Introducing Latent Variables

• Define a K-dimensional binary random variable z.

▲□▶▲□▶▲≡▶▲≡▶ ∮□▶ ∮ ◎ ♀ ()

Introducing Latent Variables

- Define a K-dimensional binary random variable z.
- z has a 1-of-K representation such that a particular element z_k is 1 and all of the others are zero. Hence:

$$z_k \in \{0, 1\}$$
 (6)
 $\sum_k z_k = 1$ (7)

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Introducing Latent Variables

- Define a K-dimensional binary random variable z.
- z has a 1-of-K representation such that a particular element z_k is 1 and all of the others are zero. Hence:

$$z_k \in \{0, 1\}$$
 (6)
 $\sum_k z_k = 1$ (7)

 The marginal distribution over z is specified in terms of the mixing coefficients:

And, recall,
$$0 \le \pi_k \le 1$$
 and $\sum_k \pi_k = 1$.
(8)
Corso (SUNY at Buffalo)
Clustering / Unsupervised Methods

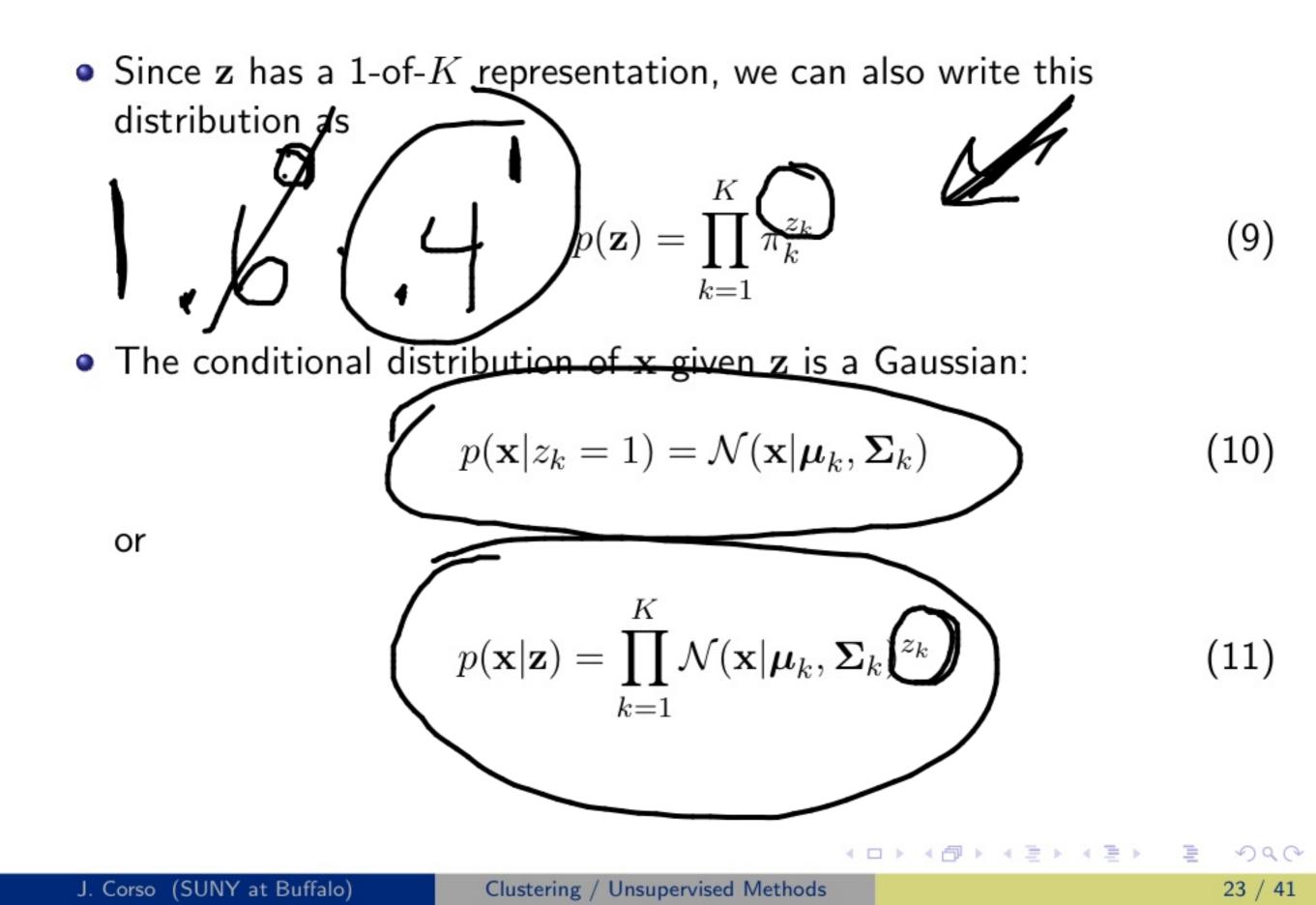
 Since z has a 1-of-K representation, we can also write this distribution as

$$p(\mathbf{z}) = \prod_{k=1}^{K} \pi_k^{z_k}$$

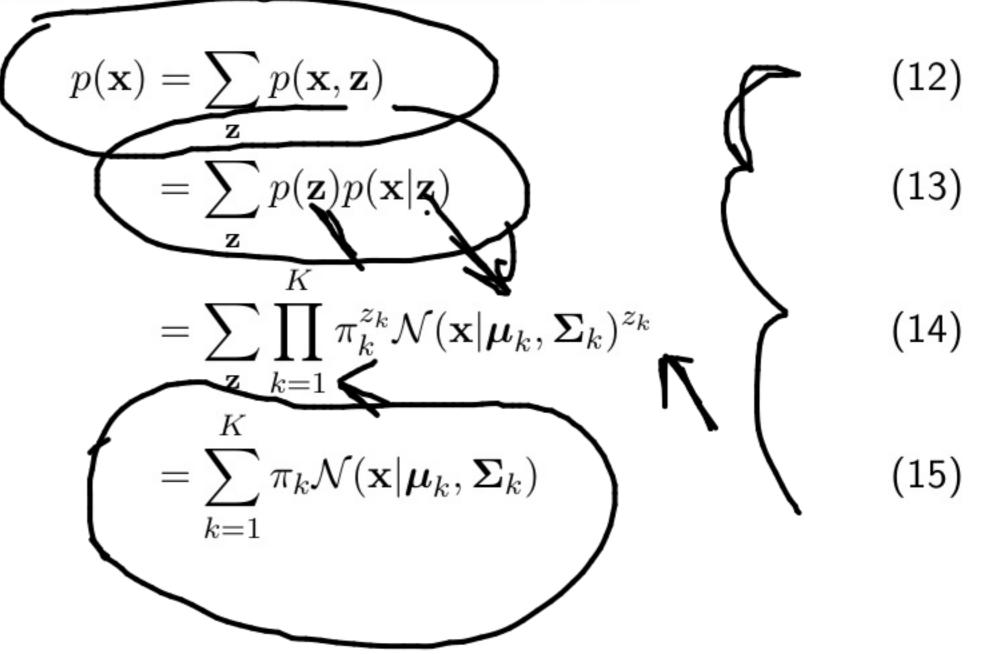
DQC

1

(9)



• We are interested in the marginal distribution of x:



DQC

1

- 4 回 ト - 4 回 ト

< 🗆 🕨

• We are interested in the marginal distribution of **x**:

p

$$(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z})$$
(12)
$$= \sum_{\mathbf{z}} p(\mathbf{z}) p(\mathbf{x} | \mathbf{z})$$
(13)
$$= \sum_{\mathbf{z}} \prod_{k=1}^{K} \pi_{k}^{z_{k}} \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})^{z_{k}}$$
(14)
$$= \sum_{k=1}^{K} \pi_{k} \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})$$
(15)

 So, given our latent variable z, the marginal distribution of x is a Gaussian mixture.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

• We are interested in the marginal distribution of **x**:

p

$$(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z})$$
(12)
$$= \sum_{\mathbf{z}} p(\mathbf{z}) p(\mathbf{x} | \mathbf{z})$$
(13)
$$= \sum_{\mathbf{z}} \prod_{k=1}^{K} \pi_{k}^{z_{k}} \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})^{z_{k}}$$
(14)
$$= \sum_{k=1}^{K} \pi_{k} \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k})$$
(15)

- So, given our latent variable z, the marginal distribution of x is a Gaussian mixture.
- If we have N observations $\mathbf{x}_1, \ldots, \mathbf{x}_N$, then because of our chosen representation, it follows that we have a latent variable \mathbf{z}_n for each observed data point \mathbf{x}_n .

