

Defⁿ: A configuration (ID) I of a TM M is an instantaneous description

- specified by:
- the current state q of M
 - the contents w of all tapes together
 - the head position on each tape.

For one-tape TMs it is convenient to encode IDs by strings over the alphabet $\Gamma' = Q \cup \Gamma$ ($M = (Q, \Sigma, \Gamma, \delta, B, s, q_{acc}, q_{rej})$ wlog. $Q \cap \Gamma = \emptyset$)

ID $I = u q c v$ means: $\left\{ \begin{array}{l} M \text{ is in state } q \text{ scanning char } c \\ u \text{ includes all non-blank cells to the left, } v \text{ ditto to right.} \end{array} \right.$

Text p168 includes c as first char of v

The initial ID of M on an input $x \in \Sigma^*$ is (scanning first bit of x).

$I_0(x)$ = sx or $\Lambda sx \#$ using "UNIX convention"

What if $x = \epsilon$? $I_0(x) = \underline{SB}$ or just s or $\Lambda s \#$ no ambiguity.

not totally clear which one text would write

★ Code M to write B only at left or right end.

\Rightarrow in $u q c v$, u and v have no B s

Use ' $\%_0$ ' as alias - B otherwise

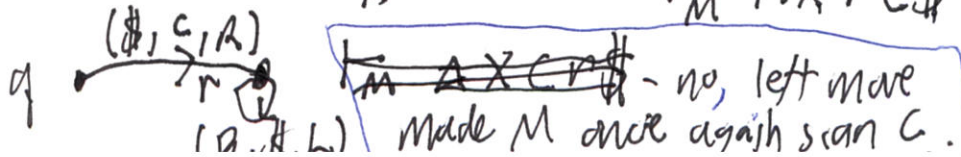
• if $c = B$ then $u = \epsilon$ or $v = \epsilon$.

say we read all of x , going to

OK to be scanning B temporarily at one end to "make an endmarker" to make more room

$I = \Lambda x q \# \xrightarrow{M} \Lambda x c r B \xrightarrow{M} \Lambda x r c \#$

Defⁿ $I \xrightarrow{M} J$ if ID J can follow from I by executing one instruction of M .



Definition: A computation of a TM M on an input $x \in \Sigma^*$ is a sequence (I_0, I_1, \dots, I_t) of IDs such that:

- I_0 is the starting ID on input x . (whatever encoding you use for k -tape TMs)
- for all j , $1 \leq j \leq t$, $I_{j-1} \vdash_M I_j$ (text says this in prose)
- I_t is a halting ID, meaning: (general) $(\exists J) I_t \vdash_M J$

The computation accepts iff I_t has q_{acc} . (By conv.) I_t has state q_{acc} or q_{rej} .
 $\equiv I_t$ is an accepting ID.

Similarly to grammar derivations: define $I \vdash_M^0 J$ for any ID I ,

$I \vdash_M^k J$ iff there is some ID I' s.t. $I \vdash_M I' \wedge I' \vdash_M^{k-1} J$.

$I \vdash_M^* J$ iff for some $k \geq 0$, $I \vdash_M^k J$.

\vdash called "turnstile".
Text says "yields". LaTeX `\vdash` on page 79

Defn: $L(M) = \{x \in \Sigma^* : I_0(x) \vdash_M^* J \text{ for some accepting ID } J\}$

Some "Good Housekeeping" features: ① If M writes no internal blanks, then when it "wants to" go to q_{acc} , it can execute a routine that erases the entire tape except a single 1, leading to the unique accepting ID $I_f = \underline{q_{acc} 1}$.

• Likewise, a halting rejecting computation can wlog. end in $I_{rej} = \underline{q_{rej} 0}$.

§5.3 Forward reference: In any accepting ID $u q c v$, we can let v' be the maximum prefix of v having chars in Σ only, and if $c \in \Sigma$, output = cv' .
If $c \notin \Sigma$, output = ϵ . ② If y is the intended output, can arrange $I_f = \underline{q_{acc} y}$.

Key Defns: A language $A \subseteq \Sigma^*$ is

- Turing recognizable (text) ③
- Turing acceptable ← (standard)
- computably enumerable (c.e.) ←
- recursively enumerable (r.e.)

if there is a det^s TM M s.t. $A = L(M)$.

