

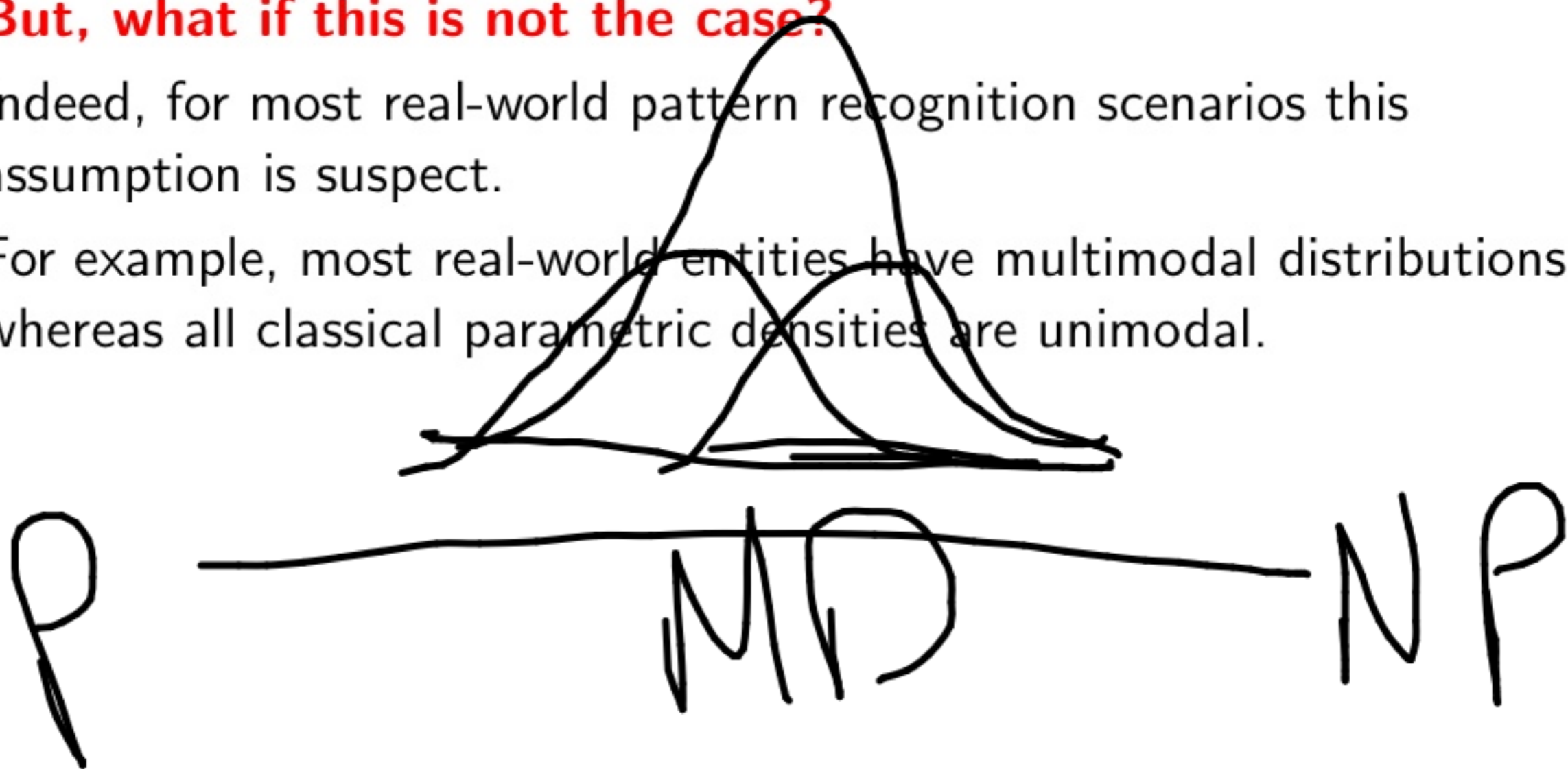
# Nonparametric Methods

Jason Corso

SUNY at Buffalo

# Nonparametric Methods Overview

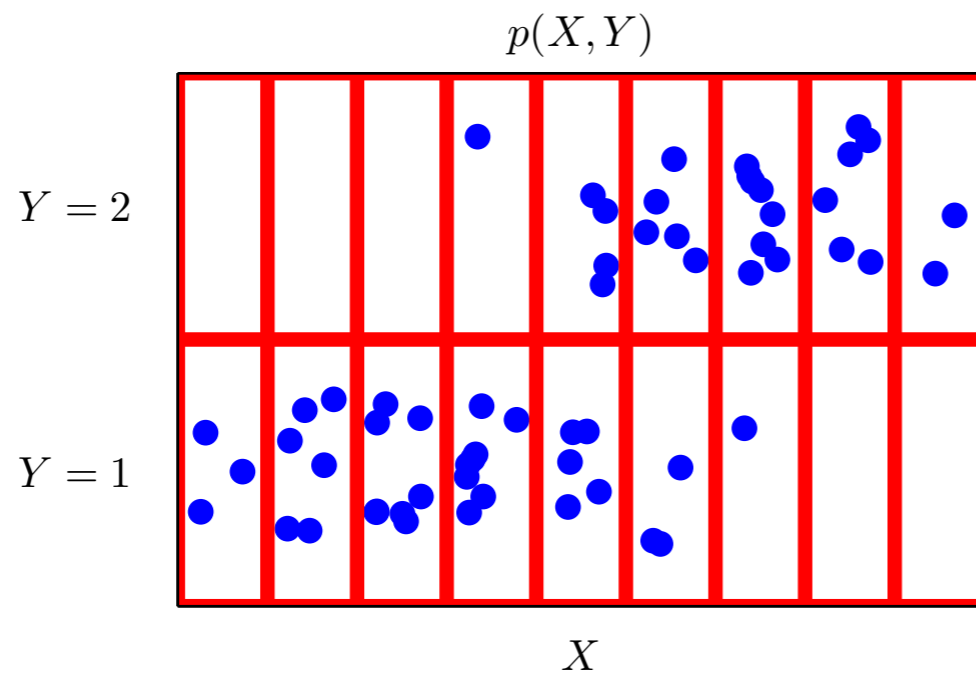
- Previously, we've assumed that the forms of the underlying densities were of some particular known parametric form.
- **But, what if this is not the case?**
- Indeed, for most real-world pattern recognition scenarios this assumption is suspect.
- For example, most real-world entities have multimodal distributions whereas all classical parametric densities are unimodal.



