

# The Impact of Solvers on Modeling: The Solvation-Layer Interface Condition

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## BEM and SLIC Collaboration



Jay Bardhan

How do available solvers influence our choice of model?

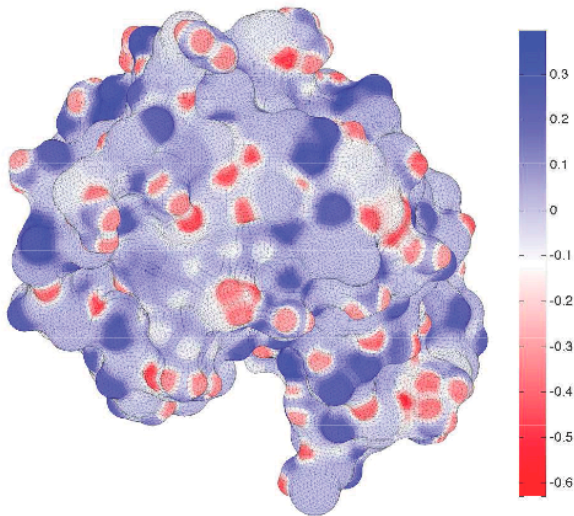
Nonlinear BEM is powerful,  
but neglected because  
it requires specialized solvers.

# Outline

- 1 Modeling
- 2 Solvers
- 3 Conclusions

# Bioelectrostatics

## The Natural World

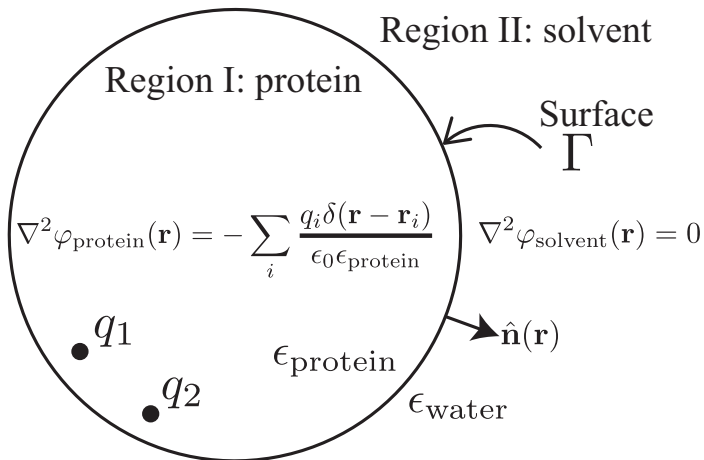


Induced Surface Charge on Lysozyme

# Bioelectrostatics

## Physical Model

### Electrostatic Potential $\phi$



# Bioelectrostatics

## Mathematical Model

We can write a Boundary Integral Equation (BIE) for the induced surface charge  $\sigma$ ,

$$\sigma(\vec{r}) + \hat{\epsilon} \int_{\Gamma} \frac{\partial}{\partial n(\vec{r})} \frac{\sigma(\vec{r}') d^2\vec{r}'}{4\pi\|\vec{r} - \vec{r}'\|} = -\hat{\epsilon} \sum_{k=1}^Q \frac{\partial}{\partial n(\vec{r})} \frac{q_k}{4\pi\|\vec{r} - \vec{r}_k\|}$$

$$(\mathcal{I} + \hat{\epsilon}D^*) \sigma(\vec{r}) =$$

where we define

$$\hat{\epsilon} = 2 \frac{\epsilon_I - \epsilon_{II}}{\epsilon_I + \epsilon_{II}} < 0$$



# Biomolecular Modeling

## Problems

This model is inaccurate for solvation energy.

# Biomolecular Modeling

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This model is inaccurate for solvation energy.

Thus practitioners adjust atomic radii to fit full atomistic simulation energies.

# Biomolecular Modeling

## Problems

However, a given atom

- can have two different radii in different molecules

# Biomolecular Modeling

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However, a given atom

- can have two different radii in different molecules
- can have two different radii in the **same** molecule

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- has a temperature-dependent radius

# Biomolecular Modeling

## Problems

However, a given atom

- can have two different radii in different molecules
- can have two different radii in the **same** molecule
- has a solvent-dependent radius
- has a temperature-dependent radius

For example, the volume of a carbon atom can vary by **50%** in a single molecule.

