

Prim's Algorithm

For every $v \in V \setminus S$ maintain

- $d[v] = \min_{u \in S: (u,v) \in E} w(u, v)$:
the weight of the lightest edge between v and S
- $\pi[v] = \arg \min_{u \in S: (u,v) \in E} w(u, v)$:
 $(\pi[v], v)$ is the lightest edge between v and S

In every iteration

- Pick $u \in V \setminus S$ with the smallest $d[u]$ value
- Add $(\pi[u], u)$ to F
- Add u to S , update d and π values.

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In every iteration

- Pick $u \in V \setminus S$ with the smallest $d[u]$ value extract_min
- Add $(\pi[u], u)$ to F
- Add u to S , update d and π values. decrease_key

Use a **priority queue** to support the operations

Def. A **priority queue** is an **abstract** data structure that maintains a set U of elements, each with an associated key value, and supports the following operations:

- $\text{insert}(v, \text{key_value})$: insert an element v , whose associated key value is key_value .
- $\text{decrease_key}(v, \text{new_key_value})$: decrease the key value of an element v in queue to new_key_value
- $\text{extract_min}()$: return and remove the element in queue with the smallest key value
- ...

Prim's Algorithm

MST-Prim(G, w)

- 1: $s \leftarrow$ arbitrary vertex in G
- 2: $S \leftarrow \emptyset, d(s) \leftarrow 0$ and $d[v] \leftarrow \infty$ for every $v \in V \setminus \{s\}$
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- 4: **while** $S \neq V$ **do**
- 5: $u \leftarrow$ vertex in $V \setminus S$ with the minimum $d[u]$
- 6: $S \leftarrow S \cup \{u\}$
- 7: **for each** $v \in V \setminus S$ such that $(u, v) \in E$ **do**
- 8: **if** $w(u, v) < d[v]$ **then**
- 9: $d[v] \leftarrow w(u, v)$
- 10: $\pi[v] \leftarrow u$
- 11: **return** $\{(u, \pi[u]) \mid u \in V \setminus \{s\}\}$

Prim's Algorithm Using Priority Queue

MST-Prim(G, w)

- 1: $s \leftarrow$ arbitrary vertex in G
- 2: $S \leftarrow \emptyset, d(s) \leftarrow 0$ and $d[v] \leftarrow \infty$ for every $v \in V \setminus \{s\}$
- 3: $Q \leftarrow$ empty queue, for each $v \in V: Q.\text{insert}(v, d[v])$
- 4: **while** $S \neq V$ **do**
- 5: $u \leftarrow Q.\text{extract_min}()$
- 6: $S \leftarrow S \cup \{u\}$
- 7: **for** each $v \in V \setminus S$ such that $(u, v) \in E$ **do**
- 8: **if** $w(u, v) < d[v]$ **then**
- 9: $d[v] \leftarrow w(u, v), Q.\text{decrease_key}(v, d[v])$
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Running Time of Prim's Algorithm Using Priority Queue

$$O(n) \times (\text{time for extract_min}) + O(m) \times (\text{time for decrease_key})$$

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heap	$O(\log n)$	$O(\log n)$	$O(m \log n)$
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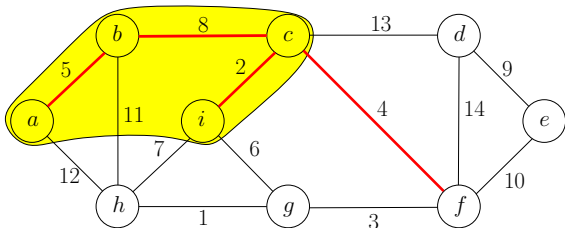
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Lemma (u, v) is in MST, if and only if there exists a **cut** $(U, V \setminus U)$, such that (u, v) is the lightest edge between U and $V \setminus U$.

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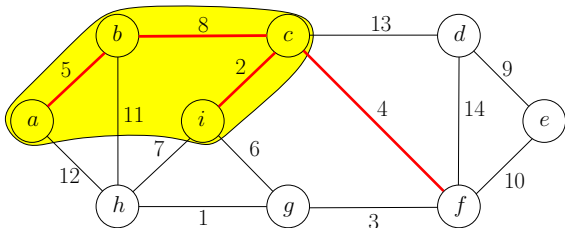
Lemma (u, v) is in MST, if and only if there exists a **cut** $(U, V \setminus U)$, such that (u, v) is the lightest edge between U and $V \setminus U$.



- (c, f) is in MST because of cut $(\{a, b, c, i\}, V \setminus \{a, b, c, i\})$

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- (c, f) is in MST because of cut $(\{a, b, c, i\}, V \setminus \{a, b, c, i\})$
- (i, g) is not in MST because no such cut exists

“Evidence” for $e \in \text{MST}$ or $e \notin \text{MST}$

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- $e \in \text{MST} \leftrightarrow$ there is a cut in which e is the lightest edge
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Thus, the minimum spanning tree is unique with assumption.

Outline

- 1 Minimum Spanning Tree
 - Kruskal's Algorithm
 - Reverse-Kruskal's Algorithm
 - Prim's Algorithm
- 2 Single Source Shortest Paths
 - Dijkstra's Algorithm
- 3 Shortest Paths in Graphs with Negative Weights
- 4 All-Pair Shortest Paths and Floyd-Warshall

algorithm	graph	weights	SS?	running time
Simple DP	DAG	\mathbb{R}	SS	$O(n + m)$
Dijkstra	U/D	$\mathbb{R}_{\geq 0}$	SS	$O(n \log n + m)$
Bellman-Ford	U/D	\mathbb{R}	SS	$O(nm)$
Floyd-Warshall	U/D	\mathbb{R}	AP	$O(n^3)$

- DAG = directed acyclic graph U = undirected D = directed
- SS = single source AP = all pairs

s - t Shortest Paths

Input: (directed or undirected) graph $G = (V, E)$, $s, t \in V$

$$w : E \rightarrow \mathbb{R}_{\geq 0}$$

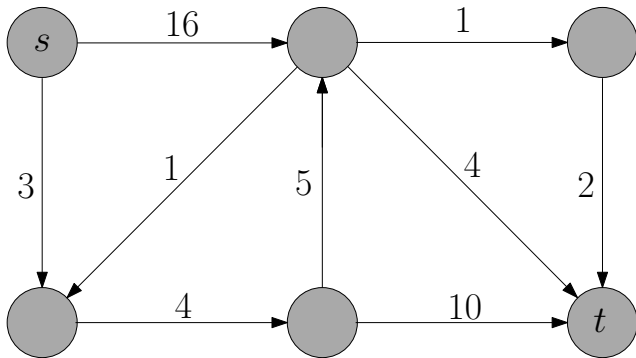
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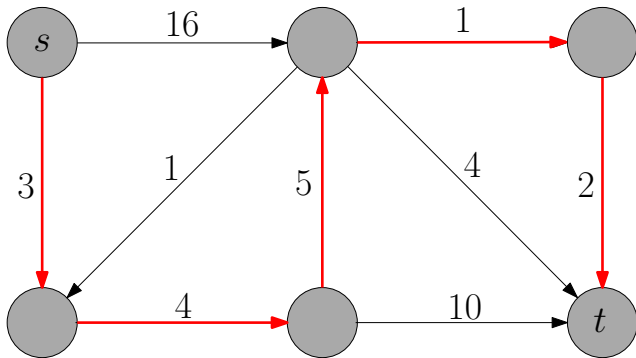