 \bullet We need to also express the conditional probability of z given x.

<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

- We need to also express the conditional probability of z given x.
- Denote this conditional $p(z_k = 1 | \mathbf{x})$ as $\gamma(z_k)$.

DQC

-

< 🗆 🕨

- We need to also express the conditional probability of z given x.
- Denote this conditional $p(z_k = 1 | \mathbf{x})$ as $\gamma(z_k)$ We can derive this value with Bayes' theorem:

$$(\gamma(z_k)) \doteq p(z_k = 1 | \mathbf{x}) = \frac{p(z_k = 1)p(\mathbf{x} | z_k = 1)}{\sum_{j=1}^{K} p(z_j = 1)p(\mathbf{x} | z_j = 1)} .$$

$$(16)$$

$$(16)$$

$$(17)$$

$$(17)$$

$$(17)$$

DQA

- \bullet We need to also express the conditional probability of z given $\mathbf{x}.$
- Denote this conditional $p(z_k = 1 | \mathbf{x})$ as $\gamma(z_k)$.
- We can derive this value with Bayes' theorem:

$$\gamma(z_k) \doteq p(z_k = 1 | \mathbf{x}) = \frac{p(z_k = 1)p(\mathbf{x} | z_k = 1)}{\sum_{j=1}^{K} p(z_j = 1)p(\mathbf{x} | z_j = 1)}$$
(16)
$$= \frac{\pi_k \sqrt{(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}}{\sum_{j=1}^{K} \pi_j \sqrt{(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}}$$
(17)

 View π_k as the prior probability of z_k = 1 and the quantity γ(z_k) as the corresponding posterior probability once we have observed x.

イロト (部) (注) (注) (注) (の)

- \bullet We need to also express the conditional probability of z given $\mathbf{x}.$
- Denote this conditional $p(z_k = 1 | \mathbf{x})$ as $\gamma(z_k)$.
- We can derive this value with Bayes' theorem:

$$\gamma(z_k) \doteq p(z_k = 1 | \mathbf{x}) = \frac{p(z_k = 1)p(\mathbf{x} | z_k = 1)}{\sum_{j=1}^{K} p(z_j = 1)p(\mathbf{x} | z_j = 1)}$$
(16)
$$= \frac{\pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^{K} \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$
(17)

- View π_k as the prior probability of $z_k = 1$ and the quantity $\gamma(z_k)$ as the corresponding posterior probability once we have observed \mathbf{x} .
- γ(z_k) can also be viewed as the responsibility that component k takes
 for explaining the observation x.

<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Sampling from the GMM

• To sample from the GMM, we can first generate a value for z from the marginal distribution $p(\mathbf{z})$. Denote this sample $\hat{\mathbf{z}}$.

< □ ▶ < □ ▶ < 三 ▶ < 三 ▶ < 三 • りへ ○

Sampling from the GMM

- To sample from the GMM, we can first generate a value for z from the marginal distribution $p(\mathbf{z})$. Denote this sample $\hat{\mathbf{z}}$.
- Then, sample from the conditional distribution $p(\mathbf{x}|\hat{\mathbf{z}})$.

< □ ▶ < □ ▶ < 三 ▶ < 三 ▶ < 三 ⑦ < ?

Sampling

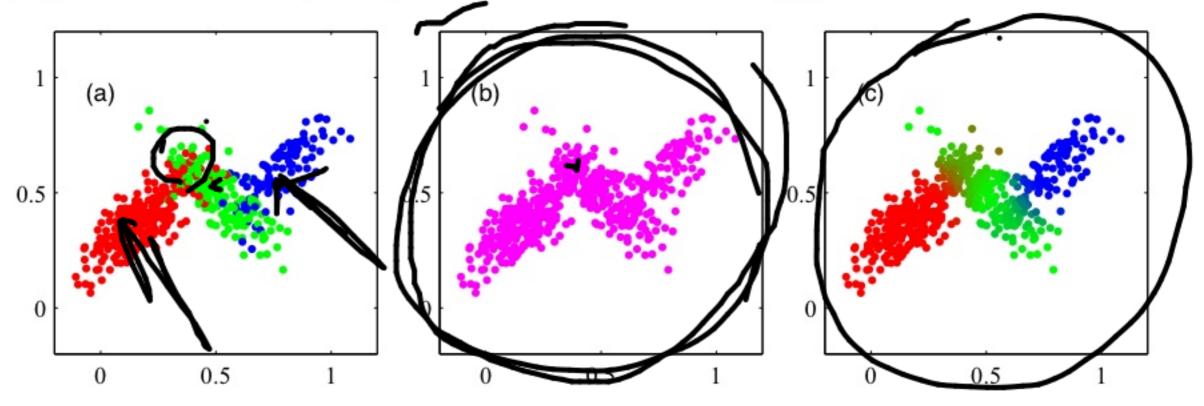
Sampling from the GMM

- To sample from the GMM, we can first generate a value for z from the marginal distribution $p(\mathbf{z})$. Denote this sample $\hat{\mathbf{z}}$.
- Then, sample from the conditional distribution $p(\mathbf{x}|\hat{\mathbf{z}})$.
- The figure below-left shows samples from a three-mixture and colors the samples based on their z. The figure below-middle shows samples from the marginal $p(\mathbf{x})$ and ignores \mathbf{z} . On the right, we show the $\gamma(z_k)$ for each sampled point, colored accordingly.

◆□▶ ◆□▶ ▲三▶ ▲三▶ 三 ∽) ◇ (~)

Sampling from the GMM

- To sample from the GMM, we can first generate a value for z from the marginal distribution p(z). Denote this sample \hat{z} .
- Then, sample from the conditional distribution $p(\mathbf{x}|\hat{\mathbf{z}})$.
- The figure below-left shows samples from a three mixture and colors the samples based on their z. The figure below-middle shows samples from the marginal p(x) and ignores z. On the right, we show the γ(z_k) for each sampled point, colored accordingly.



DQQ

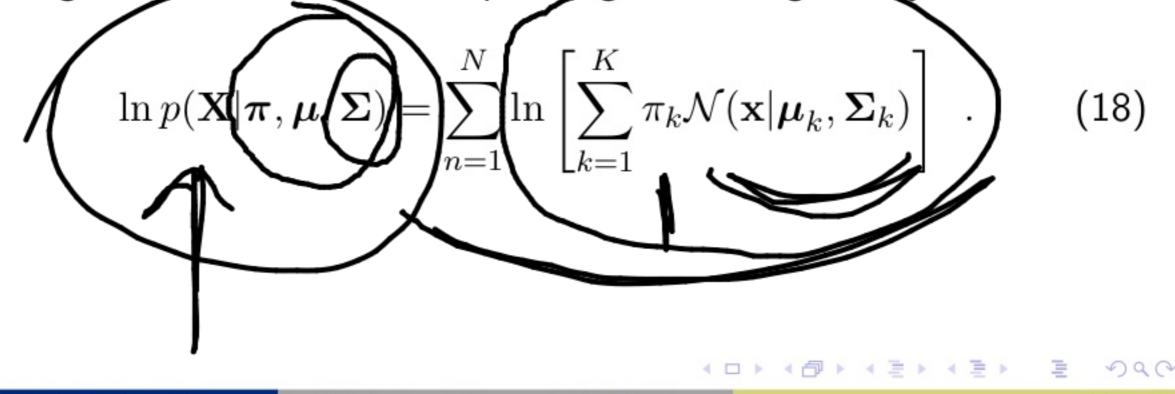
• Suppose we have a set of N i.i.d. observations $\{x_1, \ldots, x_N\}$ that we wish to model with a GMM.