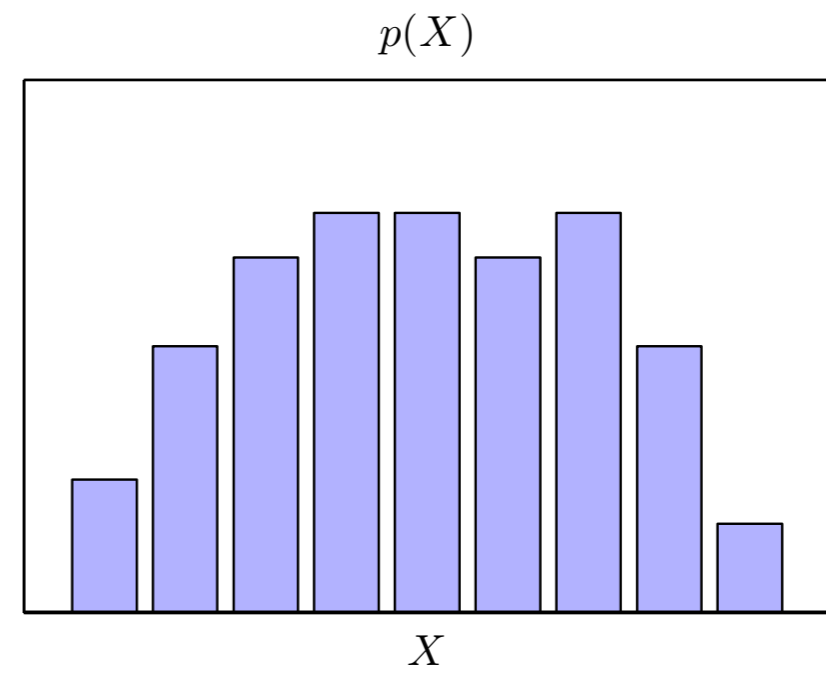
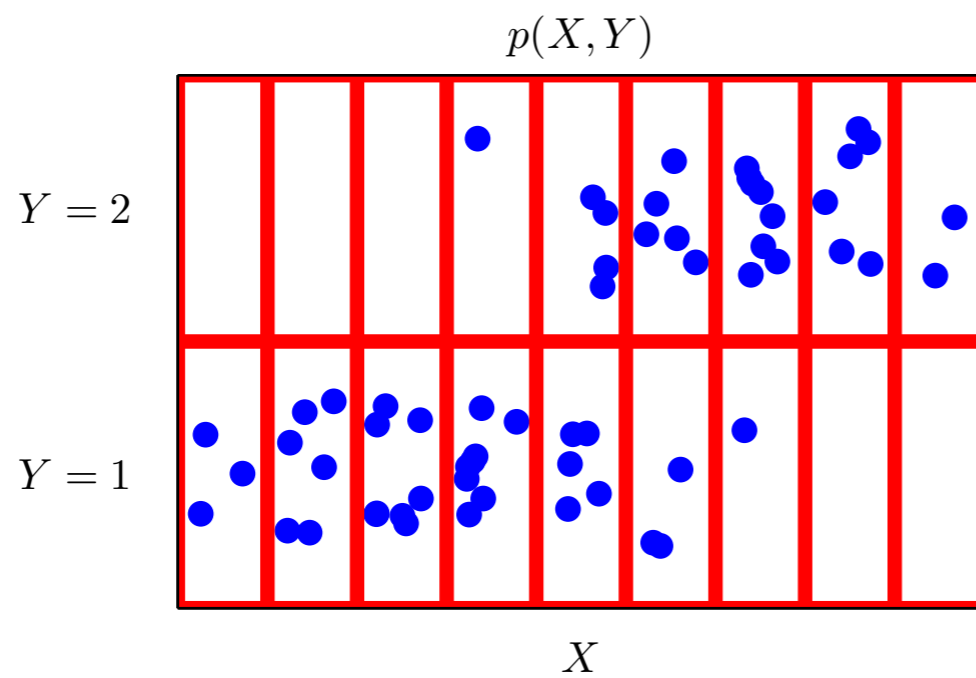
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- **But, what if this is not the case?**
- Indeed, for most real-world pattern recognition scenarios this assumption is suspect.
- For example, most real-world entities have multimodal distributions whereas all classical parametric densities are unimodal.
- We will examine **nonparametric** procedures that can be used with arbitrary distributions and without the assumption that the underlying form of the densities are known.
  - Histograms.
  - Kernel Density Estimation / Parzen Windows.
  - k-Nearest Neighbor Density Estimation.
  - Real Example in Figure-Ground Segmentation