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Output: shortest paths from s to **all other vertices** $v \in V$

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Reason for Considering Single Source Shortest Paths Problem

- We do not know how to solve s - t shortest path problem more efficiently than solving single source shortest path problem

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- We do not know how to solve s - t shortest path problem more efficiently than solving single source shortest path problem
- Shortest paths in directed graphs is more general than in undirected graphs: we can replace every undirected edge with two anti-parallel edges of the same weight

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Single Source Shortest Paths

Input: directed graph $G = (V, E)$, $s \in V$

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Output: $\pi[v], v \in V \setminus s$: the parent of v in shortest path tree

$d[v], v \in V \setminus s$: the length of shortest path from s to v

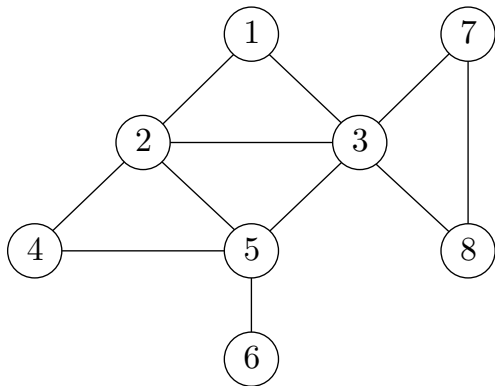
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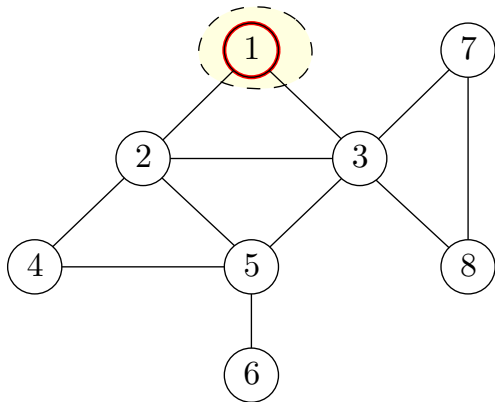
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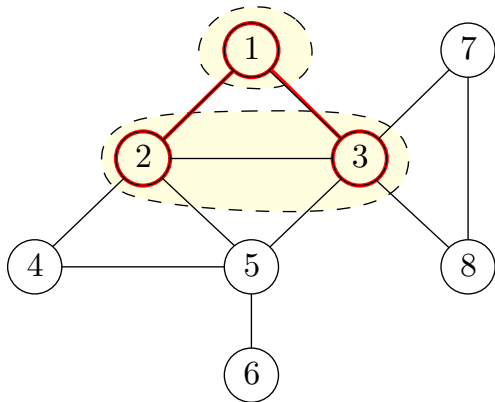
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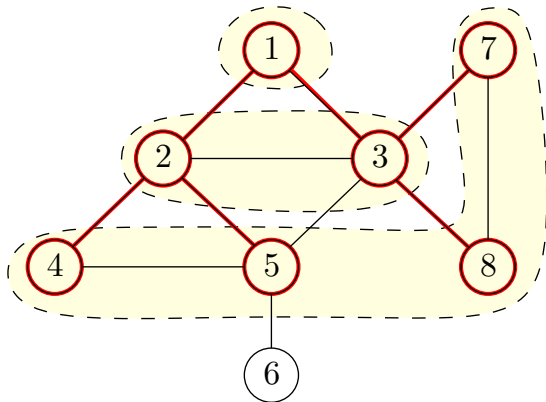
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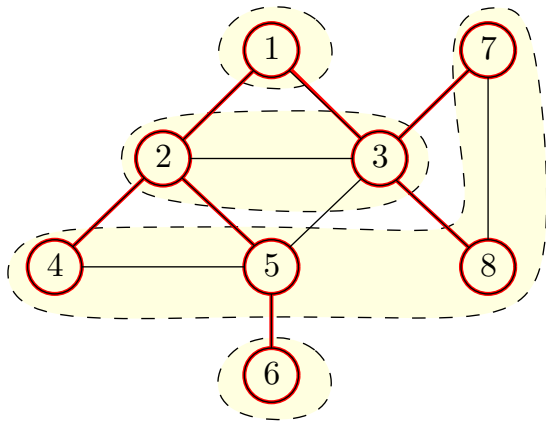
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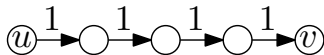
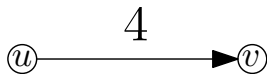
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Shortest Path Algorithm by Running BFS

- 1: replace (u, v) of length $w(u, v)$ with a path of $w(u, v)$ unit-weight edges, for every $(u, v) \in E$
- 2: run BFS
- 3: $\pi[v] \leftarrow$ vertex from which v is visited
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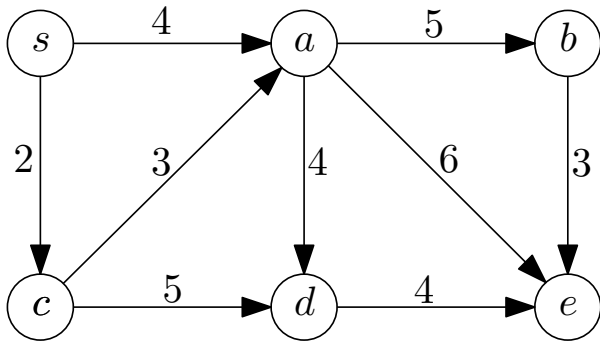
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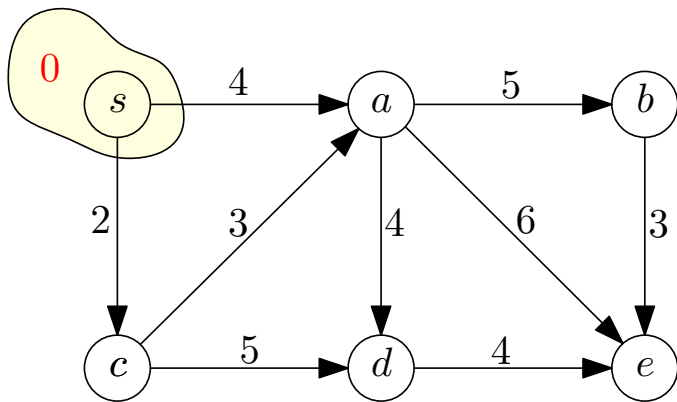
Shortest Path Algorithm by Running BFS Virtually