◆□▶ ◆□▶ ◆ 三▶ ◆ 三 ● のへぐ

- Suppose we have a set of N i.i.d. observations {x₁,..., x_N} that we wish to model with a GMM.
- Consider this data set as an N × d matrix X in which the nth row is given by x_n^T.

- Suppose we have a set of N i.i.d. observations $\{x_1, \ldots, x_N\}$ that we wish to model with a GMM.
- Consider this data set as an $N \times d$ matrix **X** in which the n^{th} row is given by $\mathbf{x}_n^{\mathsf{T}}$.
- Similarly, the corresponding latent variables define an $N \times K$ matrix \mathbf{Z} with rows $\mathbf{z}_n^{\mathsf{T}}$.

- Suppose we have a set of N i.i.d. observations {x₁,..., x_N} that we wish to model with a GMM.
- Consider this data set as an N × d matrix X in which the nth row is given by x_n^T.
- Similarly, the corresponding latent variables define an N × K matrix
 Z with rows z_n^T.
- The log-likelihood of the corresponding GMM is given by



- Suppose we have a set of N i.i.d. observations $\{\mathbf{x}_1, \ldots, \mathbf{x}_N\}$ that we wish to model with a GMM.
- Consider this data set as an $N \times d$ matrix **X** in which the n^{th} row is given by $\mathbf{x}_n^{\mathsf{T}}$.
- Similarly, the corresponding latent variables define an $N \times K$ matrix **Z** with rows $\mathbf{z}_n^{\mathsf{T}}$.
- The log-likelihood of the corresponding GMM is given by

$$\ln p(\mathbf{X}|\boldsymbol{\pi},\boldsymbol{\mu},\boldsymbol{\Sigma}) = \sum_{n=1}^{N} \ln \left(\sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k,\boldsymbol{\Sigma}_k) \right).$$
(18)
• Ultimately, we want to find the values of the parameter $\boldsymbol{\pi},\boldsymbol{\mu},\boldsymbol{\Sigma}$ that maximize this function.

m

• However, maximizing the log-likelihood terms for GMMs is much more complicated than for the case of a single Gaussian. Why?

 $\checkmark Q (~$

<ロト < 団ト < 巨ト < 巨ト = 巨

- However, maximizing the log-likelihood terms for GMMs is much more complicated than for the case of a single Gaussian. Why?
- The difficulty arises from the sum over k inside of the log-term. The log function no longer acts directly on the Gaussian, and no closed-form solution is available.

 $\checkmark Q (~$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■

• There is a significant problem when we apply MLE to estimate GMM parameters.

▲□▶▲□▶▲□▶▲□▶ ■ のへで

- There is a significant problem when we apply MLE to estimate GMM parameters.
- Consider simply covariances defined by $\Sigma_k = \sigma_k^2 \mathbf{I}$.

▲□▶▲□▶▲≡▶▲≡▶ ● ● ● ●

- There is a significant problem when we apply MLE to estimate GMM parameters.
- Consider simply covariances defined by $\Sigma_k = \sigma_k^2 \mathbf{I}$.
- Suppose that one of the components of the mixture model, j, has its mean μ_j exactly equal to one of the data points so that $\mu_j = \mathbf{x}_n$ for some n.

< □ ▶ < □ ▶ < 三 ▶ < 三 ▶ < 三 • りへ ○

- There is a significant problem when we apply MLE to estimate GMM parameters.
- Consider simply covariances defined by $\Sigma_k = \sigma_k^2 \mathbf{I}$.
- Suppose that one of the components of the mixture model, j, has its mean μ_j exactly equal to one of the data points so that $\mu_j = \mathbf{x}_n$ for some n.
- This term contributes

$$\mathcal{N}(\mathbf{x}_n | \mathbf{x}_n, \sigma_j^2 \mathbf{I}) = \frac{1}{(2\pi)^{(1/2)} \sigma_j}$$
(19)

< □ ▶ < □ ▶ < 三 ▶ < 三 ▶ = のへ ○

- There is a significant problem when we apply MLE to estimate GMM parameters.
- Consider simply covariances defined by $\Sigma_k = \sigma_k^2 \mathbf{I}$.
- Suppose that one of the components of the mixture model, j, has its mean μ_j exactly equal to one of the data points so that $\mu_j = \mathbf{x}_n$ for some n.
- This term contributes

$$\mathcal{N}(\mathbf{x}_n | \mathbf{x}_n, \sigma_j^2 \mathbf{I}) = \frac{1}{(2\pi)^{(1/2)} \sigma_j}$$
(19)

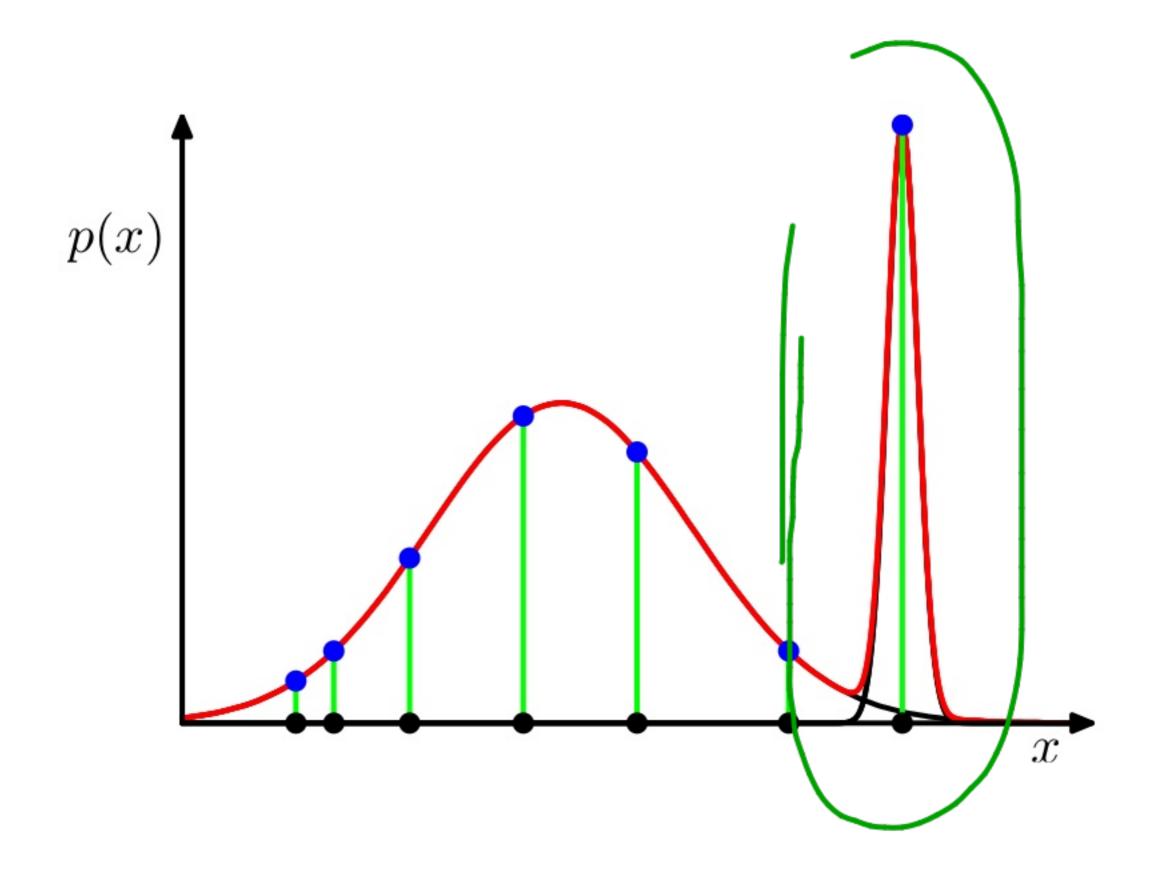
• Consider the limit $\sigma_j \rightarrow 0$ to see that this term goes to infinity and hence the log-likelihood will also go to infinity.

