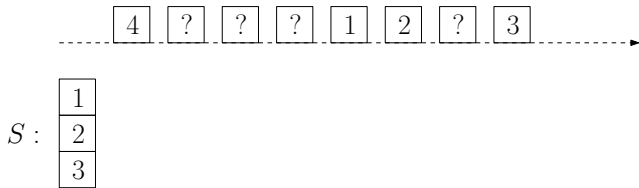


Analysis of Greedy Algorithm

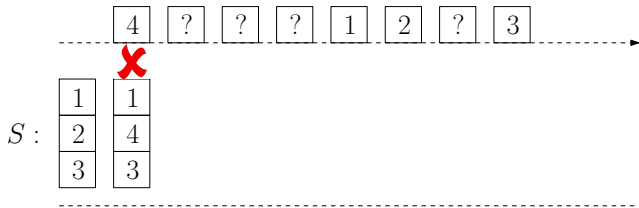
- **Safety:** Prove that the reasonable strategy is “safe” (key)
- **Self-reduce:** Show that the remaining task after applying the strategy is to solve a (many) smaller instance(s) of the same problem (usually easy)

Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **There is an optimum solution in which p^* is evicted at time 1.**



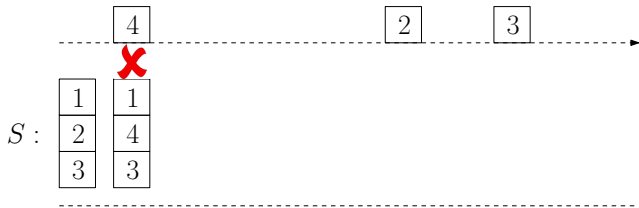
Proof.

- 1 S : any optimum solution
- 2 p^* : page in cache not requested until furthest in the future.
 - In the example, $p^* = 3$.



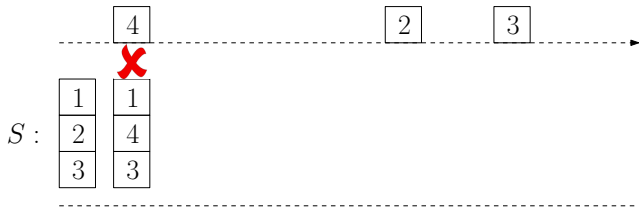
Proof.

- 1 S : any optimum solution
- 2 p^* : page in cache not requested until furthest in the future.
 - In the example, $p^* = 3$.
- 3 Assume S evicts some $p' \neq p^*$ at time 1; otherwise done.
 - In the example, $p' = 2$.

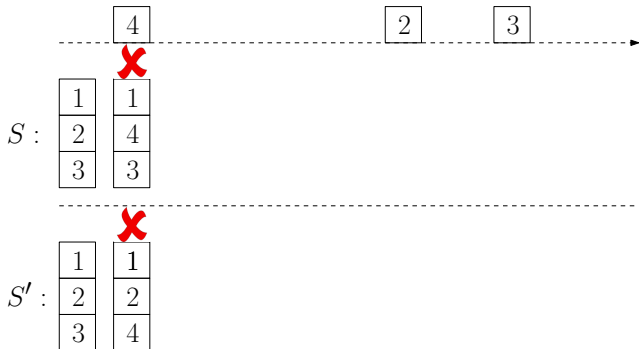


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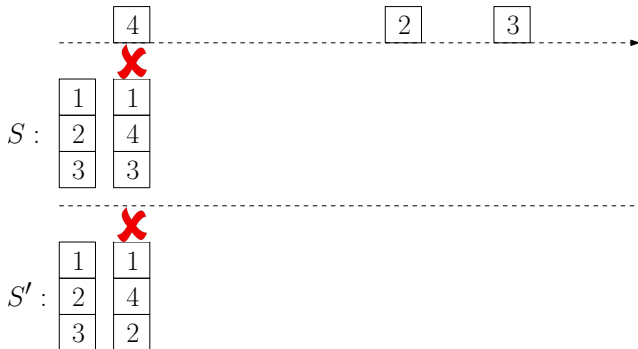


Proof.



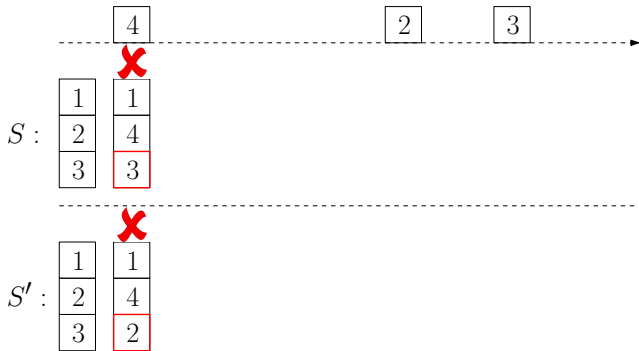
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- ④ Create S' . S' evicts $p^*(=3)$ instead of $p'(=2)$ at time 1.



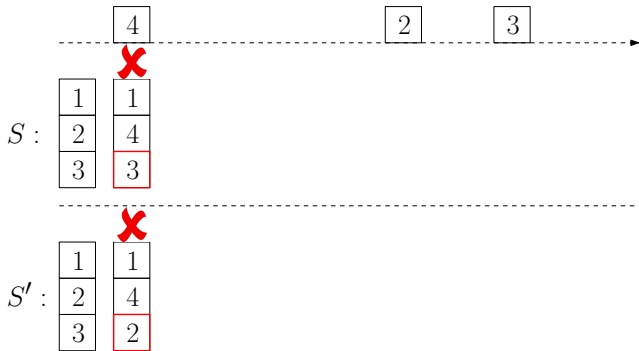
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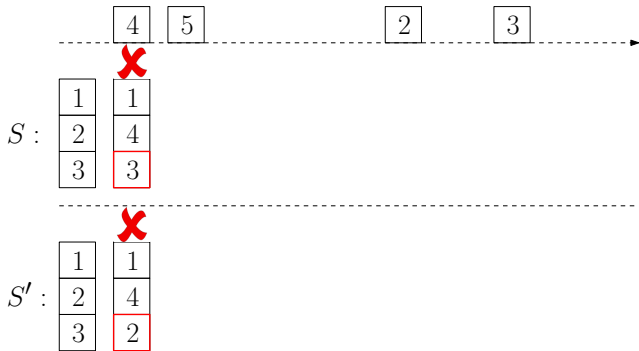
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- 4 Create S' . S' evicts $p^*(=3)$ instead of $p' (=2)$ at time 1.
- 5 After time 1, cache status of S and that of S' differ by only 1 page. S' contains $p' (=2)$ and S contains $p^*(=3)$.



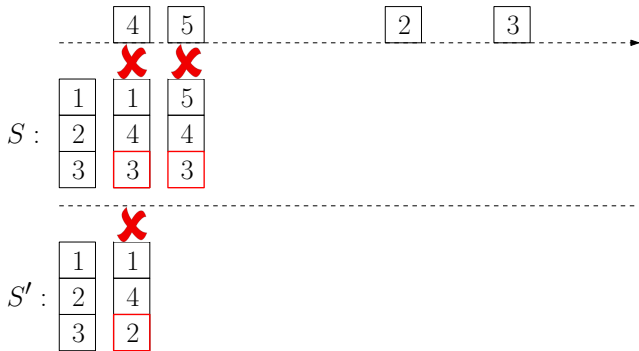
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- 6 From now on, S' will “copy” S .