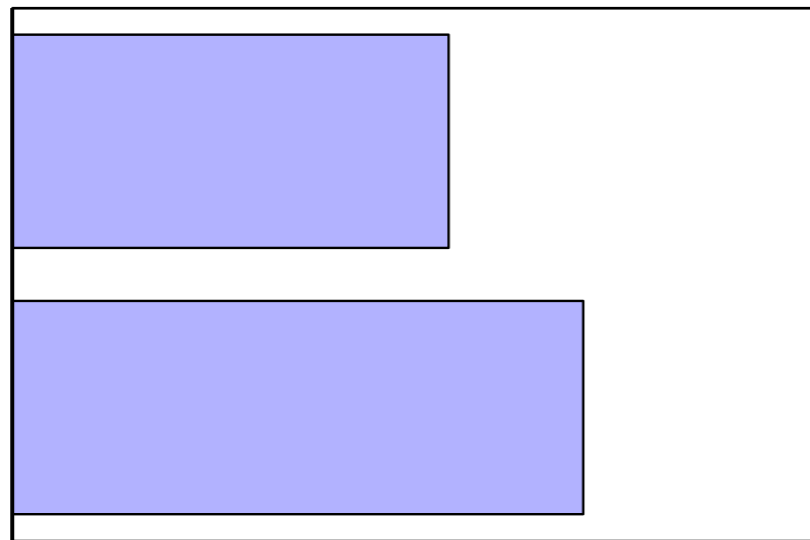
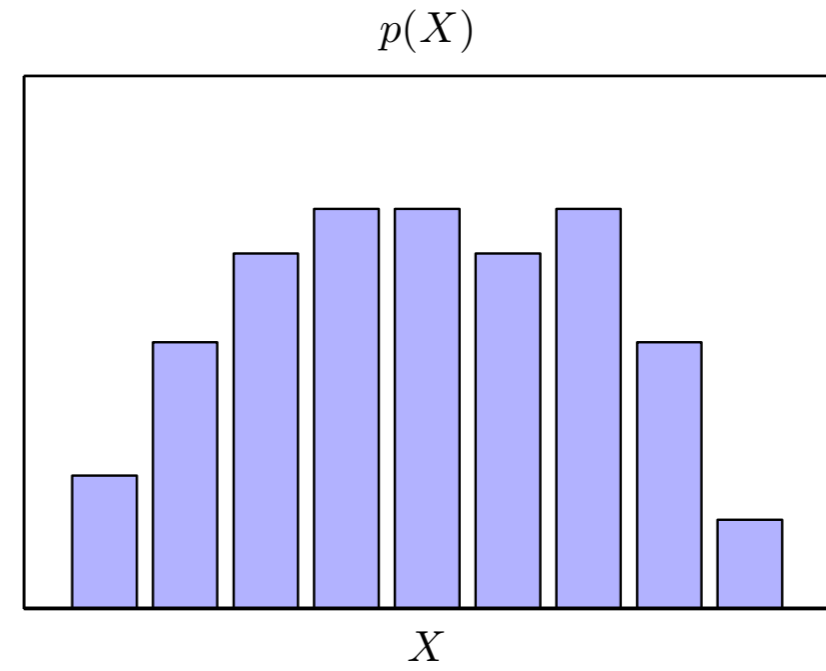
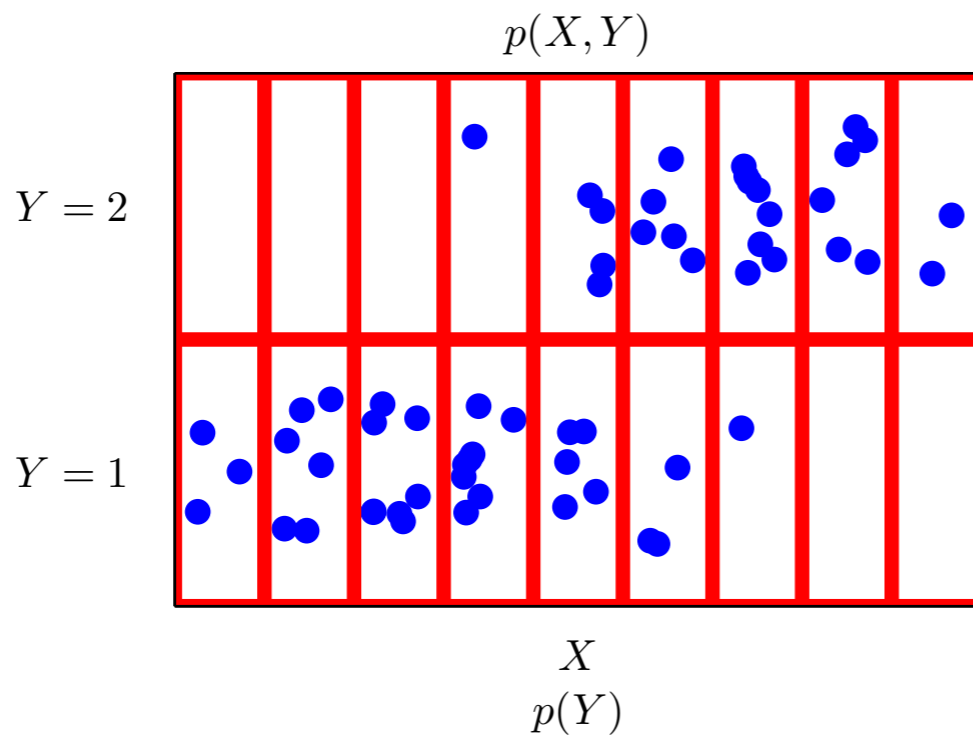
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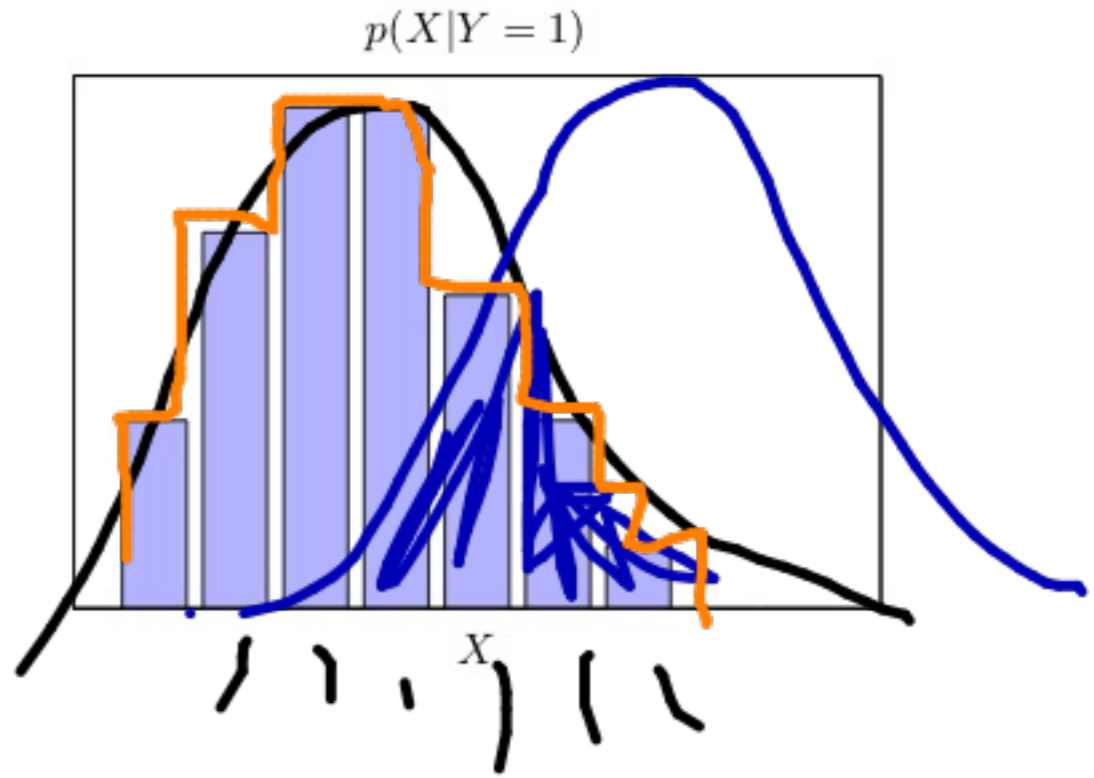
