



University at Buffalo

Department of Computer Science
and Engineering

School of Engineering and Applied Sciences

Exceptions

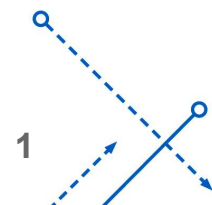
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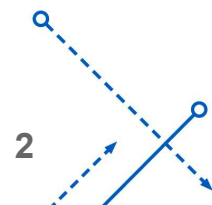
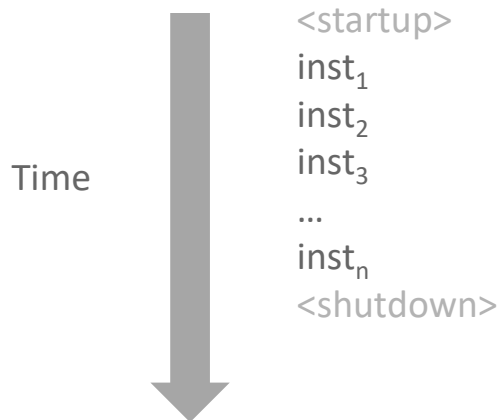
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Control Flow

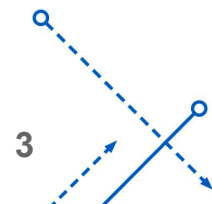
- Processors do only one thing:
 - From startup to shutdown, a CPU simply reads and executes (interprets) a sequence of instructions, one at a time
 - This sequence is the CPU's *control flow* (or *flow of control*)

Physical control flow



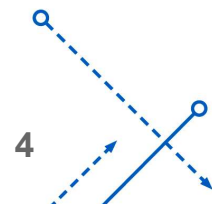
Altering the Control Flow

- Up to now: two mechanisms for changing control flow:
 - Jumps and branches
 - Call and return
 React to changes in *program state*
- Insufficient for a useful system:
Difficult to react to changes in *system state*
 - Data arrives from a disk or a network adapter
 - Instruction divides by zero
 - User hits Ctrl-C at the keyboard
 - System timer expires
- System needs mechanisms for “exceptional control flow”



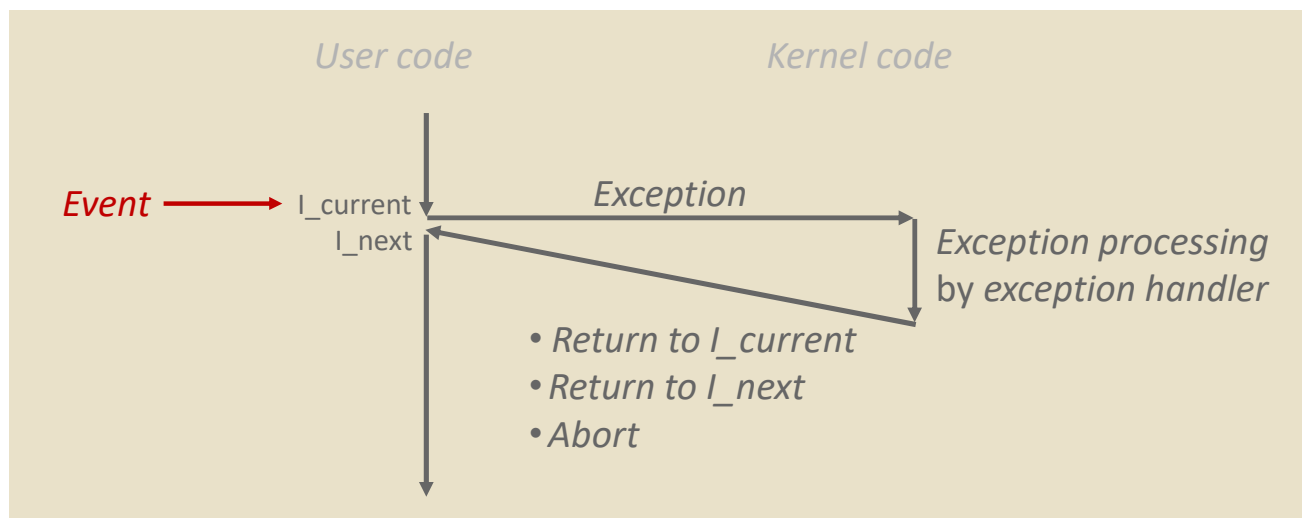
Exceptional Control Flow

- Exists at all levels of a computer system
- Low level mechanisms
 - 1. **Exceptions**
 - Change in control flow in response to a system event (i.e., change in system state)
 - Implemented using combination of hardware and OS software
- Higher level mechanisms
 - 2. **Process context switch**
 - Implemented by OS software and hardware timer
 - 3. **Signals**
 - Implemented by OS software
 - 4. **Nonlocal jumps**: `setjmp()` and `longjmp()`
 - Implemented by C runtime library

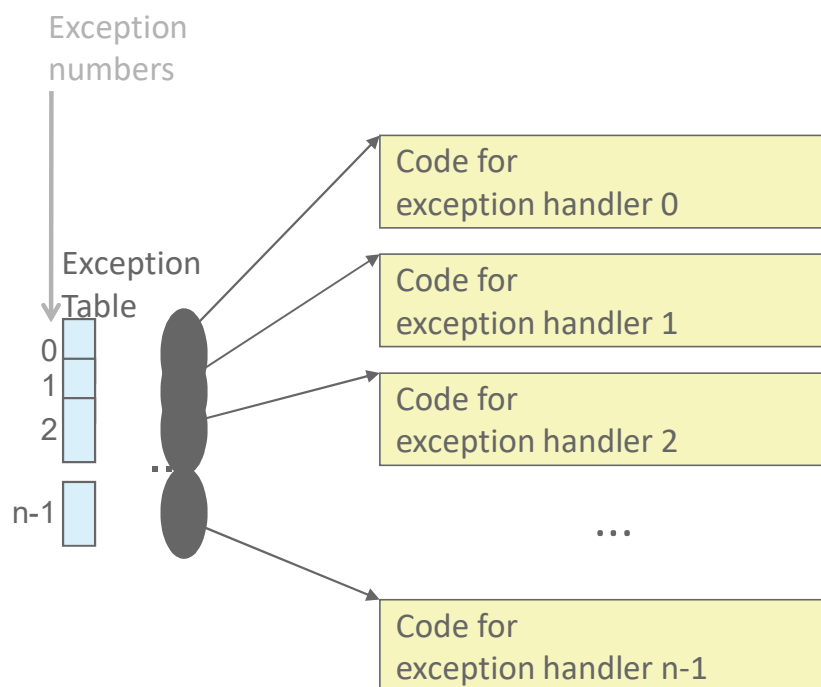


Exceptions

- An *exception* is a transfer of control to the OS *kernel* in response to some *event* (i.e., change in processor state)
 - Kernel is the memory-resident part of the OS
 - Examples of events: Divide by 0, arithmetic overflow, page fault, I/O request completes, typing Ctrl-C

