

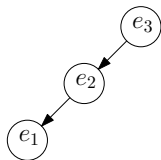
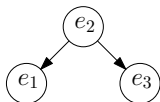
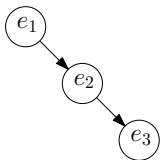
Optimum Binary Search Tree

- n elements $e_1 < e_2 < e_3 < \dots < e_n$
- e_i has frequency f_i
- goal: build a binary search tree for $\{e_1, e_2, \dots, e_n\}$ with the minimum accessing cost:

$$\sum_{i=1}^n f_i \times (\text{depth of } e_i \text{ in the tree})$$

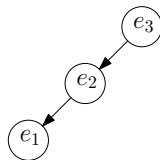
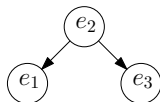
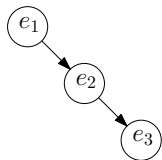
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- Example: $f_1 = 10, f_2 = 5, f_3 = 3$



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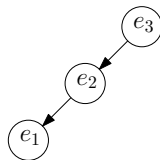
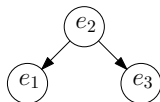
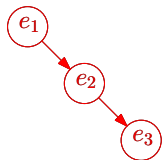
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- $10 \times 1 + 5 \times 2 + 3 \times 3 = 29$
- $10 \times 2 + 5 \times 1 + 3 \times 2 = 31$
- $10 \times 3 + 5 \times 2 + 3 \times 1 = 43$

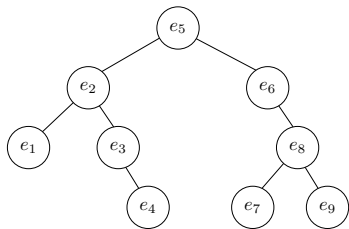
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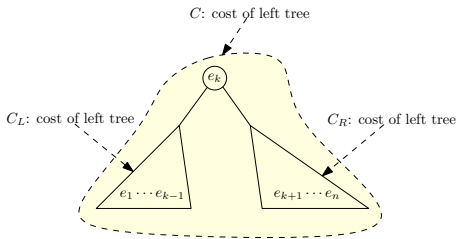


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- suppose we decided to let e_k be the root
- e_1, e_2, \dots, e_{k-1} are on left sub-tree
- $e_{k+1}, e_{k+2}, \dots, e_n$ are on right sub-tree
- d_j : depth of e_j in our tree
- C, C_L, C_R : cost of tree, left sub-tree and right sub-tree



- $d_1 = 3, d_2 = 2, d_3 = 3, d_4 = 4, d_5 = 1,$
- $d_6 = 2, d_7 = 4, d_8 = 3, d_9 = 4,$
- $C = 3f_1 + 2f_2 + 3f_3 + 4f_4 + f_5 + 2f_6 + 4f_7 + 3f_8 + 4f_9$
- $C_L = 2f_1 + f_2 + 2f_3 + 3f_4$
- $C_R = f_6 + 3f_7 + 2f_8 + 3f_9$
- $C = C_L + C_R + \sum_{j=1}^9 f_j$



$$\begin{aligned}
 C &= \sum_{\ell=1}^n f_{\ell} d_{\ell} = \sum_{\ell=1}^n f_{\ell} (d_{\ell} - 1) + \sum_{\ell=1}^n f_{\ell} \\
 &= \sum_{\ell=1}^{k-1} f_{\ell} (d_{\ell} - 1) + \sum_{\ell=k+1}^n f_{\ell} (d_{\ell} - 1) + \sum_{\ell=1}^n f_{\ell} \\
 &= C_L + C_R + \sum_{\ell=1}^n f_{\ell}
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- In general, $opt[i, j] =$

$$\begin{cases} 0 & \text{if } i = j + 1 \\ \min_{k:i \leq k \leq j} (opt[i, k-1] + opt[k+1, j]) + \sum_{\ell=i}^j f_{\ell} & \text{if } i \leq j \end{cases}$$

Optimum Binary Search Tree

- 1: $fsum[0] \leftarrow 0$
- 2: **for** $i \leftarrow 1$ **to** n **do** $fsum[i] \leftarrow fsum[i - 1] + f_i$
 $\triangleright fsum[i] = \sum_{j=1}^i f_j$
- 3: **for** $i \leftarrow 0$ **to** n **do** $opt[i + 1, i] \leftarrow 0$
- 4: **for** $\ell \leftarrow 1$ **to** n **do**
- 5: **for** $i \leftarrow 1$ **to** $n - \ell + 1$ **do**
- 6: $j \leftarrow i + \ell - 1, opt[i, j] \leftarrow \infty$
- 7: **for** $k \leftarrow i$ **to** j **do**
- 8: **if** $opt[i, k - 1] + opt[k + 1, j] < opt[i, j]$ **then**
- 9: $opt[i, j] \leftarrow opt[i, k - 1] + opt[k + 1, j]$
- 10: $\pi[i, j] \leftarrow k$
- 11: $opt[i, j] \leftarrow opt[i, j] + fsum[j] - fsum[i - 1]$

Print-Tree(i, j)

```
1: if  $i > j$  then  
2:   return  
3: else  
4:   print('(')  
5:   Print-Tree( $i, \pi[i, j] - 1$ )  
6:   print( $\pi[i, j]$ )  
7:   Print-Tree( $\pi[i, j] + 1, j$ )  
8:   print('')
```

Outline

- 1 Weighted Interval Scheduling
- 2 Subset Sum Problem
- 3 Knapsack Problem
- 4 Longest Common Subsequence
 - Longest Common Subsequence in Linear Space
- 5 Shortest Paths in Directed Acyclic Graphs
- 6 Matrix Chain Multiplication
- 7 Optimum Binary Search Tree
- 8 Summary**
- 9 Summary of Studies Until Nov 1st

Dynamic Programming

- Break up a problem into many **overlapping** sub-problems
- Build solutions for larger and larger sub-problems
- Use a **table** to store solutions for sub-problems for reuse

Comparison with greedy algorithms

- Greedy algorithm: each step is making a small progress towards constructing the solution
- Dynamic programming: the whole solution is constructed in the last step

Comparison with divide and conquer

- Divide and conquer: an instance is broken into many **independent** sub-instances, which are solved separately.
- Dynamic programming: the sub-instances we constructed are overlapping.

Definition of Cells for Problems We Learnt

- Weighted interval scheduling: $opt[i] =$ value of instance defined by jobs $\{1, 2, \dots, i\}$
- Subset sum, knapsack: $opt[i, W'] =$ value of instance with items $\{1, 2, \dots, i\}$ and budget W'
- Longest common subsequence: $opt[i, j] =$ value of instance defined by $A[1..i]$ and $B[1..j]$
- Shortest paths in DAG: $f[v] =$ length of shortest path from s to v
- Matrix chain multiplication, optimum binary search tree:
 $opt[i, j] =$ value of instances defined by matrices i to j

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- Introduction:
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 - Topological Ordering problem: topological-sort algorithm

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 - Exercise problems: Fractional knapsack problem, scheduling problem (min weighted sum of completion times)

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 - Exercise problems: Closest Pair, Convex Hull, Two Matrix Multiplication

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Quiz 6 about Dynamic Programming algorithms

- Fours problems about Dynamic programming algorithms