

CSE 431/531: Algorithm Analysis and Design (Spring 2024)

Greedy Algorithms

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Goals of algorithm design

- 1 Design efficient algorithms to solve problems
- 2 Design more efficient algorithms to solve problems

Common Paradigms for Algorithm Design

- Greedy Algorithms: shortest path problem
- Divide and Conquer: merge-sort, binary search
- Dynamic Programming: shortest path problem, Fibonacci number

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- They often run in polynomial time due to their simplicity: easy to come up with, easy to analyze running time.
- Hard to see correctness. Mostly, it is not correct. E.g. $\min f(x)$

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- Safety: Prove that the reasonable strategy is “safe”
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Outline

- 1 Toy Example: Box Packing
- 2 Interval Scheduling
 - Interval Partitioning
- 3 Offline Caching
 - Heap: Concrete Data Structure for Priority Queue
- 4 Data Compression and Huffman Code
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- 6 Exercise Problems

Box Packing

Input: n boxes of capacities c_1, c_2, \dots, c_n

m items of sizes s_1, s_2, \dots, s_m

Can put **at most 1** item in a box

Item j can be put into box i if $s_j \leq c_i$

Output: A way to put as many items as possible in the boxes.

Example:

- Box capacities: 60, 40, 25, 17, 12
- Item sizes: 45, 41, 20, 19, 16

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Designing a Reasonable Strategy for Box Packing

- Q: Take box 1. Which item should we put in box 1?

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Designing a Reasonable Strategy for Box Packing

- Q: Take box 1. Which item should we put in box 1?
- A: The item of the largest size that can be put into the box.

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- formal proof via **exchanging argument:**

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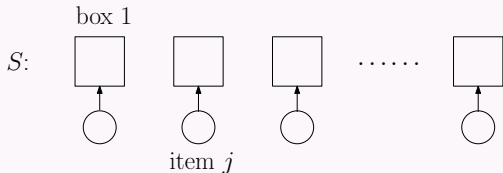
Proof.

- Let $j =$ largest item that box 1 can hold.
- Take any optimum solution S . If j is put into Box 1 in S , done.

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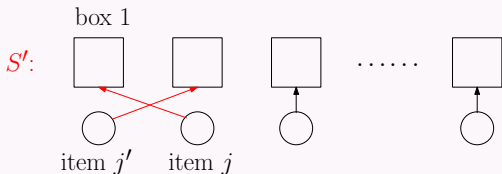
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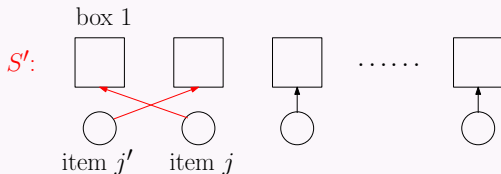


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- $s_{j'} \leq s_j$, and swapping gives another solution S'
- S' is also an optimum solution. In S' , j is put into Box 1. □

- Notice that the exchanging operation is only for the sake of analysis; it is not a part of the algorithm.

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- Self-reduce: Show that the remaining task after applying the strategy is to solve a (many) smaller instance(s) of the same problem
- Trivial: we decided to put Item j into Box 1, and the remaining instance is obtained by removing Item j and Box 1.

Generic Greedy Algorithm

- 1: **while** the instance is non-trivial **do**
- 2: make the choice using the greedy strategy
- 3: reduce the instance

Greedy Algorithm for Box Packing

- 1: $T \leftarrow \{1, 2, 3, \dots, m\}$
- 2: **for** $i \leftarrow 1$ to n **do**
- 3: **if** some item in T can be put into box i **then**
- 4: $j \leftarrow$ the largest item in T that can be put into box i
- 5: print(“put item j in box i ”)
- 6: $T \leftarrow T \setminus \{j\}$

Why “Safety” + “Self-reduce” \implies Optimality?

- Let $\text{BP}(B, T)$ denote a box-packing instance.
- $\phi(1, 2, \dots, m) \mapsto \{1, 2, \dots, n, \text{NULL}\}$ denote packing strategy. e.g., $\phi(2) = 3$ means item 2 is put into box 3.
- $\text{val}(\phi) :=$ the number of items packed by ϕ .
- ϕ_g : the packing strategy obtained by greedy algorithm.

Proof.

- Base case: When $|B| = 1$ or $|T| = 1$.
- Inductive case: (Hypothesis) Assume Greedy alg solves $\text{BP}(B', T')$ optimally for $|B'| = n - 1$ and $|T'| = m - 1$.



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Proof.