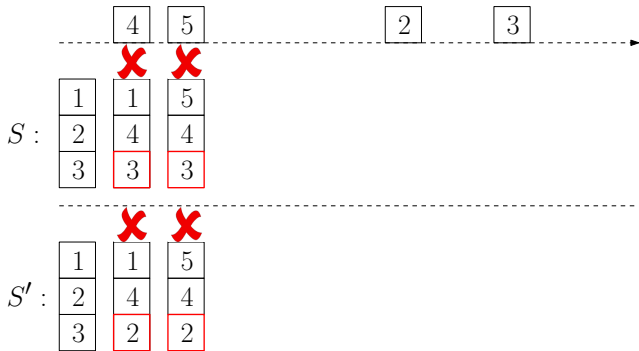
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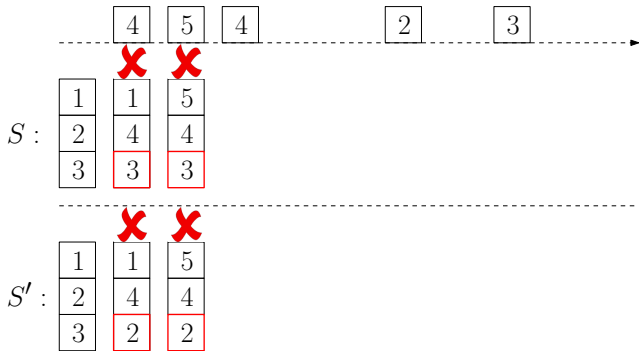
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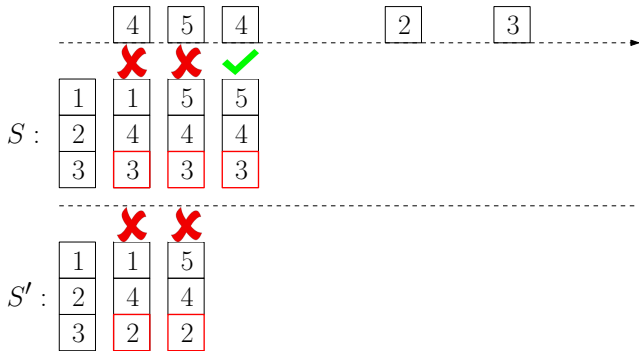
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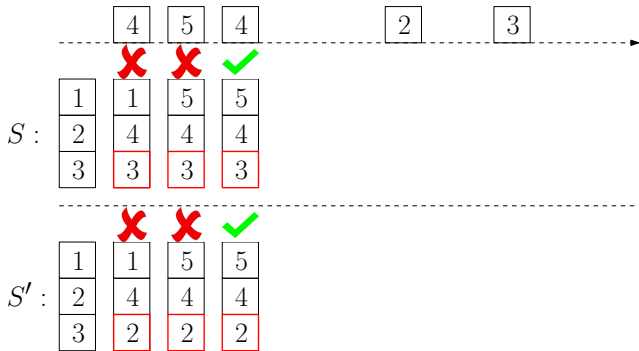
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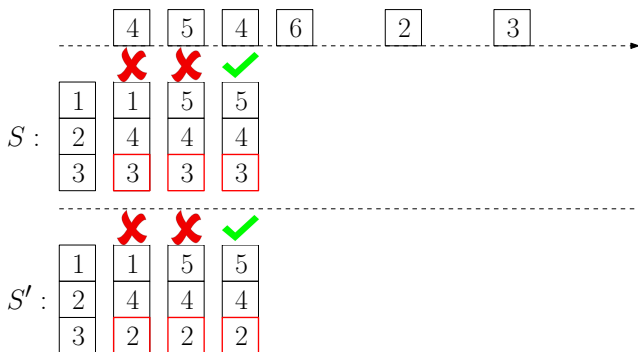
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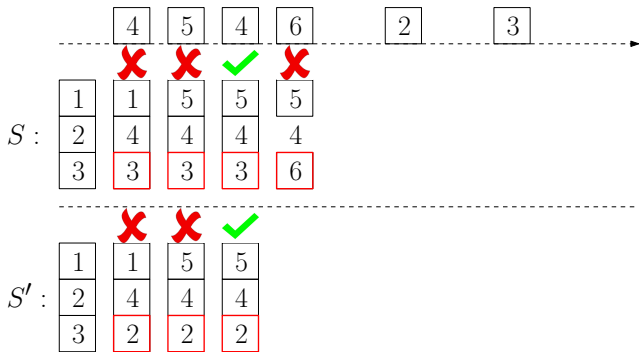
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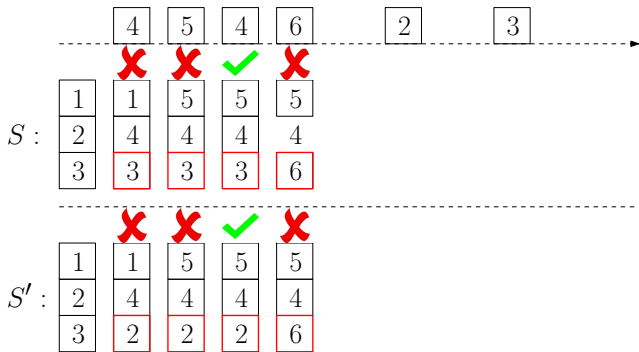
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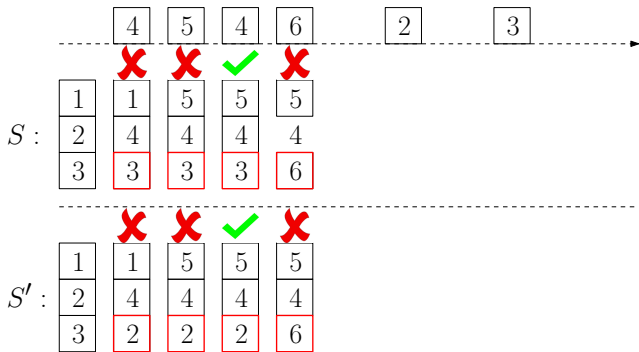
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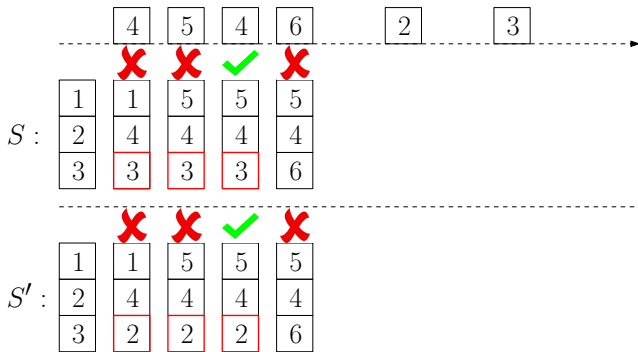


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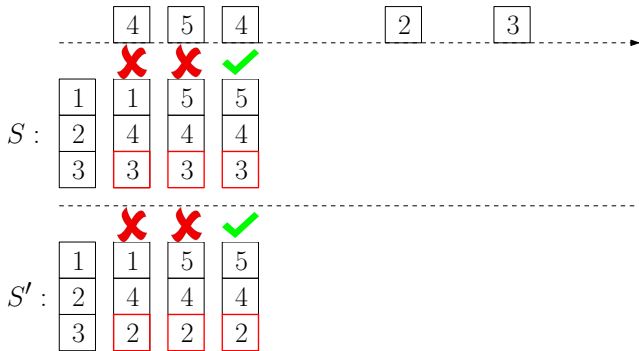


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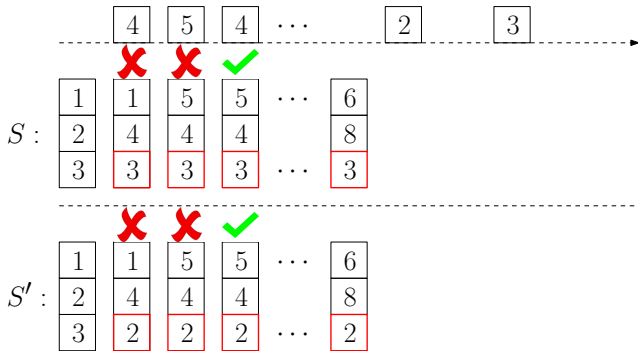
Proof.

