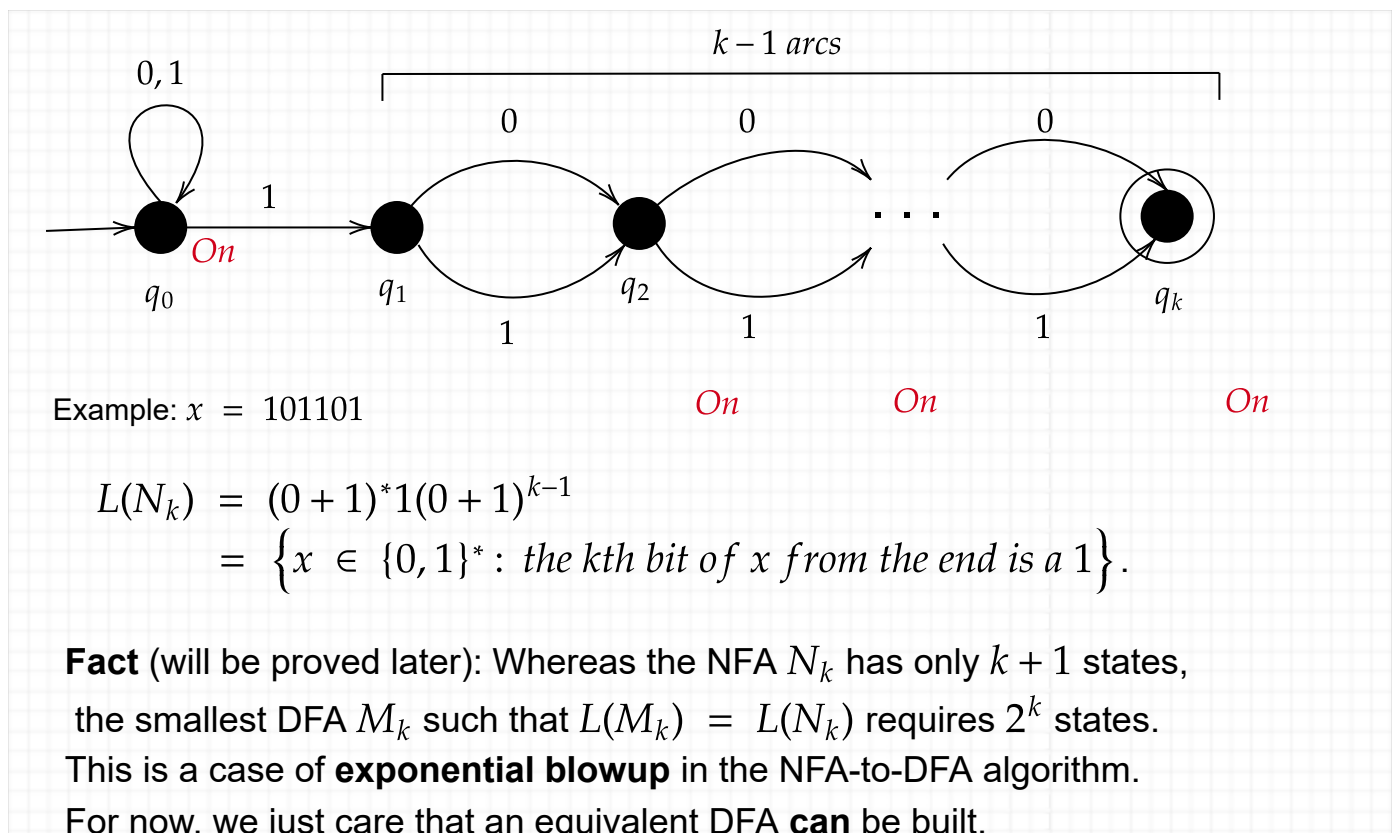


## The Main Theorem About Regular Expressions and Finite Automata

**Theorem:** For any language  $A$  over an alphabet  $\Sigma$ , the following statements are equivalent:

1. There is a regular expression  $\alpha$  such that  $A = L(\alpha)$ .
2. There is an NFA  $N$  such that  $A = L(N)$ .
3. There is a DFA  $M$  such that  $A = L(M)$ .

Example (moved up from last time): The "Leap of Faith" NFAs  $N_k$  for any  $k > 1$ :



## From NFA to DFA

**Theorem** (part two of Kleene's Theorem): Given any NFA  $N = (Q, \Sigma, \delta, s, F)$  we can build a DFA  $M = (Q, \Sigma, \Delta, S, \mathcal{F})$  such that  $L(M) = L(N)$ .