- 1: $S \leftarrow \{s\}, d(s) \leftarrow 0$
- 2: **while** $|S| \leq n$ **do**
- 3: find a $v \notin S$ that minimizes $\min_{u \in S: (u,v) \in E} \{d[u] + w(u, v)\}$
- 4: $S \leftarrow S \cup \{v\}$
- 5: $d[v] \leftarrow \min_{u \in S: (u,v) \in E} \{d[u] + w(u, v)\}$

Virtual BFS: Example

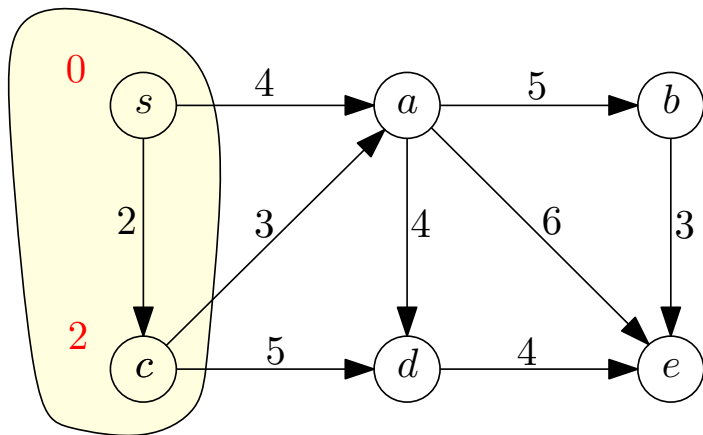


Virtual BFS: Example



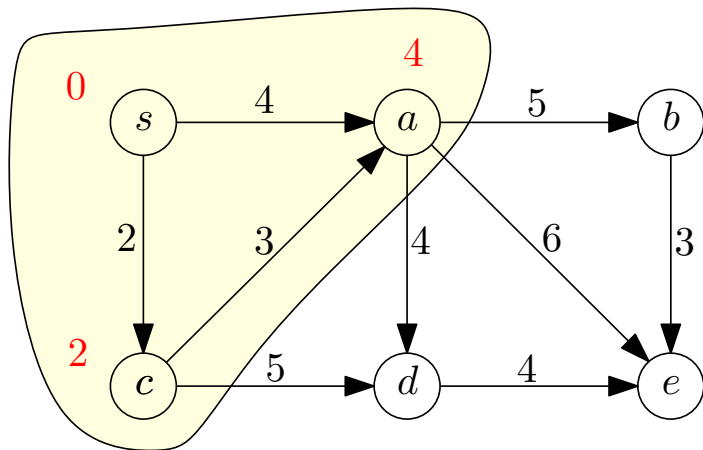
Time 0

Virtual BFS: Example



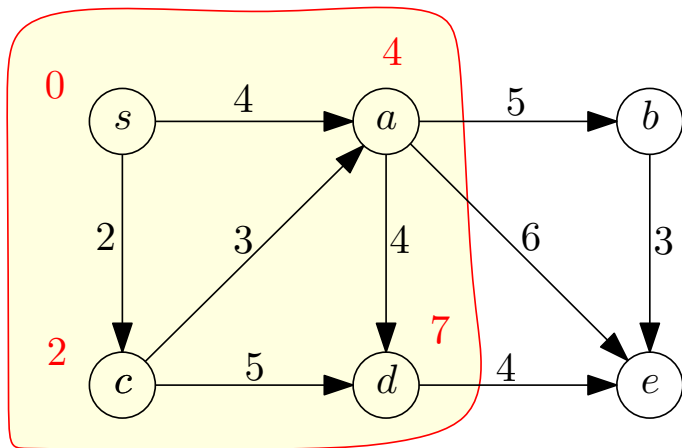
Time 2

Virtual BFS: Example



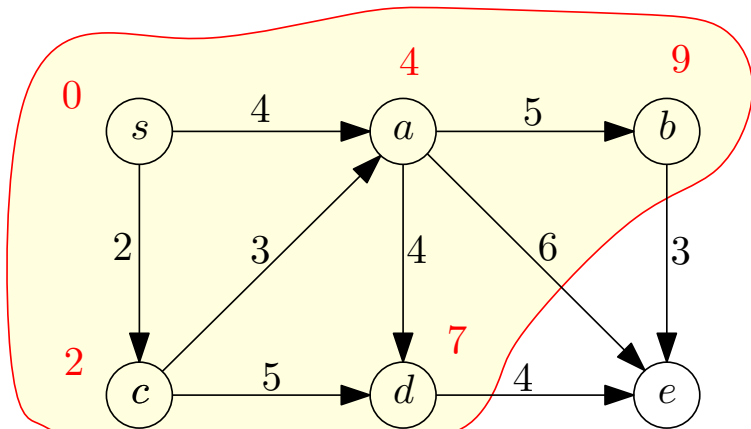
Time 4

Virtual BFS: Example



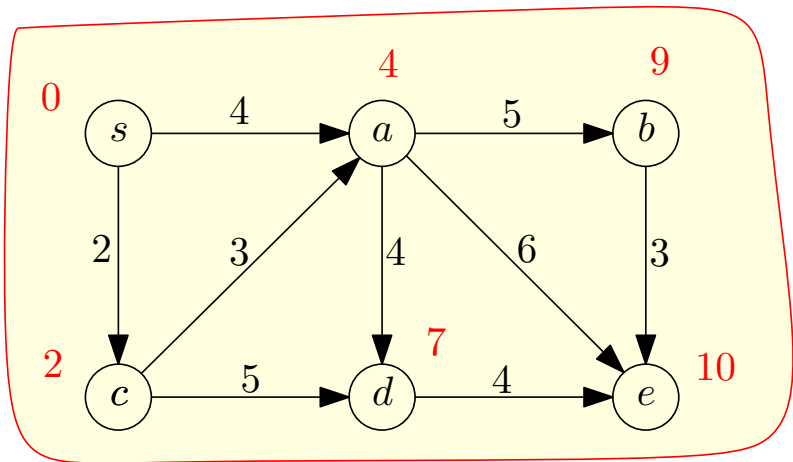
Time 7

Virtual BFS: Example



Time 9

Virtual BFS: Example



Time 10

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Dijkstra's Algorithm

Dijkstra(G, w, s)