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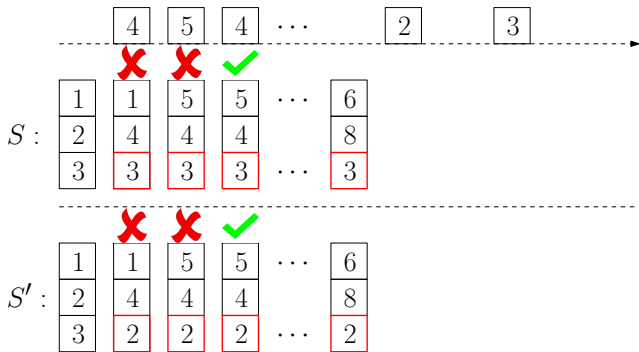
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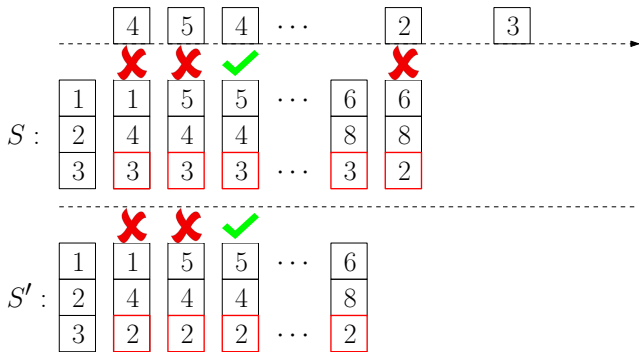


Proof.

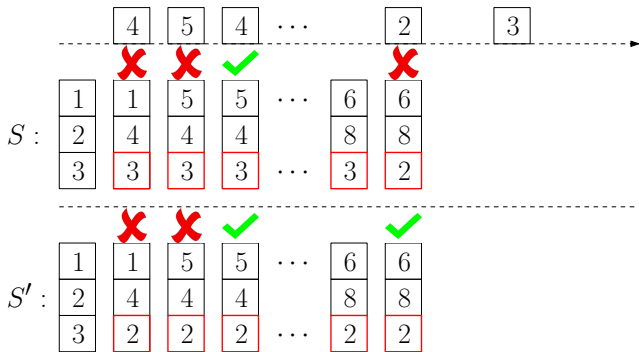
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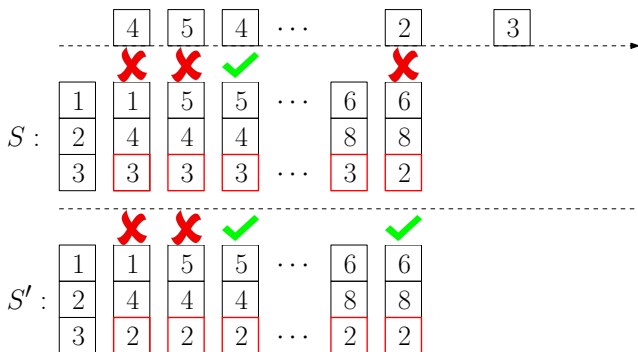
Proof.



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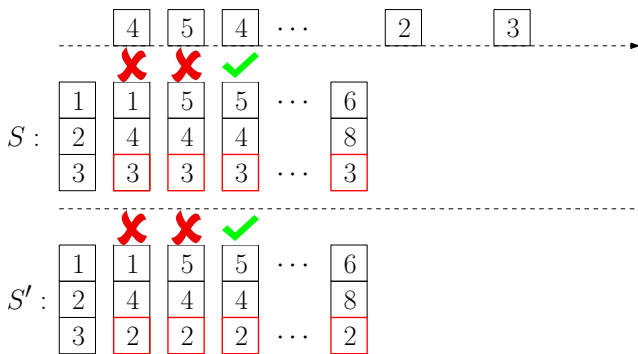


Proof.



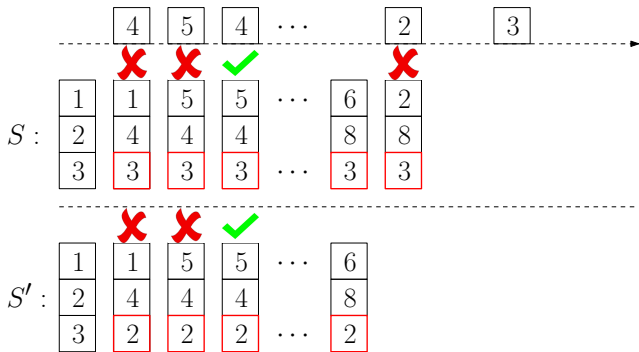
Proof.

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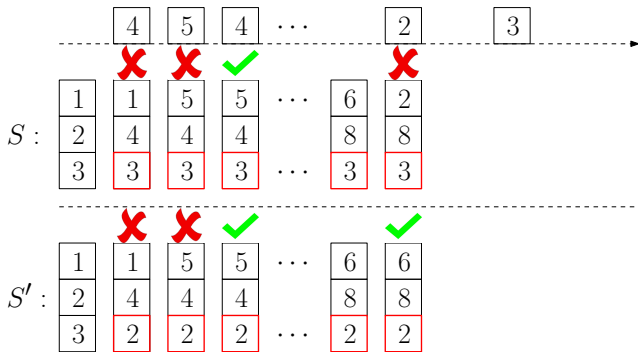
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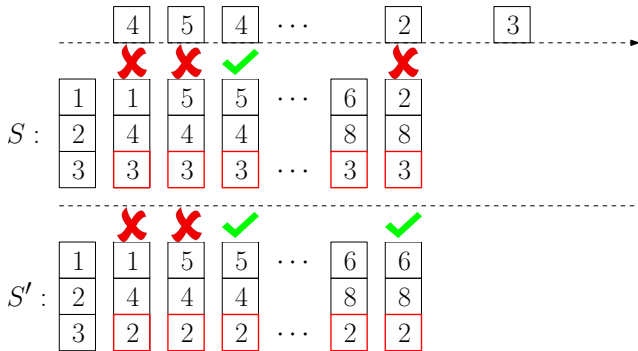
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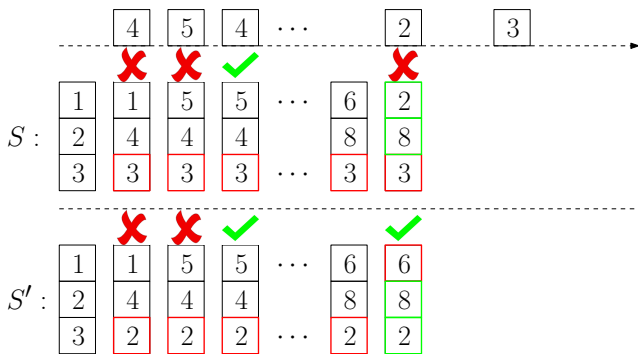
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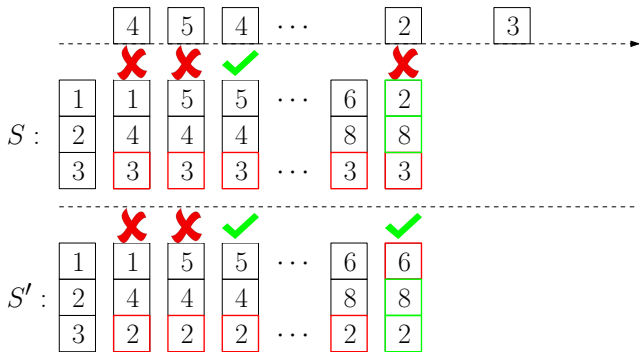
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- 10 So far, S' has 1 less page-miss than S does.

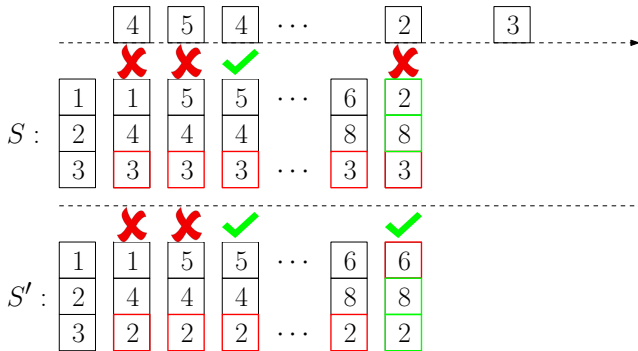


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- 9 If S evicts $p^*(=3)$ for $p'(=2)$, then S won't be optimum. Assume otherwise.
- 10 So far, S' has 1 less page-miss than S does.
- 11 The status of S' and that of S only differ by 1 page.

