

# Bellman-Ford Algorithm

## Bellman-Ford( $G, w, s$ )

```
1:  $f[s] \leftarrow 0$  and  $f[v] \leftarrow \infty$  for any  $v \in V \setminus \{s\}$ 
2: for  $\ell \leftarrow 1$  to  $n - 1$  do
3:   for each  $(u, v) \in E$  do
4:     if  $f[u] + w(u, v) < f[v]$  then
5:        $f[v] \leftarrow f[u] + w(u, v)$ 
6: return  $f$ 
```

- Issue: when we compute  $f[u] + w(u, v)$ ,  $f[u]$  may be changed since the end of last iteration
- This is OK: it can only “accelerate” the process!
- After iteration  $\ell$ ,  $f[v]$  is **at most** the length of the shortest path from  $s$  to  $v$  that uses at most  $\ell$  edges
- $f[v]$  is always the length of **some path** from  $s$  to  $v$

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- After iteration  $\ell$ :

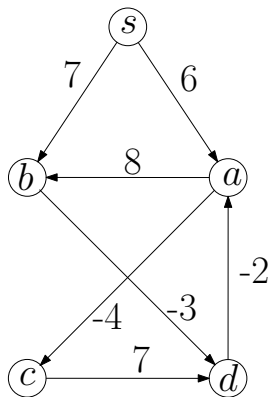
$$\begin{aligned} & \text{length of shortest } s\text{-}v \text{ path} \\ & \leq f[v] \\ & \leq \text{length of shortest } s\text{-}v \text{ path using at most } \ell \text{ edges} \end{aligned}$$

- Assuming there are no negative cycles:

$$\begin{aligned} & \text{length of shortest } s\text{-}v \text{ path} \\ & = \text{length of shortest } s\text{-}v \text{ path using at most } n - 1 \text{ edges} \end{aligned}$$

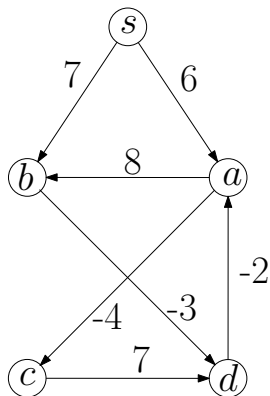
- So, assuming there are no negative cycles, after iteration  $n - 1$ :

$$f[v] = \text{length of shortest } s\text{-}v \text{ path}$$



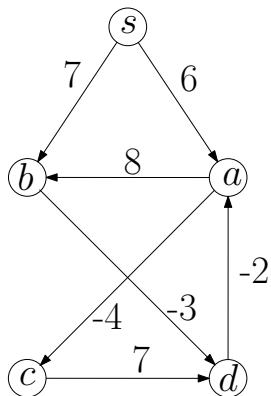
- order in which we consider edges:  
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vertices	$s$	$a$	$b$	$c$	$d$
$f$	0	$\infty$	$\infty$	$\infty$	$\infty$