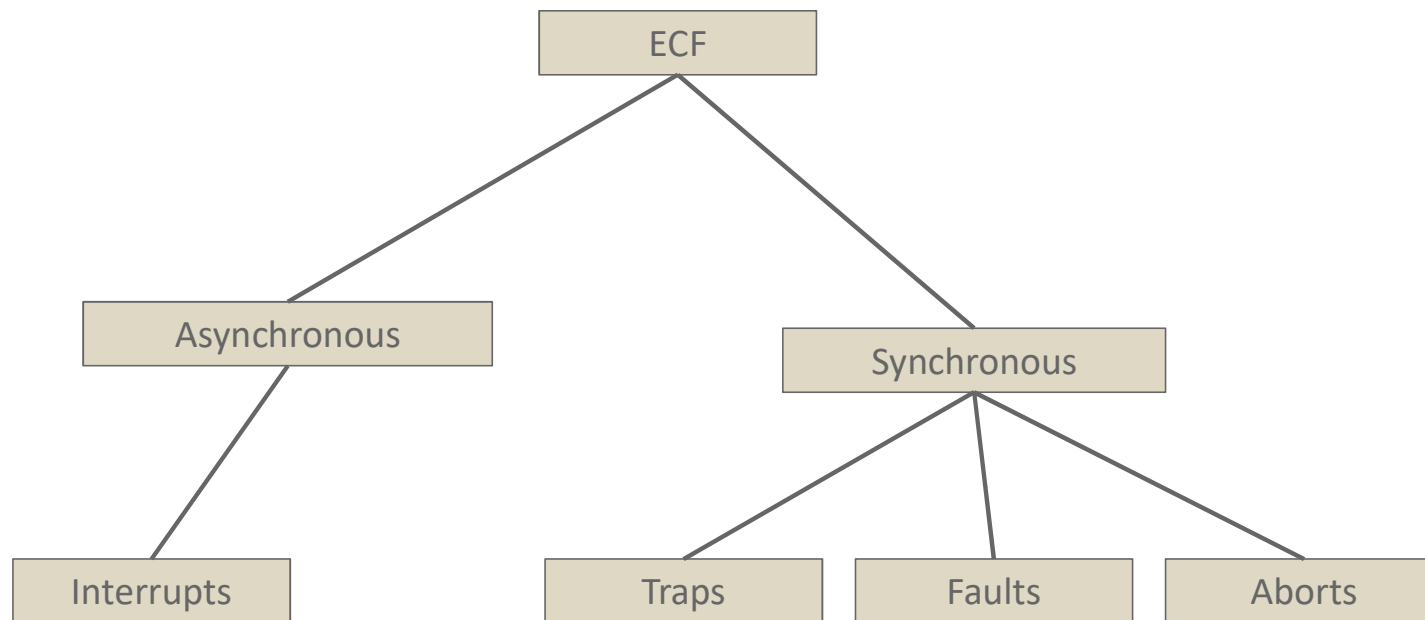


Exception Tables



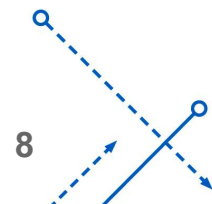
- Each type of event has a unique exception number k
- k = index into exception table (a.k.a. interrupt vector)
- Handler k is called each time exception k occurs

(partial) Taxonomy



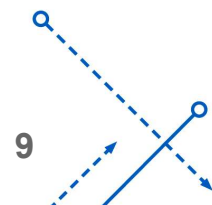
Asynchronous Exceptions (Interrupts)

- Caused by events external to the processor
 - Indicated by setting the processor's *interrupt pin*
 - Handler returns to “next” instruction
- Examples:
 - Timer interrupt
 - Every few ms, an external timer chip triggers an interrupt
 - Used by the kernel to take back control from user programs
 - I/O interrupt from external device
 - Hitting Ctrl-C at the keyboard
 - Arrival of a packet from a network
 - Arrival of data from a disk



Synchronous Exceptions

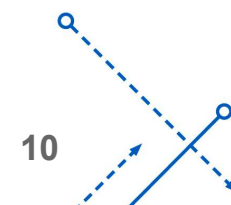
- Caused by events that occur as a result of executing an instruction:
 - **Traps**
 - Intentional, set program up to “trip the trap” and do something
 - Examples: **system calls**, gdb breakpoints
 - Returns control to “next” instruction
 - **Faults**
 - Unintentional but possibly recoverable
 - Examples: page faults (recoverable), protection faults (unrecoverable), floating point exceptions
 - Either re-executes faulting (“current”) instruction or aborts
 - **Aborts**
 - Unintentional and unrecoverable
 - Examples: illegal instruction, parity error, machine check
 - Aborts current program



System Calls

- Each x86-64 system call has a unique ID number
- Examples:

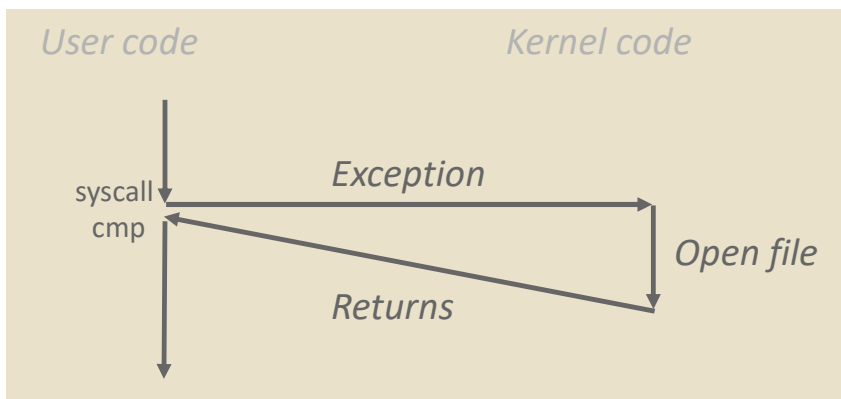
<i>Number</i>	<i>Name</i>	<i>Description</i>
0	read	Read file
1	write	Write file
2	open	Open file
3	close	Close file
4	stat	Get info about file
57	fork	Create process
59	execve	Execute a program
60	_exit	Terminate process
62	kill	Send signal to process



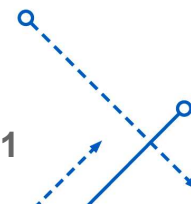
System Call Example: Opening File

- User calls: `open(filename, options)`
- Calls `__open` function, which invokes system call instruction `syscall`

```
0000000000e5d70 <__open>:
...
e5d79: b8 02 00 00 00  mov $0x2,%eax # open is syscall #2
e5d7e: 0f 05          syscall    # Return value in %rax
e5d80: 48 3d 01 f0 ff ff  cmp $0xffffffffffff001,%rax
...
e5dfa: c3            retq
```



- `%rax` contains syscall number
- Other arguments in `%rdi`, `%rsi`, `%rdx`, `%r10`, `%r8`, `%r9`
- Return value in `%rax`
- Negative value is an error corresponding to negative `errno`



System Call Example: Opening File

- User calls: `open(filename, options)`
- Calls `__open` function, which invokes system call instruction `syscall`

```

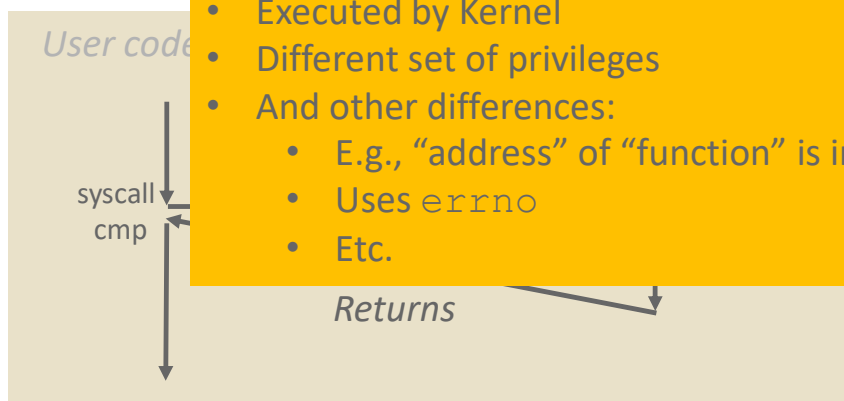
000000000000e5d79: <__open>
...
e5d79: b
e5d7e: 0
e5d80: 4
...
e5dfa: c3
  
```

Almost like a function call

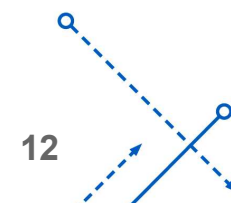
- Transfer of control
- On return, executes next instruction
- Passes arguments using calling convention
- Gets result in `%rax`

One Important exception!

- Executed by Kernel
- Different set of privileges
- And other differences:
 - E.g., "address" of "function" is in `%rax`
 - Uses `errno`
 - Etc.



- Negative value is an error corresponding to negative `errno`

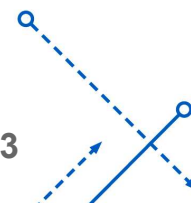
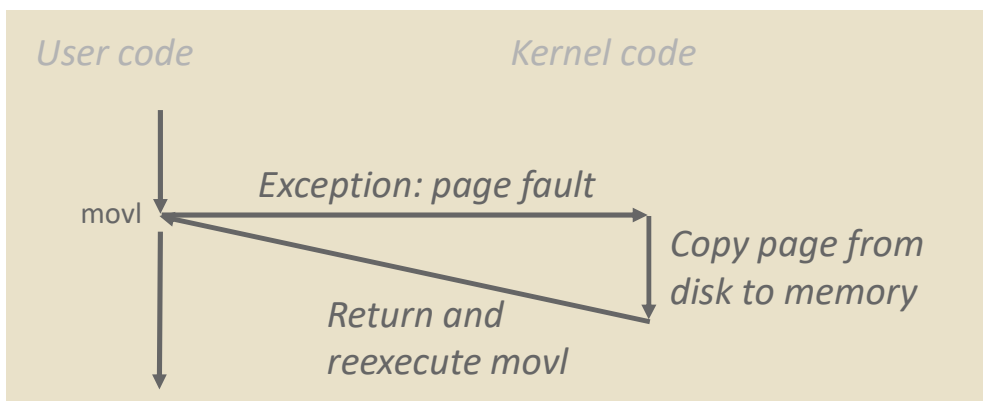