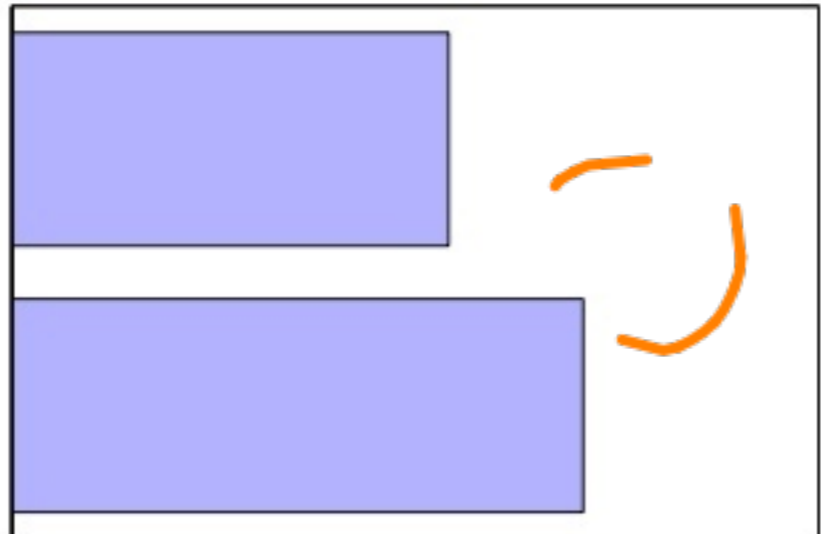
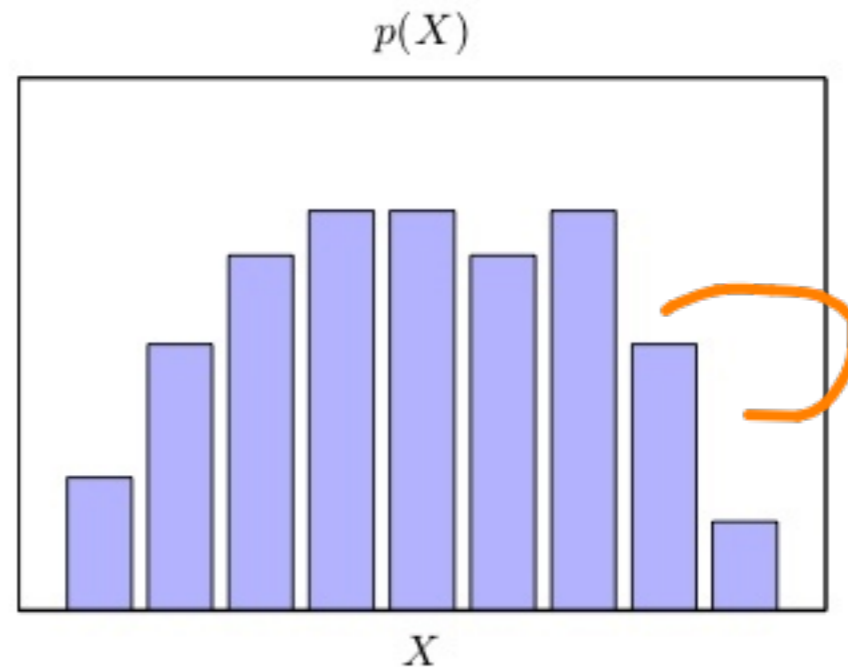
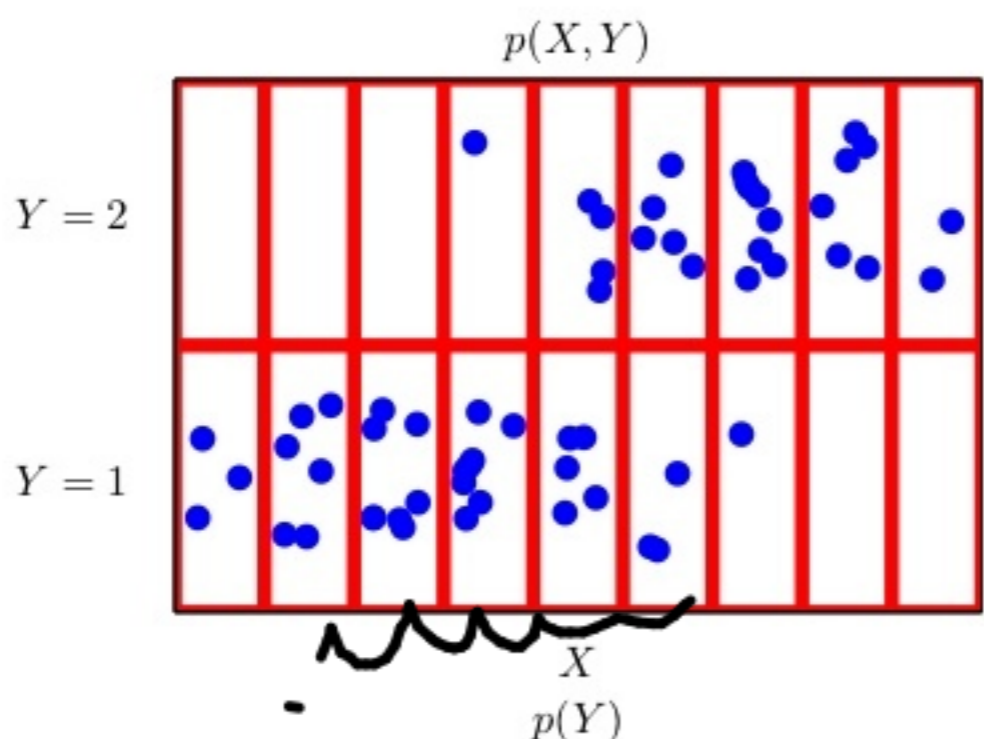
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# Histogram Density Representation

