#### Plex

Plex is an interface for manifold topology that encodes a CW-comple (DAG). It allows true *dimension independent* programming, and meshes. Below are two tetrahedra sharing a face and the correspor



**Basic Operations**: cone() for in-edges and support() for out-edges and support() for out transitive closures in the graph closure() and star().

#### **Nonconforming Extension**

We augment the interface with parent() and child() operations to subfaces, and we break the cone()/support() duality such that

- $p \in supp(q) \implies q \in cone(p)$
- star(p) covers the support of p's basis functions (also for FVM and
- cone(p) covers the boundary of p, but not child subfaces



The snaking lines show parent(d), parent(e), and  $parent(\delta)$ ; the bold support arrows do not have matching cone arrows, breaking the duality that is present in conformal meshes.

# The Impact of Structured AMR Representation on Software Design in PETSc https://arxiv.org/abs/1508.02470

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Nonconforming FEM: 
$$H^{1}$$
 Conformal Space  
ex as a Hasse diagram  
arbitrary subsetting of  
inding Hasse diagram.  
• Finite element assembly using *Plex opera*.  
discrete dual space  $V_h^*$ .  
• Nodal bases of nonconformal meshes are in-  
We constrain degrees of freedom of *child* properties of the constraint degrees of freedom of *child* properties of the subset of the constraints automating  
• Nodal bases of nonconformal meshes are in-  
We constrain degrees of freedom of *child* properties of the constraints automating  
• Nodal bases of nonconformal meshes are in-  
We constrain degrees of freedom of *child* properties of the subset of the definition of *child* properties of the global dual basis. For effect the subset of the definition of experiments for  $H^1$  conformed the support() relation also describes the support () relation also describes th







### ces on Nonconformal Meshes

ations (right) requires a nodal basis W for the

*overdetermined*: W has linear dependencies.

points to  $anchors() := closure() \circ parent()$ .

synchronization (DMGlobalToLocalBegin()

ically computed

ormal construction:

element T,

dual sp.], S(T) [reference cell CW-complex]),

ir *pullbacks* and *pushforwards*,

ck function f from  $K_i$  to reference cell] functional  $\sigma$  from reference cell to  $K_i$ ].

# $\delta_{jk} \Rightarrow \operatorname{supp}(\psi_k) = \bigcup \operatorname{star}(p)$ asis of P")

reference cell, and the requirement says that oport for functions "attached" to the points. The to mesh points, because the support of the within the *star()* of that point.

ompactly supported basis functions.

 $(\varphi_i^{-1}\mathcal{F}) \Rightarrow \varphi_i^* \varphi_i^{-*} \psi \in P(\varphi_i^{-1}\mathcal{F})$ line up")

space of P(T) on  $X \subset \overline{T}$ . This makes sure that npatible. This will allow us to build approximate space. The notation is somewhat dense, so for  $H^{\perp}$ ,

 $f^*\psi \in P(\mathcal{F}),$ 

 $\psi \in P(\varphi_i^{-1}\mathcal{F})$ 

# $\Rightarrow \exists M \in S_n \text{ s.t. } \mathcal{Q}_i^p = M \mathcal{Q}_j^q.$ up, modulo permutations")

nes that the dual bases of adjacent cells match oush functionals forward into each other. The polytopes in S and ensure that we choose the r example, the outward normal for a shared face is opposite for two cells sharing it, and only one direction must be chosen. Similarly, point evaluations on faces must follow the dihedral symmetries of the polytope.

## Capabilities

Energy Office of Advanced Scientific Computing, the NSF SI2 Program, and the Rice Intel Parallel Computing Cente

- Parallel mesh loading, partitioning, and redistribution for load balance FEM and FVM discretizations
- Unstructured data layout with boundary condition elimination Multigrid and block solvers

## Finite Volume Example



## The above figure shows a shock impinging on an oblique density contrast simulating using the Euler equation discretized with a TVD FV method, reproduced using TS ex11:

./ex11 -ufv\_vtk\_interval 1 -monitor density,energy -f -grid\_size 2,1 -grid\_bounds -1,1.,0.,1 -bc\_wall 1,2,3,4 -ufv\_use\_amr -refine\_vec\_tagger\_box 0.5,inf -coarsen\_vec\_tagger\_box 0,1.e-2 -refine\_tag\_view -coarsen\_tag\_view -physics euler -eu\_type iv\_shock -ufv\_cfl 10 -eu\_alpha 60. -grid\_skew\_60 -eu\_gamma 1.4 -eu\_amach 2.02 -eu\_rho2 -3. -petscfv\_type leastsquares -petsclimiter\_type minmod -petscfv\_compute\_gradients 0 -ts\_final\_time 1 -ts\_ssp\_type rks2 -ts\_ssp\_nstages 10

## **Finite Element Example**



With this concise, flexible interface, Plex supports

- -dm\_type p4est -dm\_forest\_partition\_overlap 1 -dm\_forest\_maximum\_refinement 6 -dm\_forest\_minimum\_refinement 2 -dm\_forest\_initial\_refinement 2

### Instantaneous variable-viscosity Stokes simulation with exponential viscosity constrast $e^{2Bx}$ , reproduced using SNES ex69:

./ex69 -dm\_plex\_separate\_marker -dm\_refine 4 -vel\_petscspace\_order 2 -pres\_petscspace\_order 1 -ksp\_rtol 1e-12 -pc\_type fieldsplit -pc\_fieldsplit\_type schur -pc\_fieldsplit\_schur\_factorization\_type full -pc\_fieldsplit\_schur\_precondition a11 -fieldsplit\_velocity\_pc\_type lu -fieldsplit\_pressure\_ksp\_rtol 1e-12 -fieldsplit\_pressure\_pc\_type lu -dm\_view hdf5:sol.h5 -sol\_vec\_view hdf5:sol.h5::append