< □ ▶ < □ ▶ < 三 ▶ < 三 ▶ < 三 り < ○

- There is a significant problem when we apply MLE to estimate GMM parameters.
- Consider simply covariances defined by $\Sigma_k = \sigma_k^2 \mathbf{I}$.
- Suppose that one of the components of the mixture model, j, has its mean µ_j exactly equal to one of the data points so that µ_j = x_n for some n.
- This term contributes

$$\mathcal{N}(\mathbf{x}_n | \mathbf{x}_n, \sigma_j^2 \mathbf{I}) = \frac{1}{(2\pi)^{(1/2)} \sigma_j}$$
(19)

- Consider the limit σ_j → 0 to see that this term goes to infinity and hence the log-likelihood will also go to infinity.
- Thus, the maximization of the log-likelihood function is not a well posed problem because such a singularity will occur whenever one of the components collapses to a single, specific data point.



DQC

▲ロ ▶ ▲圖 ▶ ▲ 圖 ▶ ▲ 圖 ▶ ■

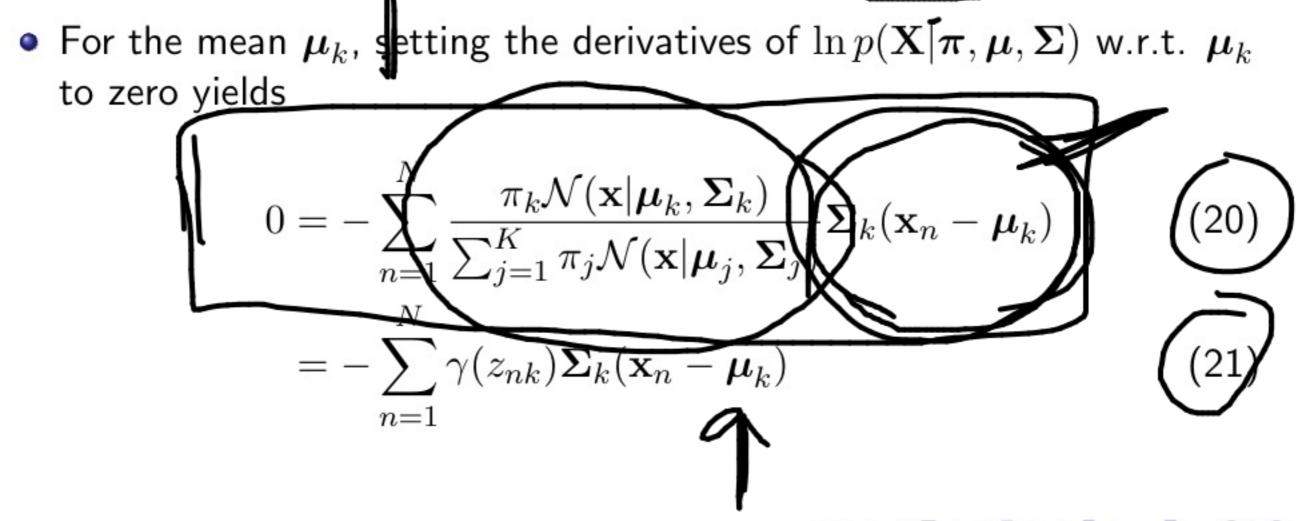
• Expectation-Maximization or EM is an elegant and powerful method for finding MLE solutions in the case of missing data such as the latent variables z indicating the mixture component.

 $\checkmark \land \land \land \land$

- Expectation-Maximization or EM is an elegant and powerful method for finding MLE solutions in the case of missing data such as the latent variables z indicating the mixture component.
- Recall the conditions that must be satisfied at a maximum of the likelihood function.

 $\checkmark \land \land \land$

- Expectation-Maximization or EM is an elegant and powerful method for finding MLE solutions in the case of missing data such as the latent variables z indicating the mixture component.
- Recall the conditions that must be satisfied at a maximum of the likelihood function.

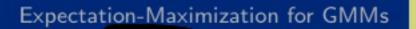


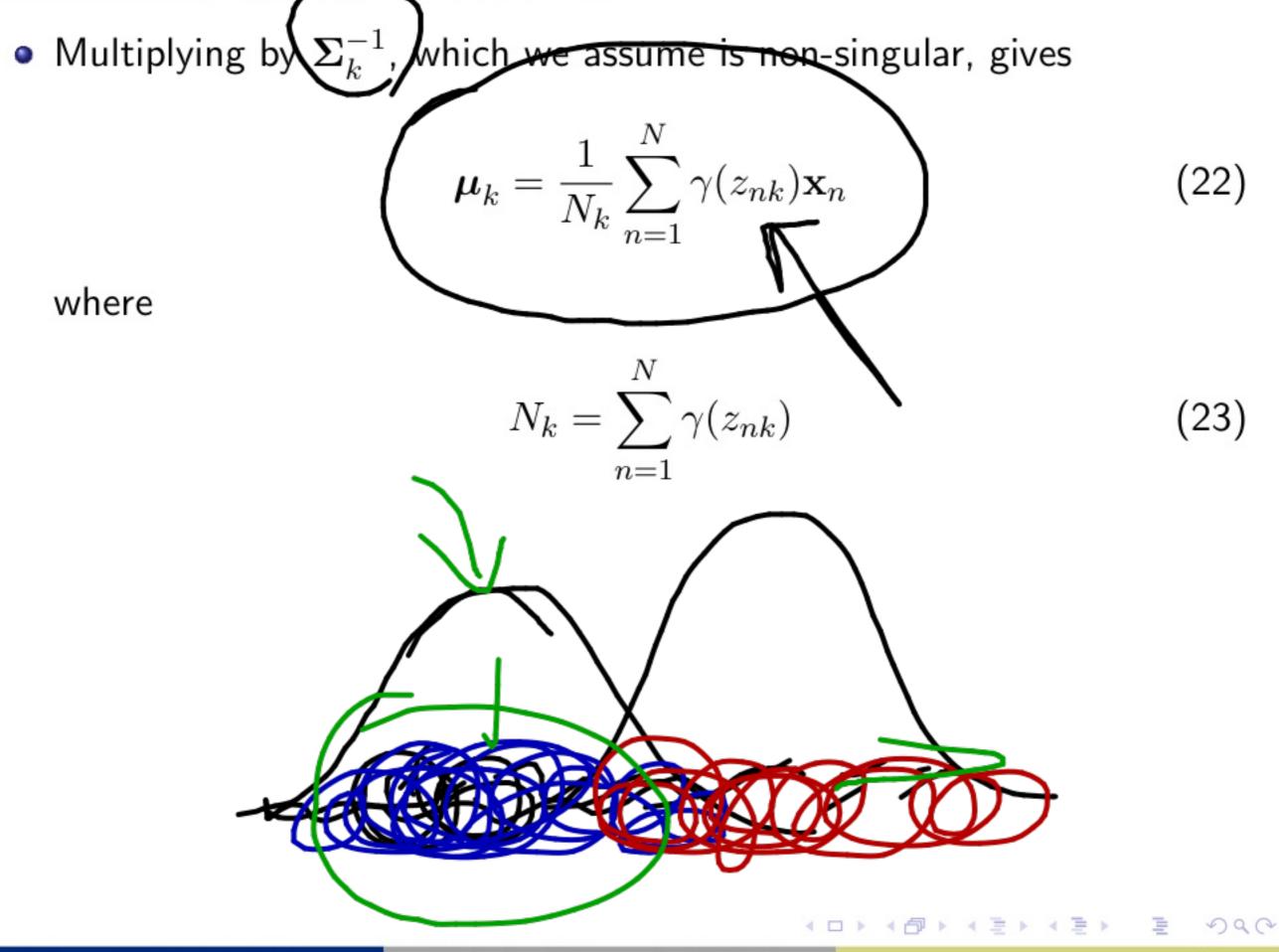
DQA

- Expectation-Maximization or EM is an elegant and powerful method for finding MLE solutions in the case of missing data such as the latent variables z indicating the mixture component.
- Recall the conditions that must be satisfied at a maximum of the likelihood function.
- For the mean μ_k , setting the derivatives of $\ln p(\mathbf{X}| \pi, \mu, \Sigma)$ w.r.t. μ_k to zero yields

$$0 = -\sum_{n=1}^{N} \frac{\pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^{K} \pi_j \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)} \boldsymbol{\Sigma}_k(\mathbf{x}_n - \boldsymbol{\mu}_k)$$
(20)
$$= -\sum_{n=1}^{N} \gamma(z_{nk}) \boldsymbol{\Sigma}_k(\mathbf{x}_n - \boldsymbol{\mu}_k)$$
(21)

Note the natural appearance of the responsibility terms on the RHS.