Fault Example: Page Fault

- User writes to memory location
- That portion (page) of user's memory is currently on disk

```
int a[1000];
main ()
{
    a[500] = 13;
}
```

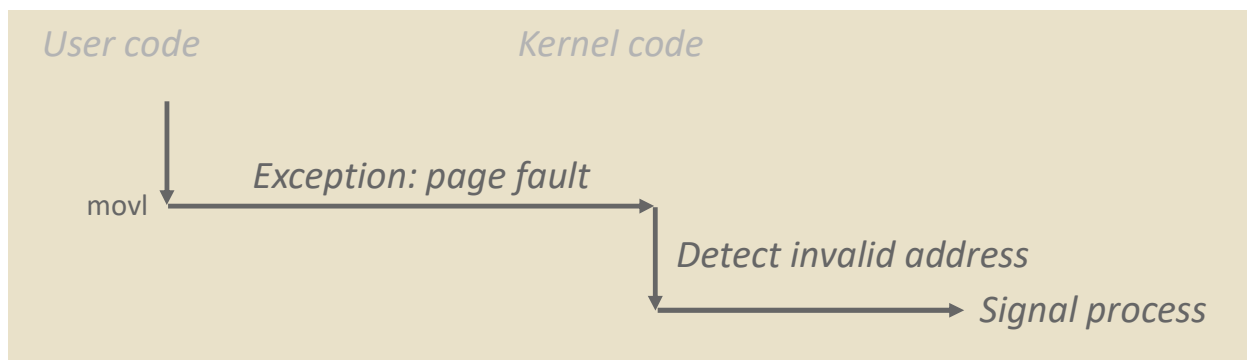
80483b7: c7 05 10 9d 04 08 0d movl \$0xd,0x8049d10



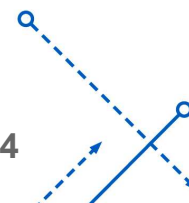
Fault Example: Invalid Memory Reference

```
int a[1000];
main ()
{
    a[5000] = 13;
}
```

80483b7: c7 05 60 e3 04 08 0d movl \$0xd,0x804e360



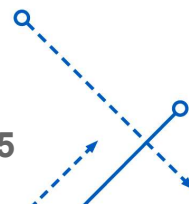
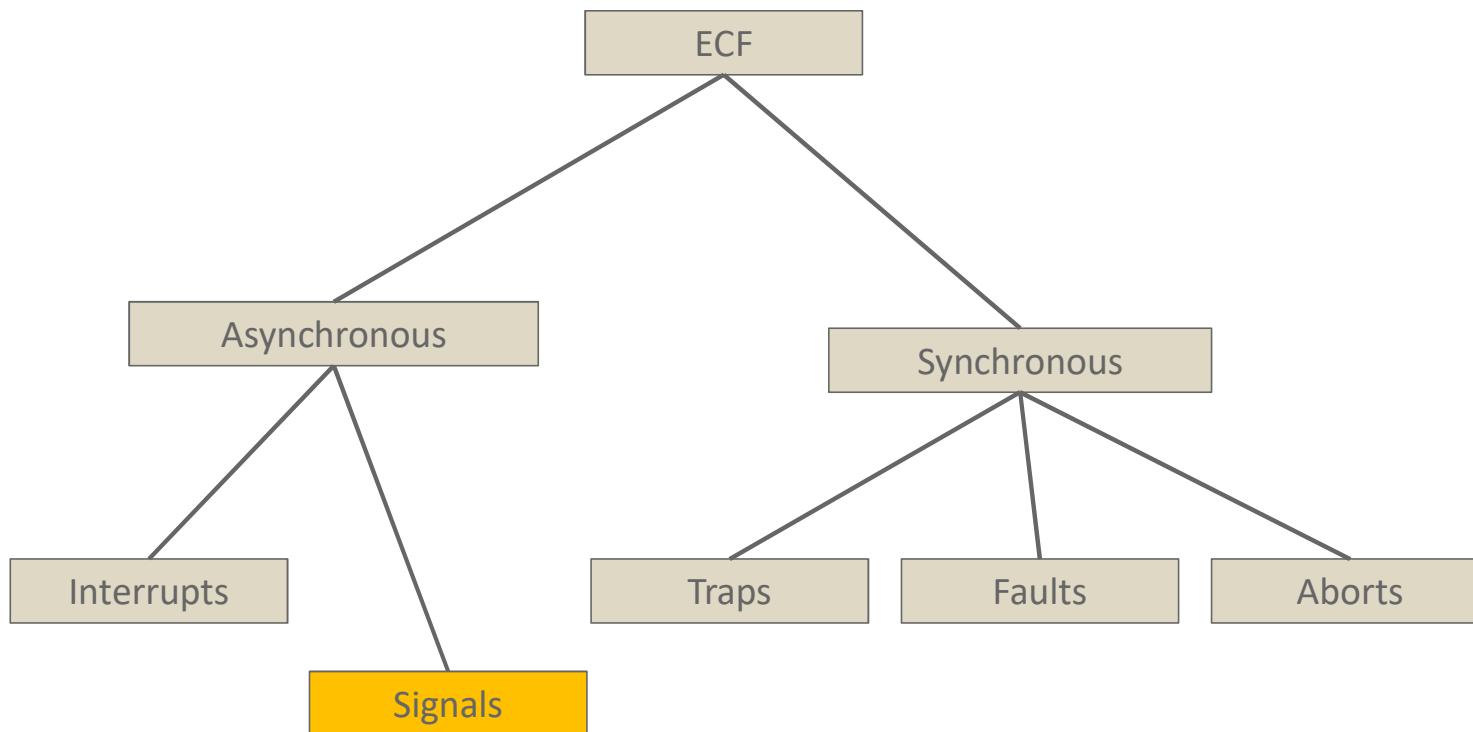
- Sends SIGSEGV signal to user process
- User process exits with “segmentation fault”