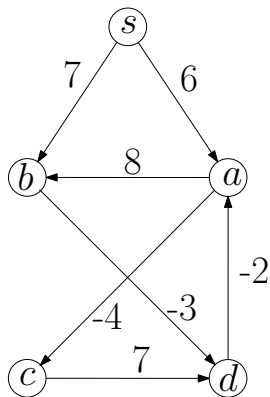
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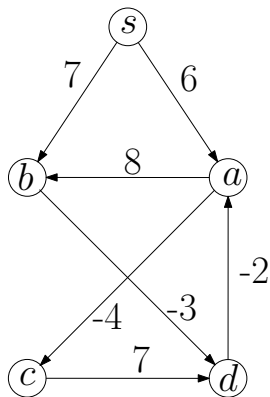
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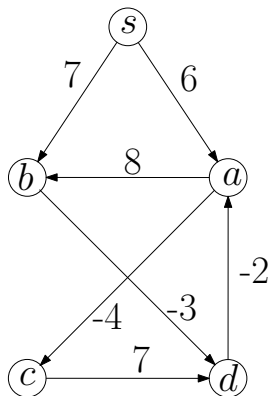
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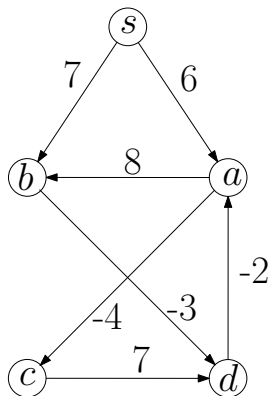
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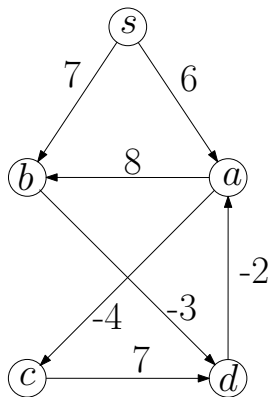
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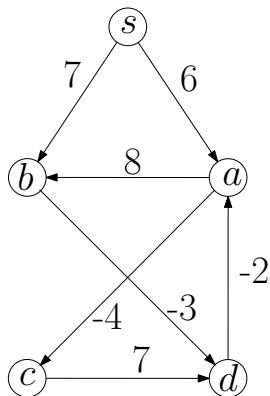
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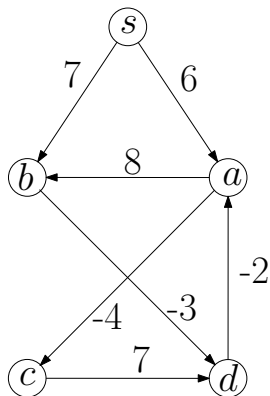
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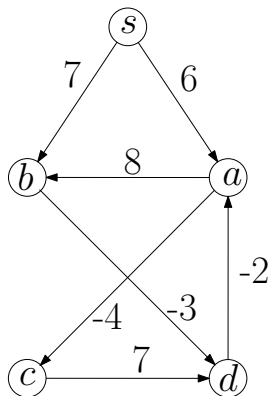
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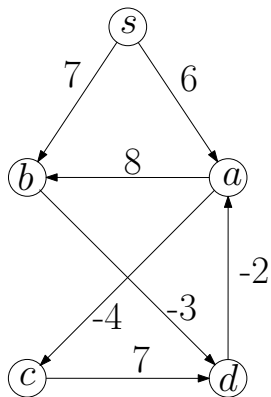
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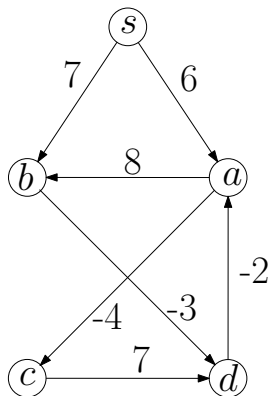
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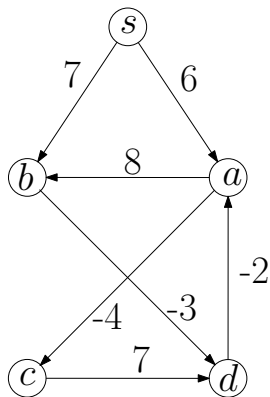
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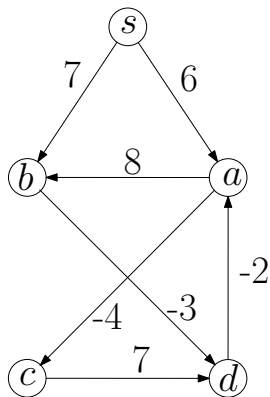


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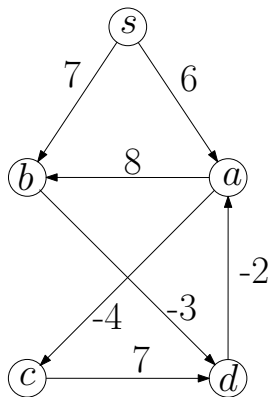