- Consider a single continuous variable  $x$  and let's say we have a set  $\mathcal{D}$  of  $N$  of them  $\{x_1, \dots, x_N\}$ . Our goal is to model  $p(x)$  from  $\mathcal{D}$ .



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- This gives us:



$$p_i = \frac{n_i}{N \Delta_i}$$

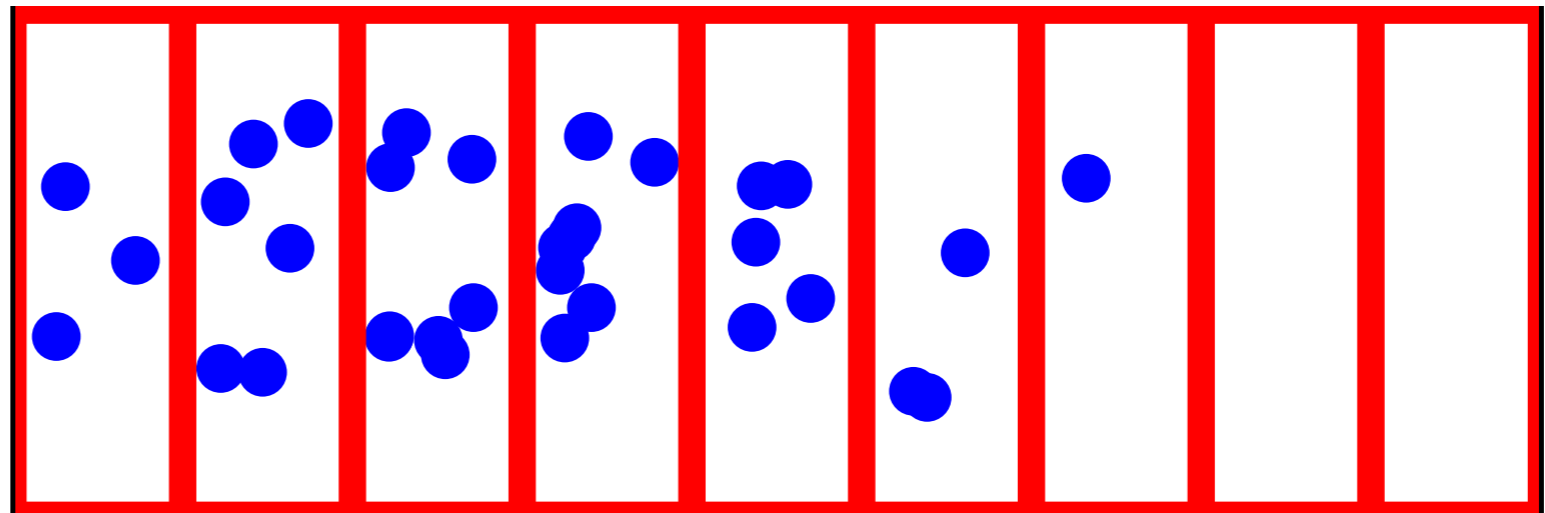
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- This gives us:

$$p_i = \frac{n_i}{N \Delta_i} \quad (1)$$

- Hence the model for the density  $p(x)$  is constant over the width of each bin. (And often the bins are chosen to have the same width  $\Delta_i = \Delta$ .)