A is decidable if in addition for all x , $\exists_0(x) \stackrel{r}{\vdash}_M \exists_1 \vee \exists_0(x) \stackrel{*}{\vdash}_M \text{rej}$

Equivalently, say $M(x) \downarrow$ (\downarrow = "halts") if, and M is total if $\forall x M(x) \downarrow$.

Then A is decidable $\equiv A = L(M)$ for some total DTM M .

synonym recursive. Furthermore, suppose that for all $x \in \Sigma^*$:

$x \in A \Rightarrow M(x)$ halts and outputs 1
 $x \notin A \Rightarrow M(x)$ halts and outputs 0

Then A is decidable.

Then as a function computer / transducer, M computes the total characteristic function χ_A

$\chi_A(x) = \begin{cases} 1, & \text{if } x \in A \\ 0, & \text{if } x \notin A \end{cases}$

which for Myhill-Nerode we just write $A(x)$ halts and equals 1, ie. possibly $M(x) \uparrow$ doesn't halt.

Note: If we only have $\forall x: x \in A \Rightarrow M(x) \downarrow = 1$, ie. possibly $M(x) \uparrow$ when $x \notin A$, then A is Turing-recognizable.

A might be decidable by another machine M' , or not (Shu. \rightarrow not!)
 by default total, $\text{dom}(f) = \Sigma^*$

Defn: A function $f: \Sigma^* \rightarrow \Sigma^*$ is (total) computable if there is a total DTM M that computes $f: \forall x \in \Sigma^* : \exists_0(x) \stackrel{*}{\vdash}_M q f(x)$ where q is a halting state.

If f is a partial function and $\forall x \in \text{dom}(f) M(x) \downarrow = f(x)$, then f is partial computable.

A is decidable $\Leftrightarrow \chi_A$ is total computable

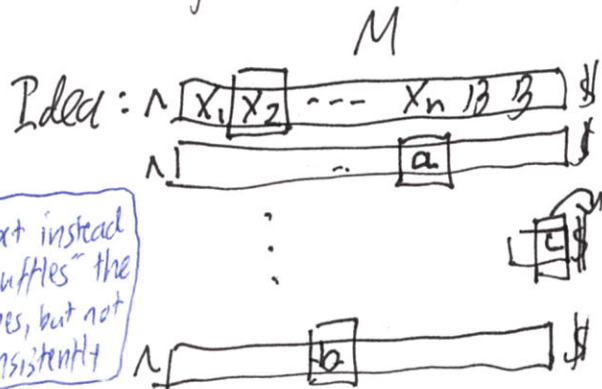
(with domain A) \rightarrow A is c.e. $\Leftrightarrow \chi_A$ is partial computable

Rest of Ch 3 = TMs and Programs.

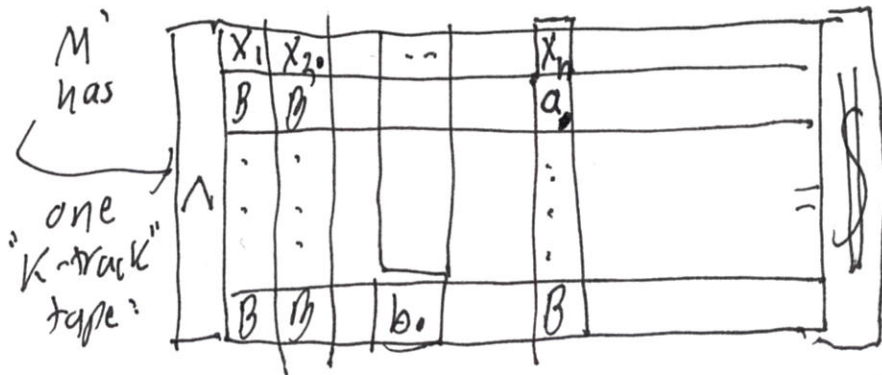
Moreover they compute the same (partial) function. (4)

(3-13 in text)

Theorem: For every k -tape TM $M = (Q, \Sigma, \Gamma, \delta, B, s, F)$ we can design a 1-tape TM $M' = (Q', \Sigma, \Gamma', \delta', B, s', F')$ s.t. $L(M') = L(M)$.