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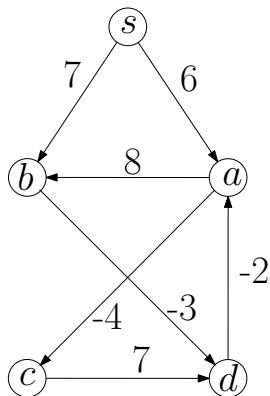
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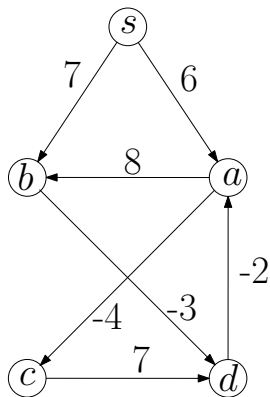
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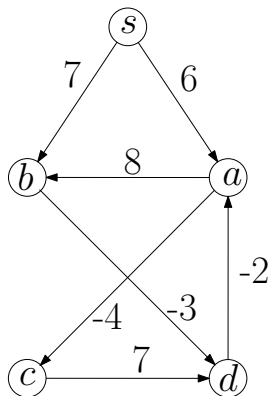
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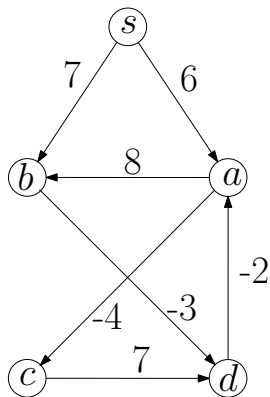
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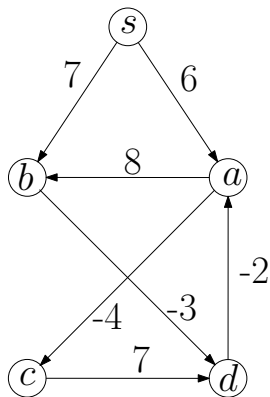
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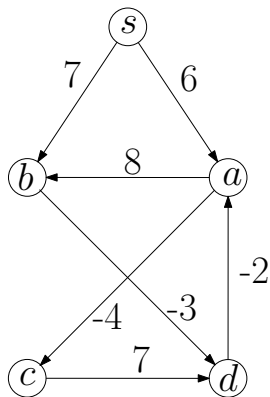
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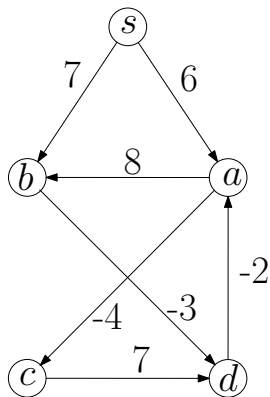


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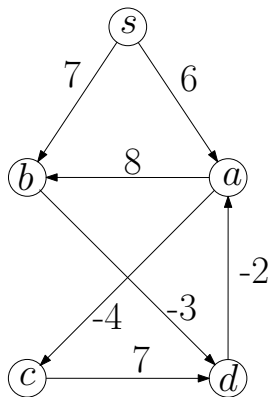




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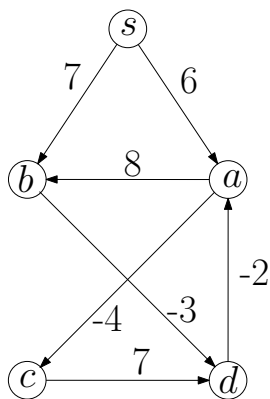
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- end of iteration 1: 0, 2, 7, 2, 4
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- end of iteration 3: 0, 2, 7, -2, 4
- **Algorithm terminates in 3 iterations, instead of 4.**

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- 2: **for**  $\ell \leftarrow 1$  to  $n$  **do**
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- Running time =  $O(nm)$

# Outline

- 1 Minimum Spanning Tree
  - Kruskal's Algorithm
  - Reverse-Kruskal's Algorithm
  - Prim's Algorithm
- 2 Single Source Shortest Paths
  - Dijkstra's Algorithm
- 3 Shortest Paths in Graphs with Negative Weights
- 4 All-Pair Shortest Paths and Floyd-Warshall