Notice that  $s$  got capitalized to  $S$ , which hints that  $S$  is a *set* rather than a single element. And  $\delta$  got capitalized to  $\Delta$ .  $Q$  and  $F$  were already sets, but they got...curlier. What does that mean? Well, that they are "of an even higher order"---sets of sets, for instance. An important set of sets is:

$\mathcal{P}(Q)$ , also written  $2^Q$ , called the *power set* of  $Q$  and defined as  $\{R : R \subseteq Q\}$ .

Unlike what textbooks tend to say, we will not necessarily make  $Q$  be all of  $\mathcal{P}(Q)$ , just those subsets  $R$  that are *reachable* from  $S$ . What this means is that the states of the DFA will be sets of states of the NFA---the states that are *possible* upon *processing* a given part of the input string  $x$ .

This suggests the question, which states (of  $N$ ) are possible before we process any chars in  $x$ ? Obviously the start state  $s$  of  $N$  is possible, but are there any others? Yes, if there are  $\epsilon$ -transitions out of  $s$ . Define  $E(s)$  to be the set of states of  $N$  that are reachable this way. If  $N$  has no  $\epsilon$ -arcs (out of  $s$  or overall), then  $E(s)$  is just  $\{s\}$ . Thus we begin building  $M$  by taking  $S = E(s)$ . We could have said " $S$ " in place of " $E(s)$ " to begin with, but the notation is useful to define

$$E(R) = \{r : \text{for some } q \in R, N \text{ can process } \epsilon \text{ from } q \text{ to } r\}$$

for any subset  $R$  of states. This is called the *epsilon-closure* of  $R$ . If  $E(R) = R$  then  $R$  is already *epsilon-closed*. It sounds "weeny" technical, but we will only need to use subsets that are  $\epsilon$ -closed. The insight is that *the states of the DFA are the possible subsets of states of the NFA*.

To make the DFA equivalent to the NFA, at least in terms of the language it accepts, we need to build on the correspondence we started with  $s$  and  $S$ . Let  $x \in \Sigma^*$  be some input of length  $n$ . For  $i = 0, 1, \dots, n-1, n$  the design goal  $G(i)$  for  $M$  is to arrange that:

$$M \text{ upon reading } x_1x_2 \cdots x_i \text{ is in the state } R_i = \{r : N \text{ can process } x_1x_2 \cdots x_i \text{ from } s \text{ to } r\}.$$

Now when  $i = 0$ , the initial portion  $x_1x_2 \cdots x_i$  is  $\epsilon$  (more "Zen" reasoning), so  $R_0$  turns out to be just another name for  $E(s)$ . By setting  $S = E(s)$ , what we've done is achieve the property  $G(0)$ . We can now use this as the basis for an induction  $G(i-1) \implies G(i)$  which we build  $\Delta$  to achieve. This will give us the final property  $G(n)$ , which states:

$$M \text{ upon reading all of } x \text{ is in the state } R_n = \{r : N \text{ can process } x \text{ from } s \text{ to } r\}.$$

Now  $N$  accepts  $x$  if and only if  $R_n$  includes at least one accepting state  $f \in F$ , i.e.,  $R_n \cap F \neq \emptyset$ . Thus when we regard a possible subset  $R$  as a state of  $M$ , we should call it accepting if and only if  $R \cap F \neq \emptyset$ . Thus the property  $G(n)$  will imply  $x \in L(M) \iff x \in L(N)$ , and getting this for all  $n$  and  $x$  of length  $n$  will yield the conclusion  $L(M) = L(N)$ . So thus far we have defined:

- $Q = \{\text{possible } R \subseteq Q\}$ ;
- $S = E(s)$ ;
- $\mathcal{F} = \{R \in Q : R \cap F \neq \emptyset\}$ .

And  $\Sigma$  is the same. The only component of  $M$  left to define is  $\Delta$ . For any  $P \in Q$  and  $c \in \Sigma$  define

$$\Delta(P, c) = \{r : \text{for some } p \in P, N \text{ can process } c \text{ from } p \text{ to } r\}.$$

This set is automatically  $\epsilon$ -closed, since  $c \cdot \epsilon^* = c$  so any trailing  $\epsilon$ -arcs can count as part of processing  $c$ . If we assume  $G(i-1)$  as our induction hypothesis, take the set  $R_{i-1}$  which the property  $G(i-1)$  refers to, and define  $R_i = \Delta(R_{i-1}, x_i)$ , then we only need to show that  $R_i$  has the property required for the conclusion  $G(i)$ . This is that  $R_i$  equals the set of states that  $N$  can process the bits  $x_1 \cdots x_i$  to. The core of the proof is finally to observe that:

$N$  can process  $x_1x_2 \cdots x_{i-1}x_i$  from  $s$  to  $r$  if and only if there is a state  $p$  such that  $N$  can process  $x_1x_2 \cdots x_{i-1}$  from  $s$  to  $p$  (which by IH  $G(i-1)$  includes  $p$  into  $R_{i-1}$ ) and such that  $N$  can process the char  $x_i$  from  $p$  to  $r$ .