Text instead "shuffles" the tapes, but not consistently



Use \bullet as an extra char marker for the current location of each head

Hence $\Gamma' = \Gamma \cup (\Gamma \cup \mathbf{P})^k$ where \mathbf{P} is a dotted copy of Γ .
 (includes B and B_\bullet)

In this manner, even $\exists D I$ of M is "replicated" by an $\exists D I'$ of M'

If $I \xrightarrow{M} J$, then M' can build the corresponding J' from I' , but it usually will require one L-to-R-to-L pass between Λ and $\$$.

Thus M' simulates M . \boxtimes initially $s = n$, always $s \leq t$
 (I.e. M' is operationally equivalent to M .) $s \leq \max\{t, n\}$ always $s \leq t$

Note: If s is the current/typical distance from Λ to $\$$, then each pass requires up to $4s$ steps (can do in $2s+2$)

Hence if it takes M t steps to halt, M' halts in $O(st)$ steps.

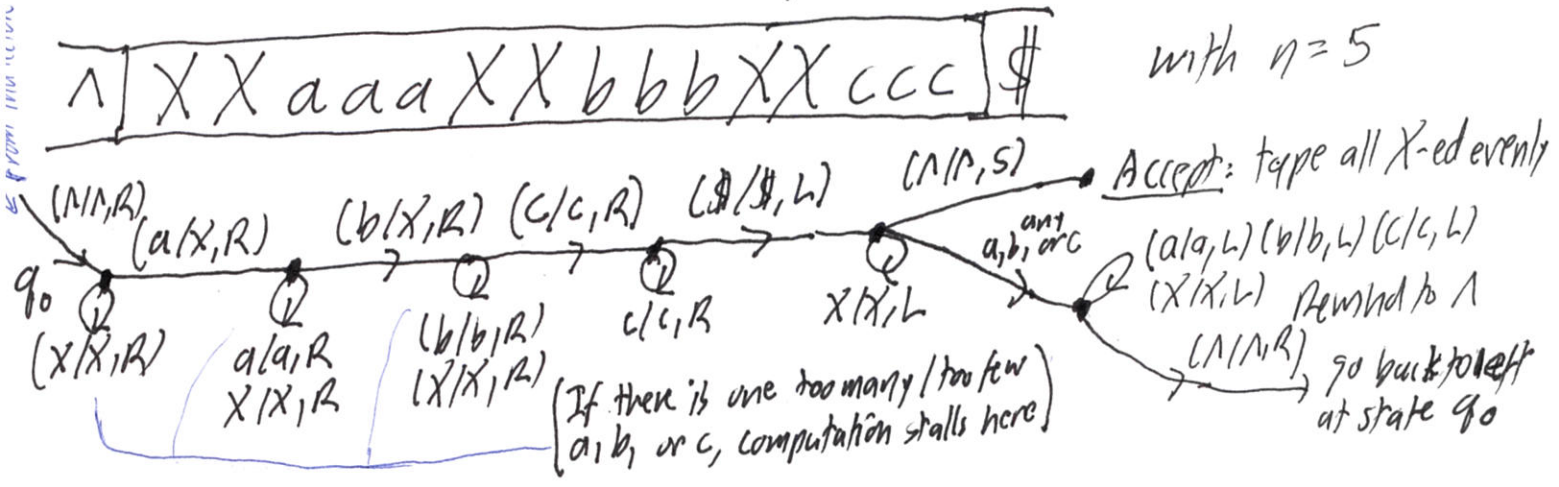
Especially when $t = O(n)$, M' can take $O(n^2)$ time.

At the end we will care about the time and space to solve problems.