Bin Number

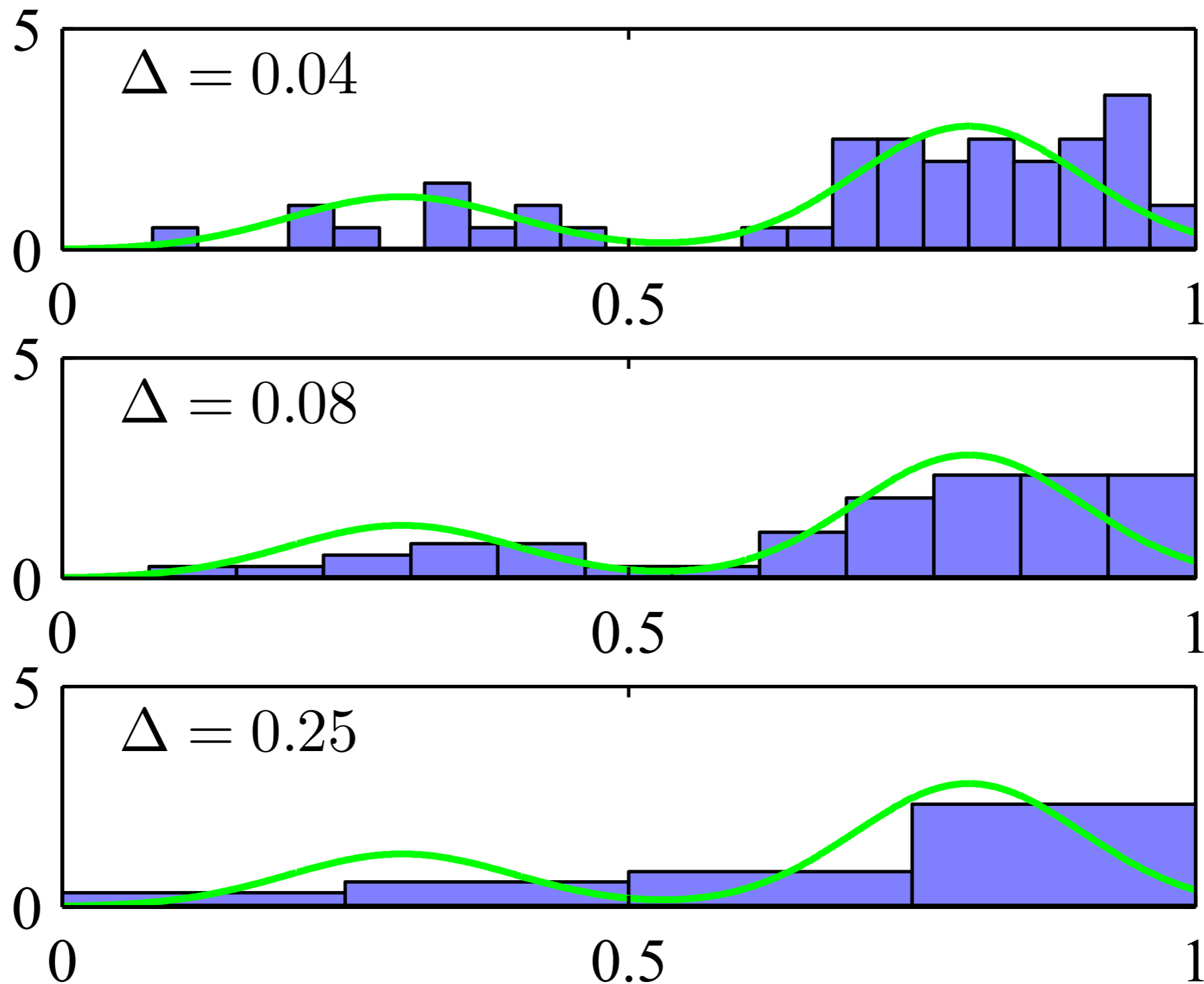
0 1 2

$\bar{\Delta}$

Bin Count

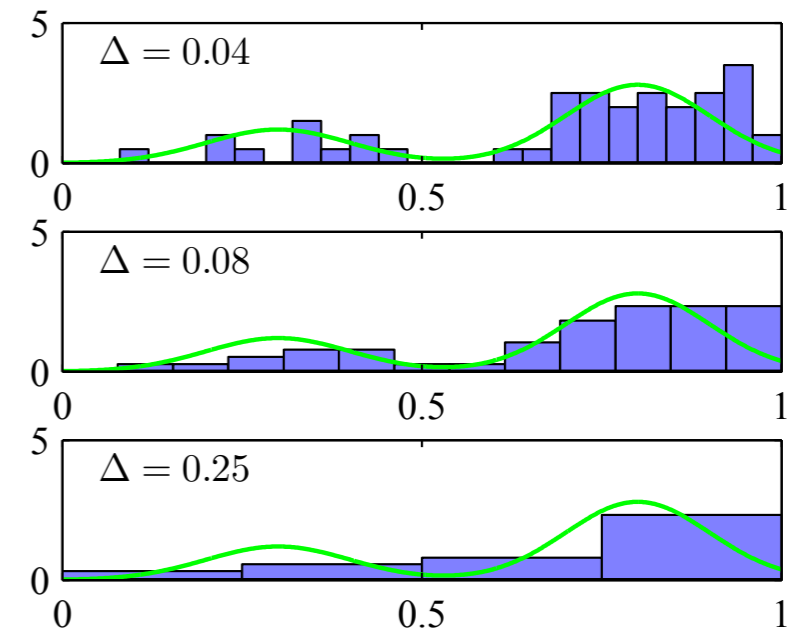
3 6 7

# Histogram Density as a Function of Bin Width



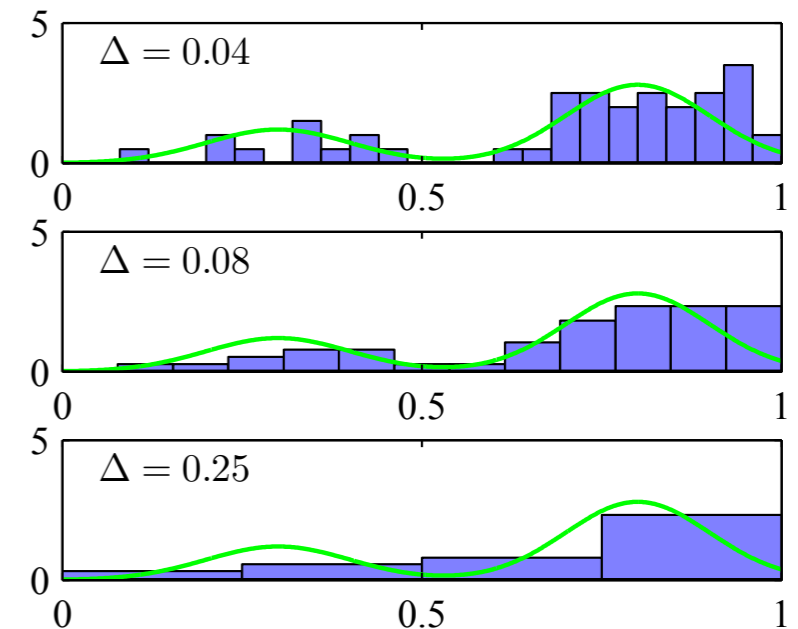
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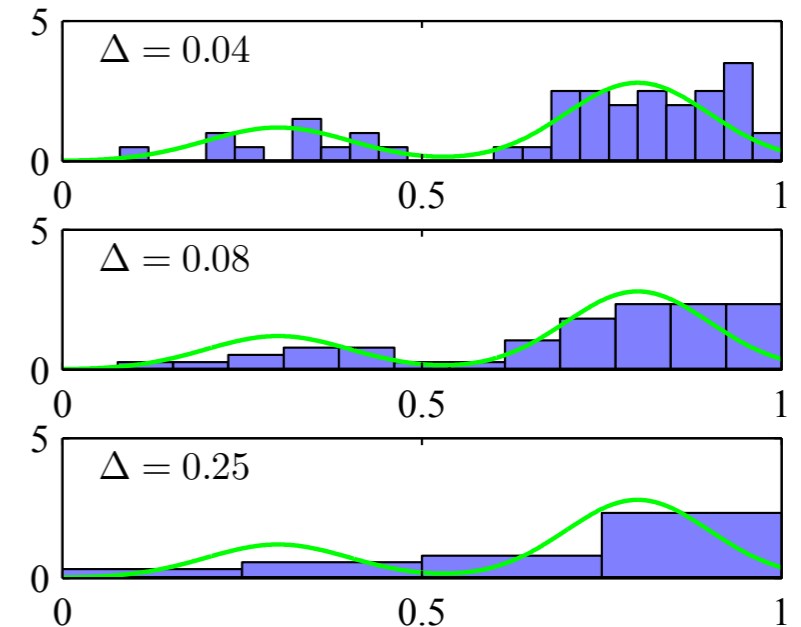
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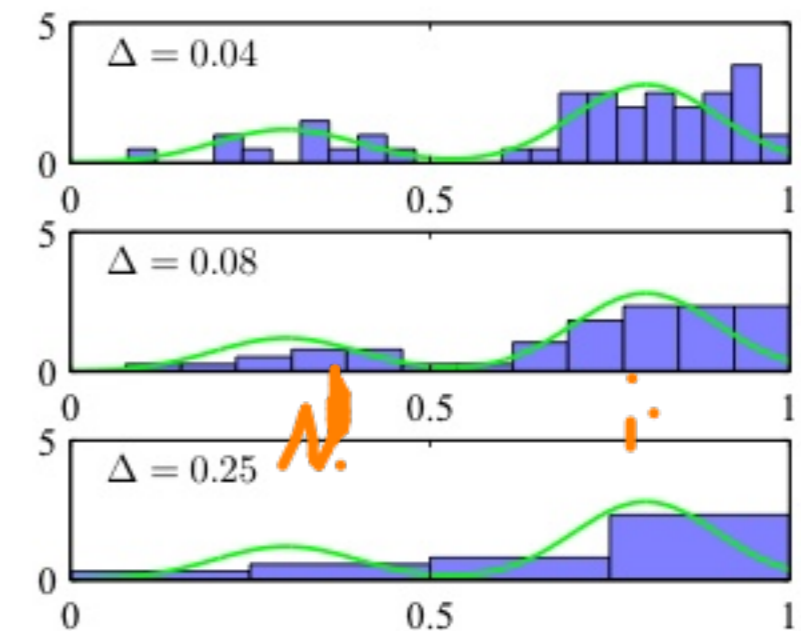
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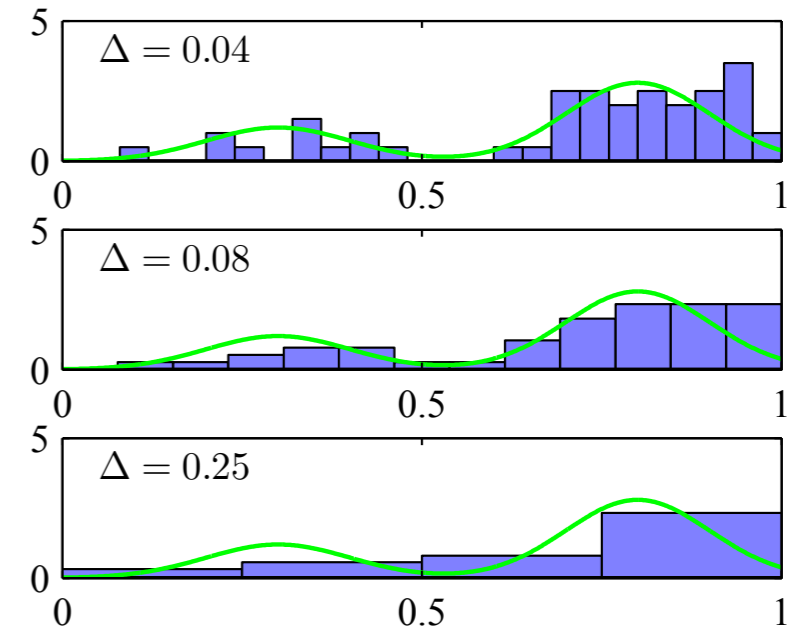
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- It appears that the *best results* are obtained for some intermediate value of  $\Delta$ , which is given in the middle figure.
- In principle, a histogram density model is also dependent on the choice of the edge location of each bin.



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  - Can be computed sequentially if data continues to come in.
- Disadvantages:
  - The estimated density has discontinuities due to the bin edges rather than any property of the underlying density.