J. Corso (SUNY at Buffalo)

32 / 41

• Multiplying by $\mathbf{\Sigma}_k^{-1}$, which we assume is non-singular, gives

$$\boldsymbol{\mu}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) \mathbf{x}_{n}$$

where

$$N_k = \sum_{n=1}^N \gamma(z_{nk}) \tag{23}$$

 We see the kth mean is the weighted mean over all of the points in the dataset.

▲□▶▲□▶▲□▶▲□▶ □ りへ⊙

(22)

• Multiplying by $\mathbf{\Sigma}_k^{-1}$, which we assume is non-singular, gives

$$\boldsymbol{\mu}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) \mathbf{x}_{n}$$
(22)

where

$$N_k = \sum_{n=1}^N \gamma(z_{nk}) \tag{23}$$

- We see the k^{th} mean is the weighted mean over all of the points in the dataset.
- Interpret N_k as the number of points assigned to component k.

32 / 41

▲□▶▲□▶▲≡▶▲≡▶ ● ● のへで

• Multiplying by $\mathbf{\Sigma}_k^{-1}$, which we assume is non-singular, gives

$$\boldsymbol{\mu}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) \mathbf{x}_{n}$$
(22)



 We see the kth mean is the weighted mean over all of the points in the dataset.

 $N_k = \sum_{n=1}^N \gamma(z_{nk})$

- > Interpret N_k as the number of points assigned to component k.
 - We find a similar result for the cogariance matrix:

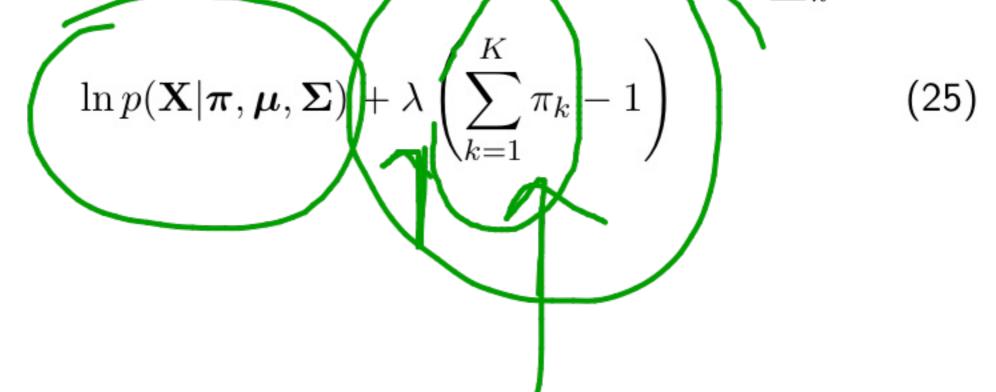
$$\boldsymbol{\Sigma}_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) (\boldsymbol{x}_{n} - \boldsymbol{\mu}_{k}) (\boldsymbol{x}_{n} - \boldsymbol{\mu}_{k})^{\mathsf{T}}$$
(24)

23)

• We also need to maximize $\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ with respect to the mixing coefficients π_k .

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三 のへで

- We also need to maximize ln p(X|π, μ, Σ) with respect to the mixing coefficients π_k.
- Introduce a Lagrange multiplier to enforce the constraint $\sum_k \pi_k = 1$.



DQA

- We also need to maximize $\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ with respect to the mixing coefficients π_k .
- Introduce a Lagrange multiplier to enforce the constraint $\sum_k \pi_k = 1$.

$$\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) + \lambda \left(\sum_{k=1}^{K} \pi_k - 1\right)$$
(25)

• Maximizing it yields:

$$0 = \frac{1}{N_k} \sum_{n=1}^{\infty} \gamma(z_{nk}) + \lambda$$
(26)

< □ ▶ < □ ▶ < 三 ▶ < 三 ▶ < 三 • りへ ?

- We also need to maximize $\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ with respect to the mixing coefficients π_k .
- Introduce a Lagrange multiplier to enforce the constraint $\sum_k \pi_k = 1$.

$$\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) + \lambda \left(\sum_{k=1}^{K} \pi_k - 1\right)$$
(25)

• Maximizing it yields:

$$0 = \frac{1}{N_k} \sum_{n=1}^{\infty} \gamma(z_{nk}) + \lambda$$
(26)

• After multiplying both sides by π and summing over k, we get

$$\lambda = -N \tag{27}$$

◆□▶ ◆□▶ ◆ ≧▶ ◆ ≧ → ⑦ < ??

- We also need to maximize ln p(X|π, μ, Σ) with respect to the mixing coefficients π_k.
- Introduce a Lagrange multiplier to enforce the constraint $\sum_k \pi_k = 1$.

$$\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) + \lambda \left(\sum_{k=1}^{K} \pi_k - 1\right)$$
(25)

Maximizing it yields:

$$0 = \frac{1}{N_k} \sum_{n=1}^{\infty} \gamma(z_{nk}) + \lambda$$
(26)

• After multiplying both sides by π and summing over k, we get

$$\lambda = -N \tag{27}$$

• Eliminate λ and rearrange to obtain: $\pi_{k} = N_{k} \qquad (28)$ J. Corso (SUNY at Buffalo)
Clustering / Unsupervised Methods 33 / 41

 So, we're done, right? We've computed the maximum likelihood solutions for each of the unknown parameters.

 $\mathcal{A} \subset \mathcal{A}$

E

- So, we're done, right? We've computed the maximum likelihood solutions for each of the unknown parameters.
- Wrong!

 $\mathcal{A} \subset \mathcal{A}$

◆□▶ ◆□▶ ◆≧▶ ◆≧▶

- So, we're done, right? We've computed the maximum likelihood solutions for each of the unknown parameters.
- Wrong!
- The responsibility terms depend on these parameters in an intricate way:

$$\gamma(z_k) \doteq p(z_k = 1 | \mathbf{x}) = \frac{\pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

 $\checkmark Q (~$

3

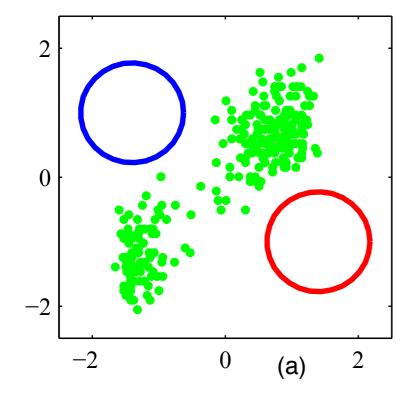
▲□▶ ▲□▶ ▲□▶ ▲□▶

- So, we're done, right? We've computed the maximum likelihood solutions for each of the unknown parameters.
- Wrong!
- The responsibility terms depend on these parameters in an intricate way:

$$\gamma(z_k) \doteq p(z_k = 1 | \mathbf{x}) = \frac{\pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

- But, these results do suggest an iterative scheme for finding a solution to the maximum likelihood problem.
 - **①** Chooce some initial values for the parameters, $m{\pi}, m{\mu}, m{\Sigma}$.
 - Our contract of the set of the
 - Output the second se
 - Bepeat 2 and 3 until convergence.