How does this finish the proof? Let's see... We can make a small change to the definition of  $\Delta(P, c)$  that makes it quicker and less error-prone to calculate  $M$  from  $N$ , by a process that examples will view as an instance of *breadth-first search*.

### Example

We make a slight change to the heart of the proof where we left off. The change saves some time in executing the NFA-to-DFA construction when  $\epsilon$ -arcs are present and reduces errors. First define

$$\underline{\delta}(p, c) = E(\{q : (p, c, q) \in \delta\})$$

for any state  $p \in Q$  and char  $c$ . Recall  $E(\cdot)$  is  $\epsilon$ -closure. So what this means in simple terms is:

1. **First** take arc(s) on  $c$  out of the state  $p$ .
  - If there are none, **stop** and put  $\underline{\delta}(p, c) = \emptyset$ .
  - Else collect all states  $q$  reached on those arc(s).
2. **Then**, for each state  $q$  reached by processing  $c$ , add states reached on any series of  $\epsilon$ -arcs out of  $q$ , if there are any.

Now we can give a new definition of the DFA's transition function  $\Delta$ : for any  $P \subseteq Q$  and  $c \in \Sigma$ ,

$$\Delta(P, c) = \bigcup_{p \in P} \underline{\delta}(p, c).$$

The difference is that we avoid worrying about initial  $\epsilon$ -arcs that could come before processing  $c$ . We only have to track *trailing* ones in a machine diagram. The reason is that the trailing arcs at the previous step already took care of any initial ones now. Initializing the start state  $S$  of the DFA  $M$  to have all states reached by  $\epsilon$ -arcs out of  $s$  in  $N$  sets this in motion. We need to prove for all  $i$ :

$$G(i) : \Delta^*(S, x_1 \cdots x_i) = \{r : N \text{ can process } x_1 \cdots x_i \text{ from } s \text{ to } r\}.$$

Here we have *extended*  $\Delta$ , a function of a state and a char, to  $\Delta^*$  which is a function of a state and a *string*, by the basis  $\Delta^*(R, \epsilon) = R$  for all  $R \in Q$  and for  $i \geq 1$ ,

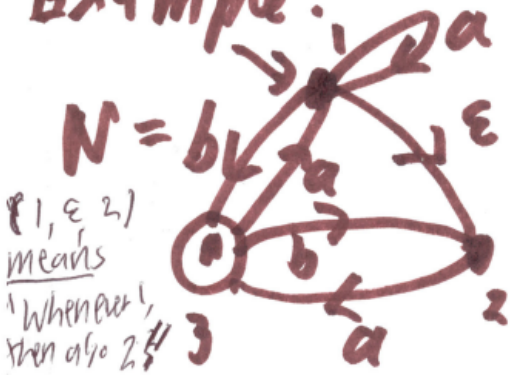
$$\Delta^*(R, x_1 \cdots x_{i-1}x_i) = \Delta(\Delta^*(R, x_1 \cdots x_{i-1}), x_i).$$

So let  $R_{i-1}$  stand for  $\Delta^*(S, x_1 \cdots x_{i-1})$ . Then by the inductive hypothesis  $G(i-1)$ ,  $R_{i-1}$  equals the set of states  $q$  such that  $N$  can process  $x_1 \cdots x_{i-1}$  from  $s$  to  $q$ . Now put  $R_i = \Delta(R_{i-1}, x_i)$ .

- Let  $r \in R_i$ . Then  $r \in \underline{\delta}(q, x_i)$  for some  $q \in R_{i-1}$ . By IH  $G(i-1)$ ,  $N$  can process  $x_1 \cdots x_{i-1}$  from  $s$  to  $q$ . And  $N$  can process  $x_i$  from  $q$  to  $r$  by definition of  $r \in \underline{\delta}(q, x_i)$ . So  $N$  can process  $x_1 \cdots x_i$  from  $s$  to  $r$ .
- Suppose  $N$  can process  $x_1 \cdots x_i$  from  $s$  to  $r$ . Then---and this is the key point---the processing goes to some state  $q$  just before the char  $x_i$  is processed. By IH  $G(i-1)$ ,  $q$  belongs to  $R_{i-1}$ . Moreover,  $r \in \underline{\delta}(q, x_i)$  because we first do the step that processed the char  $x_i$  at  $q$ , then any trailing  $\epsilon$ -arcs. Thus  $r \in \Delta(R_{i-1}, x_i)$ , which means  $r \in R_i$ .