# Biomolecular Modeling

## Problems

Why is this a bad model?

- Ignores experimental data (crystal radii)



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- Not robust to solute/solvent/temperature changes

# Biomolecular Modeling

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- Not robust to solute/solvent/temperature changes
- Misses sensitivity to local electrostatic conditions

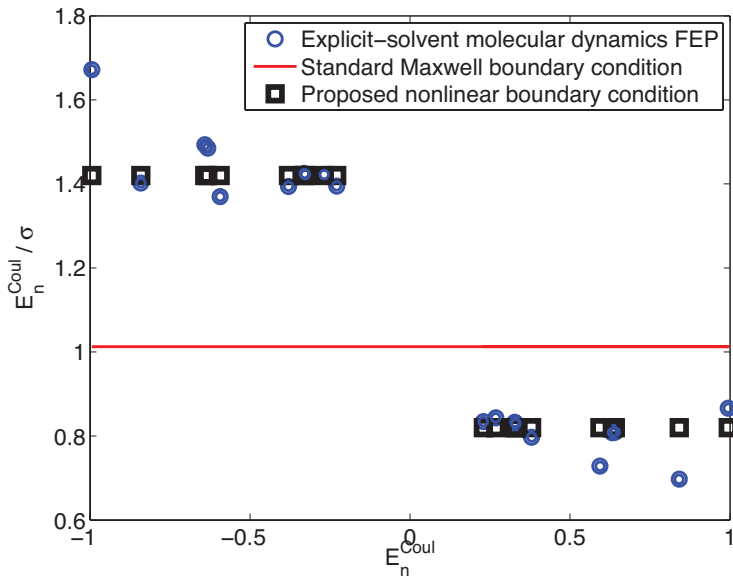
# Biomolecular Modeling

## Problems

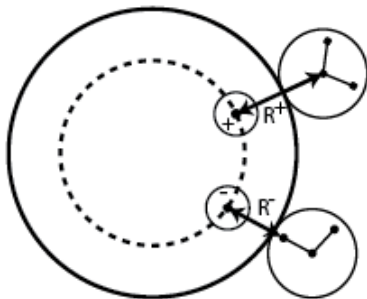
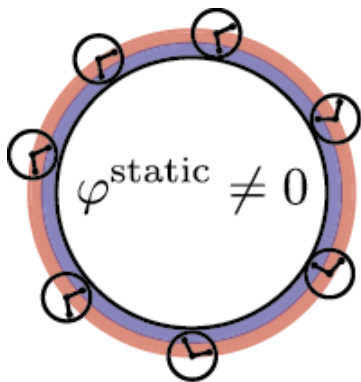
Why is this a bad model?

- Ignores experimental data (crystal radii)
- Not robust to solute/solvent/temperature changes
- Misses sensitivity to local electrostatic conditions
- Gives nonsense for the entropy

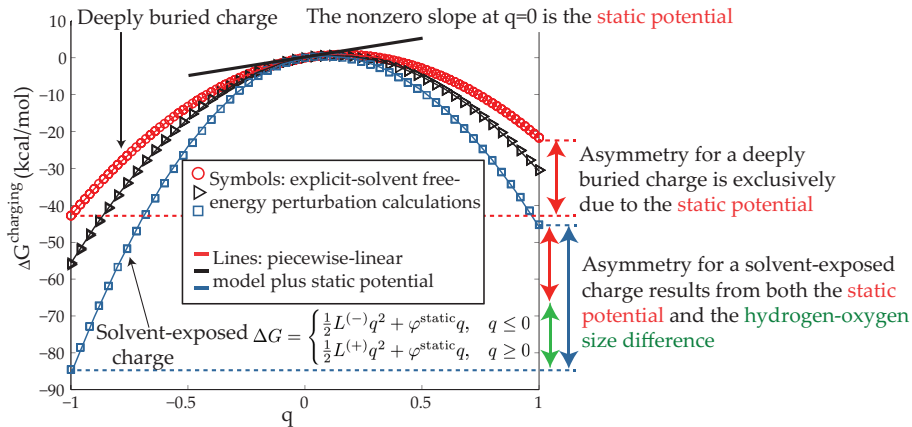
# Origins of Electrostatic Asymmetry



# Origins of Electrostatic Asymmetry



# Origins of Electrostatic Asymmetry



# Main Idea

## Solvation-Layer Interface Condition (SLIC)

Instead of assuming the model and energy and deriving the radii,

$$\epsilon_I \frac{\partial \Phi_I}{\partial n} = \epsilon_{II} \frac{\partial \Phi_{II}}{\partial n}$$