# All-Pair Shortest Paths

## All Pair Shortest Paths

**Input:** directed graph  $G = (V, E)$ ,  
 $w : E \rightarrow \mathbb{R}$  (can be negative)

**Output:** shortest path from  $u$  to  $v$  for every  $u, v \in V$



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- Running time =  $O(n^2m)$

# Summary of Shortest Path Algorithms we learned

algorithm	graph	weights	SS?	running time
Simple DP	DAG	$\mathbb{R}$	SS	$O(n + m)$
Dijkstra	U/D	$\mathbb{R}_{\geq 0}$	SS	$O(n \log n + m)$
Bellman-Ford	U/D	$\mathbb{R}$	SS	$O(nm)$
Floyd-Warshall	U/D	$\mathbb{R}$	AP	$O(n^3)$

- DAG = directed acyclic graph    U = undirected    D = directed
- SS = single source    AP = all pairs

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- For simplicity, extend the  $w$  values to non-edges:

$$w(i, j) = \begin{cases} 0 & i = j \\ \text{weight of edge } (i, j) & i \neq j, (i, j) \in E \\ \infty & i \neq j, (i, j) \notin E \end{cases}$$

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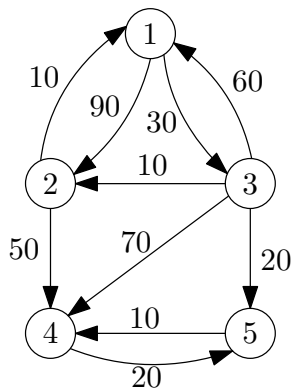
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- Issue: do not know in which order we compute  $f[i, j]$ 's
- $f^k[i, j]$ : length of shortest path from  $i$  to  $j$  that only uses vertices  $\{1, 2, 3, \dots, k\}$  as intermediate vertices

# Example for Definition of $f^k[i, j]$ 's



$$f^0[1, 4] = \infty$$

$$f^1[1, 4] = \infty$$

$$f^2[1, 4] = 140 \quad (1 \rightarrow 2 \rightarrow 4)$$

$$f^3[1, 4] = 90 \quad (1 \rightarrow 3 \rightarrow 2 \rightarrow 4)$$

$$f^4[1, 4] = 90 \quad (1 \rightarrow 3 \rightarrow 2 \rightarrow 4)$$

$$f^5[1, 4] = 60 \quad (1 \rightarrow 3 \rightarrow 5 \rightarrow 4)$$

$$w(i, j) = \begin{cases} 0 & i = j \\ \text{weight of edge } (i, j) & i \neq j, (i, j) \in E \\ \infty & i \neq j, (i, j) \notin E \end{cases}$$

- $f^k[i, j]$ : length of shortest path from  $i$  to  $j$  that only uses vertices  $\{1, 2, 3, \dots, k\}$  as intermediate vertices

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$$f^k[i, j] = \begin{cases} w(i, j) & k = 0 \\ \min \left\{ \begin{array}{l} f^k[i, v] + w(v, j) \\ f^k[v, i] + w(i, v) \end{array} \right\} & k = 1, 2, \dots, n \end{cases}$$

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$$f^k[i, j] = \begin{cases} w(i, j) & k = 0 \\ \min \left\{ \begin{array}{l} f^{k-1}[i, j] \\ \text{weight of edge } (i, j) \end{array} \right\} & k = 1, 2, \dots, n \end{cases}$$



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## Floyd-Warshall( $G, w$ )

```
1:  $f^0 \leftarrow w$ 
2: for  $k \leftarrow 1$  to  $n$  do
3:   copy  $f^{k-1} \rightarrow f^k$ 
4:   for  $i \leftarrow 1$  to  $n$  do
5:     for  $j \leftarrow 1$  to  $n$  do
6:       if  $f^{k-1}[i, k] + f^{k-1}[k, j] < f^k[i, j]$  then
7:          $f^k[i, j] \leftarrow f^{k-1}[i, k] + f^{k-1}[k, j]$ 
```