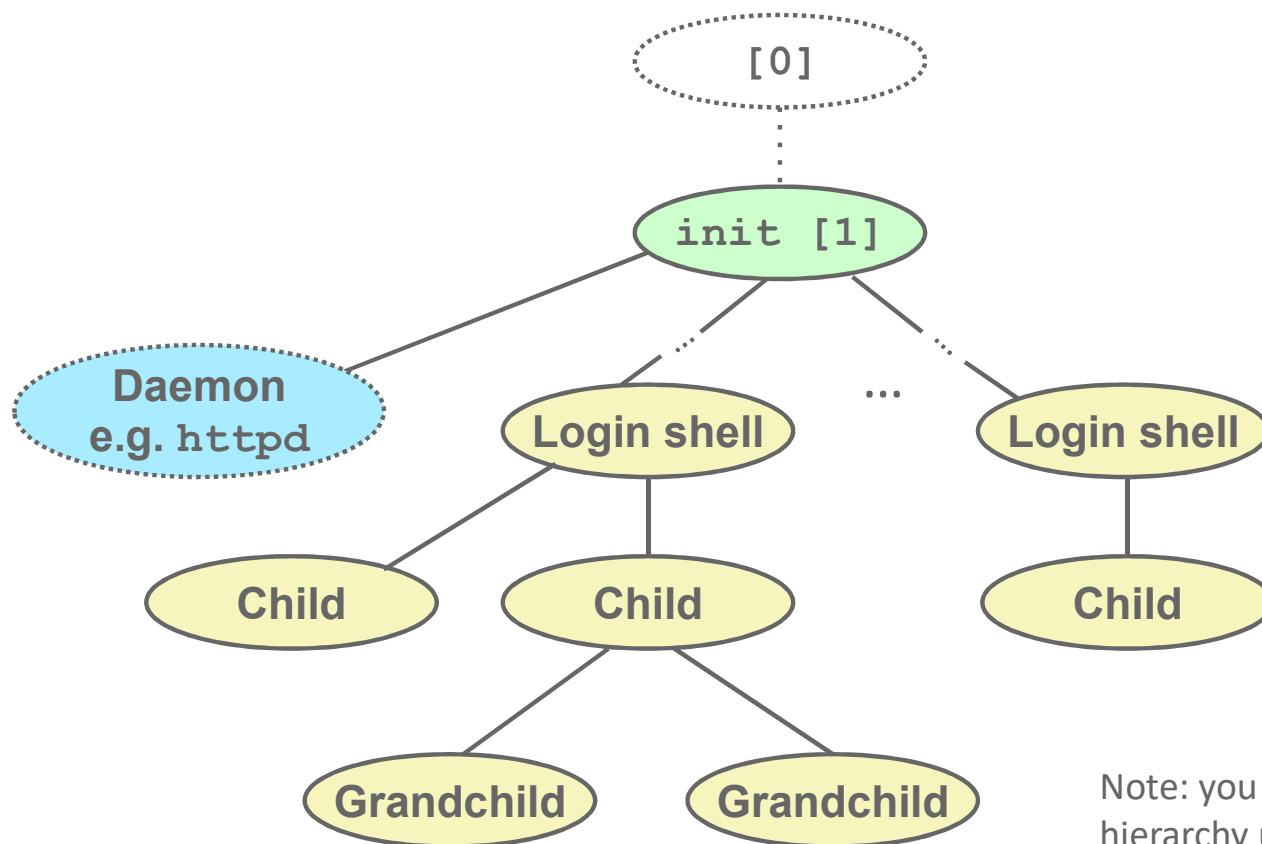
(partial) Taxonomy

Handled in kernel

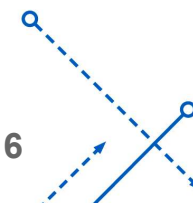
Handled in user process



Linux Process Hierarchy

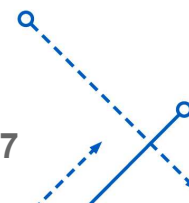


Note: you can view the hierarchy using the Linux `ps tree` command



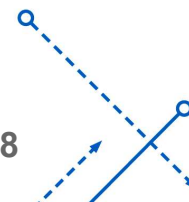
Shell Programs

- A *shell* is an application program that runs programs on behalf of the user.
 - **sh** Original Unix shell (Stephen Bourne, AT&T Bell Labs, 1977)
 - **csh/tcsh** BSD Unix C shell
 - **bash** “Bourne-Again” Shell (default Linux shell)
- Simple shell
 - Described in the textbook, starting at p. 753
 - Implementation of a very elementary shell
 - Purpose
 - Understand what happens when you type commands
 - Understand use and operation of process control operations



Simple Shell Example

```
linux> ./shellex
> /bin/ls -l csapp.c  Must give full pathnames for programs
-rw-r--r-- 1 bryant users 23053 Jun 15  2015 csapp.c
> /bin/ps
  PID TTY          TIME CMD
 31542 pts/2        00:00:01 tcsh
 32017 pts/2        00:00:00 shellex
 32019 pts/2        00:00:00 ps
> /bin/sleep 10 &  Run program in background
32031 /bin/sleep 10 &
> /bin/ps
  PID TTY          TIME CMD
 31542 pts/2        00:00:01 tcsh
 32024 pts/2        00:00:00 emacs
 32030 pts/2        00:00:00 shellex
 32031 pts/2        00:00:00 sleep  Sleep is running
 32033 pts/2        00:00:00 ps      in background
> quit
```



Problem with Shells

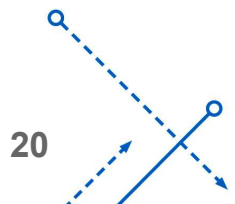
- Shell designed to run indefinitely
 - Should not accumulate unneeded resources
 - Memory
 - Child processes
 - File descriptors
- Our example shell correctly waits for and reaps foreground jobs
- But what about background jobs?
 - Will become zombies when they terminate
 - Will never be reaped because shell (typically) will not terminate
 - Will create a memory leak that could run the kernel out of memory





ECF to the Rescue!

- Solution: Exceptional control flow
 - The kernel will interrupt regular processing to alert us when a background process completes
 - In Unix, the alert mechanism is called a *signal*



Signals

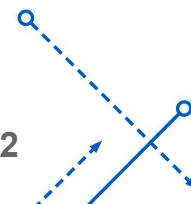
- A *signal* is a small message that notifies a process that an event of some type has occurred in the system
 - Akin to exceptions and interrupts
 - Sent from the kernel (sometimes at the request of another process) to a process
 - Signal type is identified by small integer ID's (1-30)
 - Only information in a signal is its ID and the fact that it arrived

<i>ID</i>	<i>Name</i>	<i>Default Action</i>	<i>Corresponding Event</i>
2	SIGINT	Terminate	User typed ctrl-c
9	SIGKILL	Terminate	Kill program (cannot override or ignore)
11	SIGSEGV	Terminate	Segmentation violation
14	SIGALRM	Terminate	Timer signal
17	SIGCHLD	Ignore	Child stopped or terminated

