

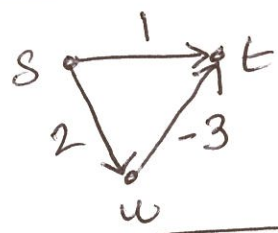
Nov 20

# Shortest Path Problem

Input (•) Directed graph  $G = (V, E)$   
 $\forall e \in E, c_e$  ( $c_e < 0$  is allowed)  
 BUT no negative cycle  
 (•)  $t \in V$

Output:  $\forall s \in V$ , output a shortest  $s-t$  path

Attempt 1: Run Dijkstra



shortest  $s-t$  path:  $s, u, t$   
 but Dijkstra picks:  $st$

Attempt 2: Add some  $\Delta > 0$  to all edge costs so that new costs  $c'_e = c_e + \Delta \geq 0$   
 $\rightarrow$  Run Dijkstra

Doesn't work! see T/F #7 on piazza (Above example with  $\Delta=3$  works)

UPSHOT: There is no known greedy or Divide & Conquer algo for this problem

Assume (for now): We only care about the cost of a shortest  $s-t$  path

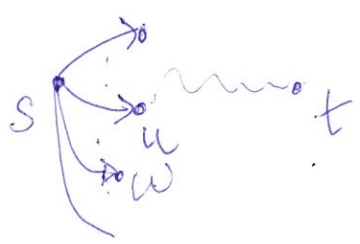
Goal: Design a ~~big~~ dynamic program

Attempt 3:  $OPT(s) =$  cost of shortest  $s-t$  path  $\forall s \in V$

(Q1) How many subproblems?  $OPT(s) \forall s \in S \Rightarrow n$  subproblems

(Q2) Recursive formula ( $s \neq t$ )

if shortest  $s-t$  path uses  $(s, u)$  as the first edge:

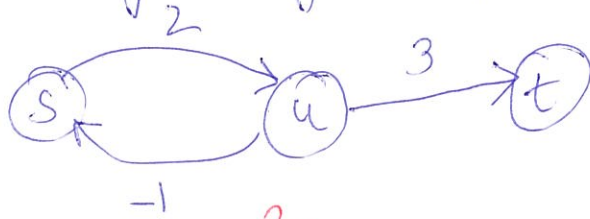


$$OPT(s) = c_{(s,u)} + OPT(u)$$

More generally;

recurrence 
$$OPT(s) = \min_{\substack{w: (s,w) \\ \in E}} \{ C_{(s,w)} + OPT(w) \}$$

(Q3) Total ordering among sub-problems:



$$OPT(s) = C_{(s,u)} + OPT(u)$$

$$OPT(u) = \min \{ C_{(u,t)} + OPT(t), C_{(u,s)} + OPT(s) \}$$

Cycle in dependence (special b/w u & s)  $\Rightarrow$  X total ordering.

Solution: Introduce an (implicit) parameter to the sub-problem

$\uparrow$  not part of the problem def

$\rightarrow$  have the parameter keep track of how "close" we are to t

Attempt 4: See video from last year: gives a correct dynamic program but has exp. ~~res~~ number of sub-problems.

Attempts: Bellman-Ford algo

$OPT(s, i) =$  cost of the shortest s-t path with  $0 \leq i \leq n-1 \leq i$  edges.

Prop: If G has no negative cycle  $\Rightarrow \forall s \in V, \exists$  a shortest s-t path that is simple.  $\Rightarrow$  always  $\exists$  a shortest s-t path  $\leq n-1$  edges

If (idea): If not



can drop this since total cost of cycle  $\geq 0$

Sub-problems:  $OPT(s, i)$

$\forall s \in V$

$\forall 0 \leq i \leq n-1$

Goal:  $OPT(s, n-1)$

$\forall s \in V$

Cost of shortest  $s-t$  path with  $\leq i$  edges in it

(Q7) How many subproblems?  $n \cdot n = n^2$

Let's focus on  $d (= s)$

$$OPT(d, 0) = \infty \quad [d \neq t]$$

$$OPT(d, 1) = 4 \quad [d, t]$$

$$OPT(d, 2) = 6 - 3 \quad [d, a, t]$$

$$OPT(d, 3) = 3 \quad [d, a, t]$$

$$OPT(d, 4) = 6 - 4 - 2 + 2 \quad [d, a, b, e, t]$$

$$n-1=5 \quad OPT(d, 5) = 6 - 4 - 2 - 3 + 3 = 2 \quad [d, a, b, e, c, t]$$

$$OPT(d, 6) = OPT(d, 7) = \dots = 0$$