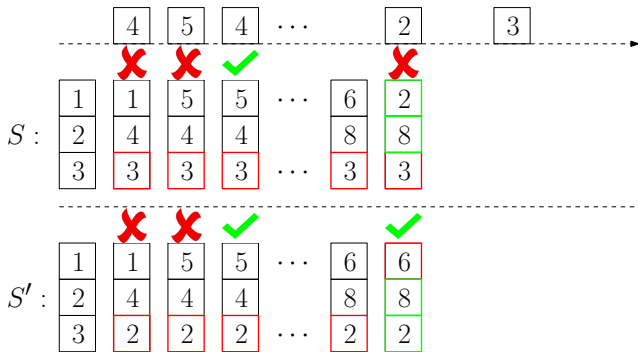


Proof.



Proof.

- 12 We can then guarantee that S' make at most the same number of page-misses as S does.



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- 12 We can then guarantee that S' make at most the same number of page-misses as S does.
- Idea: if S has a page-hit and S' has a page-miss, we use the opportunity to make the status of S' the same as that of S . □

- Thus, we have shown how to create another solution S' with the same number of page-misses as that of the optimum solution S . Thus, we proved

Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **There is an optimum solution in which p^* is evicted at time 1.**

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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **It is safe to evict p^* at time 1.**

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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **It is safe to evict p^* at time 1.**

Theorem The furthest-in-future strategy is optimum.

```
1: for  $t \leftarrow 1$  to  $T$  do
2:   if  $\rho_t$  is in cache then do nothing
3:   else if there is an empty page in cache then
4:     evict the empty page and load  $\rho_t$  in cache
5:   else
6:      $p^* \leftarrow$  page in cache that is not used furthest in the future
7:     evict  $p^*$  and load  $\rho_t$  in cache
```

Q: How can we make the algorithm as fast as possible?

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- The running time can be made to be $O(n + T \log k)$.
- For each page p , use a linked list (or an array with dynamic size) to store the time steps in which p is requested.
 - We can find the next time a page is requested easily.
- Use a priority queue data structure to hold all the pages in cache, so that we can easily find the page that is requested furthest in the future.

time	0	1	2	3	4	5	6	7	8	9	10	11	12
pages		P1	P5	P4	P2	P5	P3	P2	P4	P3	P1	P5	P3

P1:

1	10
---	----

P2:

4	7
---	---

P3:

6	9	12
---	---	----

P4:

3	8
---	---

P5:

2	5	11
---	---	----

priority queue

pages	priority values

time	0	1	2	3	4	5	6	7	8	9	10	11	12
pages		P1	P5	P4	P2	P5	P3	P2	P4	P3	P1	P5	P3

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pages		P1	P5	P4	P2	P5	P3	P2	P4	P3	P1	P5	P3



P1: 1 10

P2: 4 7

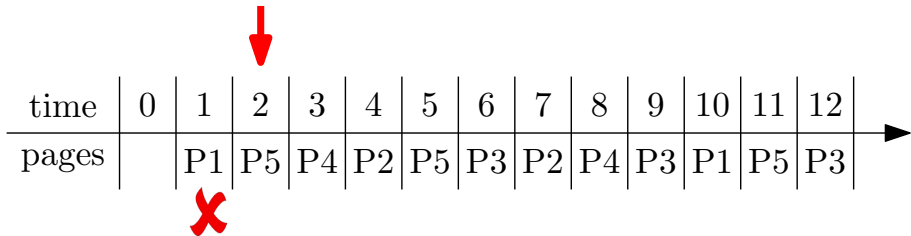
P3: 6 9 12

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P5: 2 5 11

priority queue

pages	priority values
P1	10



P1:

1	10
---	----

P2:

4	7
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P3:

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P4:

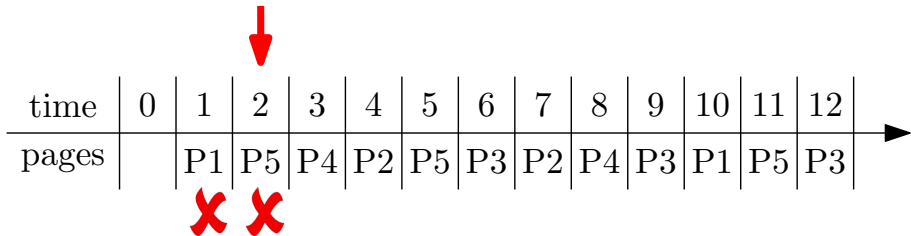
3	8
---	---

P5:

2	5	11
---	---	----

priority queue

pages	priority values
P1	10



- P1:

1	10
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- P2:

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- P3:

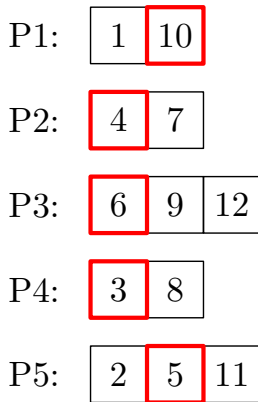
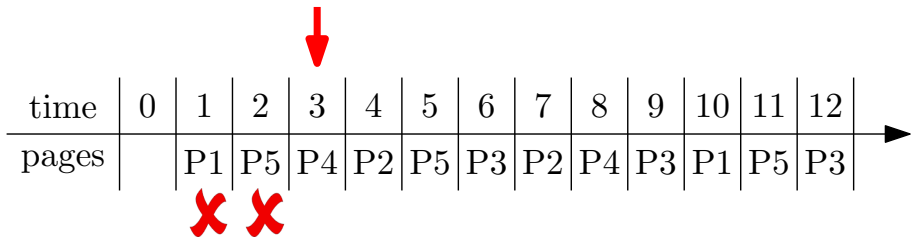
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3	8
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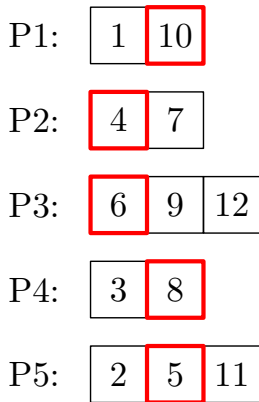
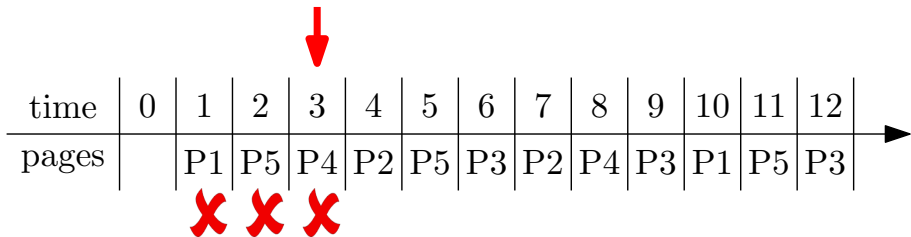
priority queue

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P5	5



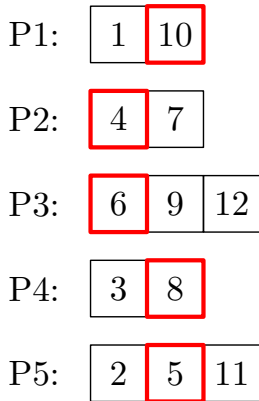
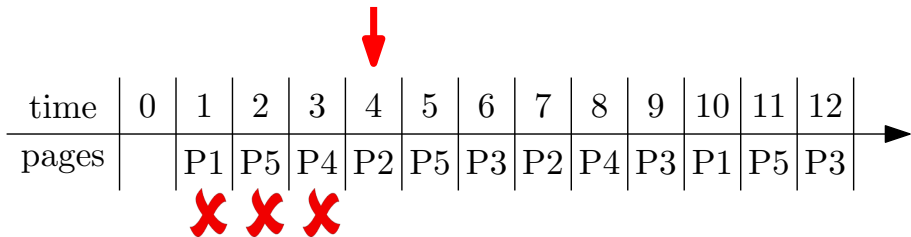
priority queue