## Floyd-Warshall( $G, w$ )

```
1:  $f^{\text{old}} \leftarrow w$ 
2: for  $k \leftarrow 1$  to  $n$  do
3:   copy  $f^{\text{old}} \rightarrow f^{\text{new}}$ 
4:   for  $i \leftarrow 1$  to  $n$  do
5:     for  $j \leftarrow 1$  to  $n$  do
6:       if  $f^{\text{old}}[i, k] + f^{\text{old}}[k, j] < f^{\text{new}}[i, j]$  then
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2: for  $k \leftarrow 1$  to  $n$  do
3:   copy  $f \rightarrow f$ 
4:   for  $i \leftarrow 1$  to  $n$  do
5:     for  $j \leftarrow 1$  to  $n$  do
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**Lemma** Assume there are no negative cycles in  $G$ . After iteration  $k$ , for  $i, j \in V$ ,  $f[i, j]$  is **exactly** the length of shortest path from  $i$  to  $j$  that only uses vertices in  $\{1, 2, 3, \dots, k\}$  as intermediate vertices.

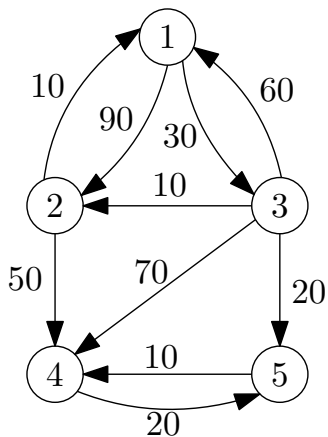
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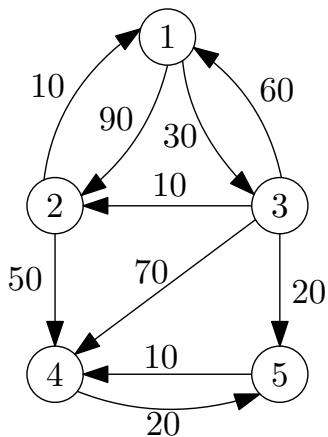
- Running time =  $O(n^3)$ .





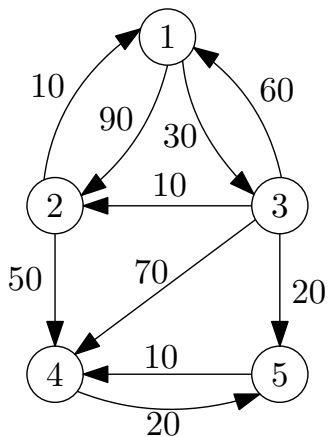
	1	2	3	4	5
1	0	90	30	$\infty$	$\infty$
