CSE 562 Database Systems

Query Processing: Physical Operators

Some slides are based or modified from originals by Database Systems: The Complete Book, Pearson Prentice Hall 2nd Edition ©2008 Garcia-Molina, Ullman, and Widom

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Algorithms for Algebra Operators

- Three primary techniques
 - Sorting
 - Hashing
 - Indexing
- Three degrees of difficulty
 - data small enough to fit in memory
 - too large to fit in main memory but small enough to be handled by a "two-pass" algorithm
 - so large that "two-pass" methods have to be generalized to "multi-pass" methods (quite unlikely nowadays)

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Outline - Query Optimization

- Overview
- Relational algebra level
 - Algebraic Transformations
- Detailed query plan level
 - Estimate Costs
 - Estimating size of results
 - Estimating # of IOs
 - Generate and compare plans

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Estimating IOs

 Count # of disk blocks that must be read (or written) to execute query plan

Additional Cost Estimation Parameters

- **B**(R) = # of blocks containing R tuples
- **f**(R) = max # of tuples of R per block
- **M** = # memory blocks available
- **HT**(i) = # levels in index i
- **LB**(i) = # of leaf blocks in index i

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Clustering Can Radically Change Cost

• Clustered file organization

R1 R2 S1 S2 R3 R4 S3 S4 ...

Clustered relation

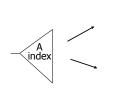
R1 R2 R3 R4 R5 R5 R7 R8 ···

Clustering index

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Clustering Index

• Index that allows tuples to be read in an order that corresponds to physical order



Α	
10	
15	
17	
19 35	
35	
37	

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Example

R1 | R2 over common attribute C

T(R1) = 10,000

T(R2) = 5,000

S(R1) = S(R2) = 1/10 block

Memory available = 101 blocks

 \rightarrow Metric: # of IOs

(ignoring writing of result)

Caution!

This may not be the best way to compare

- ignoring CPU costs
- ignoring timing
- ignoring double buffering requirements

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Example

• **Iteration Join** (conceptually – without taking into account disk block issues)

```
\label{eq:second} \begin{split} \text{for each } r \in R1 \text{ do} \\ \text{for each } s \in R2 \text{ do} \\ \text{if } r.C = s.C \text{ then output } r\text{,s pair} \end{split}
```

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Options

- Transformations: R1 ⋈ R2, R2 ⋈ R1
- Join algorithms:
 - Iteration (nested loops)
 - Merge join
 - Join with index
 - Hash join

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Example

- Merge Join (conceptually)
 - (1) if R1 and R2 not sorted, sort them
 - (2) $i \leftarrow 1$; $j \leftarrow 1$; While $(i \le T(R1)) \land (j \le T(R2))$ do if R1 $\{i\}$.C = R2 $\{j\}$.C then outputTuples else if R1 $\{i\}$.C > R2 $\{j\}$.C then $j \leftarrow j+1$ else if R1 $\{i\}$.C < R2 $\{j\}$.C then $i \leftarrow i+1$

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Example

Procedure *outputTuples*

```
While (R1{ i }.C = R2{ j }.C) \land (i \le T(R1)) do [ jj \leftarrow j; while (R1{ i }.C = R2{ jj }.C) \land (jj \le T(R2)) do [ output pair R1{ i }, R2{ jj }; jj \leftarrow jj+1 ] i \leftarrow i+1 ]
```

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Example

i	R1{i}.C	R2{j}.C	j
1	10	5	1
2	20	20	2
3	20	20	3
4	30	30	4
5	40	30	5
		50	6
		52	7

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Example

• Join with Index (Conceptually)

```
For each r \in R1 do

[ X \leftarrow \text{index } (R2, C, r.C)

for each s \in X do

output r,s pair ]
```

Note: X ← index(rel, attr, value) then X = set of rel tuples with attr = value

Assume R2.C index

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Example

- Hash Join (Conceptual)
 - Hash function h, range $0 \rightarrow k$
 - Buckets for R1: G0, G1, ... Gk
 - Buckets for R2: H0, H1, ... Hk

Algorithm

- 1) Hash R1 tuples into G buckets
- 2) Hash R2 tuples into H buckets
- 3) For i = 0 to k do match tuples in Gi, Hi buckets

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Simple Example

hash: even/odd

R1

R2

5

4

12

13

3

8 11 14

Buckets

Even: 248 R1 4 12 8 14 R2

Odd: 359 531311

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Factors that Affect Performance

- (1) Tuples of relation stored physically together?
- (2) Relations sorted by join attribute?
- (3) Indexes exist?