◆□▶ ◆□▶ ▲三▶ ▲三▶ 三 ∽) ◇ (~)



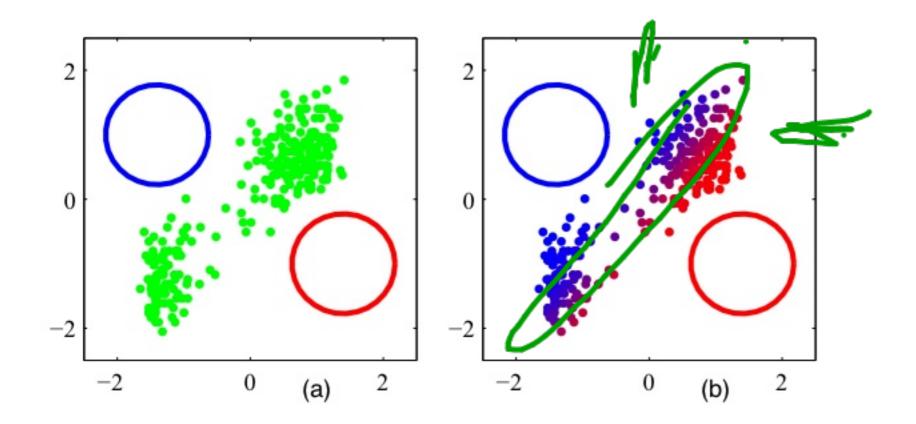
35 / 41

 $\mathcal{O} \mathcal{Q} (\mathcal{P})$

E.

< ロ ト < 四 ト < 三 ト < 三 ト</p>

Expectation-Maximization for GMMs



・ロッ ・ロッ・ ・ ヨッ

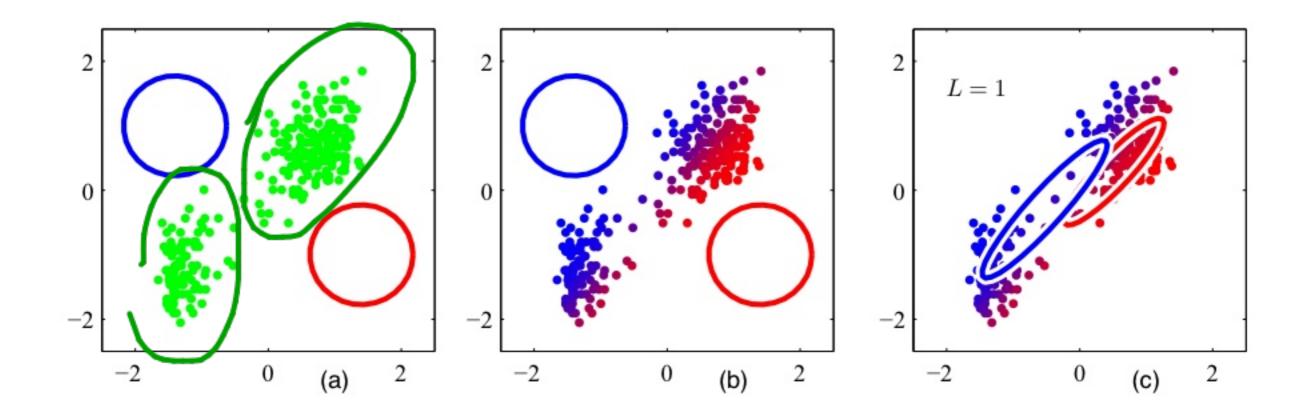
35 / 41

DQC

E

< ∃>

Expectation-Maximization for GMMs



DQC

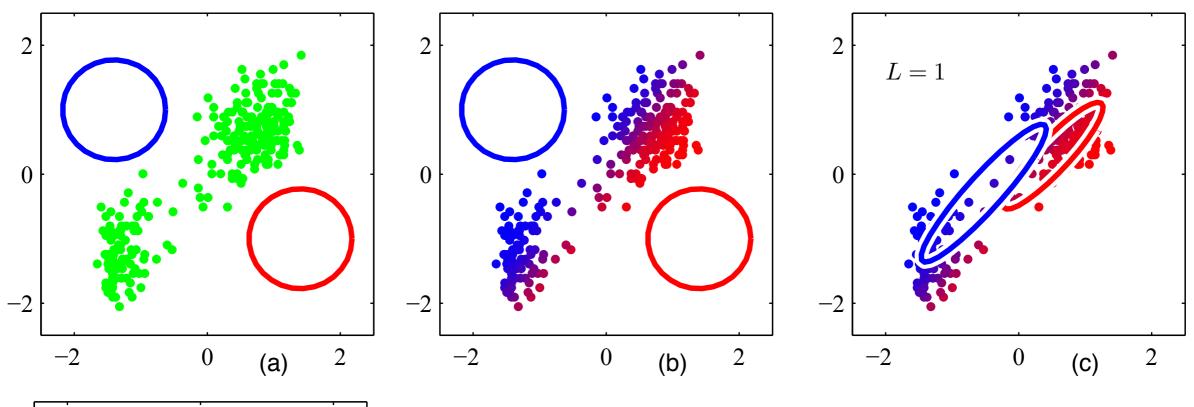
Đ.

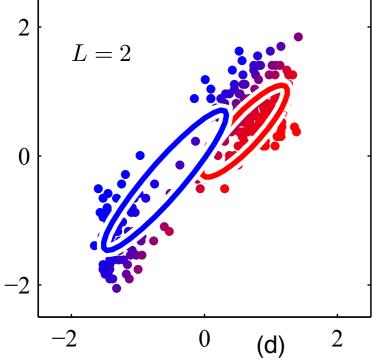
< ∃ >

.∃ →

 $\langle \Box \rangle \langle \Box \rangle \langle \langle \Box \rangle \rangle \langle \langle \Box \rangle \rangle$