2	10	0	$\infty$	50	$\infty$
3	60	10	0	70	20
4	$\infty$	$\infty$	$\infty$	0	20
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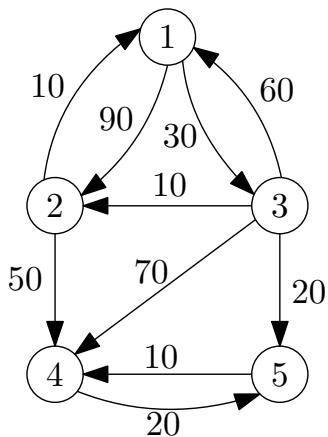
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- $i = 2, k = 1, j = 3$



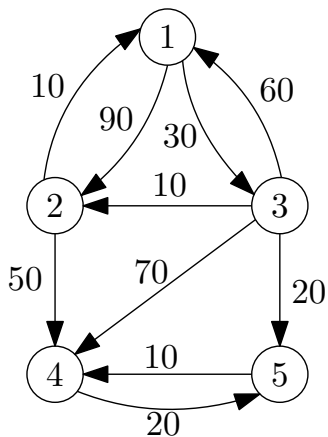
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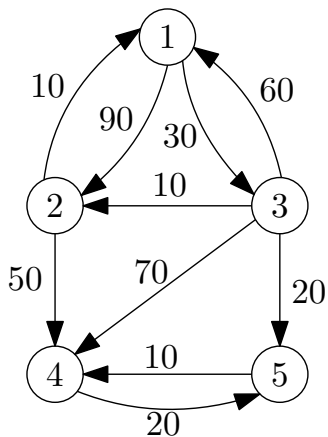
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- $i = 1, k = 2, j = 4$



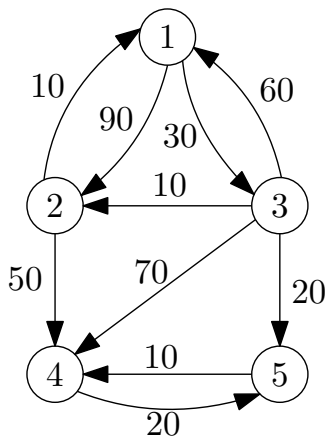
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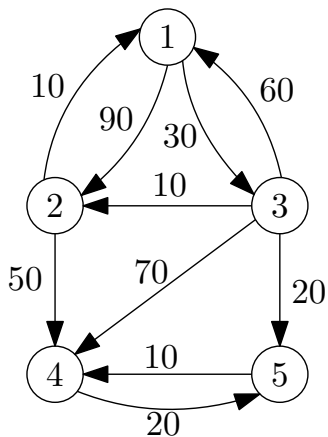
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- $i = 3, k = 2, j = 1,$



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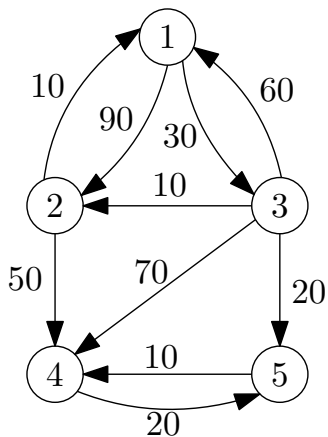
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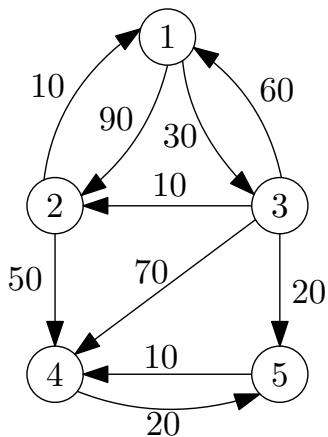
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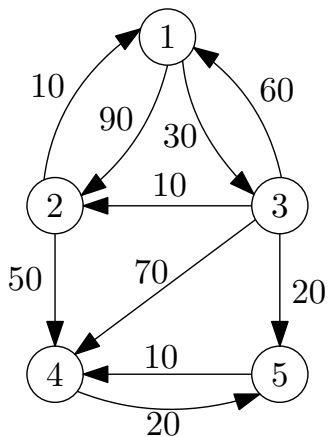
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- $i = 1, k = 3, j = 2$

# Recovering Shortest Paths

## Floyd-Warshall( $G, w$ )