Thus we have established that  $R_i$  equals the set of states  $r$  such that  $N$  can process  $x_1 \cdots x_i$  from  $s$  to  $r$ . This is the statement  $G(i)$ , which is what we had to prove to make the induction go through. This finally proves the NFA-to-DFA part of Kleene's Theorem.  $\square$

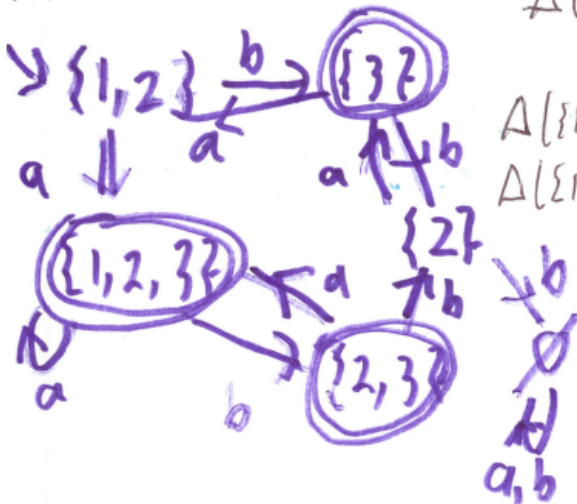
Example:



$\{1, \epsilon, 2\}$   
means  
'Whenever',  
then also 2, 3

$S = \{1, 2\}$ , not  $\{1\}$

The DFA cannot have the states  $\{1\}$  or  $\{1, 3\}$  because they have 1 but not 2.



In lecture I pointed out:

... a to any one

$\delta(p, c) = \text{find } c \text{ then } \epsilon$ . (2)

$$\delta(1, a) = \{1, 2\} \quad \delta(1, b) = \{3\}$$

$$\delta(2, a) = \{3\} \quad \delta(2, b) = \emptyset$$

$$\delta(3, a) = \{1, 2\} \quad \delta(3, b) = \{2\}$$

$$\Delta(P, c) = \bigcup_{p \in P} \delta(p, c)$$

Use Breadth First Search from  $S$ .

$$\Delta(S, a) = \delta(1, a) \cup \delta(2, a) = \{1, 2\} \cup \{3\} = \{1, 2, 3\}$$

$$\Delta(S, b) = \delta(1, b) \cup \delta(2, b) = \{3\} \cup \emptyset = \{3\}$$

$$\Delta(\{1, 2, 3\}, a) = \delta(1, a) \cup \delta(2, a) \cup \delta(3, a) = \{1, 2\} \cup \{3\} \cup \{1, 2, 3\} = \{1, 2, 3\}$$

$$\Delta(\{1, 2, 3\}, b) = \delta(1, b) \cup \delta(2, b) \cup \delta(3, b) = \{3\} \cup \emptyset \cup \{2\} = \{2, 3\}$$

$$\Delta(\{2, 3\}, a) = \delta(2, a) \cup \delta(3, a) = \{3\} \cup \{1, 2, 3\} = \{1, 2, 3\}$$

$$\Delta(\{2, 3\}, b) = \delta(2, b) \cup \delta(3, b) = \emptyset \cup \{2\} = \{2\}$$

$$\Delta(\{1, 2, 3\}, a) = \delta(1, a) \cup \delta(2, a) \cup \delta(3, a) = \{1, 2\} \cup \{3\} \cup \{1, 2, 3\} = \{1, 2, 3\}$$

$$\Delta(\{1, 2, 3\}, b) = \delta(1, b) \cup \delta(2, b) \cup \delta(3, b) = \{3\} \cup \emptyset \cup \{2\} = \{2, 3\}$$

$$\Delta(\emptyset, a) = \emptyset \quad \Delta(\emptyset, b) = \emptyset$$

No more new states: we say "The BFS has done"

The extra things pointed out have to do with how the states of the DFA tell what the NFA can and cannot process:

- The NFA cannot process the string  $bbb$  from its start state at all. However you try, you come to the NFA state 2 being unable to process a  $b$ . Nor can it process  $bbb$  from any other state.
- However,  $N$  can process  $a$  from start to any one of its three states:
  - $(1, a, 1)$
  - $(1, a, 1)(1, \epsilon, 2)$
  - $(1, \epsilon, 2)(2, a, 3)$ .

This is shown in the DFA by the single arc  $(S, a, \{1, 2, 3\})$ .

- But in the string  $x = abbb$ , even though the initial  $a$  "turns on all three lightbulbs of  $N$ ", the final  $bbb$  still cannot be processed by  $N$ . The DFA  $M$  does process it via the computation  $(S, a, \{1, 2, 3\})(\{1, 2, 3\}, b, \{2, 3\})(\{2, 3\}, b, \{2\})(\{2\}, b, \emptyset)$ , but that computation ends at  $\emptyset$ , which---when present at all---is always a dead state.