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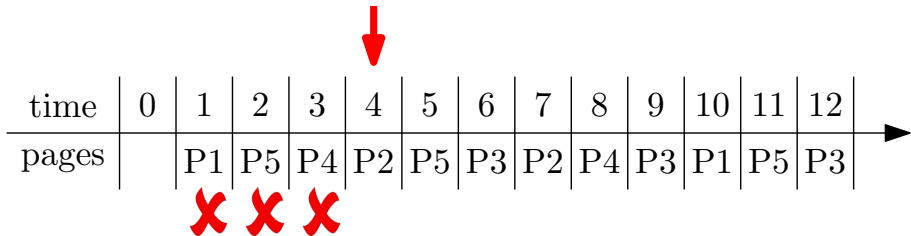
priority queue

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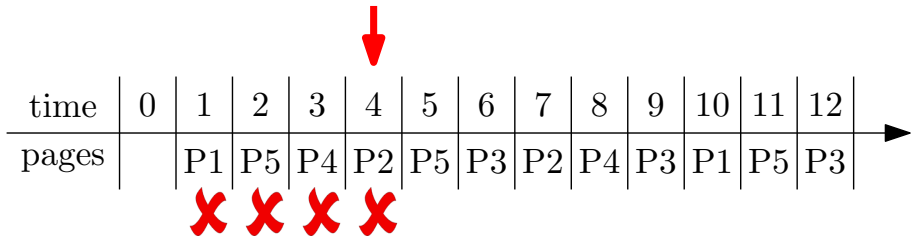
pages	priority values
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priority queue

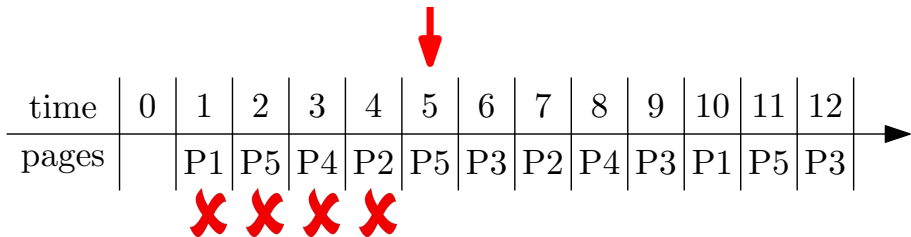
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priority queue

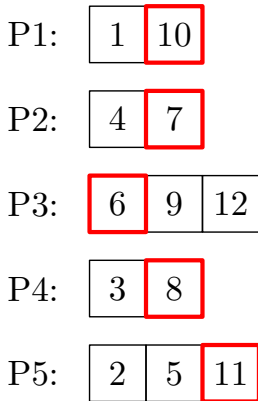
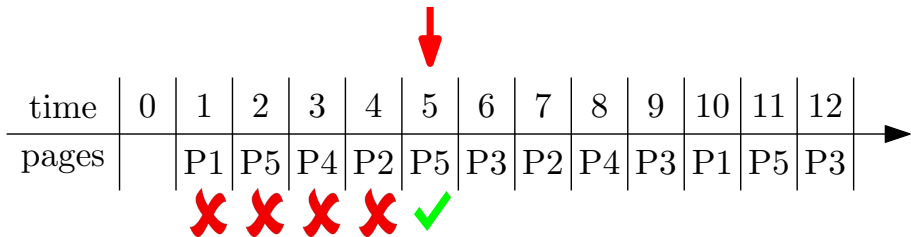
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P2:	4	7	
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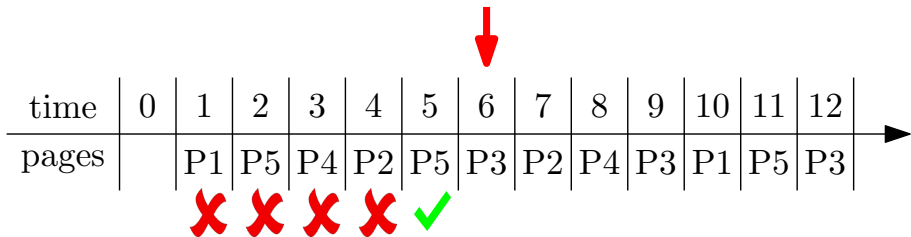
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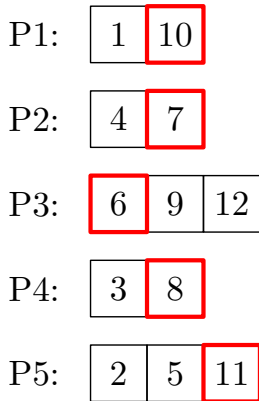
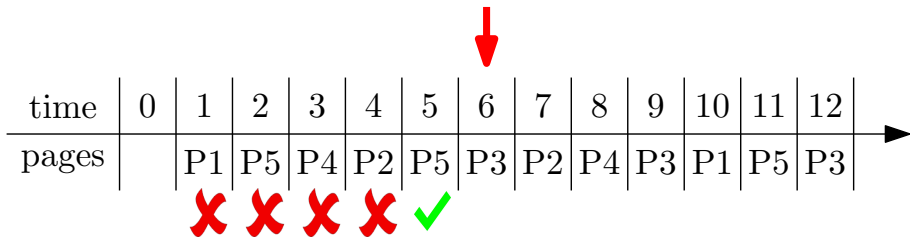
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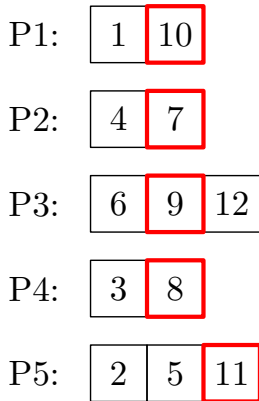
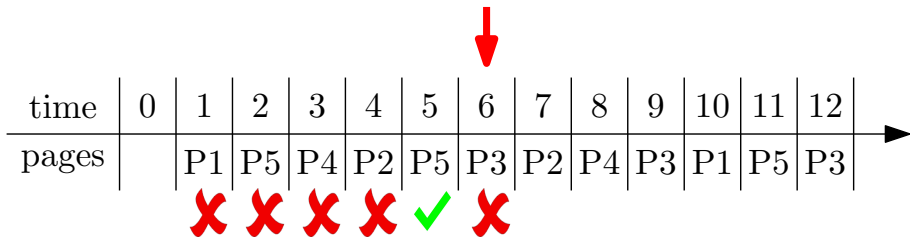
priority queue

pages	priority values
P2	7
P5	11
P4	8



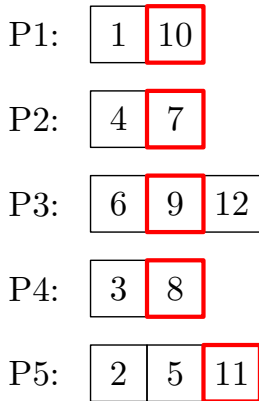
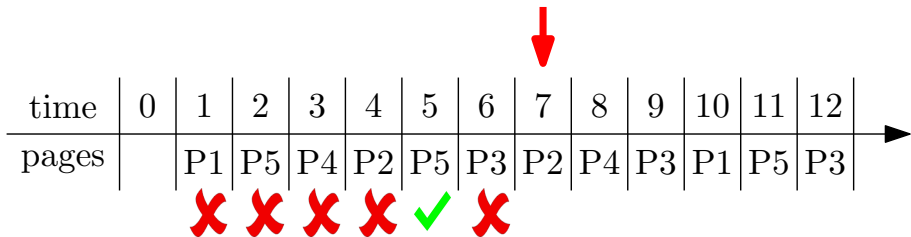
priority queue