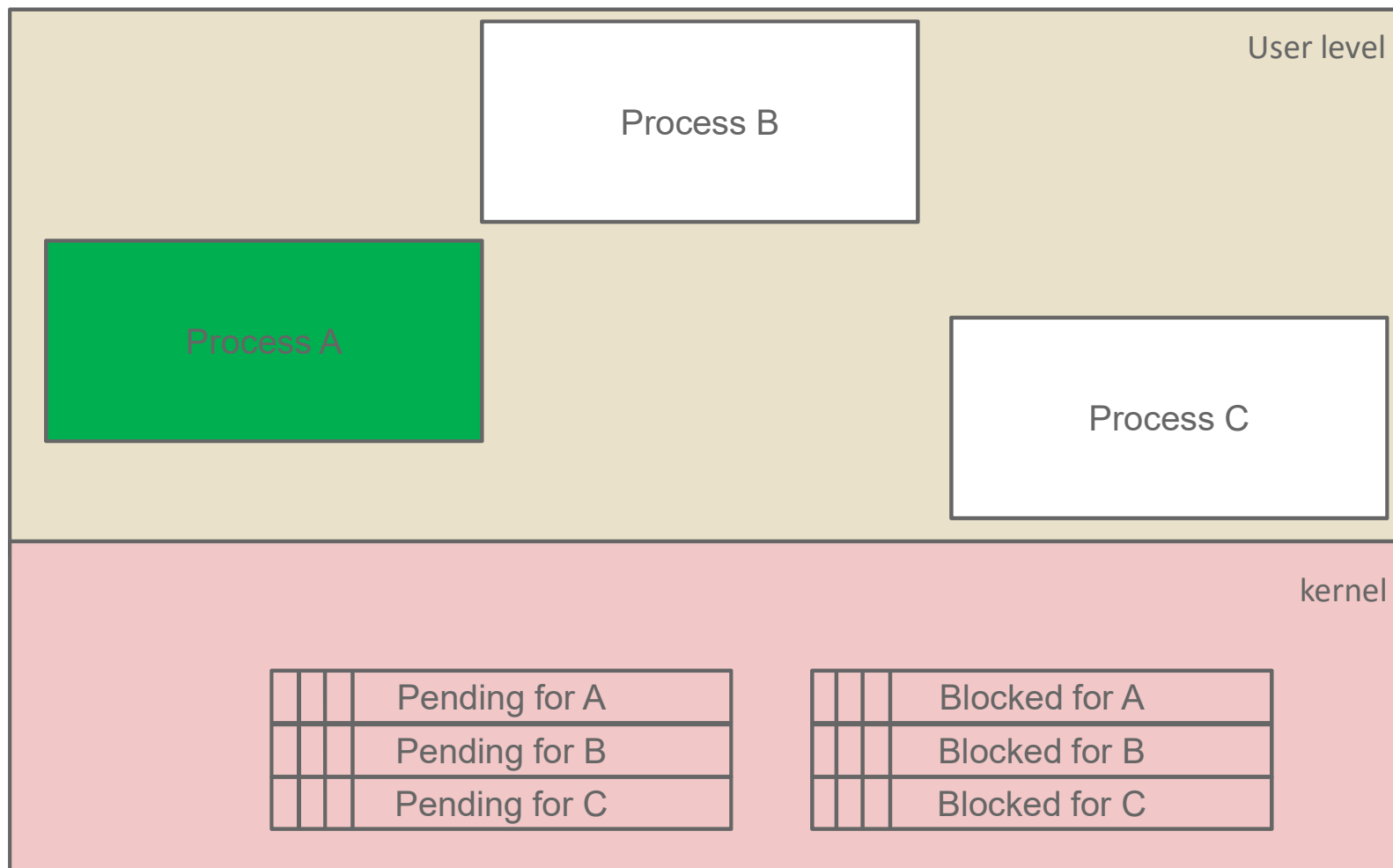


Signal Concepts: Sending a Signal

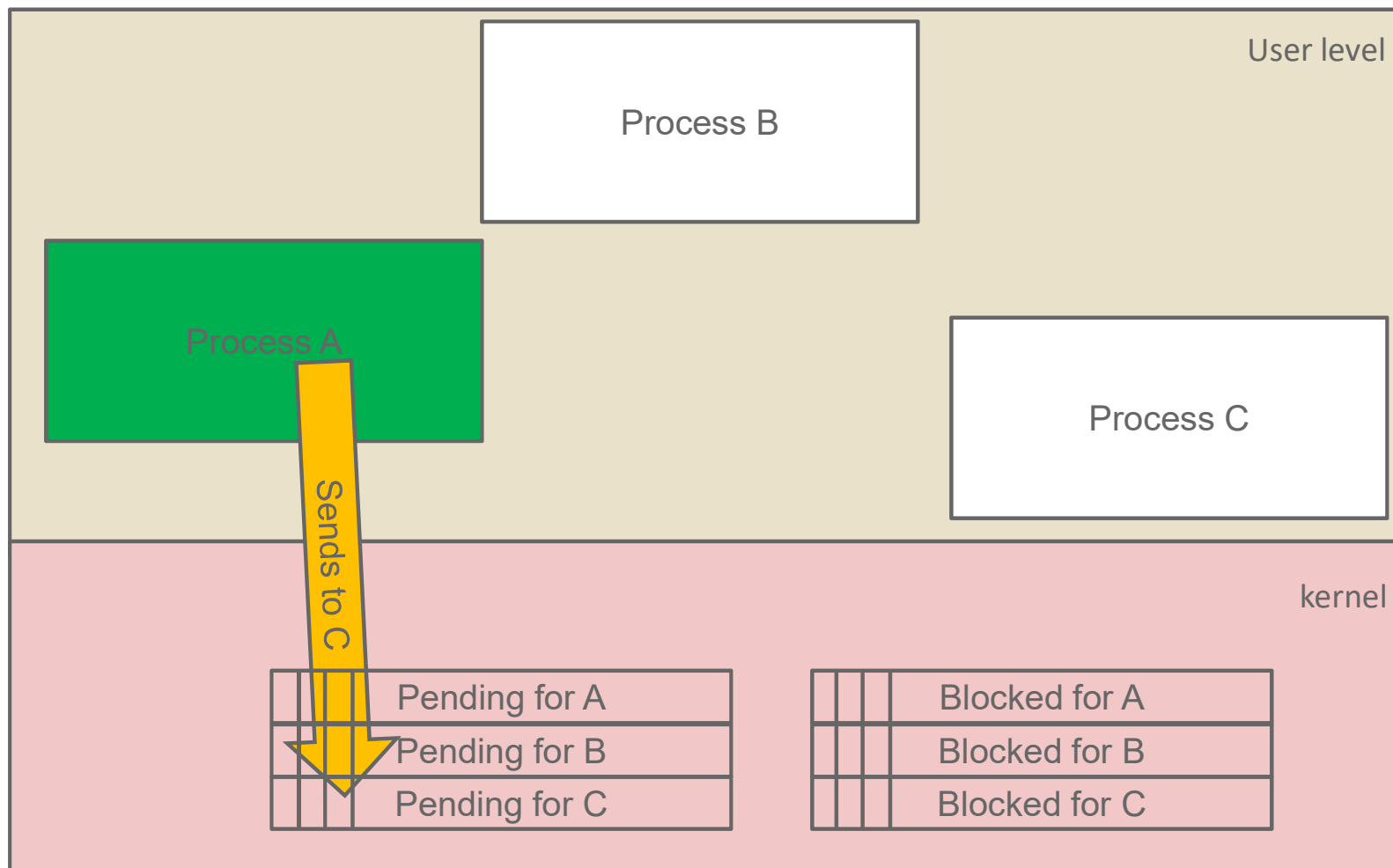
- Kernel *sends* (delivers) a signal to a *destination process* by updating some state in the context of the destination process
- Kernel sends a signal for one of the following reasons:
 - Kernel has detected a system event such as divide-by-zero (SIGFPE) or the termination of a child process (SIGCHLD)
 - Another process has invoked the **kill** system call to explicitly request the kernel to send a signal to the destination process