## Main Idea

## Solvation-Layer Interface Condition (SLIC)

assume the energy and radii and derive the model.

$$(\epsilon_I - \Delta\epsilon h(E_n)) \frac{\partial\Phi_I}{\partial n} = (\epsilon_{II} - \Delta\epsilon h(E_n)) \frac{\partial\Phi_{II}}{\partial n}$$



## Main Idea

## Solvation-Layer Interface Condition (SLIC)

Using our correspondence with the BIE form,

$$\left( \mathcal{I} + h(\mathbf{E}_n) + \hat{\epsilon} \left( -\frac{1}{2}\mathcal{I} + \mathcal{D}^* \right) \right) \sigma = \hat{\epsilon} \sum_{k=1}^Q \frac{\partial G}{\partial n}$$

where  $h$  is a diagonal nonlinear integral operator.

## SLIC

## Boundary Perturbation

$$h(E_n) = \alpha \tanh(\beta E_n - \gamma) + \mu$$

where

$\alpha$  Size of the asymmetry

$\beta$  Width of the transition region

$\gamma$  The transition field strength

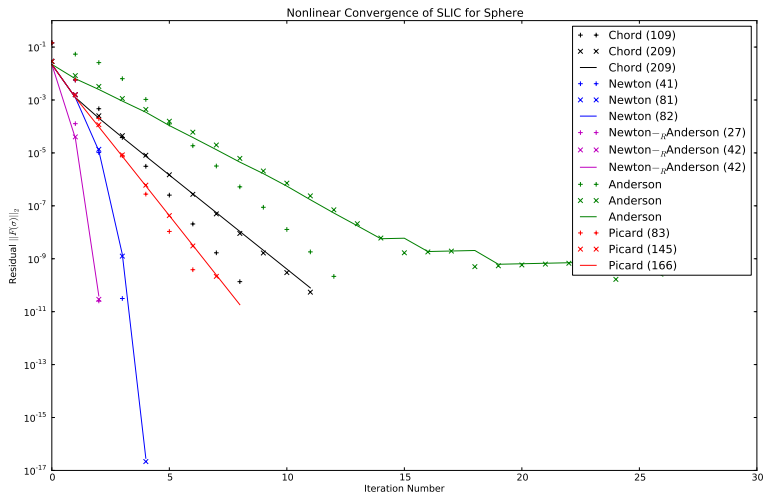
$\mu$  Assures  $h(0) = 0$ , so  $\mu = -\alpha \tanh(-\gamma)$

# Outline

- 1 Modeling
- 2 Solvers**
- 3 Conclusions

## Solving SLIC

## Sphere



# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Richardson's Method

$$u_{n+1} = u_n + \lambda (F(u_n) - b)$$

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Richardson's Method

```
-snes_type nrichardson  
-snes_linesearch_type 12  
-snes_linesearch_damping 0.05
```

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Newton's Method

$$u_{n+1} = u_n + J^{-1}(u_n) (F(u_n) - b)$$

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Newton's Method

```
-snes_type newtonls  
-snes_linesearch_type basic
```



# Nonlinear Solvers

If we are solving

$$Au + N(u)u = b$$

with Picard's Method

$$(A + \text{diag}(h(u_n))) u_{n+1} = b$$

# Nonlinear Solvers

If we are solving

$$Au + \text{diag}(h(u))u = b$$

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$$(A + \text{diag}(h(u_n))) u_{n+1} = b$$

# Nonlinear Solvers

If we are solving

$$Au + \text{diag}(h(u))u = b$$

with Picard's Method

$$J = A + \text{diag}(h(u_n)) + \text{diag}(h'(u_n))K'$$
$$J_P = A + \text{diag}(h(u_n))$$