- (Induction) Wlog, let π be the optimal solution matches our greedy sol on $\text{BP}(B, T)$, saying $\pi(j) = 1$.
- By self-reduce: $\text{BP}(B \setminus \{1\}, T \setminus \{j\})$ is a smaller BP instance.
- π and ϕ_g onto $\text{BP}(B \setminus \{1\}, T \setminus \{j\})$, denoted as π' and ϕ'_g .
- By Inductive hypothesis, ϕ'_g is the optimal sol for $\text{BP}(B \setminus \{1\}, T \setminus \{j\})$.
- $\text{val}(\pi) \geq \text{val}(\phi_g) = 1 + \text{val}(\phi'_g) \geq 1 + \text{val}(\pi') = \text{val}(\pi)$.



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Running time

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- With sorted item-sizes and box-capacities, running time is $O(\max\{n, m\})$.

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Lemma Generic algorithm is correct **if and only if** the greedy strategy is safe.

- Greedy strategy is safe: we will not miss the optimum solution
- Greedy strategy is not safe: we will miss the optimum solution for some instance, since the choices we made are irrevocable.

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Exchange argument: Proof of Safety of a Strategy

- let S be an arbitrary optimum solution.
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Outline

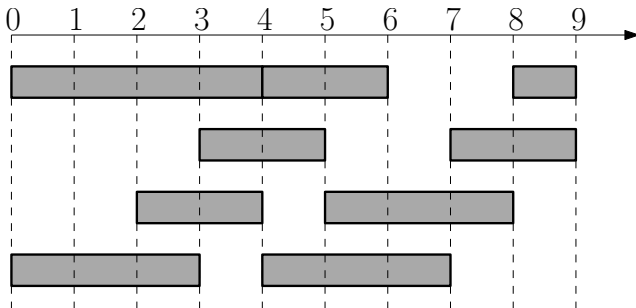
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Interval Scheduling