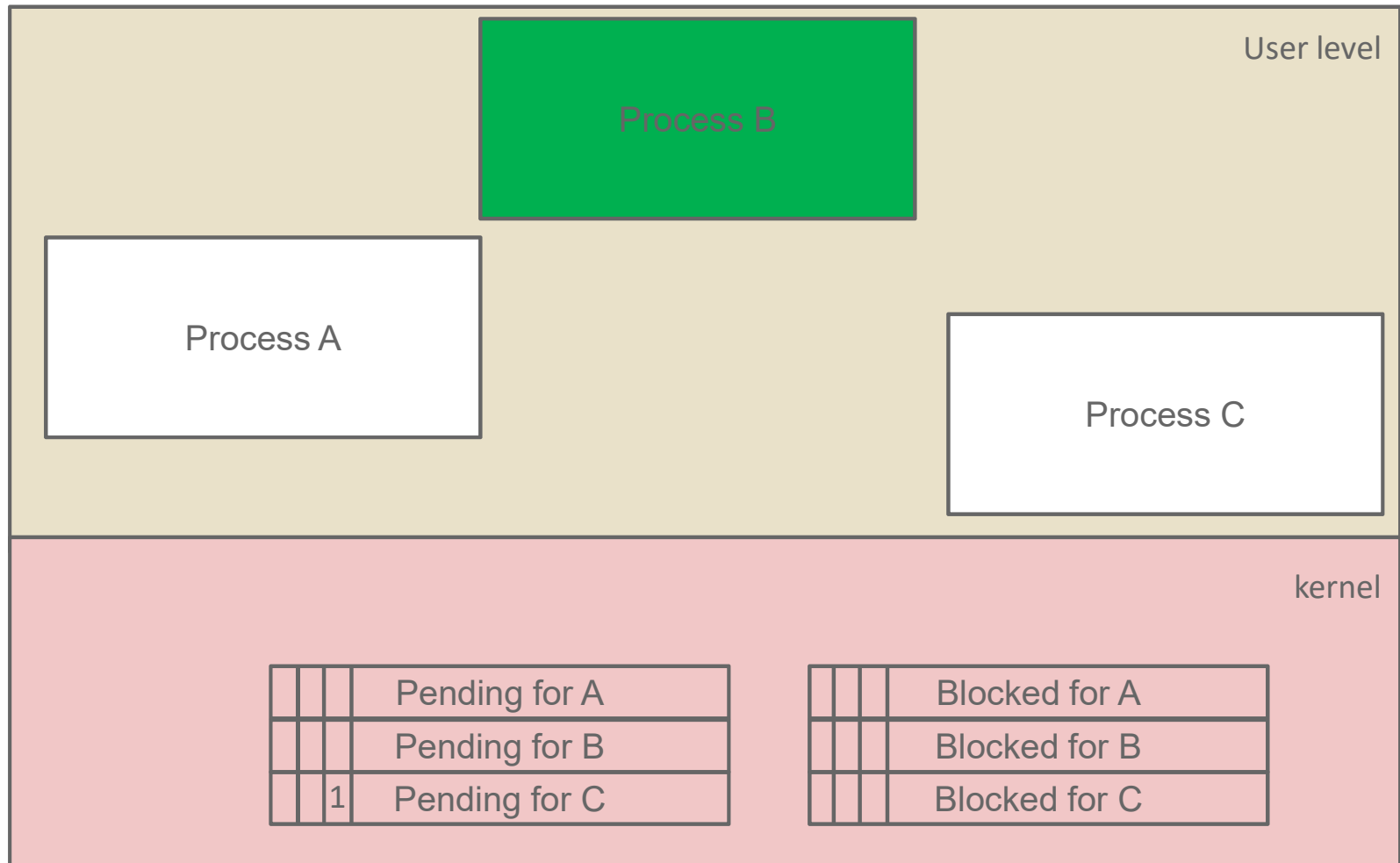
Signal Concepts: Sending a Signal



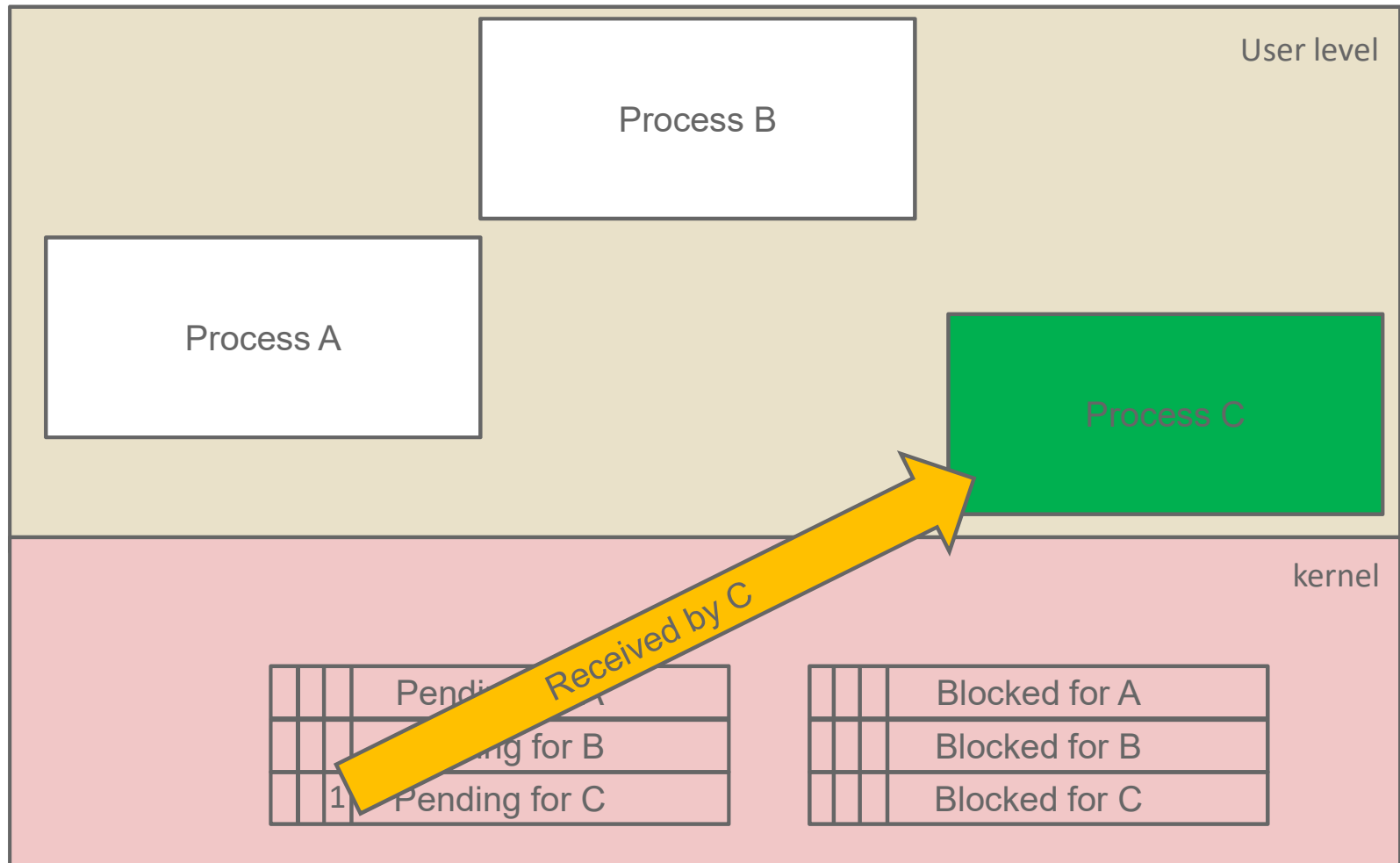
Signal Concepts: Sending a Signal



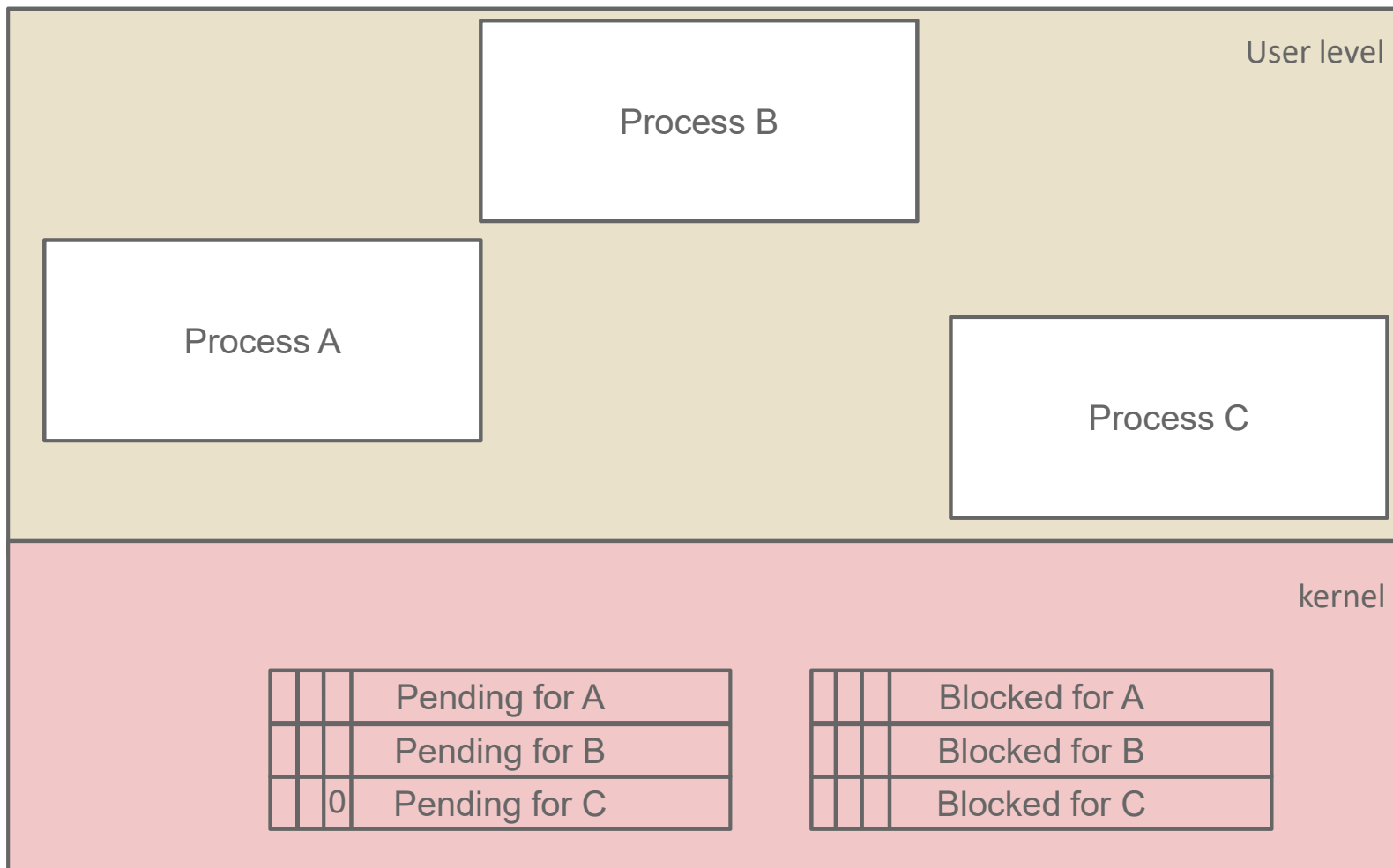
Signal Concepts: Sending a Signal



Signal Concepts: Sending a Signal

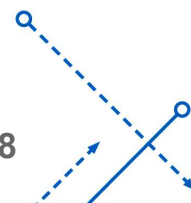
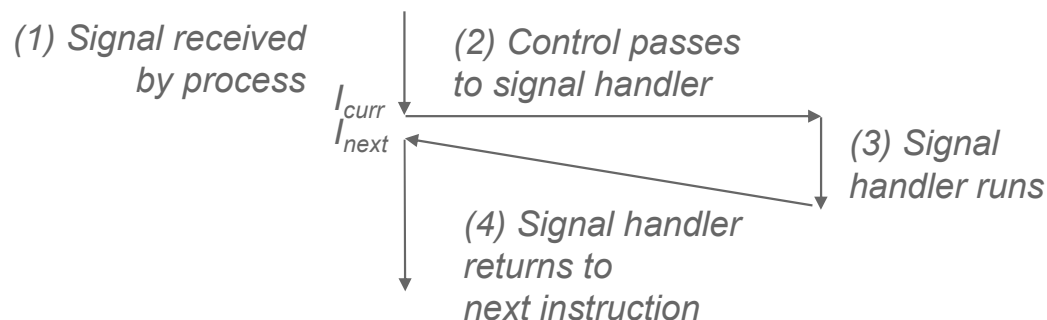


Signal Concepts: Sending a Signal



Signal Concepts: Receiving a Signal

- A destination process *receives* a signal when it is forced by the kernel to react in some way to the delivery of the signal
- Some possible ways to react:
 - **Ignore** the signal (do nothing)
 - **Terminate** the process (with optional core dump)
 - **Catch** the signal by executing a user-level function called **signal handler**
 - Akin to a hardware exception handler being called in response to an asynchronous interrupt:



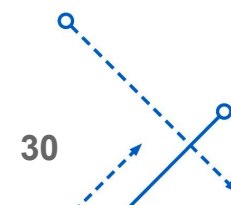
Signal Concepts: Pending and Blocked Signals

- A signal is *pending* if sent but not yet received
 - There can be at most one pending signal of any particular type
 - Important: Signals are not queued
 - If a process has a pending signal of type k, then subsequent signals of type k that are sent to that process are discarded
- A process can *block* the receipt of certain signals
 - Blocked signals can be delivered, but will not be received until the signal is unblocked
- A pending signal is received at most once

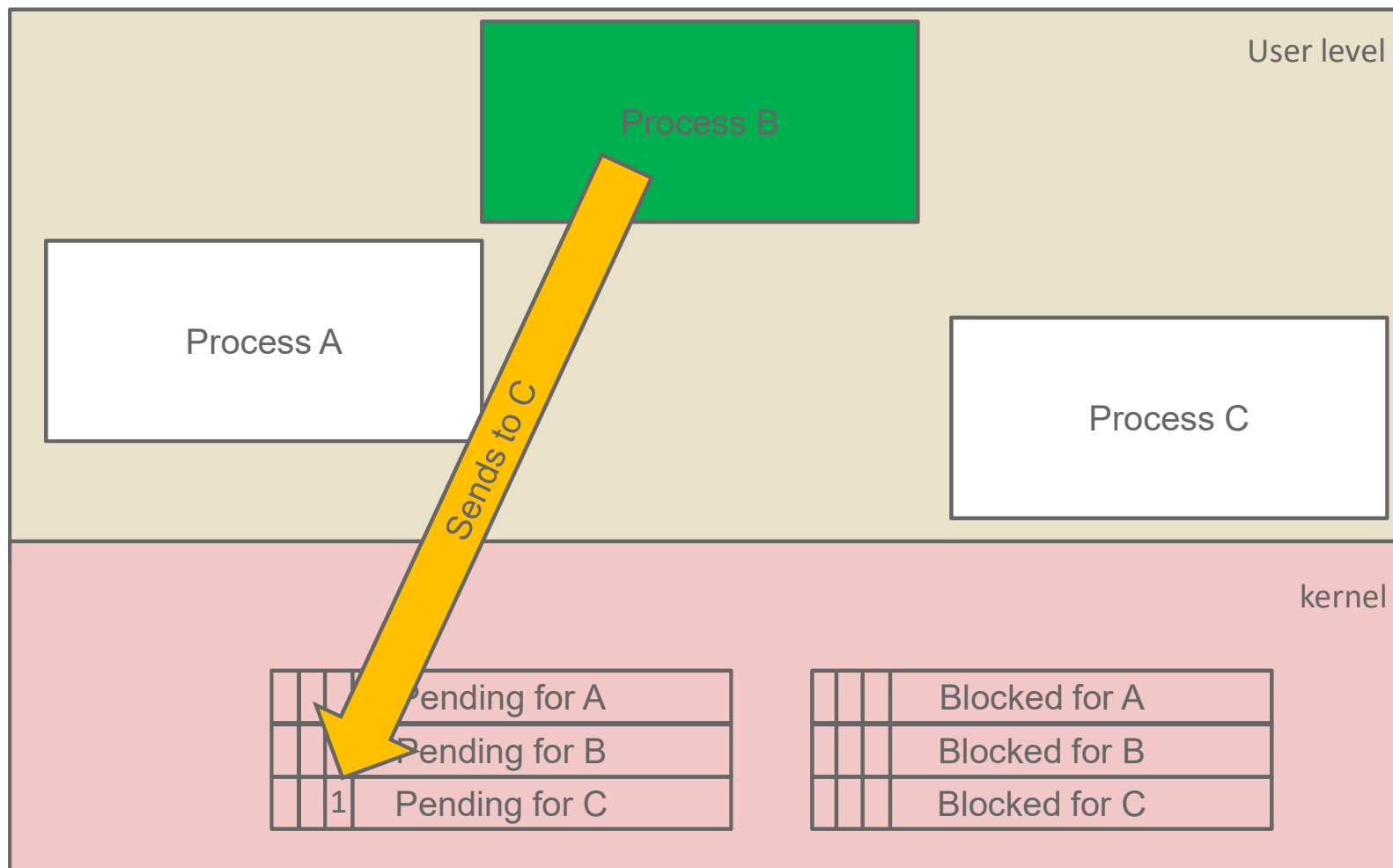


Signal Concepts: Pending/Blocked Bits

- Kernel maintains `pending` and `blocked` bit vectors in the context of each process
 - **pending**: represents the set of pending signals
 - Kernel sets bit `k` in **pending** when a signal of type `k` is delivered
 - Kernel clears bit `k` in **pending** when a signal of type `k` is received
 - **blocked**: represents the set of blocked signals
 - Can be set and cleared by using the **`sigprocmask`** function
 - Also referred to as the *signal mask*.



Signal Concepts: Sending a Signal



Sending Signals with `/bin/kill` Program

- `/bin/kill` program sends arbitrary signal to a process or process group

- Examples

- `/bin/kill -9 24818`

Send SIGKILL to process 24818

- `/bin/kill -9 -24817`

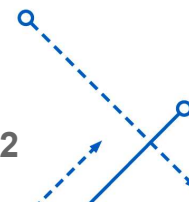
Send SIGKILL to every process in process group 24817

```
linux> ./forks 16
Child1: pid=24818 pgrp=24817
Child2: pid=24819 pgrp=24817
```

```
linux> ps
  PID TTY          TIME CMD
 24788 pts/2        00:00:00 tcsh
 24818 pts/2        00:00:02 forks
 24819 pts/2        00:00:02 forks
 24820 pts/2        00:00:00 ps
```

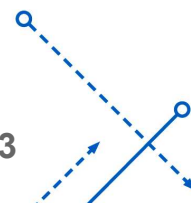
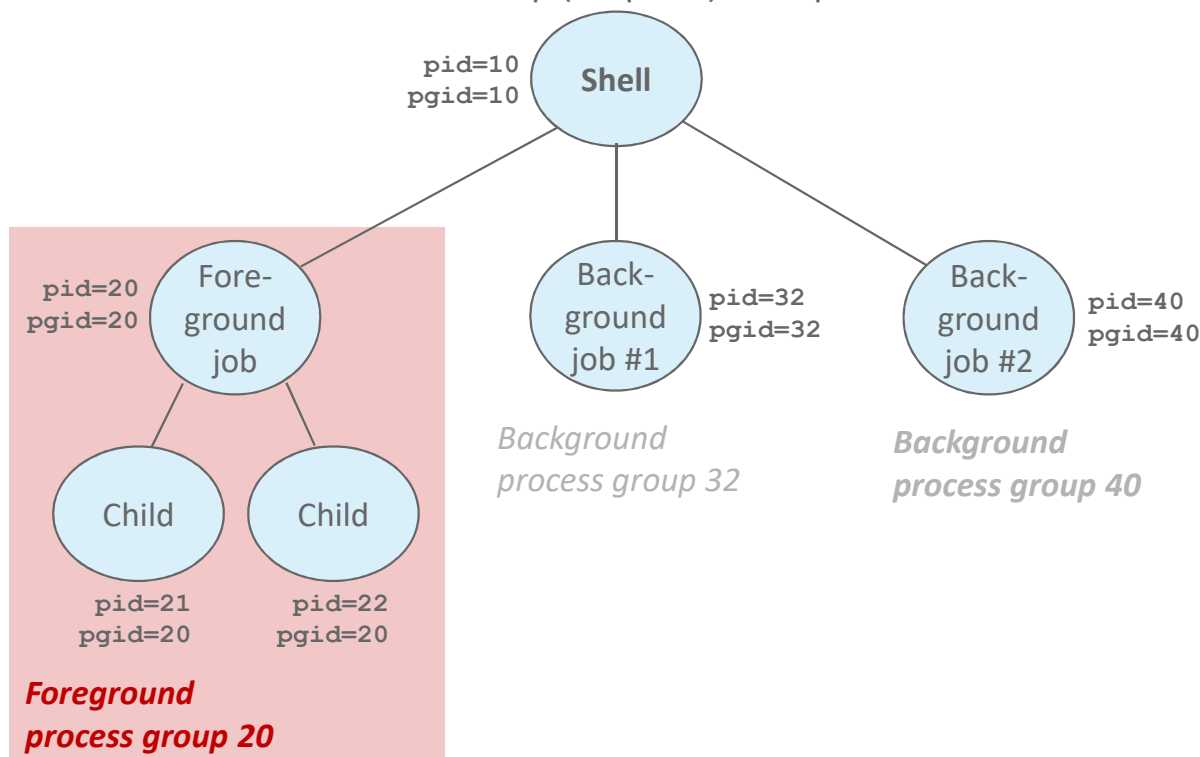
```
linux> /bin/kill -9 -24817
```

```
linux> ps
  PID TTY          TIME CMD
 24788 pts/2        00:00:00 tcsh
 24823 pts/2        00:00:00 ps
linux>
```