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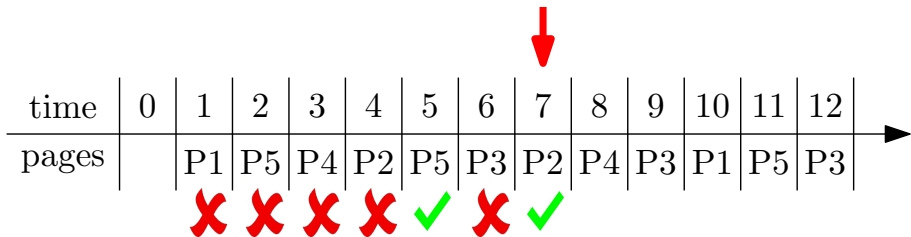
priority queue

pages	priority values
P2	7
P3	9
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priority queue

pages	priority values
P2	7
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P4	8



P1:

1	10
---	----

P2:

4	7	
---	---	--

P3:

6	9	12
---	---	----

P4:

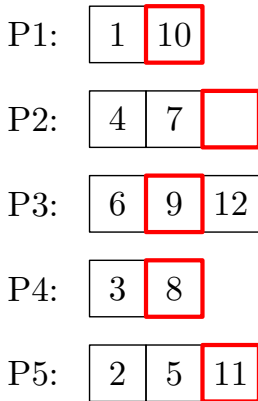
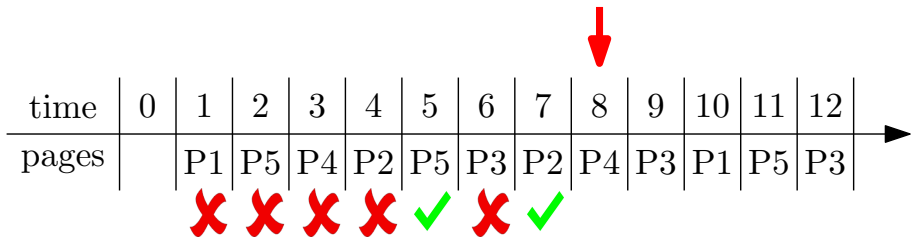
3	8
---	---

P5:

2	5	11
---	---	----

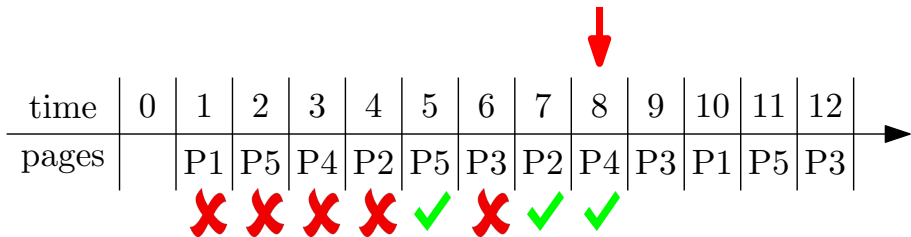
priority queue

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priority queue

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P2:

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P4:

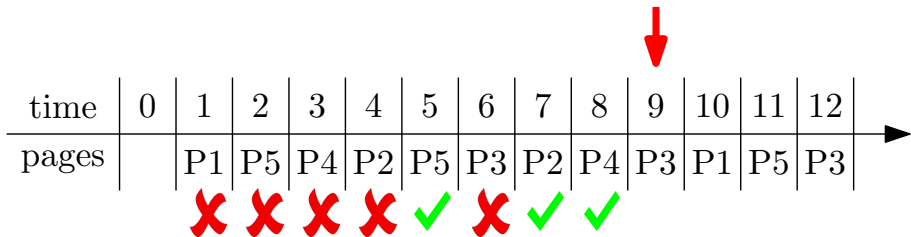
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priority queue

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P3:

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P4:

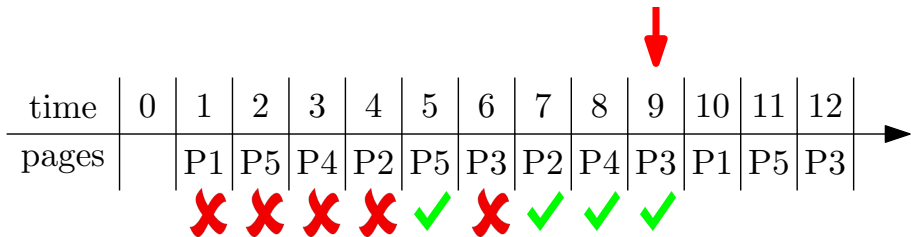
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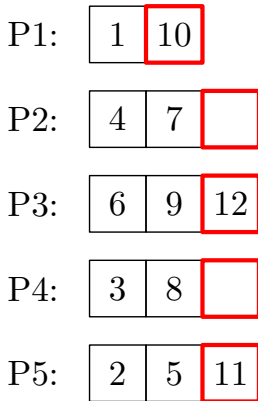
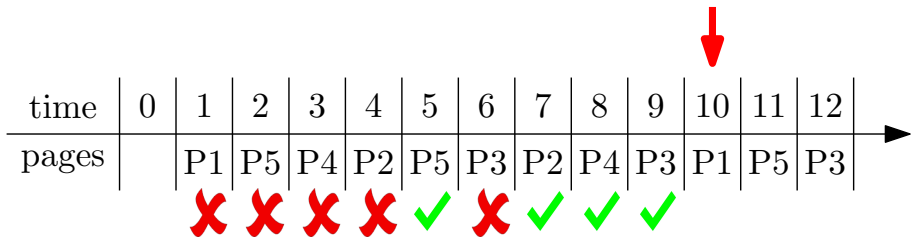
3	8	
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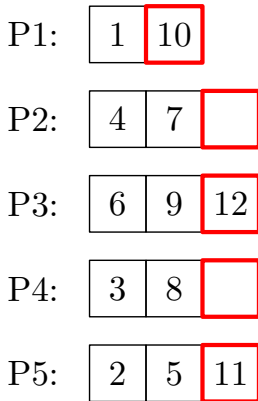
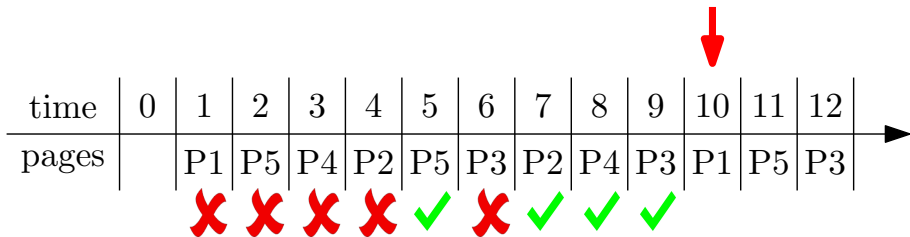
priority queue

pages	priority values
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P3	12
P4	∞



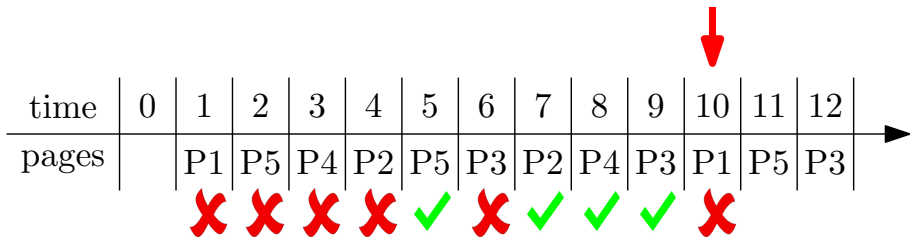
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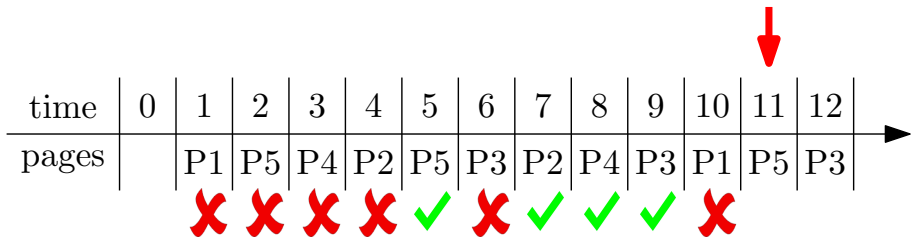
P3: 6 9 12