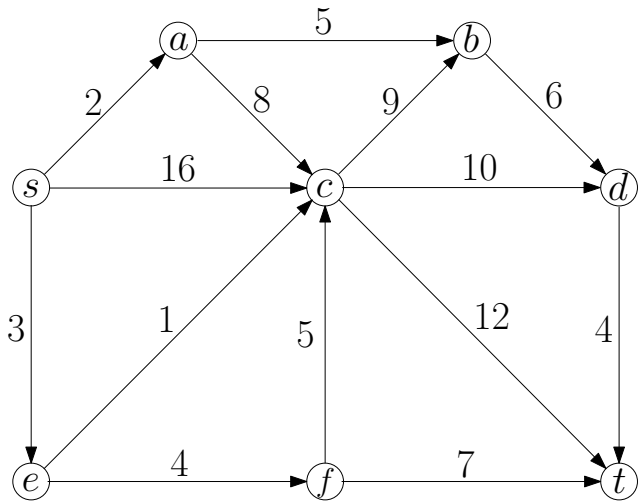
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- 5: **for** each $v \in V \setminus S$ such that $(u, v) \in E$ **do**
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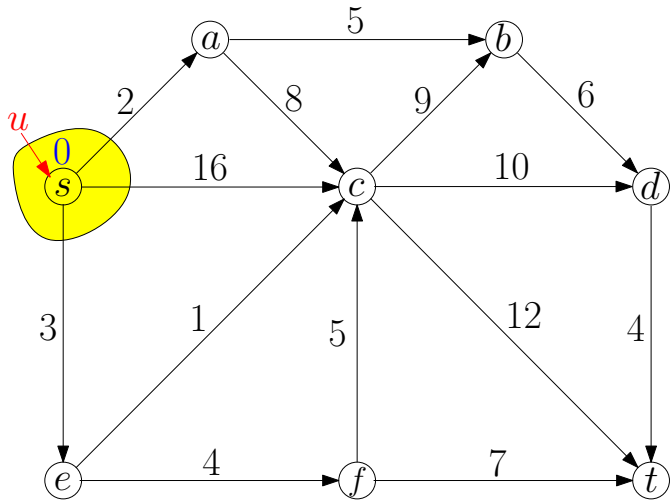
Dijkstra's Algorithm

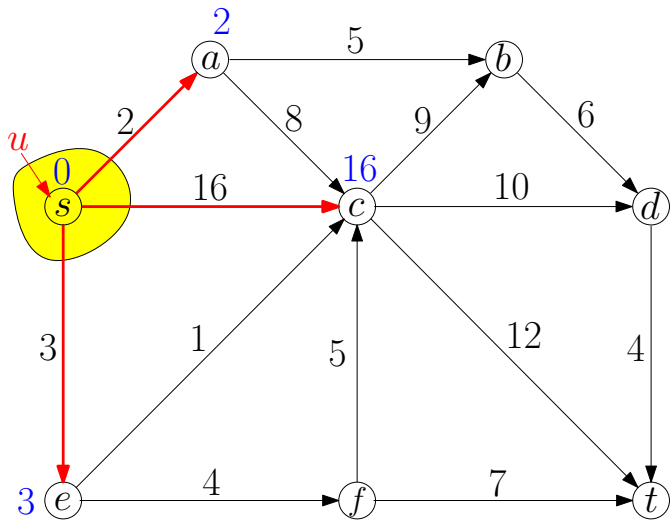
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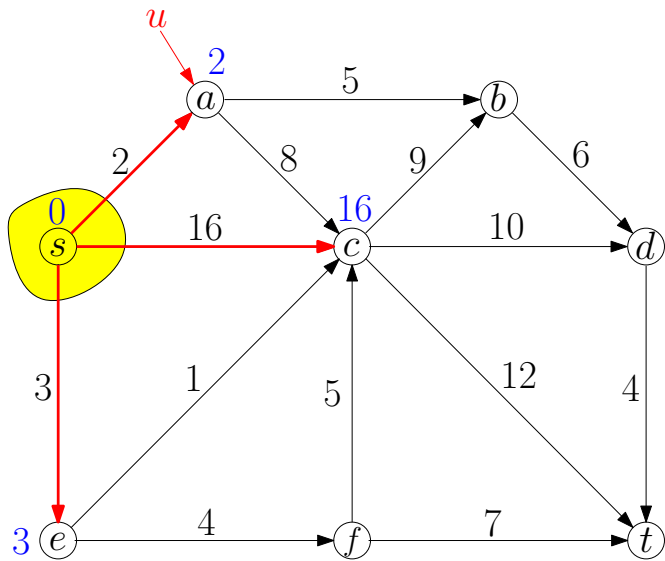
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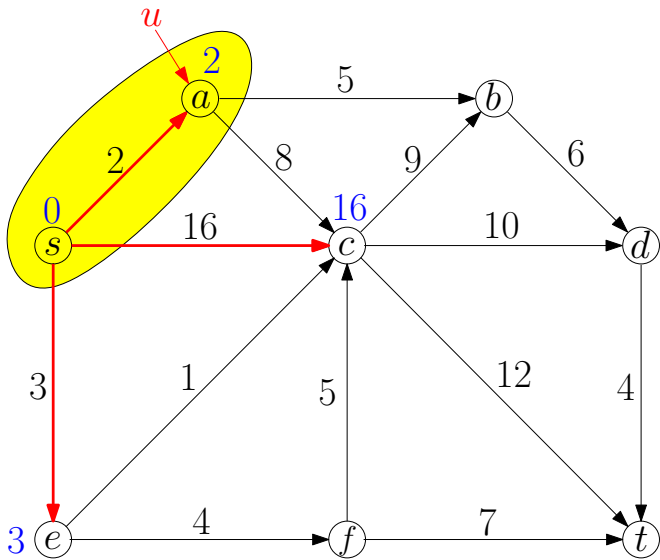
- Running time = $O(n^2)$