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Disk-Oriented Computation Model

- There are *M* main memory buffers
 - Each buffer has the size of a disk block
- The input relation is read one block at a time
- The cost is the number of blocks read
- The output buffers are not part of the M buffers mentioned above
 - Pipelining allows the output buffers of an operator to be the input of the next one
 - We do not count the cost of writing the output

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Notation

- **B(R)** = number of blocks that **R** occupies
- T(R) = number of tuples of R
- V(R,[a₁, a₂,..., a_n]) = number of distinct tuples in the projection of R on a₁, a₂,..., a_n

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One-Pass Main Memory Algorithms for Unary Operators

- Assumption: Enough memory to keep the relation
- Projection and selection:
 - Scan the input relation R and apply operator one tuple at a time
 - Cost depends on
 - clustering of R
 - whether the blocks are consecutive
- Duplicate elimination and aggregation
 - create one entry for each group and compute the aggregated value of the group
 - it becomes hard to assume that CPU cost is negligible
 - main memory data structures are needed

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Generalization of Nested-Loops

for each chunk of M-1 blocks Br of R do
 store tuples of Br in main memory
 for each block Bs of S do
 for each tuple s of Bs
 join tuples of s with matching tuples of R

Exercise: Compute the cost of the above algorithm

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One-Pass Nested Loop Join

- Assume B(R) is less than M
- Tuples of *R* should be stored in an efficient lookup structure
- **Exercise:** Find the cost of the algorithm below

```
for each block Br of R do
    store tuples of Br in main memory
for each each block Bs of S do
    for each tuple s of Bs
        join tuples of s with matching tuples of R
```

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Simple Sort-Merge Join

- Assume natural join on C
- Sort R on C using the twophase multiway merge sort
 - if not already sorted
- Sort S on C
- Merge (opposite side)
 - assume two pointers Pr,Ps to tuples on disk, initially pointing at the start
 - sets R', s' in memory
- Remarks
 - Very low average memory requirement during merging (but no guarantee on how much is needed)
 - Cost:

while Pr!=EOF and Ps!=EOF
 if *Pr[C] == *Ps[C]
 do_cart_prod(Pr,Ps)
 else if *Pr[C] > *Ps[C]
 Ps++
 else if *Ps[C] > *Pr[C]
 Pr++

function do_cart_prod(Pr,Ps)
 val = *Pr[C]
 while *Pr[C] == val
 store tuple *Pr in set R'
 while *Ps[C] == val
 store tuple *Ps in set S'
 output R' x S' // product

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Efficient Sort-Merge Join

- **Idea:** Save two disk I/O's per block by combining the second pass of sorting with the "merge"
- Step 1:

Create sorted sublists of size M for R and S

• Step 2:

Bring the first block of each sublist to a buffer

- assume no more than M sublists in all
- Step 3:

Repeatedly find the least ${\it C}$ value ${\it c}$ among the first tuples of each sublist. Identify all tuples with join value ${\it c}$ and join them.