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Generalized Broyden Method

$$u_{n+1} = u_n + \beta (F(u_n) - b) - (\mathbb{X}_k + \beta F(u_k)) \gamma_k$$
$$\gamma_i = (\mathcal{F}^T(u_k) \mathcal{F}(u_k))^{-1} \mathcal{F}^T(u_i) (F(u_i) - b)$$

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Generalized Broyden Method

```
-snes_type ngmres  
-snes_linesearch_type 12
```

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Newton –  $R$  Generalized Broyden Method

$$y = \mathcal{N}(F(\mathcal{GB}(F, \cdot, b)), x_n, b)$$
$$x_{n+1} = \mathcal{GB}(F, y, b)$$

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

with Newton –  $R$  Generalized Broyden Method

$$u' = \mathcal{GB}(F, u_n, b)$$
$$u_{n+1} = u' + J^{-1}(u')(F(u') - b)$$

# Nonlinear Solvers

If we are solving

$$F(u) = b$$

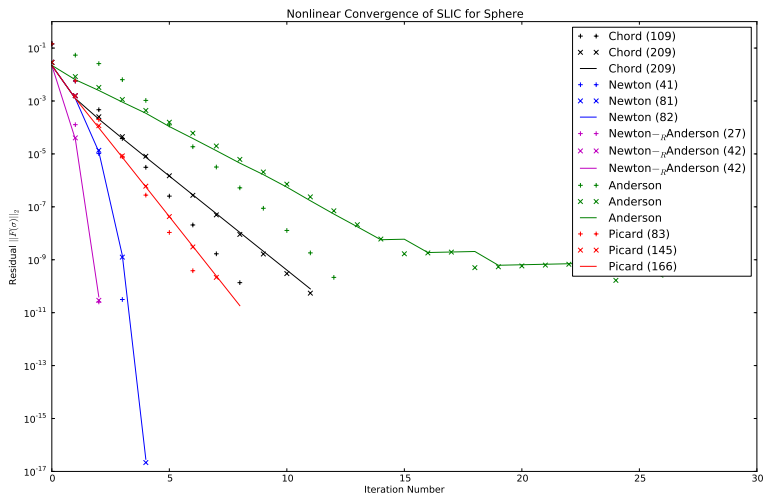
with Newton – $R$  Generalized Broyden Method

```
-snes_type newtonls  
-snes_linesearch_type basic  
-npc_snes_type ngmres  
-npc_snes_max_it 2
```