```
1:  $f \leftarrow w, \pi[i, j] \leftarrow \perp$  for every  $i, j \in V$ 
2: for  $k \leftarrow 1$  to  $n$  do
3:   for  $i \leftarrow 1$  to  $n$  do
4:     for  $j \leftarrow 1$  to  $n$  do
5:       if  $f[i, k] + f[k, j] < f[i, j]$  then
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```

## print-path( $i, j$ )

```
1: if  $\pi[i, j] = \perp$  then
2:   print( $i, j$ )
3: else
4:   print-path( $i, \pi[i, j]$ ), print-path( $\pi[i, j], j$ )
```

# Detecting Negative Cycles

## Floyd-Warshall( $G, w$ )

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7: for  $k \leftarrow 1$  to  $n$  do
8:   for  $i \leftarrow 1$  to  $n$  do
9:     for  $j \leftarrow 1$  to  $n$  do
10:      if  $f[i, k] + f[k, j] < f[i, j]$  then
11:        report "negative cycle exists" and exit
```

# Summary of Shortest Path Algorithms

algorithm	graph	weights	SS?	running time
Simple DP	DAG	$\mathbb{R}$	SS	$O(n + m)$
Dijkstra	U/D	$\mathbb{R}_{\geq 0}$	SS	$O(n \log n + m)$
Bellman-Ford	U/D	$\mathbb{R}$	SS	$O(nm)$
Floyd-Warshall	U/D	$\mathbb{R}$	AP	$O(n^3)$

- DAG = directed acyclic graph    U = undirected    D = directed
- SS = single source    AP = all pairs



CSE 431/531: Algorithm Analysis and Design (Spring 2024)

# NP-Completeness

Lecturer: Kelin Luo

*Department of Computer Science and Engineering  
University at Buffalo*

# NP-Completeness Theory

- The topics we discussed so far are **positive results**: how to design efficient algorithms for solving a given problem.
- NP-Completeness provides **negative results**: some problems can **not** be solved efficiently.

**Q:** Why do we study negative results?

# NP-Completeness Theory

- The topics we discussed so far are **positive results**: how to design efficient algorithms for solving a given problem.
- NP-Completeness provides **negative results**: some problems can **not** be solved efficiently.

**Q:** Why do we study negative results?

- A given problem  $X$  cannot be solved in polynomial time.
- Without knowing it, you will have to keep trying to find polynomial time algorithm for solving  $X$ . All our efforts are doomed!

# Efficient = Polynomial Time

- Polynomial time:  $O(n^k)$  for any constant  $k > 0$
- Example:  $O(n)$ ,  $O(n^2)$ ,  $O(n^{2.5} \log n)$ ,  $O(n^{100})$
- Not polynomial time:  $O(2^n)$ ,  $O(n^{\log n})$

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- Not polynomial time:  $O(2^n)$ ,  $O(n^{\log n})$
- Almost all algorithms we learnt so far run in polynomial time

## Reason for Efficient = Polynomial Time

- For natural problems, if there is an  $O(n^k)$ -time algorithm, then  $k$  is small, say 4
- A good cut separating problems: for most natural problems, either we have a polynomial time algorithm, or the best algorithm runs in time  $\Omega(2^{n^c})$  for some  $c$
- Do not need to worry about the computational model

# Outline

- 1 Some Hard Problems
- 2 P, NP and Co-NP
- 3 Polynomial Time Reductions and NP-Completeness
- 4 NP-Complete Problems
- 5 Dealing with NP-Hard Problems
- 6 Summary

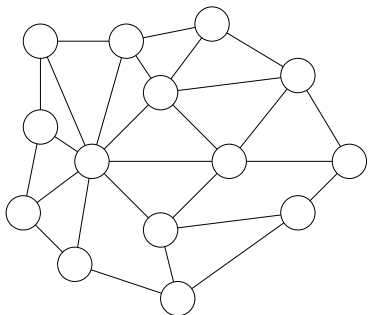
# Example: Hamiltonian Cycle Problem

**Def.** Let  $G$  be an undirected graph. A **Hamiltonian Cycle (HC)** of  $G$  is a cycle  $C$  in  $G$  that **passes each vertex of  $G$  exactly once**.

## Hamiltonian Cycle (HC) Problem

**Input:** graph  $G = (V, E)$

**Output:** whether  $G$  contains a Hamiltonian cycle





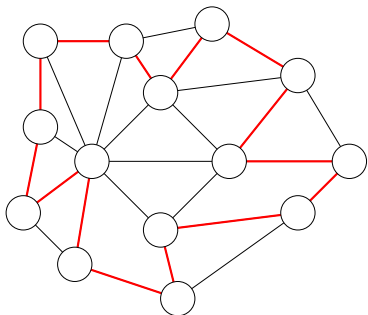
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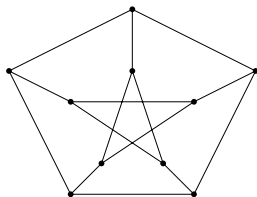
## Hamiltonian Cycle (HC) Problem

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## Example: Hamiltonian Cycle Problem



- The graph is called the **Petersen Graph**. It has no HC.