Input: n jobs, job i with start time s_i and finish time f_i

i and j are **compatible** if $[s_i, f_i)$ and $[s_j, f_j)$ are disjoint

Output: A maximum-size subset of mutually compatible jobs

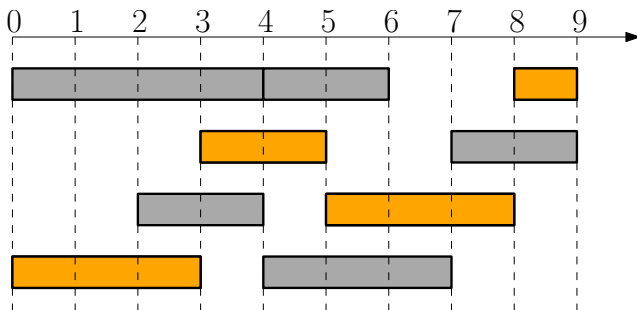


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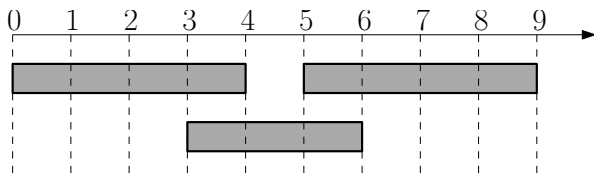
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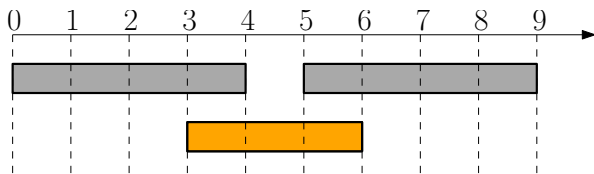
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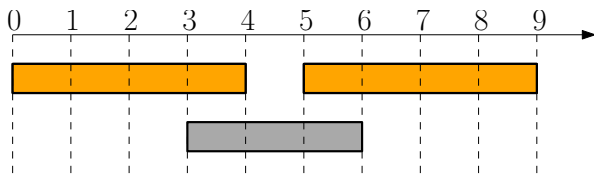
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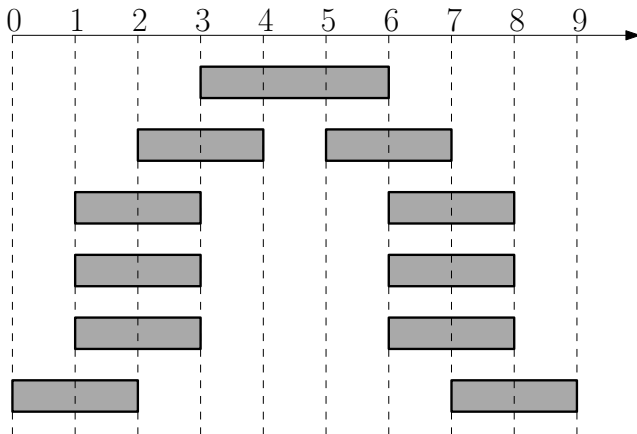
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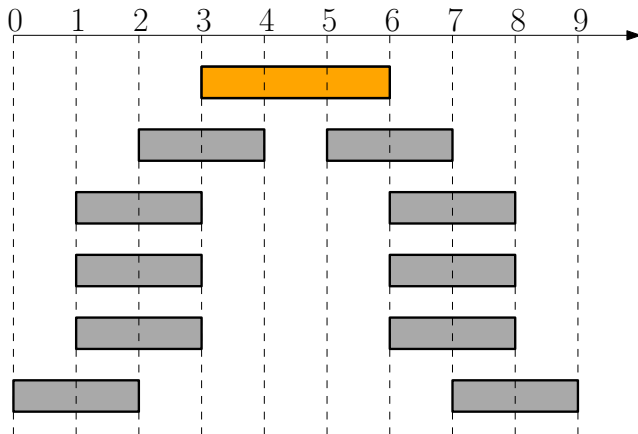
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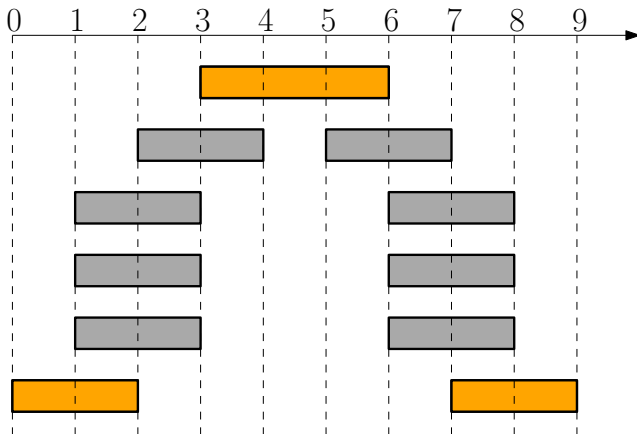
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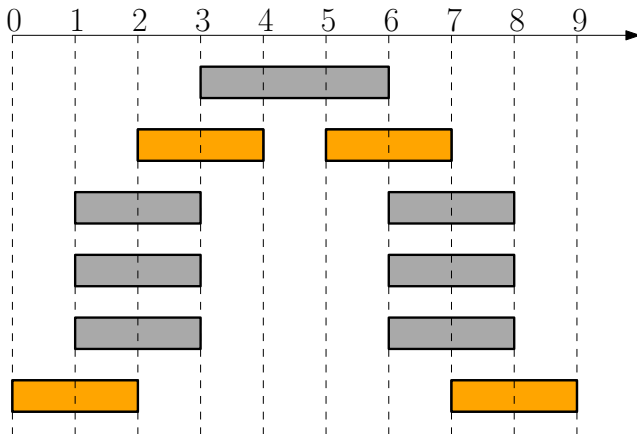
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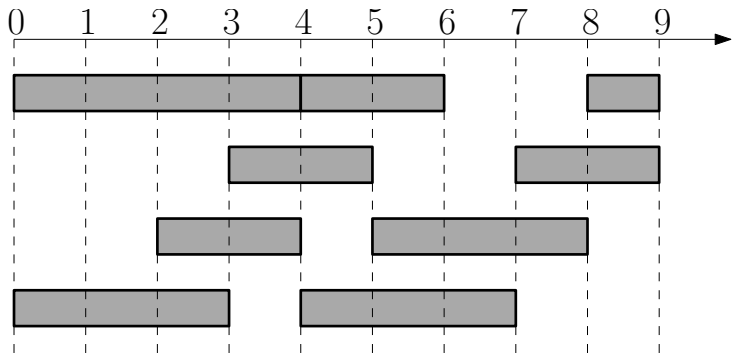
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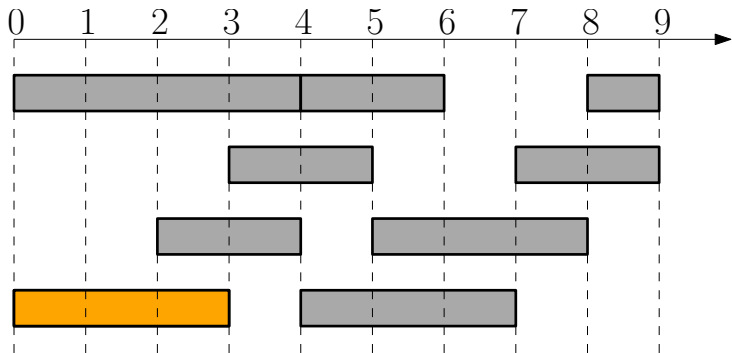
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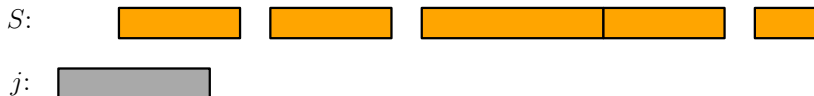


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