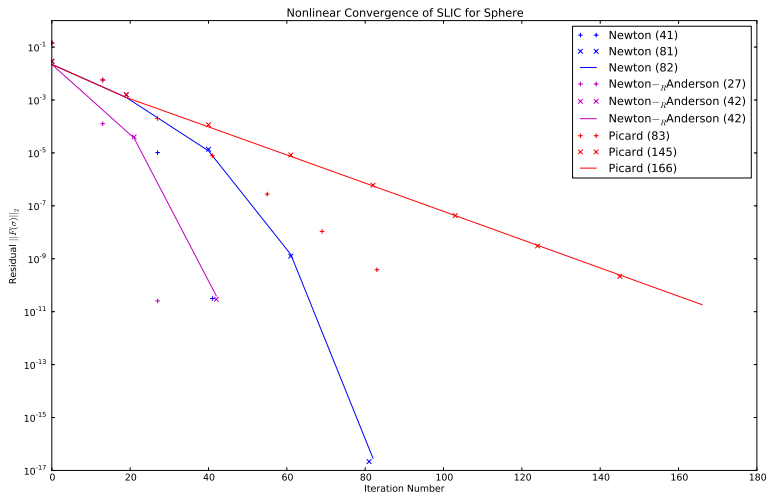
## Solving SLIC

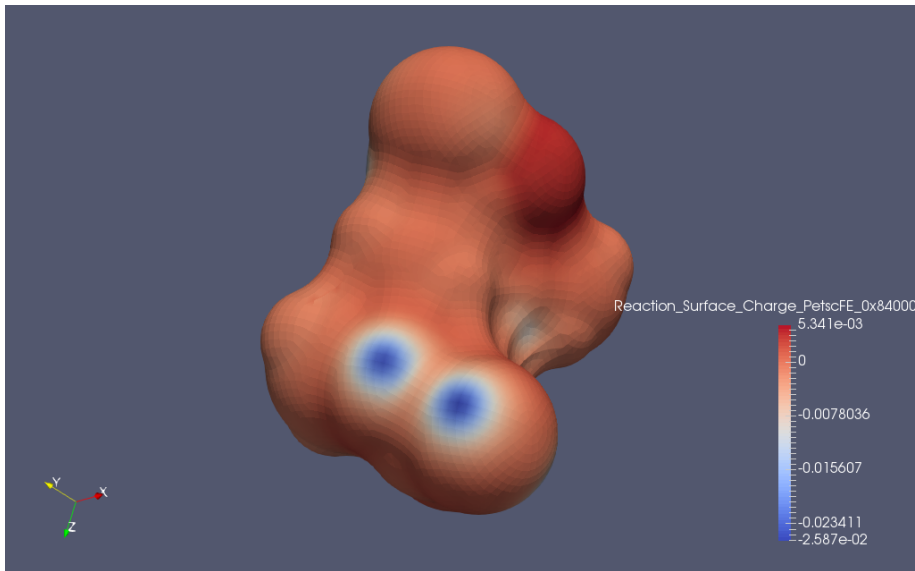
## Sphere



## Solving SLIC

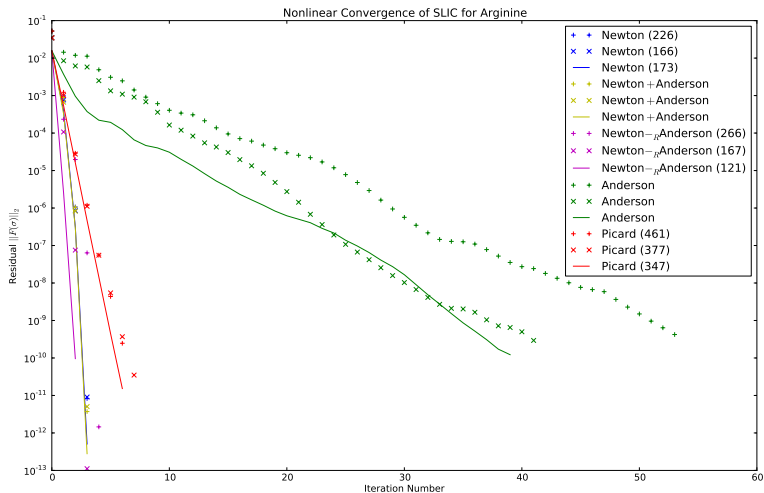
## Sphere





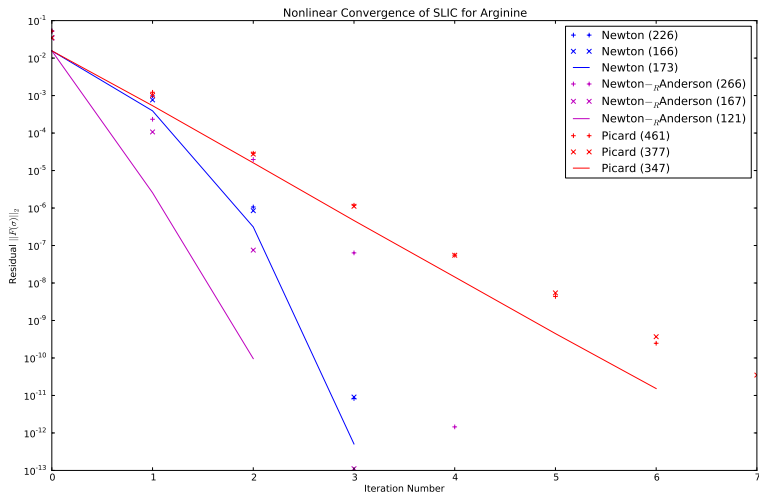
## Solving SLIC

## Arginine



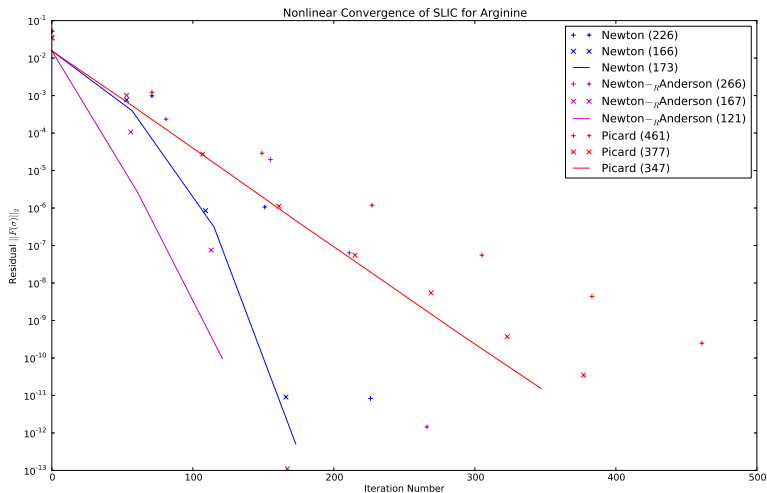