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priority queue

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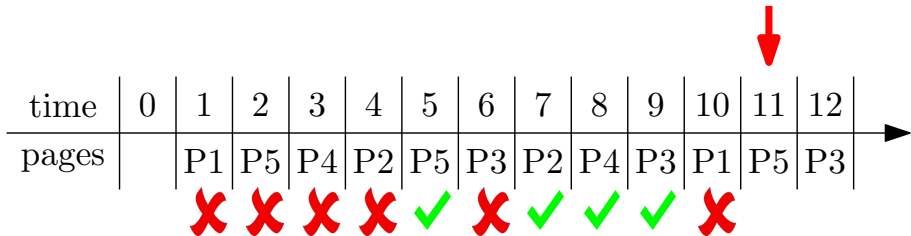
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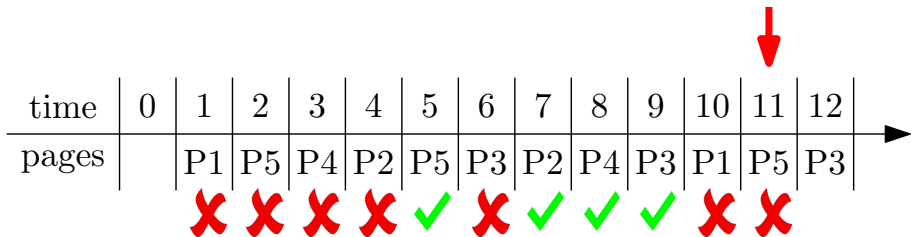
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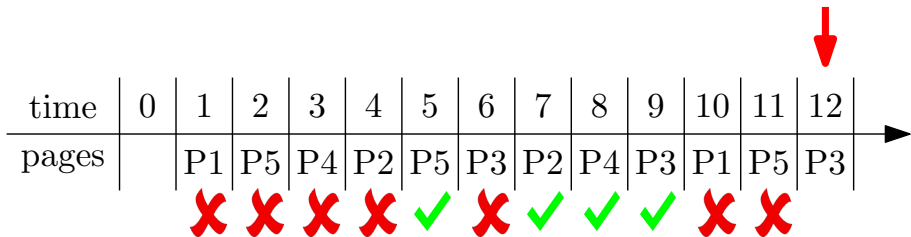
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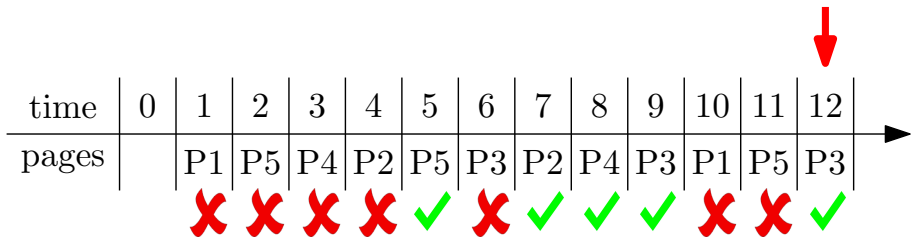
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```