 When a buffer has no more tuple that has not already been considered load another block into this buffer

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Two-Pass Hash-Based Algorithms

- General Idea: Hash the tuples of the input arguments in such a way that all tuples that must be considered together will have hashed to the same hash value
 - If there are M buffers pick M-1 as the number of hash buckets
- Example: Duplicate Elimination
 - Phase 1: Hash each tuple of each input block into one of the M-1 bucket/buffers. When a buffer fills, save to disk
 - Phase 2: For each bucket:
 - load the bucket in main memory
 - treat the bucket as a small relation and eliminate duplicates
 - save the bucket back to disk
 - Catch: Each bucket has to be less than M
 - Cost:

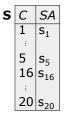
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R C RA

Efficient Sort-Merge Join Example

1 r₁ 2 r₂ 3 r₃ Assume that after first phase of multiway sort we get 4 sublists, 2 for R and 2 for S

Also assume that each block contains two tuples



R 3 7 8 10 11 13 14 16 17 18 1 2 4 5 6 9 12 15 19 20

S 1 3 5 17 2 4 16 18 19 20

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Hash-Join Algorithms

- Assuming natural join, use a hash function that
 - is the same for both input arguments R and S
 - uses only the join attributes
- **Phase 1:** Hash each tuple of *R* into one of the *M-1* buckets *R_i* and similar each tuple of *S* into one of *S_i*
- **Phase 2:** For *i*=1...*M*-1

load R_i and S_i in memory join them and save result to disk

- **Ouestion:** What is the maximum size of buckets?
- Question: Does hashing maintain sorting?

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Index-Based Join: Simplest Version

 Assume that we do natural join of R(A,B) and S(B,C) and there is an index on S

```
for each Br in R do
  for each tuple r of Br with B value b
    use index of S to find
      tuples {s<sub>1</sub> , s<sub>2</sub> ,..., s<sub>n</sub>} of S with B=b
    output {rs<sub>1</sub> , rs<sub>2</sub> ,..., rs<sub>n</sub>}
```

 Cost: Assuming R is clustered and non-sorted and the index on S is clustered on B then B(R)+T(R)B(S)/V(S,B) + some for reading index

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Example 1(a)

Iteration Join R1 ⋈ R2

- Relations not contiguous
- Recall $\begin{cases} T(R1) = 10,000 \\ T(R2) = 5,000 \\ S(R1) = S(R2) = 1/10 \text{ block} \\ MEM = 101 \text{ blocks} \end{cases}$

 $\underline{\text{Cost:}} \text{ for each R1 tuple:}$

Total =10,000 [1+5000]=50,010,000 IOs

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Opportunities in Joins Using Sorted Indexes

 Do a conventional Sort-Join avoiding the sorting of one or both of the input operands

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Can we do better?

Use our memory

- (1) Read 100 blocks of R1
- (2) Read all of R2 (using 1 block) + join
- (3) Repeat until done

Cost

for each R1 chunk:

Read chunk: 1000 IOs Read R2 $\frac{5000}{6000}$ IOs

Total =
$$\frac{10,000}{1,000}$$
 x 6000 = 60,000 IOs

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Example 1(b)

Iteration Join R2 ⋈ R1

Relations contiguous

Cost

For each R2 chunk:

Read chunk: 100 IOs Read R1: 1000 IOs 1,100

Total = 5 chunks x 1,100 = 5,500 IOs

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Can we do better?

• Reverse Join Order: R2 ⋈ R1

Total =
$$\frac{5000}{1000}$$
 x (1000 + 10,000) =

$$5 \times 11,000 = 55,000 IOs$$

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Example 1(c)

Merge Join

• Both R1, R2 ordered by C; relations contiguous

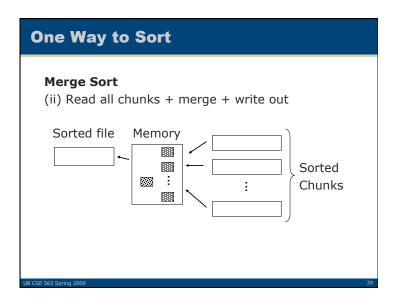


Total cost: Read R1 cost + read R2 cost = 1000 + 500 = 1,500 IOs

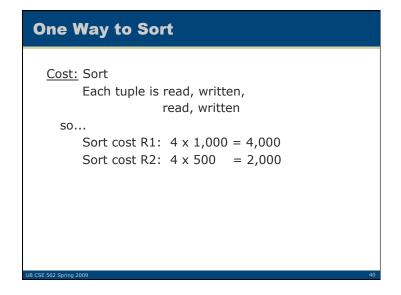
Example 1(d) Merge Join

- R1, R2 not ordered, but contiguous
- → Need to sort R1, R2 first... HOW?