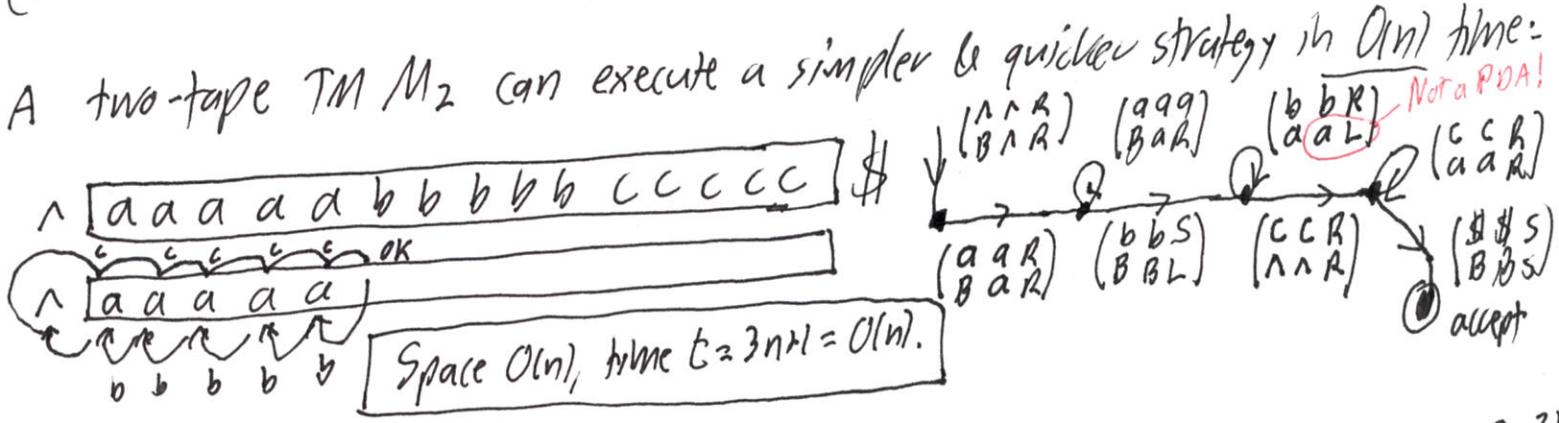
For now note: Year 2-tape machines typically take $O(n)$ time, $O(n^2)$ space.

Example (writing end of lecture again on clean sheet) (expanded a bit) (5)

$L = \{a^n b^n c^n : n \geq 1\}$. Recall our one-tape TM first verified that the input x belongs to $a^+ b^+ c^+$. It then maintains the invariant that the tape always belongs to $\wedge X^* a^i X^* b^i X^* c^i \$$, e.g.:



Here the distance between \wedge and $\$$ stays at $3n+1$, fixing the space as $s = 3n+1$. Each pass uses 2s steps. The TM does n passes. \therefore Total time $t \approx n(6n+2) = \Theta(n^2)$. (L to R to L)

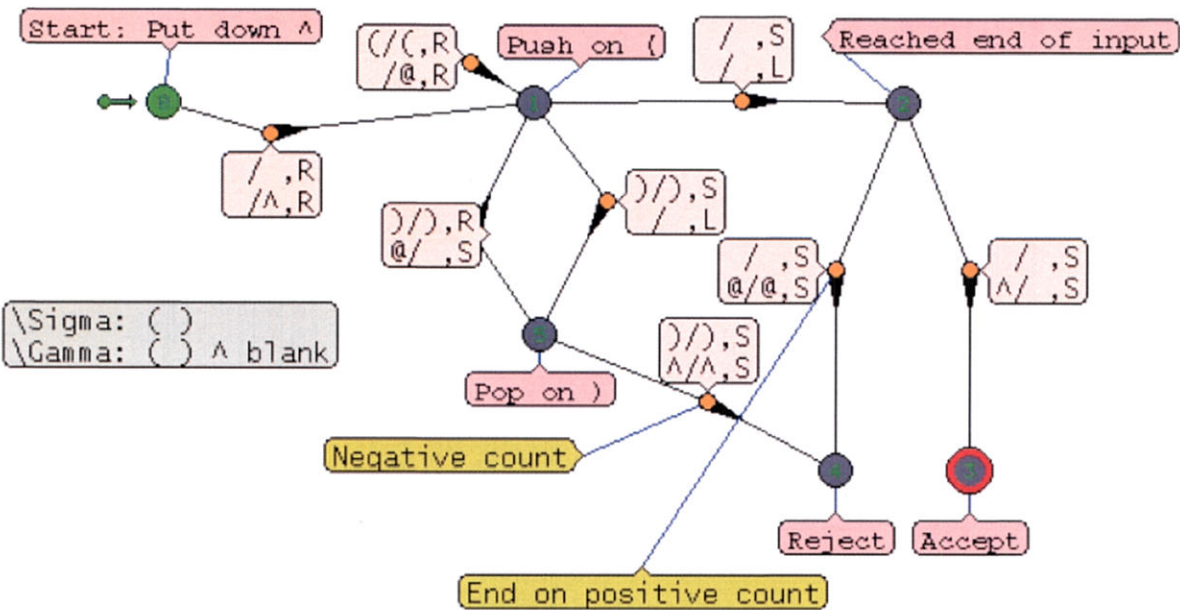


If you convert M_2 into a one-tape TM M_1 , the time becomes $\Theta(ns) = \Theta(3n^2+n) = \Theta(n^2)$ quadratic again.