1: for every  $p \leftarrow 1$  to  $n$  do
2:    $times[p] \leftarrow$  array of times in which  $p$  is requested, in
   increasing order                                 $\triangleright$  put  $\infty$  at the end of array
3:    $pointer[p] \leftarrow 1$ 
4:  $Q \leftarrow$  empty priority queue
5: for every  $t \leftarrow 1$  to  $T$  do
6:    $pointer[\rho_t] \leftarrow pointer[\rho_t] + 1$ 
7:   if  $\rho_t \in Q$  then
8:      $Q.increase\text{-}key(\rho_t, times[\rho_t, pointer[\rho_t]])$ , print "hit",
continue
9:   if  $Q.size() < k$  then
10:    print "load  $\rho_t$  to an empty page "
11:   else
12:     $p \leftarrow Q.extract\text{-}max()$ , print "evict  $p$  and load  $\rho_t$ "
13:     $Q.insert(\rho_t, times[\rho_t, pointer[\rho_t]])$      $\triangleright$  add  $\rho_t$  to  $Q$  with key
value  $times[\rho_t, pointer[\rho_t]]$ 

```

Outline

- 1 Toy Example: Box Packing
- 2 Interval Scheduling
 - Interval Partitioning
- 3 **Offline Caching**
 - **Heap: Concrete Data Structure for Priority Queue**
- 4 Data Compression and Huffman Code
- 5 Summary

- Let V be a ground set of size n .

Def. A **priority queue** is an **abstract** data structure that maintains a set $U \subseteq V$ of elements, each with an associated key value, and supports the following operations:

- $\text{insert}(v, \text{key_value})$: insert an element $v \in V \setminus U$, with associated key value key_value .
- $\text{decrease_key}(v, \text{new_key_value})$: decrease the key value of an element $v \in U$ to new_key_value
- $\text{extract_min}()$: return and remove the element in U with the smallest key value
- ...

Simple Implementations for Priority Queue

- $n =$ size of ground set V

data structures	insert	extract_min	decrease_key
array			
sorted array			

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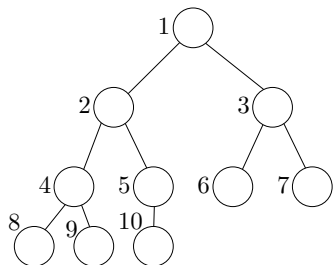
Simple Implementations for Priority Queue

- $n =$ size of ground set V

data structures	insert	extract_min	decrease_key
array	$O(1)$	$O(n)$	$O(1)$
sorted array	$O(n)$	$O(1)$	$O(n)$
heap	$O(\lg n)$	$O(\lg n)$	$O(\lg n)$

Heap

The elements in a heap is organized using a complete binary tree:

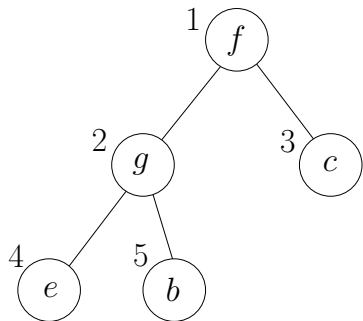


- Nodes are indexed as $\{1, 2, 3, \dots, s\}$
- Parent of node i : $\lfloor i/2 \rfloor$
- Left child of node i : $2i$
- Right child of node i : $2i + 1$

Heap

A heap H contains the following fields

- s : size of U (number of elements in the heap)
- $A[i], 1 \leq i \leq s$: the element at node i of the tree
- $p[v], v \in U$: the index of node containing v
- $key[v], v \in U$: the key value of element v

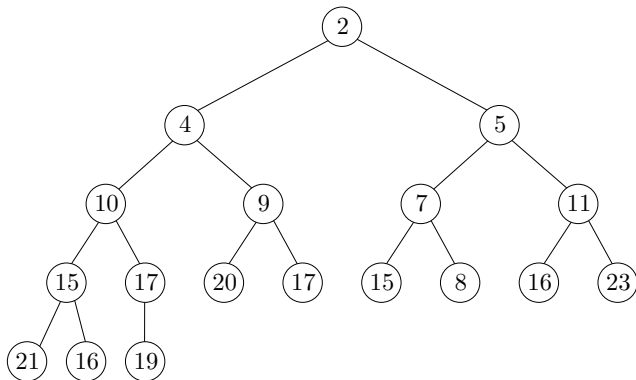


- $s = 5$
- $A = ('f', 'g', 'c', 'e', 'b')$
- $p['f'] = 1, p['g'] = 2, p['c'] = 3,$
 $p['e'] = 4, p['b'] = 5$

Heap

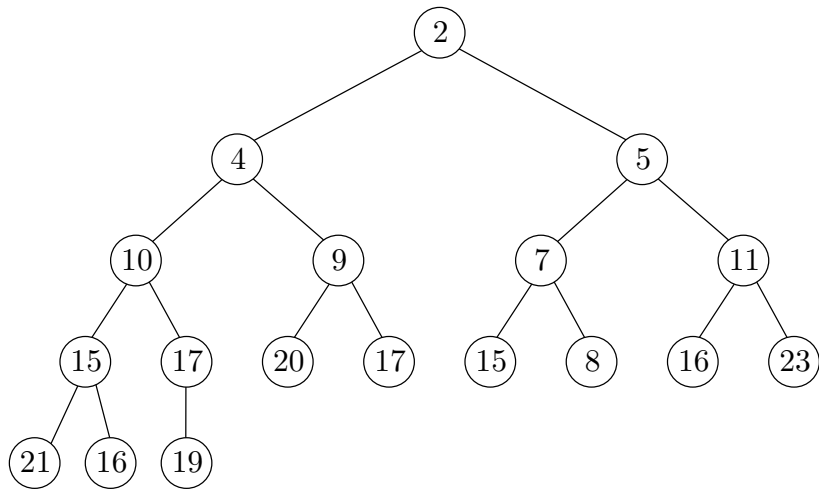
The following **heap property** is satisfied:

- for any two nodes i, j such that i is the parent of j , we have $key[A[i]] \leq key[A[j]]$.

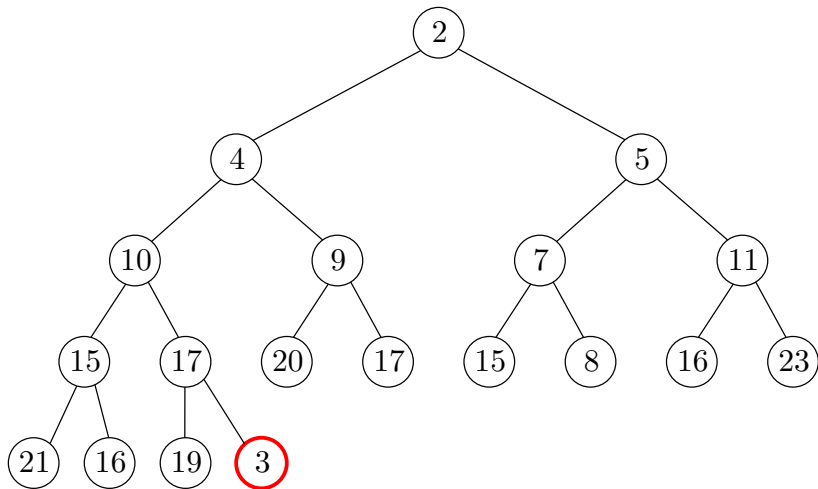


A heap. Numbers in the circles denote key values of elements.

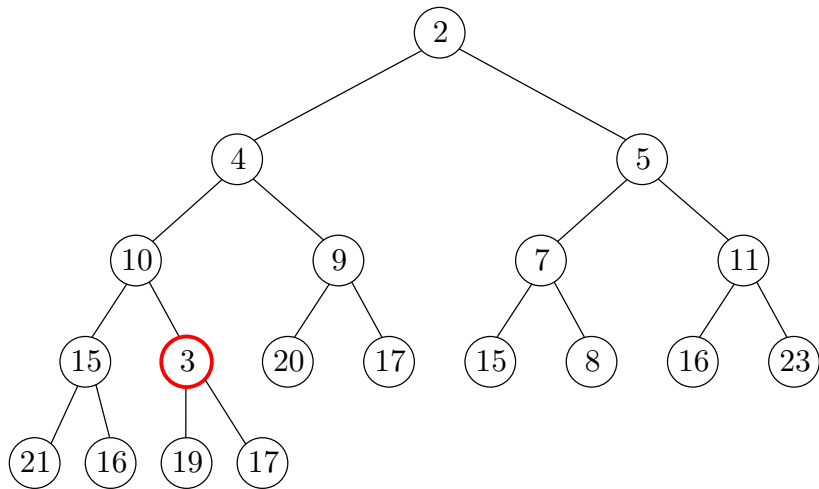
`insert(v , key_value)`



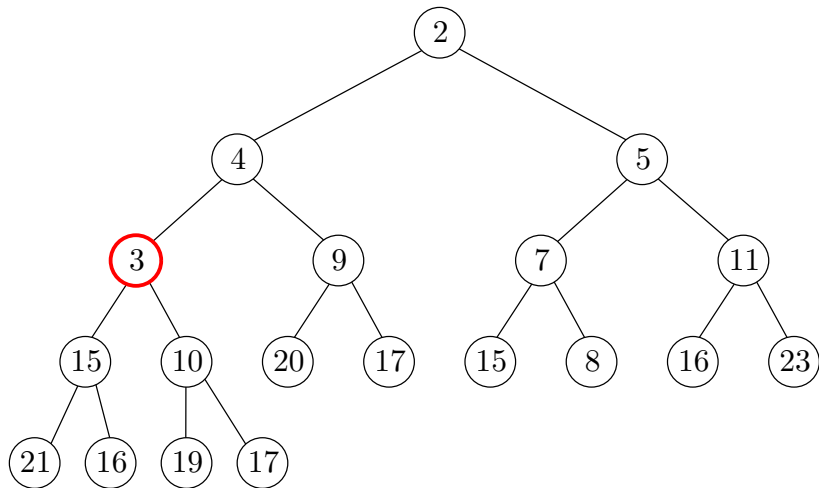
$\text{insert}(v, \text{key_value})$



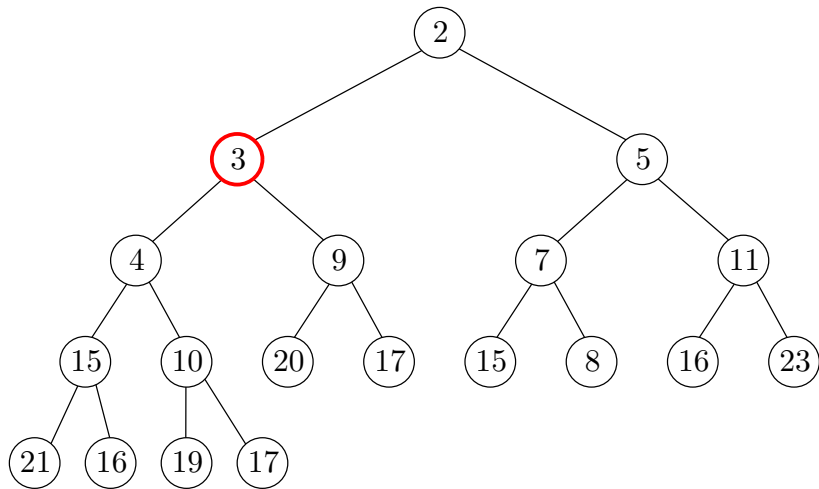
$\text{insert}(v, \text{key_value})$



$\text{insert}(v, \text{key_value})$



`insert(v , key_value)`



insert(v , key_value)

```
1:  $s \leftarrow s + 1$   
2:  $A[s] \leftarrow v$   
3:  $p[v] \leftarrow s$   
4:  $key[v] \leftarrow key\_value$   
5: heapify-up( $s$ )
```

heapify-up(i)

```
1: while  $i > 1$  do  
2:    $j \leftarrow \lfloor i/2 \rfloor$   
3:   if  $key[A[i]] < key[A[j]]$  then  
4:     swap  $A[i]$  and  $A[j]$   
5:      $p[A[i]] \leftarrow i, p[A[j]] \leftarrow j$   
6:      $i \leftarrow j$   
7:   else break
```