Expectation-Maximization for GMMs





J. Corso (SUNY at Buffalo)

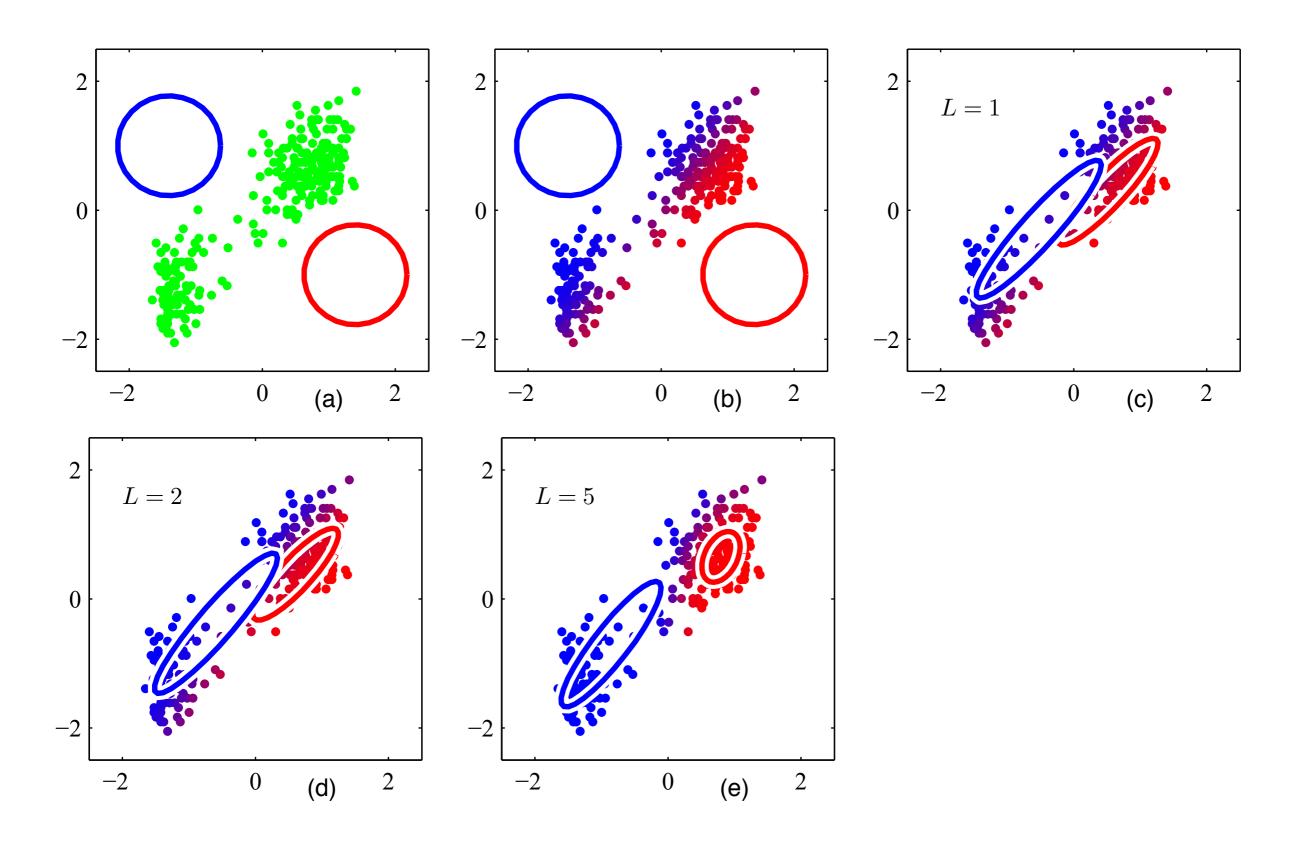
 $\mathcal{O} \mathcal{Q} \mathcal{O}$

Ð,

· ∢ Ē ▶

< □ > < @ > < ≧ >

Expectation-Maximization for GMMs



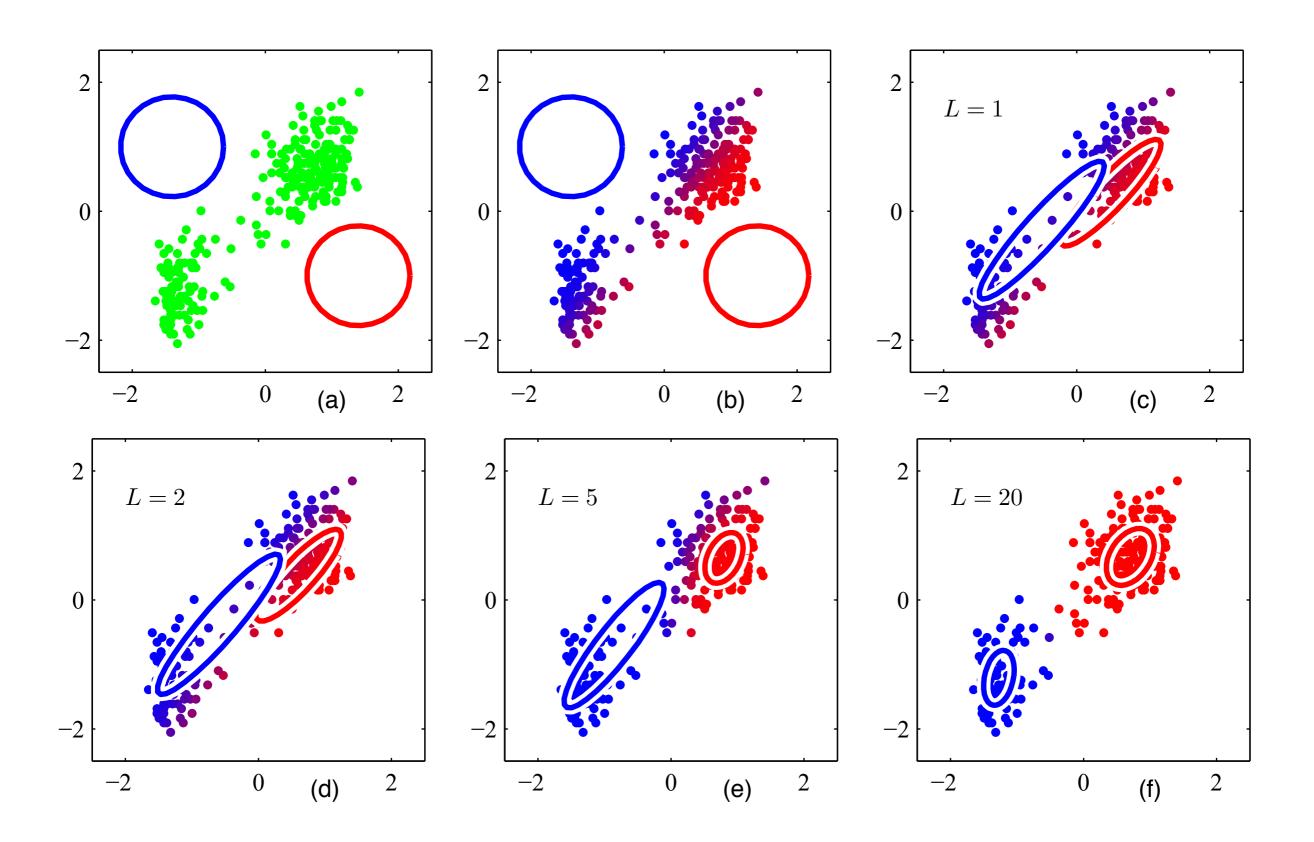
< ロ > < 回 > < 三 >

 $\mathcal{O}Q(\mathcal{P})$

Ē

- ₹ ₹ >

Expectation-Maximization for GMMs



< ロ > < 回 > < 三 >

 $\mathcal{O} \mathcal{Q} \mathcal{O}$

E

- ₹ ₹ >

• EM generally tends to take more steps than the K-Means clustering algorithm.

< □ ▶ < □ ▶ < 三 ▶ < 三 ▶ < 三 • りへ ○

- EM generally tends to take more steps than the K-Means clustering algorithm.
- Each step is more computationally intense than with K-Means too.

 $\checkmark Q (~$

▲□▶ ▲□▶ ▲三▶ ▲□▶ ■

- EM generally tends to take more steps than the K-Means clustering algorithm.
- Each step is more computationally intense than with K-Means too.
- So, one commonly computes K-Means first and then initializes EM from the resulting clusters.

 $\checkmark Q (~$

3

▲□▶ ▲□▶ ▲□▶ ▲□▶ →

- EM generally tends to take more steps than the K-Means clustering algorithm.
- Each step is more computationally intense than with K-Means too.
- So, one commonly computes K-Means first and then initializes EM from the resulting clusters.
- Care must be taken to avoid singularities in the MLE solution.

 $\checkmark Q ($

Э.

▲□▶ ▲□▶ ▲□▶ ▲□▶ →

- EM generally tends to take more steps than the K-Means clustering algorithm.
- Each step is more computationally intense than with K-Means too.
- So, one commonly computes K-Means first and then initializes EM from the resulting clusters.
- Care must be taken to avoid singularities in the MLE solution.
- There will generally be multiple local maxima of the likelihood function and EM is not guaranteed to find the largest of these.

 $\checkmark Q (~$

3

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Given a GMM, the goal is to maximize the likelihood function with respect to the parameters (the means, the covarianes, and the mixing coefficients).

1 Initialize the means, μ_k , the covariances, Σ_k , and mixing coefficients, π_k . Evaluate the initial value of the log-likelihood.

◆□▶ ◆□▶ ▲三▶ ▲三▶ ▲□▶

Given a GMM, the goal is to maximize the likelihood function with respect to the parameters (the means, the covarianes, and the mixing coefficients).

- Initialize the means, μ_k , the covariances, Σ_k , and mixing coefficients, π_k . Evaluate the initial value of the log-likelihood.
- 2 E-Step Evaluate the responsibilities using the current parameter values:

$$\gamma(z_k) = \frac{\prod_{j=1}^{K} \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^{K} \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

SQA

Given a GMM, the goal is to maximize the likelihood function with respect to the parameters (the means, the covarianes, and the mixing coefficients).