  - Scales poorly (curse of dimensionality): we would have  $M^D$  bins if we divided each variable in a  $D$ -dimensional space into  $M$  bins.



# What can we learn from Histogram Density Estimation?

- Lesson 1: To estimate the probability density at a particular location, we should consider the data points that lie within some local neighborhood of that point.
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- With these two lessons in mind, we proceed to kernel density estimation and nearest neighbor density estimation, two closely related methods for density estimation.



# The Space-Averaged / Smoothed Density

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- How will the total number of  $k$  points falling into  $\mathcal{R}$  be distributed?
- This will be a **binomial distribution**:

$$P_k = \binom{n}{k} P^k (1 - P)^{n-k} \quad (3)$$

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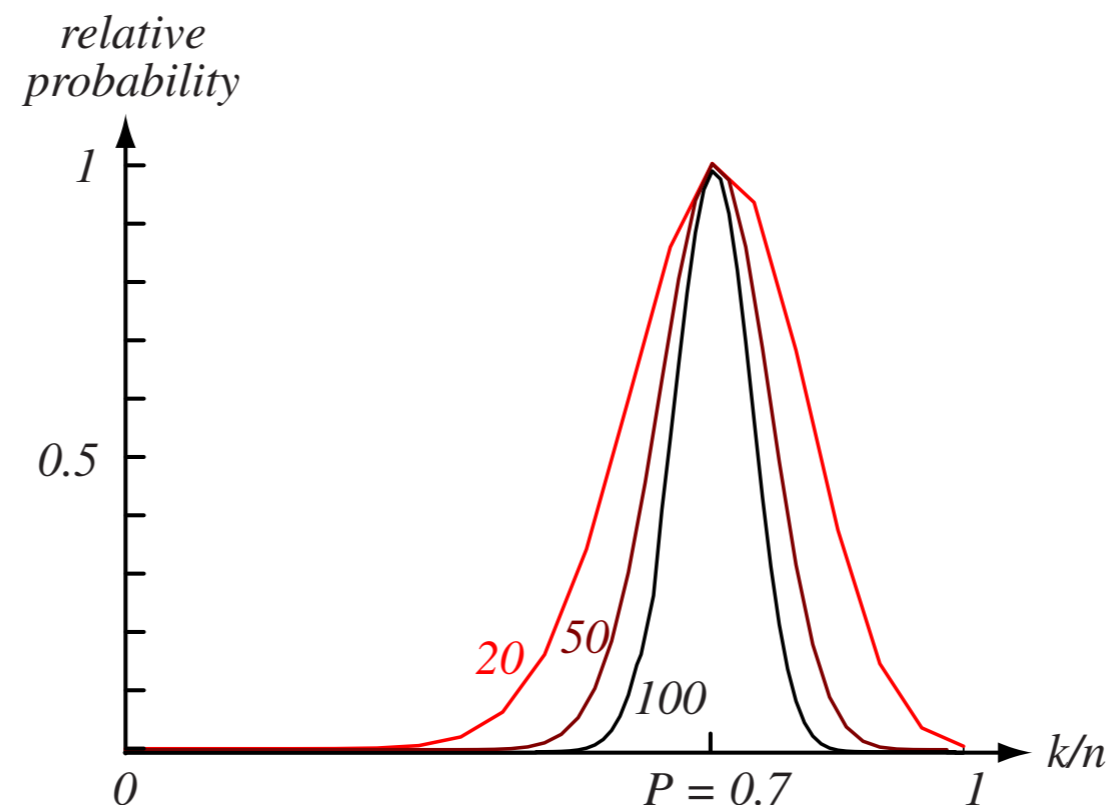
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- This estimate is increasingly accurate as  $n$  increases.