Sending Signals from the Keyboard

- Typing ctrl-c (ctrl-z) causes the kernel to send a SIGINT (SIGTSTP) to every job in the foreground process group.
 - SIGINT – default action is to terminate each process
 - SIGTSTP – default action is to stop (suspend) each process



Example of `ctrl-c` and `ctrl-z`

```
bluefish> ./forks 17
Child: pid=28108 pgrp=28107
Parent: pid=28107 pgrp=28107
<types ctrl-z>
Suspended
bluefish> ps w
  PID TTY          STAT       TIME COMMAND
 27699 pts/8        Ss          0:00 -tcsh
 28107 pts/8        T           0:01 ./forks 17
 28108 pts/8        T           0:01 ./forks 17
 28109 pts/8        R+          0:00 ps w
bluefish> fg
./forks 17
<types ctrl-c>
bluefish> ps w
  PID TTY          STAT       TIME COMMAND
 27699 pts/8        Ss          0:00 -tcsh
 28110 pts/8        R+          0:00 ps w
```

STAT (process state) Legend:

First letter:

S: sleeping

T: stopped

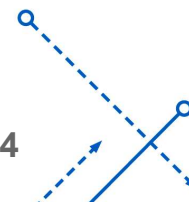
R: running

Second letter:

s: session leader

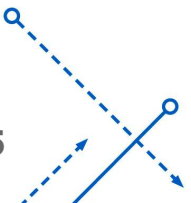
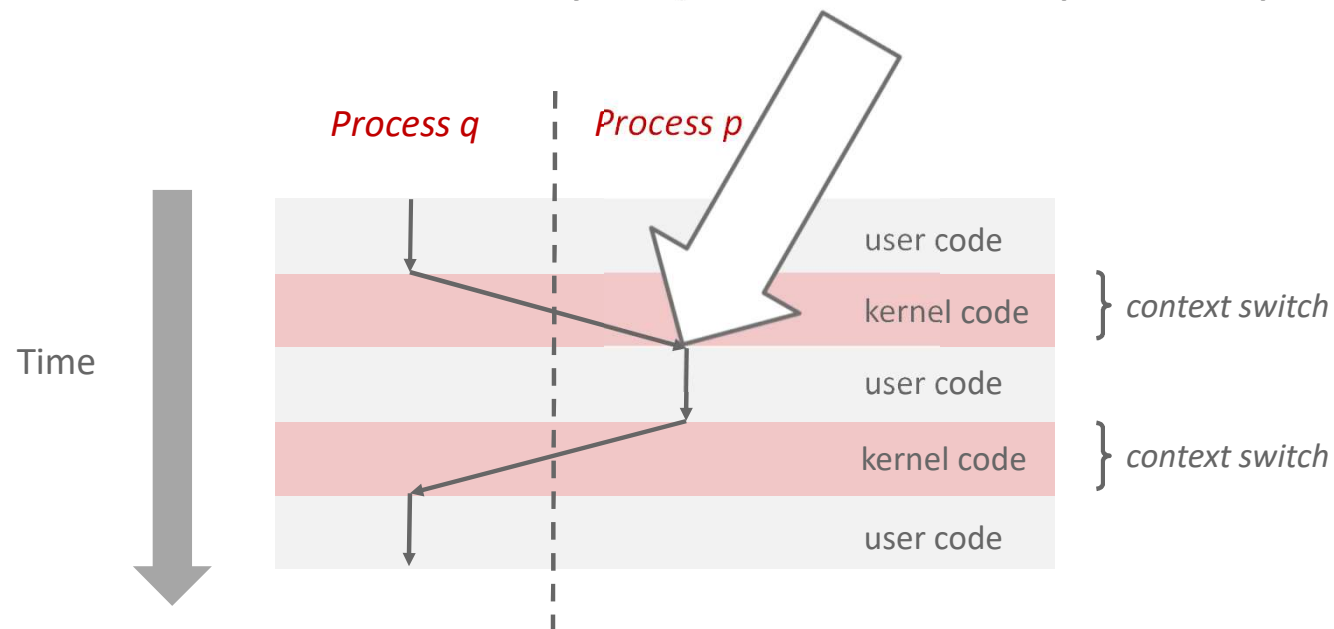
+: foreground proc group

See “man ps” for more
details



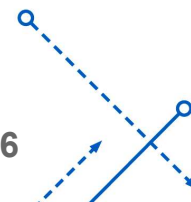
Receiving Signals

- Suppose kernel is returning from an exception handler and is ready to pass control to process p



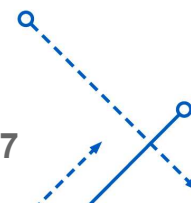
Receiving Signals

- Suppose kernel is returning from an exception handler and is ready to pass control to process p
- Kernel computes $\text{pnb} = \text{pending} \ \& \ \sim\text{blocked}$
 - The set of pending nonblocked signals for process p
- If $(\text{pnb} == 0)$
 - Pass control to next instruction in the logical flow for p
- Else
 - Choose least nonzero bit k in **pnb** and force process p to **receive** signal k
 - The receipt of the signal triggers some **action** by p
 - Repeat for all nonzero k in **pnb**
 - Pass control to next instruction in logical flow for p



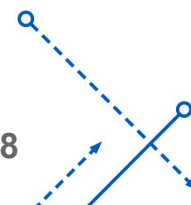
Default Actions

- Each signal type has a predefined *default action*, which is one of:
 - The process terminates
 - The process stops until restarted by a SIGCONT signal
 - The process ignores the signal



Installing Signal Handlers

- The `signal` function modifies the default action associated with the receipt of signal `signum`:
 - `handler_t *signal(int signum, handler_t *handler)`
- Different values for `handler`:
 - `SIG_IGN`: ignore signals of type `signum`
 - `SIG_DFL`: revert to the default action on receipt of signals of type `signum`
 - Otherwise, `handler` is the address of a user-level *signal handler*
 - Called when process receives signal of type `signum`
 - Referred to as *“installing”* the handler
 - Executing handler is called *“catching”* or *“handling”* the signal
 - When the handler executes its return statement, control passes back to instruction in the control flow of the process that was interrupted by receipt of the signal



Signal Handling Example

```
void sigint_handler(int sig) /* SIGINT handler */
{
    printf("So you think you can stop the bomb with ctrl-c, do you?\n");
    sleep(2);
    printf("Well...\n");
    fflush(stdout);
    sleep(1);
    printf("OK. :-)\n");
    exit(0);
}

int main(int argc, char** argv)
{
    /* Install the SIGINT handler */
    if (signal(SIGINT, sigint_handler) == SIG_ERR)
        unix_error("signal error");

    /* Wait for the receipt of a signal */
    pause();

    return 0;
}
```

sigint.c

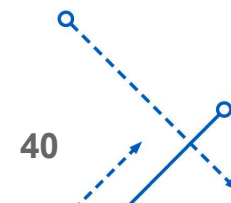


Blocking and Unblocking Signals

- Implicit blocking mechanism
 - Kernel blocks any pending signals of type currently being handled.
 - E.g., A SIGINT handler can't be interrupted by another SIGINT

- Explicit blocking and unblocking mechanism
 - `sigprocmask` function

- Supporting functions
 - `sigemptyset` – Create empty set
 - `sigfillset` – Add every signal number to set
 - `sigaddset` – Add signal number to set
 - `sigdelset` – Delete signal number from set



Temporarily Blocking Signals

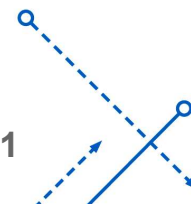
```
sigset_t mask, prev_mask;

Sigemptyset(&mask);
Sigaddset(&mask, SIGINT);

/* Block SIGINT and save previous blocked set */
Sigprocmask(SIG_BLOCK, &mask, &prev_mask);

:    /* Code region that will not be interrupted by SIGINT */

/* Restore previous blocked set, unblocking SIGINT */
Sigprocmask(SIG_SETMASK, &prev_mask, NULL);
```



Summary

- Signals provide process-level exception handling
 - Can generate from user programs
 - Can define effect by declaring signal handler
 - Be very careful when writing signal handlers
- Nonlocal jumps provide exceptional control flow within process
 - Within constraints of stack discipline