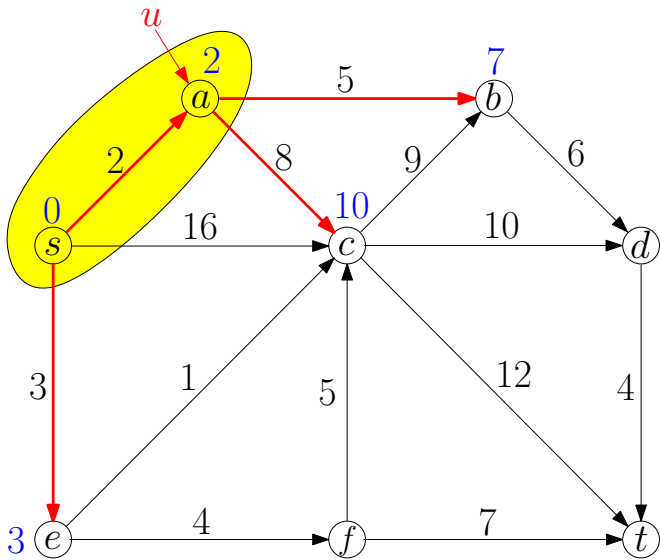


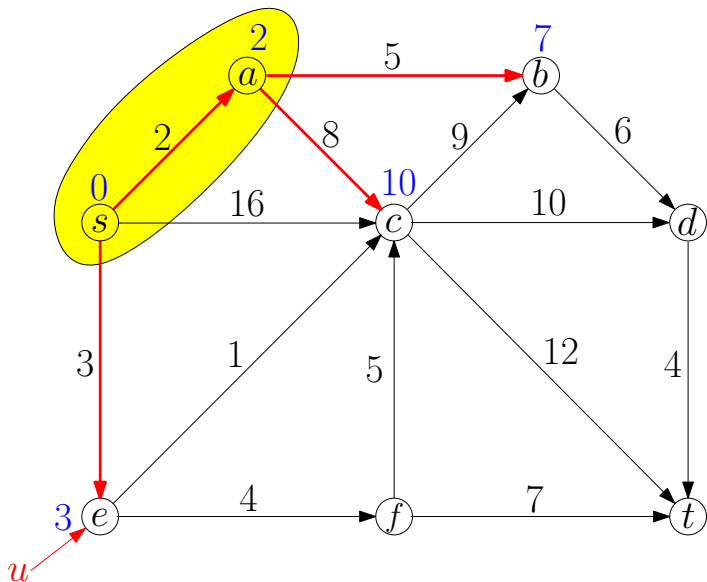


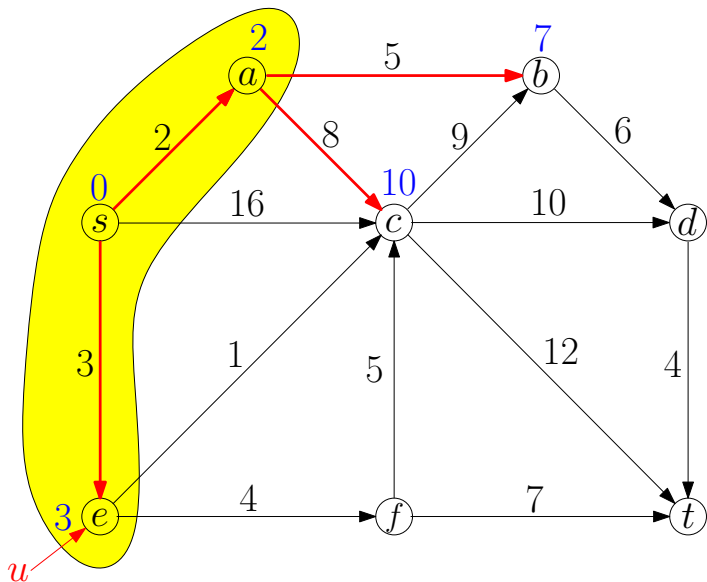


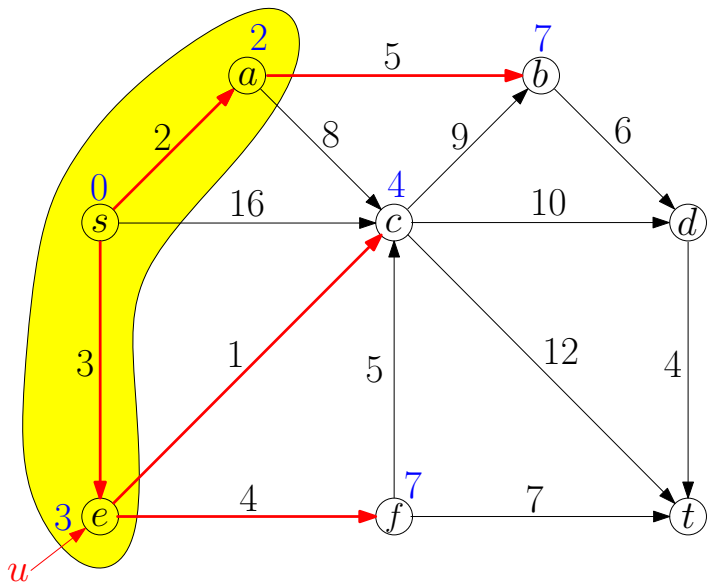


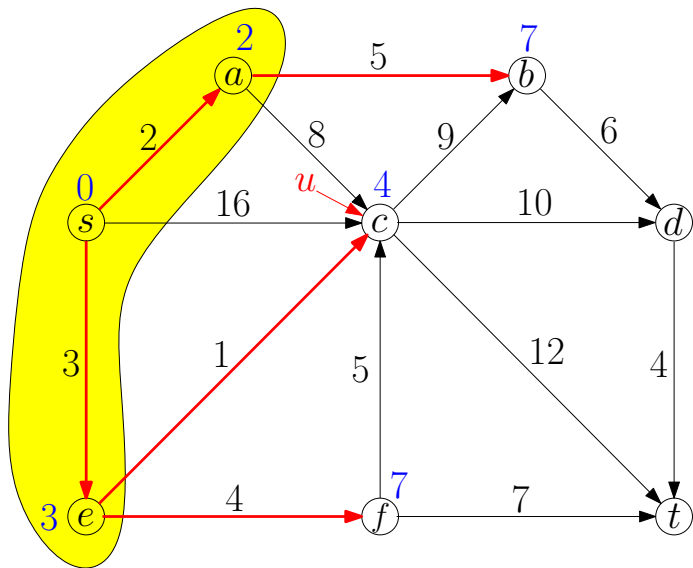


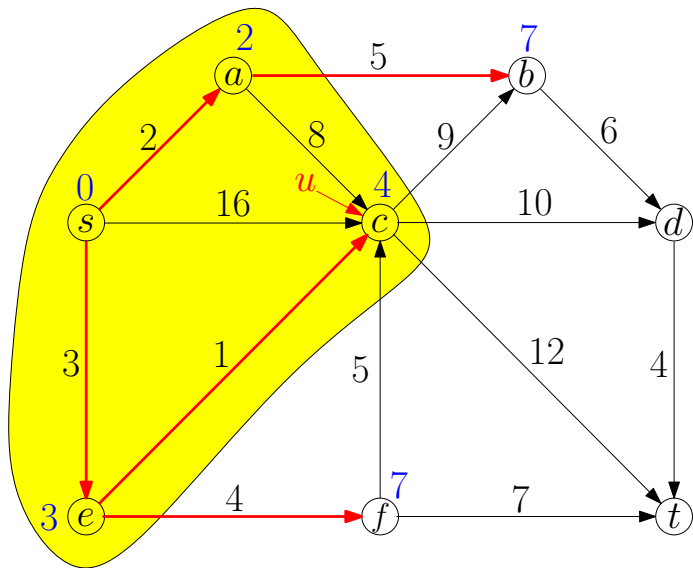


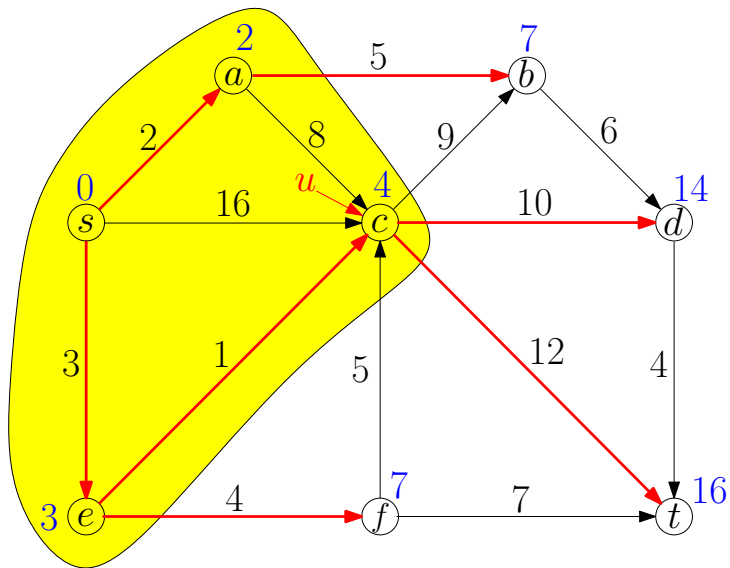


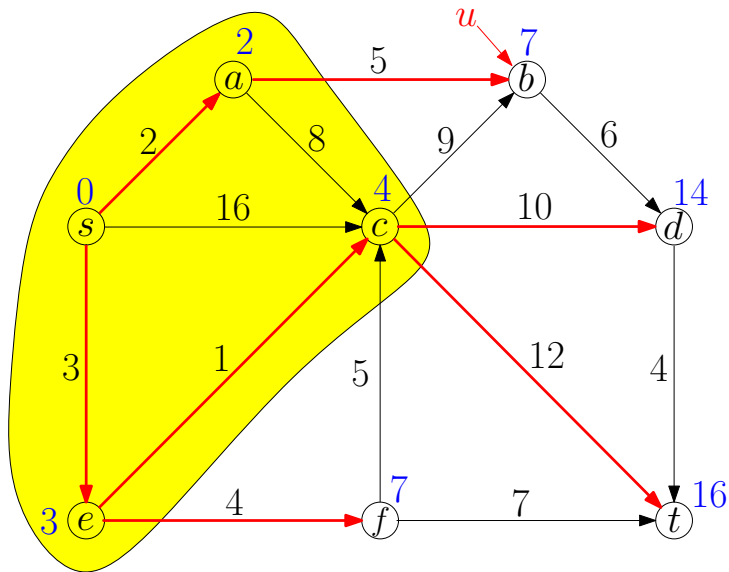


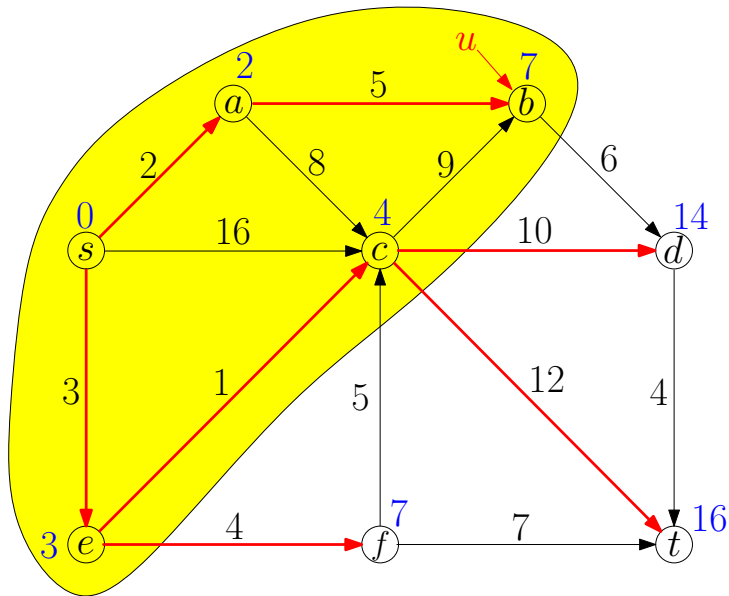


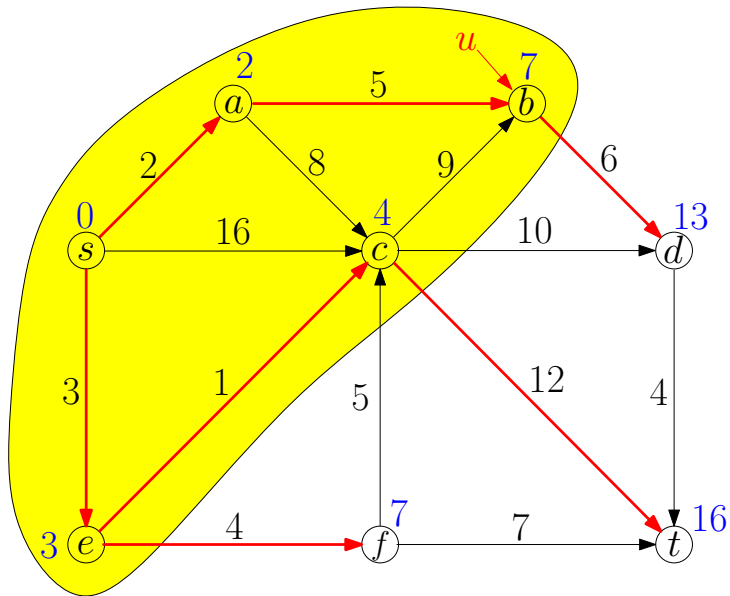


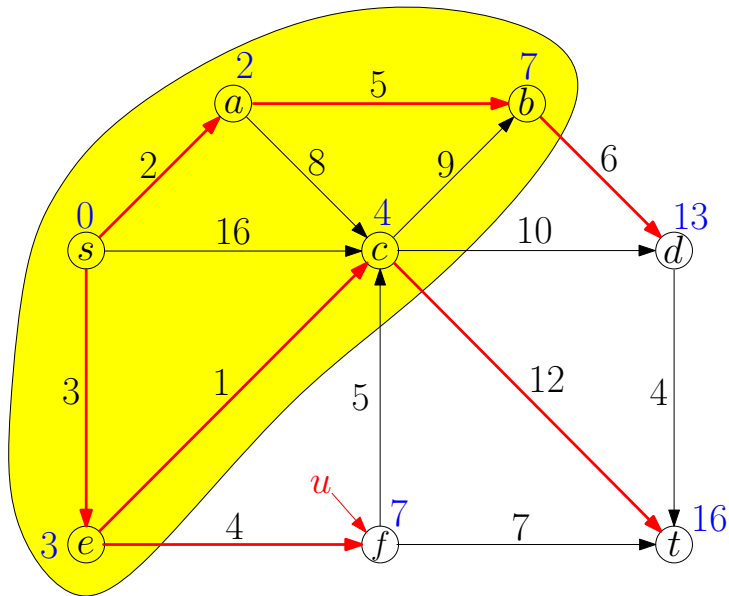


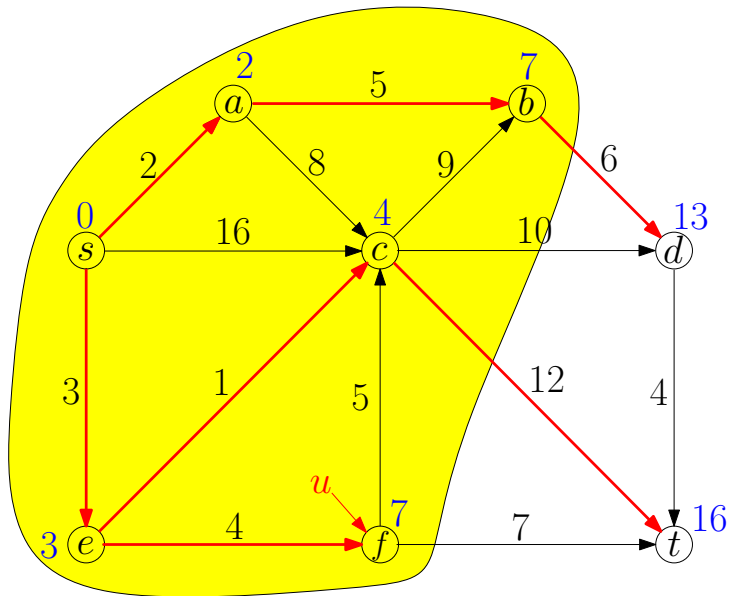


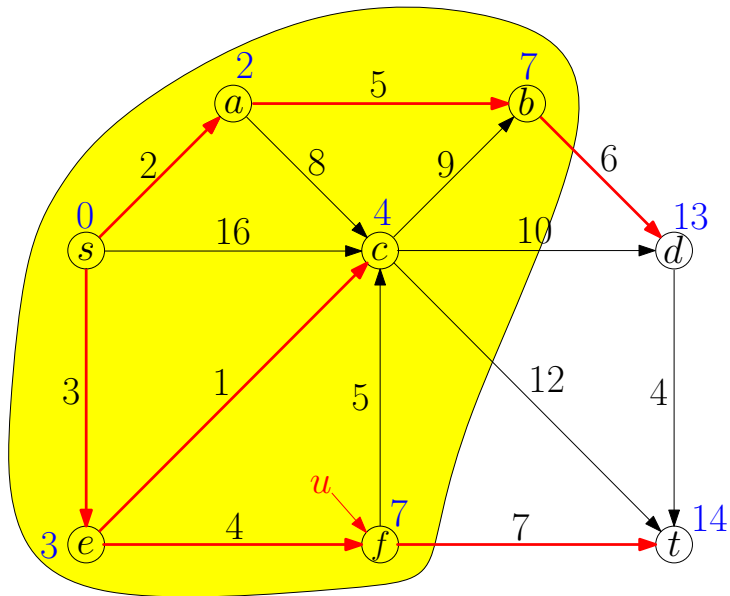


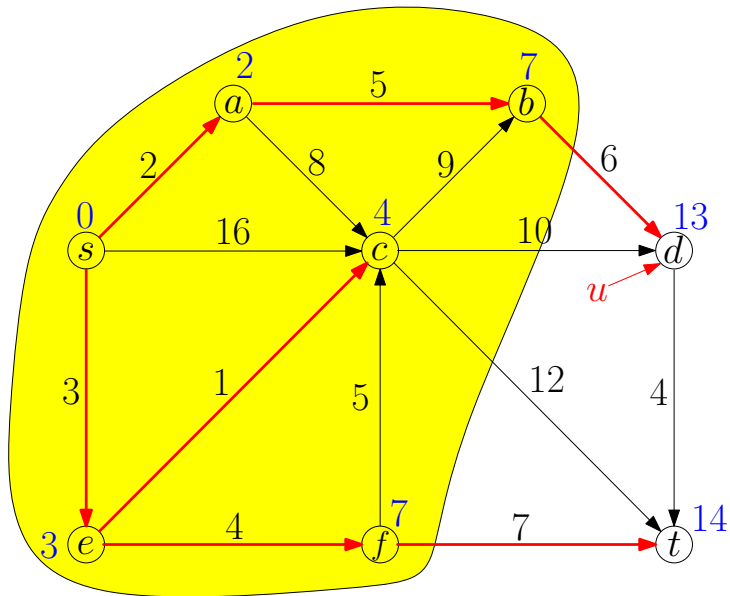