## Solving SLIC

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## Solving SLIC

## Arginine



# Outline

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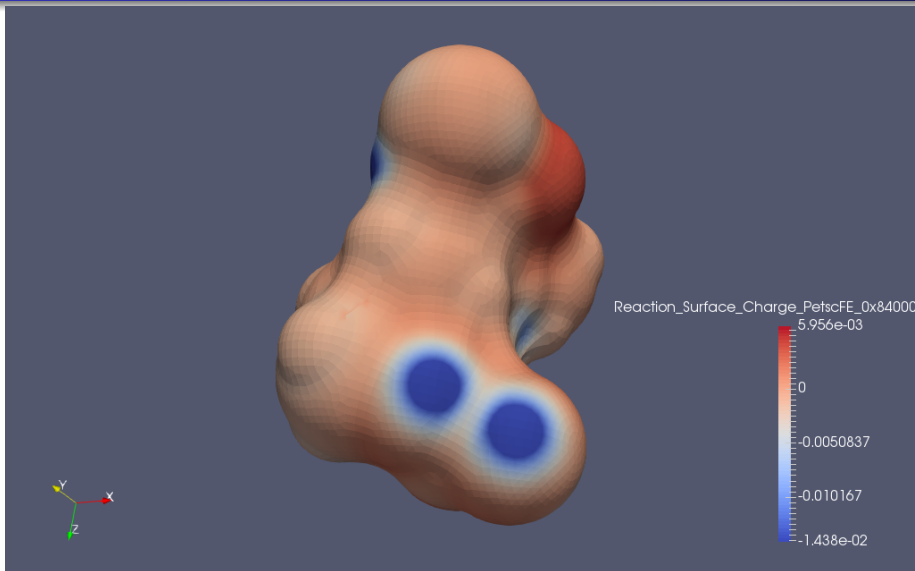
# Main Conclusion

Nonlinear Preconditioning  
can lead to significant  
speedups,  
and is accessible without  
recoding.