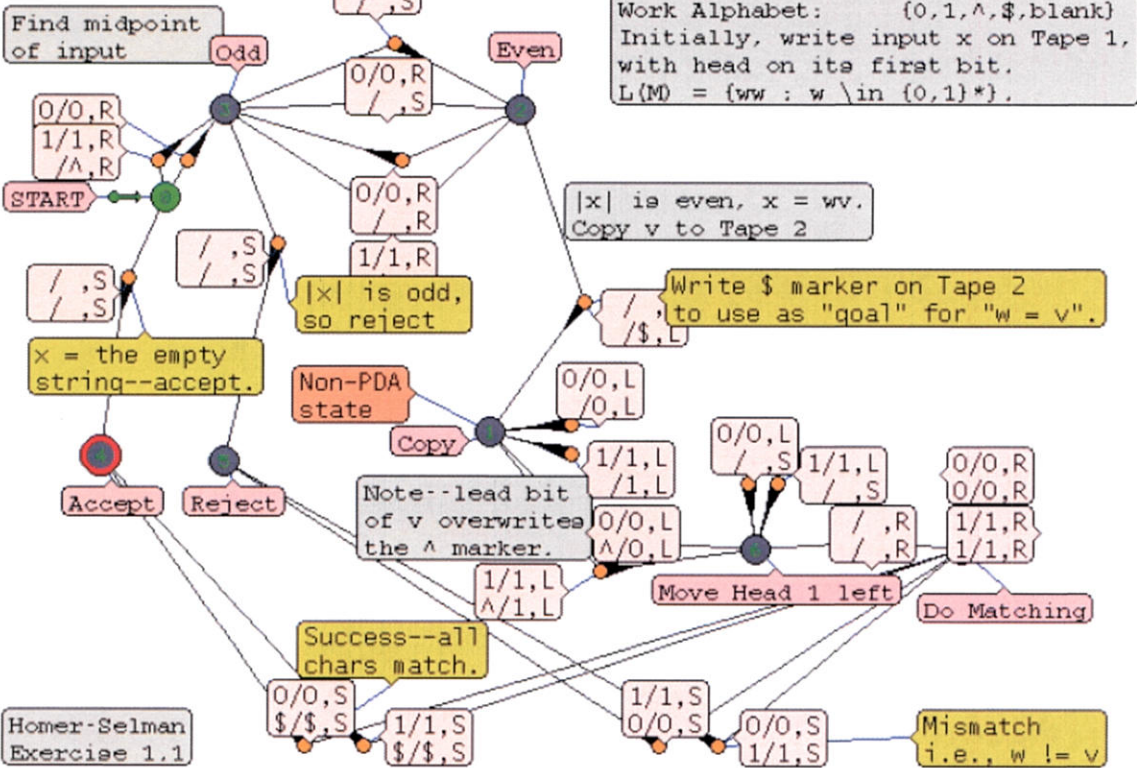
★ "Polynomial time" ignores quadratic time loss, so 1 tape and k tapes are equivalent for it. The "Universal RAM Simulator" handout sketches how this equivalence extends to a "mini-assembly" language, and thence to time in real programming languages a-la CSE 331. "Church-Turing Thesis".

Two two-tape Turing Machines, the first a DPDA, the second not

A DPDA that recognizes the language of balanced paren strings.
 Convention: start with heads on blank to left of input.