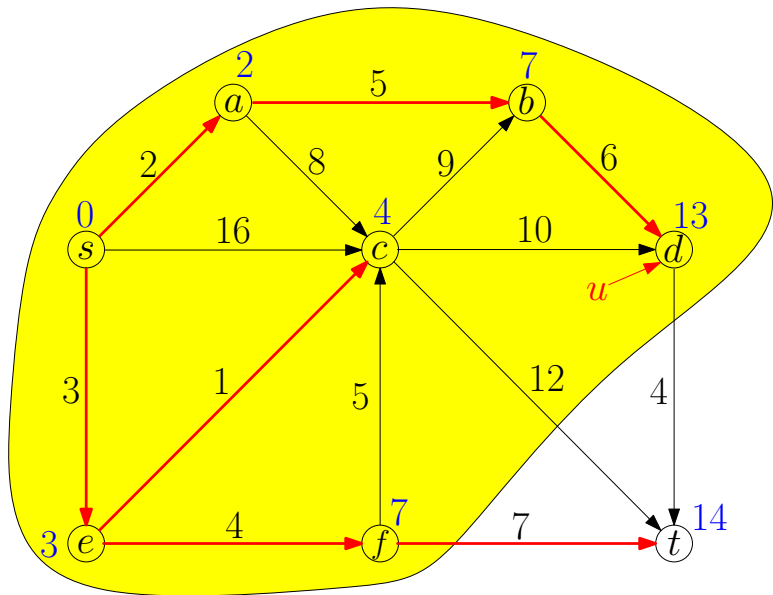


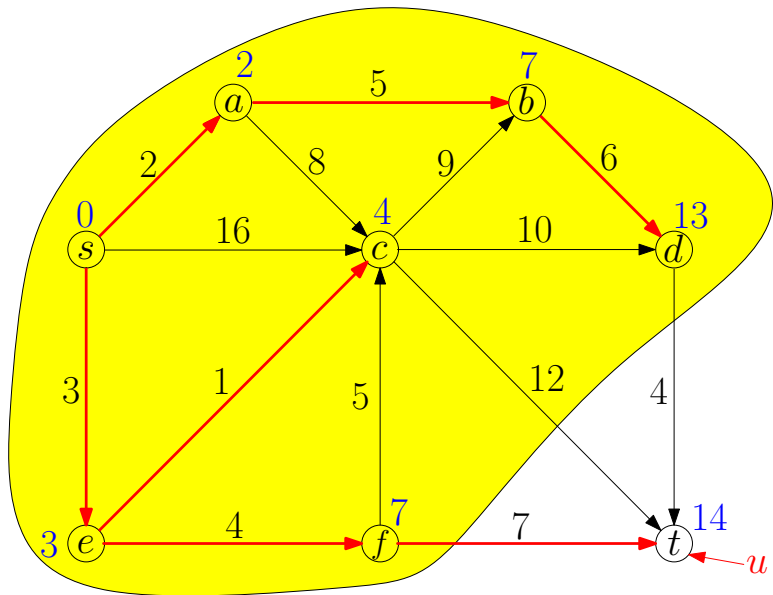


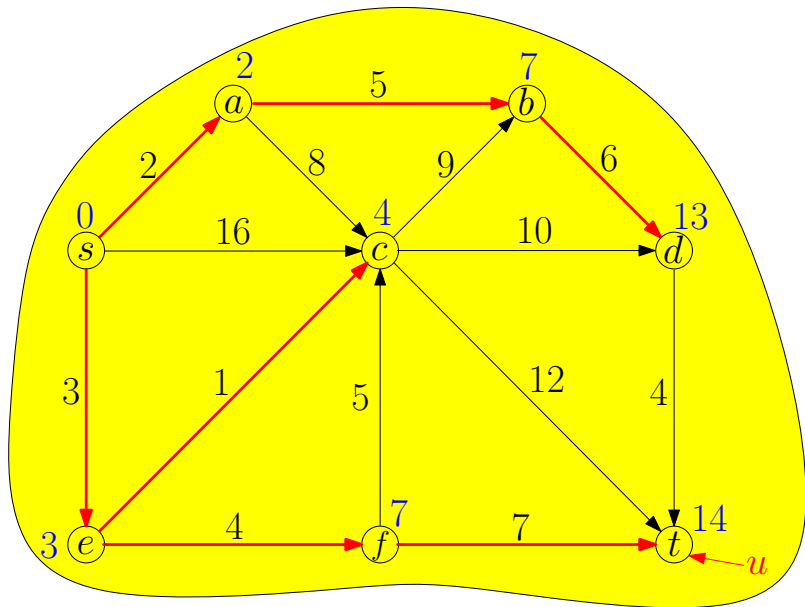












Improved Running Time using Priority Queue

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- 1: $s \leftarrow$ arbitrary vertex in G
- 2: $S \leftarrow \emptyset, d(s) \leftarrow 0$ and $d[v] \leftarrow \infty$ for every $v \in V \setminus \{s\}$
- 3: $Q \leftarrow$ empty queue, for each $v \in V: Q.insert(v, d[v])$
- 4: **while** $S \neq V$ **do**
- 5: $u \leftarrow Q.extract_min()$
- 6: $S \leftarrow S \cup \{u\}$