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Merge Sort (i) For each 100 block chunk of R: - Read chunk - Sort in memory - Write to disk R1 R2 Memory Sorted chunks



Example 1(d) (Cont.)

Merge Join

• R1,R2 contiguous, but unordered

Total cost = sort cost + join cost
=
$$6,000 + 1,500 = 7,500$$
 IOs

<u>But:</u> Iteration cost = 5,500 so merge joint does not pay off!

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Example 1(d) (Cont.)

But say R1 = 10,000 blocks contiguous

R2 = 5,000 blocks not ordered

<u>Iterate</u>: $\frac{5000}{100}$ x (100+10,000) = 50 x 10,100

= 505,000 IOs

Merge join: 5(10,000+5,000) = 75,000 IOs

Merge Join (with sort) WINS!

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Merge Sort

How much memory do we need for merge sort?

E.g: Say I have 10 memory blocks

R1
$$\stackrel{\leftarrow}{100}$$
 | 100 chunks \Rightarrow to merge, need 100 blocks!

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In General

Say k blocks in memory x blocks for relation sort

chunks = (x/k)size of chunk = k

chunks $\underline{<}$ buffers available for merge

so... $(x/k) \le k$ or $k^2 \ge x$ or $k \ge \sqrt{x}$

In Our Example

R1 is 1000 blocks, $k \ge 31.62$ R2 is 500 blocks, $k \ge 22.36$

Need at least 32 buffers

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Cost of Improved Merge Join

C = Read R1 + write R1 into runs

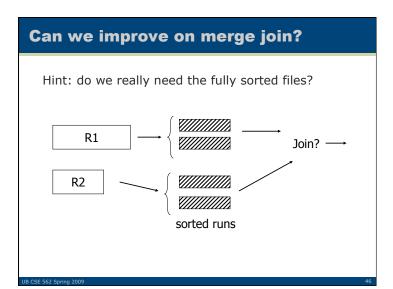
+ read R2 + write R2 into runs

+ join

= 2000 + 1000 + 1500 = 4500

→ Memory requirement?

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Example 1(e)

Index Join

- Assume R1.C index exists; 2 levels
- Assume R2 contiguous, unordered
- Assume R1.C index fits in memory

Example 1(e) (Cont.)

Cost: Reads: 500 IOs for each R2 tuple:

- probe index - free

- if match, read R1 tuple: 1 IO

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Total Cost with Index Join

(a) Total cost = 500+5000(1)1 = 5,500

(b) Total cost = 500+5000(2)1 = 10,500

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Example 1(e) (Cont.)

What is expected # of matching tuples?

(a) say R1.C is key, R2.C is foreign key then expect = 1

(b) say V(R1,C) = 5000, T(R1) = 10,000with uniform assumption expect = 10,000/5,000 = 2

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What if index does not fit in memory?

Example: say R1.C index is 201 blocks

- Keep root + 99 leaf nodes in memory
- Expected cost of each probe is $E = (0) \frac{99}{200} + (1) \frac{101}{200} \approx 0.5$

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Total Cost (including probes)

- = 500 + 5000 [Probe + get records]
- = 500 + 5000 [0.5 + 2] uniform assumption
- = 500 + 12,500 = 13,000 (case b)

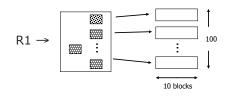
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Example 1(f)

Hash Join

- R1, R2 contiguous (un-ordered)
- → Use 100 buckets
- → Read R1, hash, + write buckets

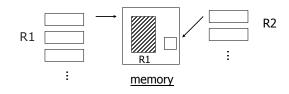


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So Far Iterate R2 ⋈ R1 55,000 (best) not contiguous Merge Join Sort+ Merge Join R1.C Index R2.C Index Iterate R2 ⋈R1 5500 1500 Merge join Sort+Merge Join $7500 \rightarrow 4500$ R1.C Index 5500 R2.C Index

Example 1(f) (Cond.)