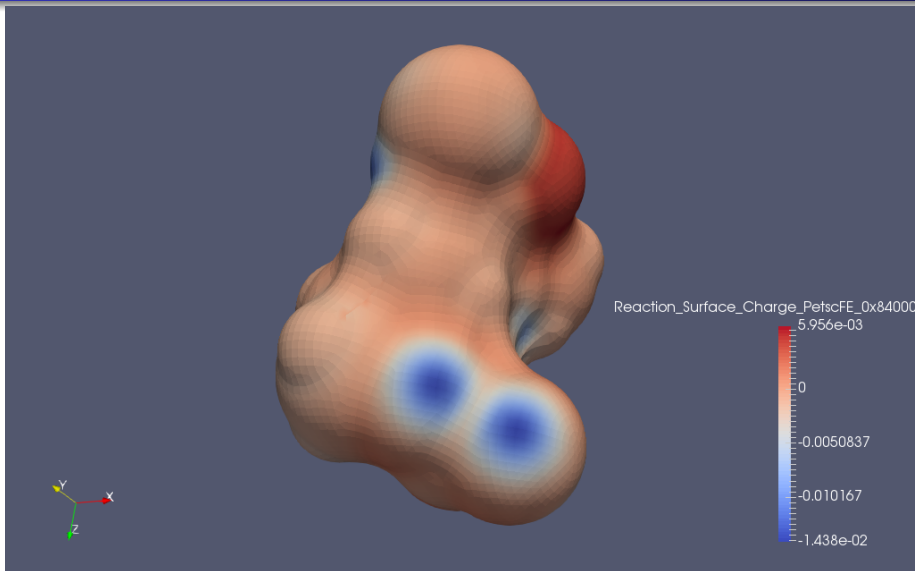
# Charge Distribution

Maxwell



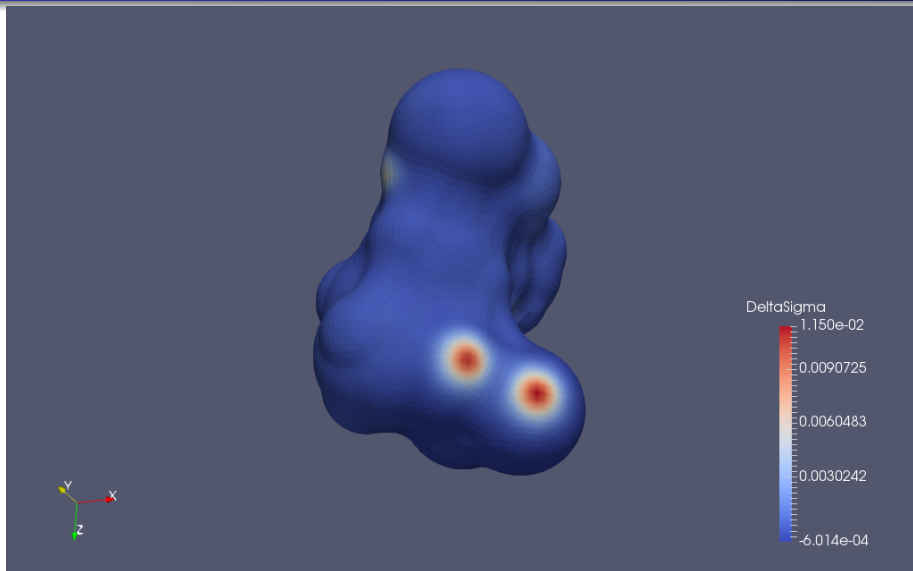
# Charge Distribution

SLIC



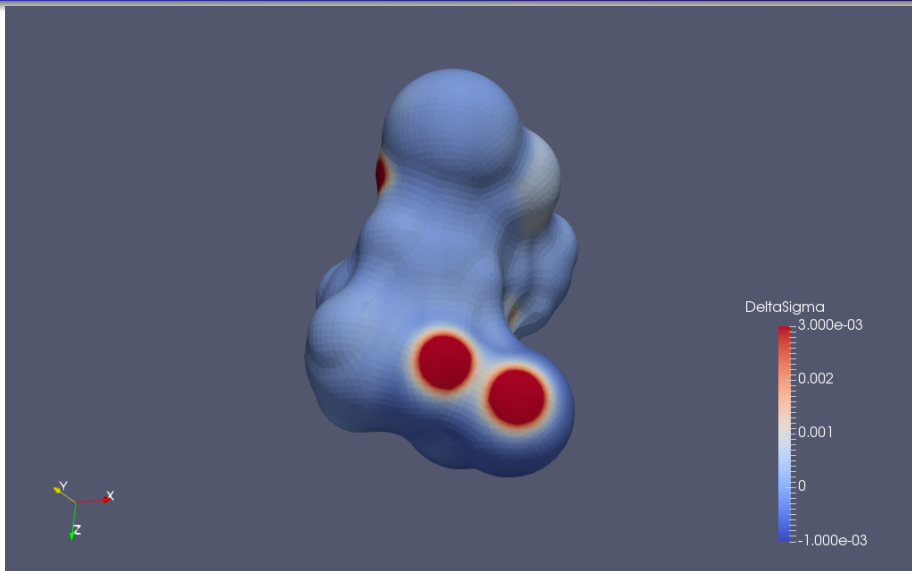
# Charge Distribution

Difference



# Charge Distribution

Difference (Rescaled)



# Future Work

- Cathodic Protection/Corrosion Prevention
- Homogenized boundary conditions
- Models of the hydrophobic interaction

# Thank You!

<http://cse.buffalo.edu/~knepley>