- 7: **for** each $v \in V \setminus S$ such that $(u, v) \in E$ **do**
- 8: **if** $d[u] + w(u, v) < d[v]$ **then**
- 9: $d[v] \leftarrow d[u] + w(u, v), Q.decrease_key(v, d[v])$
- 10: $\pi[v] \leftarrow u$
- 11: **return** (π, d)

Recall: Prim's Algorithm for MST

MST-Prim(G, w)

- 1: $s \leftarrow$ arbitrary vertex in G
- 2: $S \leftarrow \emptyset, d(s) \leftarrow 0$ and $d[v] \leftarrow \infty$ for every $v \in V \setminus \{s\}$
- 3: $Q \leftarrow$ empty queue, for each $v \in V: Q.\text{insert}(v, d[v])$
- 4: **while** $S \neq V$ **do**
- 5: $u \leftarrow Q.\text{extract_min}()$
- 6: $S \leftarrow S \cup \{u\}$
- 7: **for** each $v \in V \setminus S$ such that $(u, v) \in E$ **do**
- 8: **if** $w(u, v) < d[v]$ **then**
- 9: $d[v] \leftarrow w(u, v), Q.\text{decrease_key}(v, d[v])$
- 10: $\pi[v] \leftarrow u$
- 11: **return** $\{(u, \pi[u]) \mid u \in V \setminus \{s\}\}$

Improved Running Time

Running time:

$O(n) \times (\text{time for extract_min}) + O(m) \times (\text{time for decrease_key})$

Priority-Queue	extract_min	decrease_key	Time
Heap	$O(\log n)$	$O(\log n)$	$O(m \log n)$
Fibonacci Heap	$O(\log n)$	$O(1)$	$O(n \log n + m)$