- → Same for R2
- → Read one R1 bucket; build memory hash table
- → Read corresponding R2 bucket + hash probe



→ Then repeat for all buckets

Cost

• "Bucketize:" Read R1 + write

Read R2 + write

• Join: Read R1, R2

• Total cost = $3 \times [1000+500] = 4500$

Note: this is an approximation since buckets will vary in size and we have to round up to blocks

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Minimum Memory Requirements

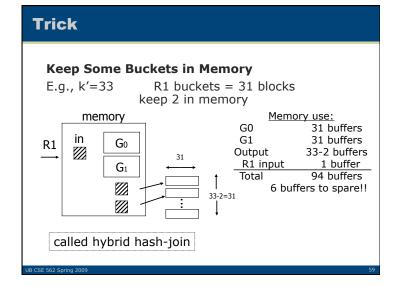
• Size of R1 bucket = (x/k)

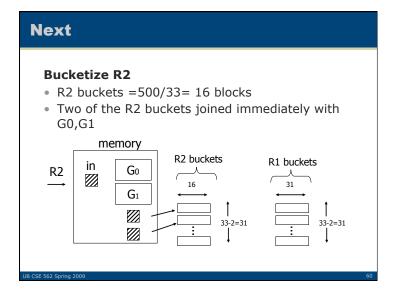
k = number of memory buffers

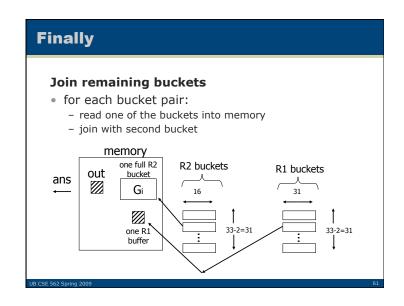
x = number of R1 blocks

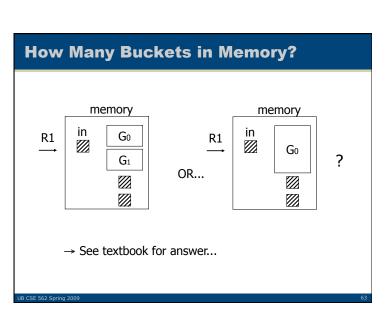
• So... (x/k) < k

• $k > \sqrt{x}$ need: k+1 total memory buffers









Cost

- Bucketize $R1 = 1000 + 31 \times 31 = 1961$
- To bucketize R2, only write 31 buckets:
 so, cost = 500 + 31 x 16 = 996
- To compare join (2 buckets already done) read $31 \times 31 + 31 \times 16 = 1457$

Total cost = 1961 + 996 + 1457 = 4414

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Another Hash Join Trick

- Only write into buckets <val,ptr> pairs
- When we get a match in join phase, must fetch tuples

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Another Hash Join Trick (Cont.)

- To illustrate cost computation, assume:
 - 100 <val,ptr> pairs/block
 - expected number of result tuples is 100
- Build hash table for R2 in memory
 5000 tuples → 5000/100 = 50 blocks
- Read R1 and match
- Read ~ 100 R2 tuples

• $\underline{\text{Total cost}} = \text{Read R2}$: 500

Read R1: 1000 Get tuples: 100

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Summary

- Iteration ok for "small" relations (relative to memory size)
- For equi-join, where relations not sorted and no indexes exist, hash join usually best
- Sort + merge join good for non-equi-join (e.g., R1.C > R2.C)
- If relations already sorted, use merge join
- If index exists, it <u>could</u> be useful (depends on expected result size)

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So Far Iterate 5500 1500 Merge join 7500 Sort+merge joint R1.C index $5500 \to 550$ R2.C index Build R.C index Build S.C index 4500+ Hash join with trick,R1 first 4414 with trick,R2 first Hash join, pointers 1600