TM deciding DOUBLEWORD



CSE396 Spt 2016: To Skim for §3.2 of text
 & 596 Universal RAM Simulator

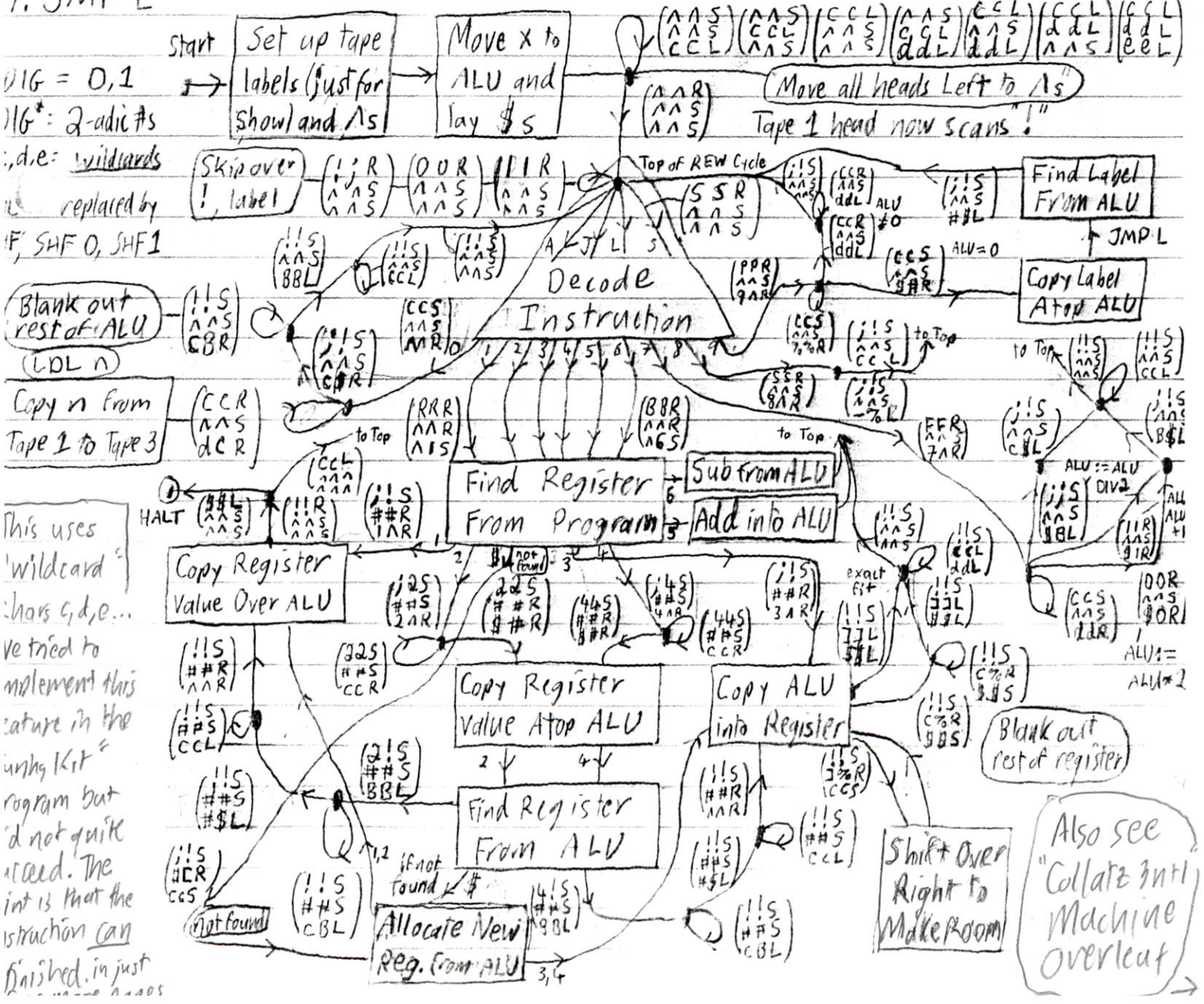
Fall 2014

0. LDR n
1. LOR Y
2. LDI Y
3. STO Y
4. STI Y
5. ADD Y
6. SUB Y
7. SHF d
8. ABS
9. JMP L

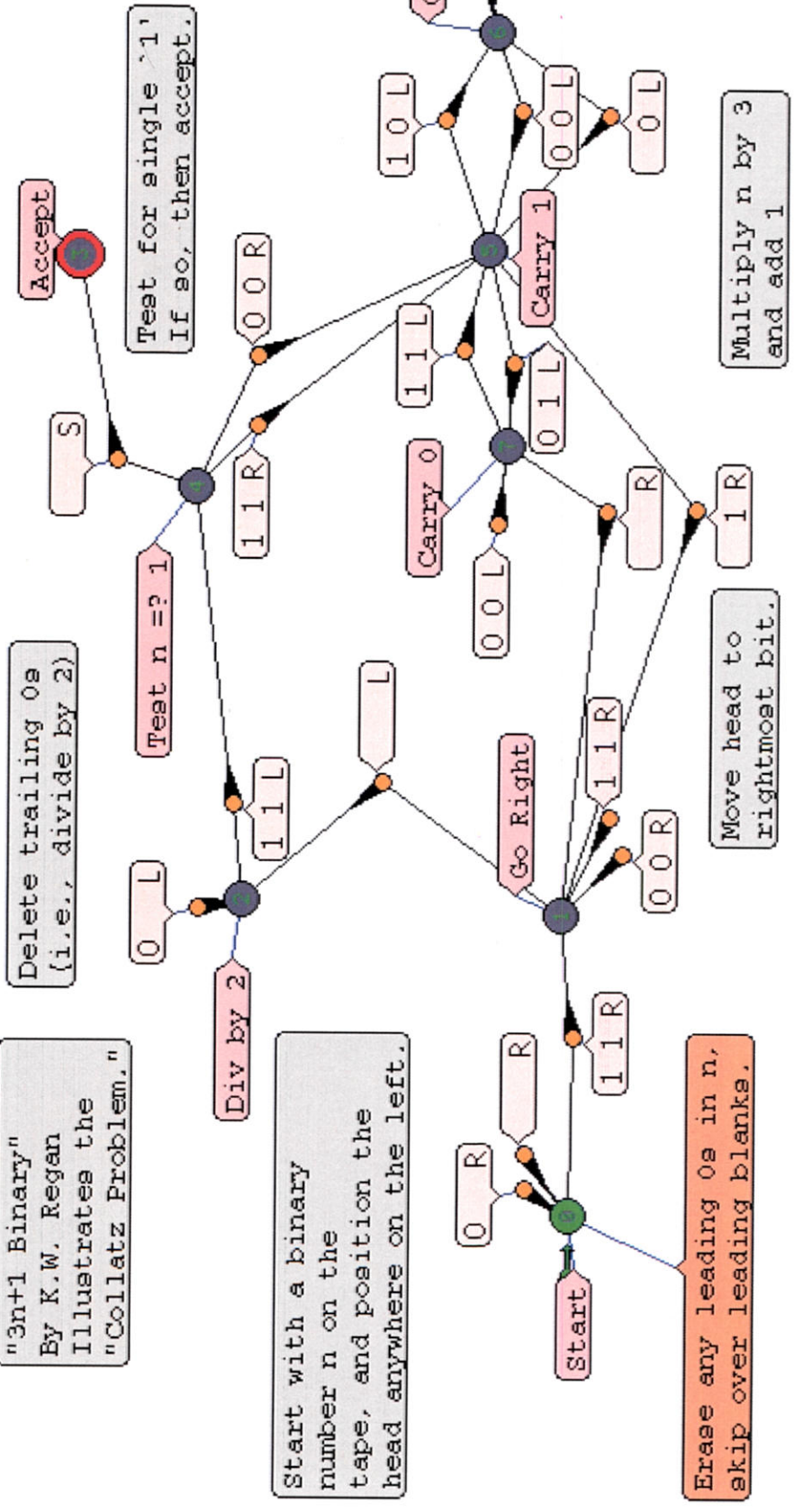
Program Syntax: INSTR = DIG*ALPH³.DIG* PFM = !INSTR*
 Register Syntax: REG = [DIG*#(-?)DIG*] REGS = REG*
 ALU Syntax: ALU = (-?)DIG* All tapes get a ---\$ delimiters

Initial: ... !INS₁; INS₂; ... INS_m; #X₁X₂...X_n ...

P	G	M	:	^	!INS ₁ ; INS ₂ ; ... INS _m ; \$	Program P
R	E	G	:	^	\$	
A	L	U	:	^	X ₁ X ₂ X ₃ X ₄ ... X _n \$	Output: Last Instr is LDR 1; putting P(x) in AL



"3n+1 Binary"
By K.W. Regan
Illustrates the
"Collatz Problem."



Start with a binary number n on the tape, and position the head anywhere on the left.

Erase any leading 0s in n, skip over leading blanks.

Move head to rightmost bit.

Multiply n by 3 and add 1