- Initialize the means, μ_k , the covariances, Σ_k , and mixing coefficients, π_k . Evaluate the initial value of the log-likelihood.
- 2 E-Step Evaluate the responsibilities using the current parameter values:

$$\gamma(z_k) = \frac{\pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

M-Step Update the parameters using the current responsibilities

$$\boldsymbol{\mu}_{k}^{\mathsf{new}} \neq \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) \mathbf{x}_{n}$$

$$\boldsymbol{\Sigma}_{k}^{\mathsf{new}} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma(z_{nk}) (\mathbf{x}_{n} - \boldsymbol{\mu}_{k}^{\mathsf{new}}) (\mathbf{x}_{n} - \boldsymbol{\mu}_{k}^{\mathsf{new}})^{\mathsf{T}}$$

$$(30)$$

$$\stackrel{\text{ew}}{=} \frac{N_k}{N} \tag{31}$$

where

$$N_k = \sum_{n=1}^N \gamma(z_{nk}) \tag{32}$$

Clustering / Unsupervised Methods

Evaluate the log-likelihood

$$\ln p(\mathbf{X}|\boldsymbol{\mu}^{\mathsf{new}}, \boldsymbol{\Sigma}^{\mathsf{new}}, \boldsymbol{\pi}^{\mathsf{new}}) = \sum_{n=1}^{N} \ln \left[\sum_{k=1}^{K} \pi_{k}^{\mathsf{new}} \mathcal{N}\left(\mathbf{x}_{n} | \boldsymbol{\mu}_{k}^{\mathsf{new}}, \boldsymbol{\Sigma}_{k}^{\mathsf{new}} \right) \right]$$
(33)

・ロト < 団ト < 三ト < 三ト < 三 ・ のへで

Evaluate the log-likelihood

$$\ln p(\mathbf{X}|\boldsymbol{\mu}^{\mathsf{new}}, \boldsymbol{\Sigma}^{\mathsf{new}}, \boldsymbol{\pi}^{\mathsf{new}}) = \sum_{n=1}^{N} \ln \left[\sum_{k=1}^{K} \pi_{k}^{\mathsf{new}} \mathcal{N}(\mathbf{x}_{n} | \boldsymbol{\mu}_{k}^{\mathsf{new}}, \boldsymbol{\Sigma}_{k}^{\mathsf{new}}) \right]$$
(33)

One of the convergence of either the parameters of the log-likelihood. If the convergence is not satisfied, set the parameters:

$$\boldsymbol{\mu} = \boldsymbol{\mu}^{\mathsf{new}} \tag{34}$$

$$\Sigma = \Sigma^{\text{new}}$$
 (35)

$$\pi = \pi^{\text{new}}$$
 (36)

and goto step 2.

 $\mathcal{A} \subset \mathcal{A}$

• The goal of EM is to find maximum likelihood solutions for models having latent variables.

<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

- The goal of EM is to find maximum likelihood solutions for models having latent variables.
- Denote the set of all model parameters as heta, and so the log-likelihood function is

$$\ln p(\mathbf{X}|\boldsymbol{\theta}) = \ln \left[\sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})\right]$$
(37)

 $\checkmark \land \land \land$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □

- The goal of EM is to find maximum likelihood solutions for models having latent variables.
- Denote the set of all model parameters as θ , and so the log-likelihood function is

$$\ln p(\mathbf{X}|\boldsymbol{\theta}) = \ln \left[\sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})\right]$$
(37)

- Note how the summation over the latent variables appears inside of the log.
 - Even if the joint distribution $p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})$ belongs to the exponential family, the marginal $p(\mathbf{X}|\boldsymbol{\theta})$ typically does not.

DQA

(四) (ヨ) (ヨ)

- The goal of EM is to find maximum likelihood solutions for models having latent variables.
- Denote the set of all model parameters as heta, and so the log-likelihood function is

$$\ln p(\mathbf{X}|\boldsymbol{\theta}) = \ln \left[\sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})\right]$$
(37)

- Note how the summation over the latent variables appears inside of the log.
 - Even if the joint distribution $p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})$ belongs to the exponential family, the marginal $p(\mathbf{X}|\boldsymbol{\theta})$ typically does not.
- If, for each sample \mathbf{x}_n we were given the value of the latent variable \mathbf{z}_n , then we would have a **complete** data set, $\{\mathbf{X}, \mathbf{Z}\}$, with which maximizing this likelihood term would be straightforward.

◆□▶ ◆□▶ ◆ ≧▶ ◆ ≧▶ ≧ �� � �

• However, in practice, we are not given the latent variables values.

 $\mathcal{O} \mathcal{Q} \mathcal{O}$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

- However, in practice, we are not given the latent variables values.
- So, instead, we focus on the expectation of the log-likelihood under the posterior distribution of the latent variables.

 $\checkmark Q (\sim$

Э.

▲ □ ▶ ▲ □ ▶ ▲ □ ▶

- However, in practice, we are not given the latent variables values.
- So, instead, we focus on the expectation of the log-likelihood under the posterior distribution of the latent variables.
- In the E-Step, we use the current parameter values θ^{old} to find the posterior distribution of the latent variables given by $p(\mathbf{Z}|\mathbf{X}, \theta^{old})$.

 \checkmark Q (\checkmark

- However, in practice, we are not given the latent variables values.
- So, instead, we focus on the expectation of the log-likelihood under the posterior distribution of the latent variables.
- In the E-Step, we use the current parameter values θ^{old} to find the posterior distribution of the latent variables given by $p(\mathbf{Z}|\mathbf{X}, \theta^{old})$.
- This posterior is used to define the **expectation of the complete-data log-likelihood**, denoted $Q(\theta, \theta^{old})$, which is given by

$$Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\mathsf{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z} | \mathbf{X}, \boldsymbol{\theta}^{\mathsf{old}}) \ln p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\theta})$$
(38)

◆□ ▶ ◆□ ▶ ◆□ ▶ ◆□ ▶ ●

- However, in practice, we are not given the latent variables values.
- So, instead, we focus on the expectation of the log-likelihood under the posterior distribution of the latent variables.
- In the E-Step, we use the current parameter values θ^{old} to find the posterior distribution of the latent variables given by $p(\mathbf{Z}|\mathbf{X}, \theta^{old})$.
- This posterior is used to define the **expectation of the complete-data log-likelihood**, denoted $Q(\theta, \theta^{old})$, which is given by

$$Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\mathsf{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z} | \mathbf{X}, \boldsymbol{\theta}^{\mathsf{old}}) \ln p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\theta})$$
(38)

• Then, in the M-step, we revise the parameters to θ^{new} by maximizing this function:

$$\boldsymbol{\theta}^{\mathsf{new}} = \arg\max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\mathsf{old}})$$
(39)

✓) Q (³

- However, in practice, we are not given the latent variables values.
- So, instead, we focus on the expectation of the log-likelihood under the posterior distribution of the latent variables.
- In the E-Step, we use the current parameter values $heta^{
 m old}$ to find the posterior distribution of the latent variables given by $p(\mathbf{Z}|\mathbf{X}, \boldsymbol{\theta}^{\mathsf{old}})$.
- This posterior is used to define the **expectation of the complete-data log-likelihood**, denoted $Q(\theta, \theta^{old})$, which is given by

$$Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\mathsf{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z} | \mathbf{X}, \boldsymbol{\theta}^{\mathsf{old}}) \ln p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\theta})$$
(38)

• Then, in the M-step, we revise the parameters to θ^{new} by maximizing this function:

$$\boldsymbol{\theta}^{\mathsf{new}} = \arg\max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta}, \boldsymbol{\theta}^{\mathsf{old}})$$
(39)

• Note that the log acts directly on the joint distribution $p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})$ and so the M-step maximization will likely be tractable. ▲□→ ▲ □ → ▲ □ → □

J. Corso (SUNY at Buffalo)

 \mathcal{A}

・ロト < 団ト < 三ト < 三ト < 三 の < (?)