# The Space-Averaged / Smoothed Density

- Assuming continuous  $p(\mathbf{x})$  and that  $\mathcal{R}$  is so small that  $p(\mathbf{x})$  does not appreciably vary within it, we can write:

$$\int_{\mathcal{R}} p(\mathbf{x}') d\mathbf{x}' \simeq p(\mathbf{x})V \quad (5)$$

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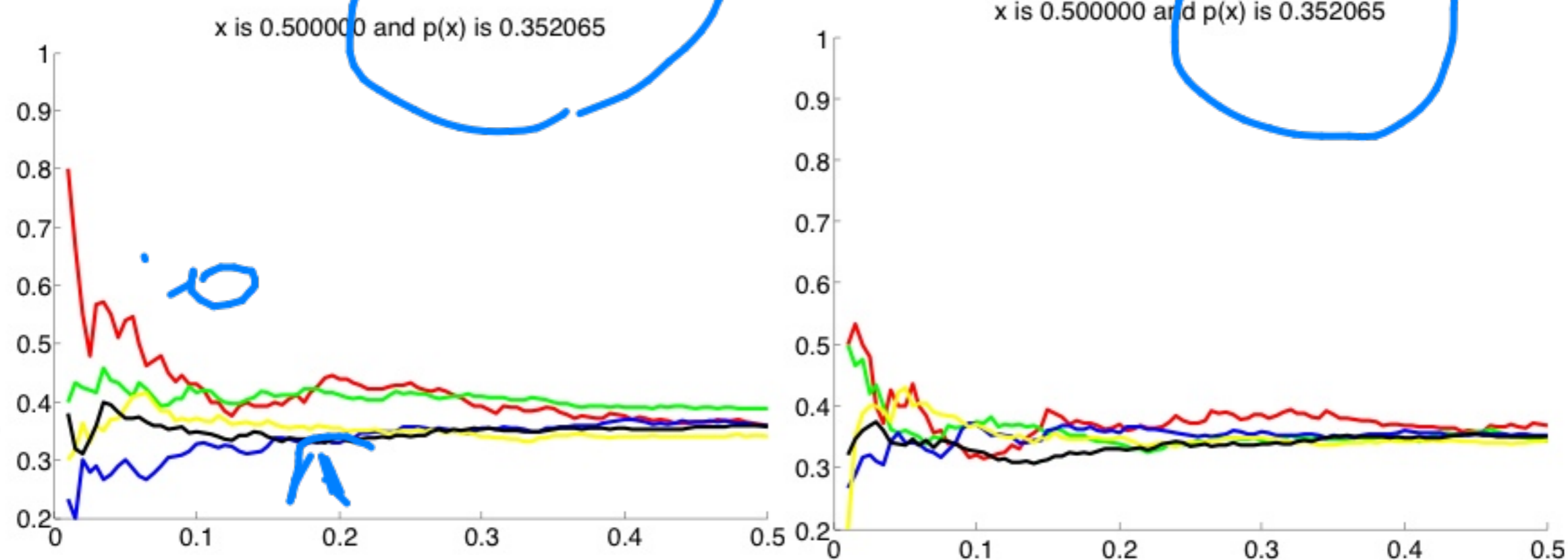
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- After some rearranging, we get the following estimate for  $p(\mathbf{x})$

$$p(\mathbf{x}) \simeq \frac{k}{nV} \quad (6)$$

# Example

- Simulated an example of example the density at 0.5 for an underlying zero-mean, unit variance Gaussian.
- Varied the volume used to estimate the density.
- Red=1000, Green=2000, Blue=3000, Yellow=4000, Black=5000.



# Practical Concerns

- The validity of our estimate depends on two contradictory assumptions:
  - 1 The region  $\mathcal{R}$  must be sufficiently small the the density is approximately constant over the region.
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- Note that in practice, we cannot let  $V$  to become arbitrarily small because the number of samples is always limited.

How can we skirt these limitations when an unlimited number of samples is available?

- To estimate the density at  $\mathbf{x}$ , form a sequence of regions  $\mathcal{R}_1, \mathcal{R}_2, \dots$  containing  $\mathbf{x}$  with the  $\mathcal{R}_1$  having 1 sample,  $\mathcal{R}_2$  having 2 samples and so on.

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- Let  $V_n$  be the volume of  $\mathcal{R}_n$ ,  $k_n$  be the number of samples falling in  $\mathcal{R}_n$ , and  $p_n(\mathbf{x})$  be the  $n$ th estimate for  $p(\mathbf{x})$ :

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$$p_n(\mathbf{x}) = \frac{k_n}{nV_n} \quad (7)$$

- If  $p_n(\mathbf{x})$  is to converge to  $p(\mathbf{x})$  we need the following three conditions

$$\lim_{n \rightarrow \infty} V_n = 0 \quad (8)$$

$$\lim_{n \rightarrow \infty} k_n = \infty \quad (9)$$

$$\lim_{n \rightarrow \infty} k_n/n = 0 \quad (10)$$

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Both of these methods converge...



