

CSE 431/531: Analysis of Algorithms

# Graph Basics

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- 1 Graphs
- 2 Connectivity and Graph Traversal
  - Testing Bipartiteness
- 3 Topological Ordering

# Examples of Graphs



Figure: Road Networks



Figure: Internet



Figure: Social Networks

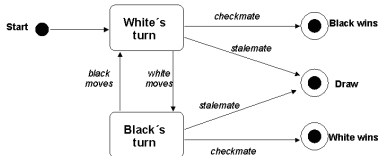
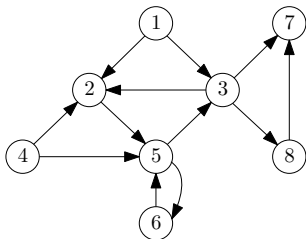


Figure: Transition Graphs

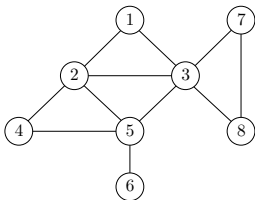
# (Undirected) Graph $G = (V, E)$



- $V$ : a set of vertices (nodes);
  - $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$
- $E$ : pairwise relationships among  $V$ ;
  - (undirected) graphs: relationship is symmetric,  $E$  contains subsets of size 2
  - $E = \{\{1, 2\}, \{1, 3\}, \{2, 3\}, \{2, 4\}, \{2, 5\}, \{3, 5\}, \{3, 7\}, \{3, 8\}, \{4, 5\}, \{5, 6\}, \{7, 8\}\}$

# Abuse of Notations

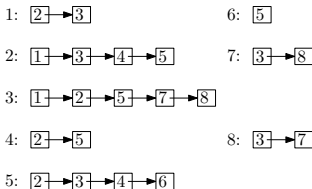
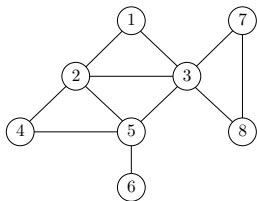
- For (undirected) graphs, we often use  $(i, j)$  to denote the set  $\{i, j\}$ .
- We call  $(i, j)$  an unordered pair; in this case  $(i, j) = (j, i)$ .



- $E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 5), (3, 5), (3, 7), (3, 8), (4, 5), (5, 6), (7, 8)\}$

- Social Network : Undirected
- Transition Graph : Directed
- Road Network : Directed or Undirected
- Internet : Directed or Undirected

# Representation of Graphs



- Adjacency matrix
  - $n \times n$  matrix,  $A[u, v] = 1$  if  $(u, v) \in E$  and  $A[u, v] = 0$  otherwise
  - $A$  is symmetric if graph is undirected
- Linked lists
  - For every vertex  $v$ , there is a linked list containing all **neighbours** of  $v$ .

# Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- $n$ : number of vertices
- $m$ : number of edges, assuming  $n - 1 \leq m \leq n(n - 1)/2$
- $d_v$ : number of neighbors of  $v$

	Matrix	Linked Lists
memory usage	$O(n^2)$	$O(m)$
time to check $(u, v) \in E$	$O(1)$	$O(d_u)$
time to list all neighbours of $v$	$O(n)$	$O(d_v)$



# Outline

- 1 Graphs
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  - Testing Bipartiteness
- 3 Topological Ordering

## Connectivity Problem

**Input:** graph  $G = (V, E)$ , (using linked lists)

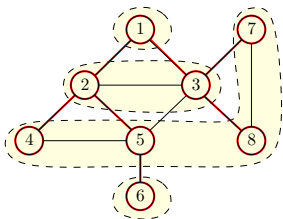
two vertices  $s, t \in V$

**Output:** whether there is a path connecting  $s$  to  $t$  in  $G$

- Algorithm: starting from  $s$ , search for all vertices that are reachable from  $s$  and check if the set contains  $t$ 
  - Breadth-First Search (BFS)
  - Depth-First Search (DFS)

# Breadth-First Search (BFS)

- Build layers  $L_0, L_1, L_2, L_3, \dots$
- $L_0 = \{s\}$
- $L_{j+1}$  contains all nodes that are not in  $L_0 \cup L_1 \cup \dots \cup L_j$  and have an edge to a vertex in  $L_j$



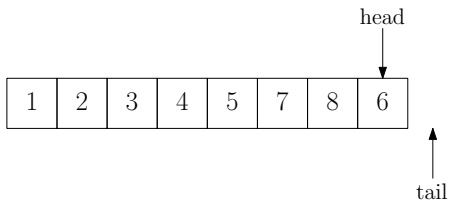
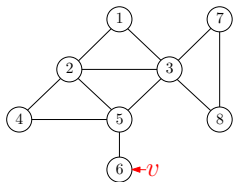
# Implementing BFS using a Queue

## BFS( $s$ )

- 1  $head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$
- 2 mark  $s$  as “visited” and all other vertices as “unvisited”
- 3 while  $head \geq tail$
- 4      $v \leftarrow queue[tail], tail \leftarrow tail + 1$
- 5     for all neighbours  $u$  of  $v$
- 6         if  $u$  is “unvisited” then
- 7              $head \leftarrow head + 1, queue[head] = u$
- 8             mark  $u$  as “visited”

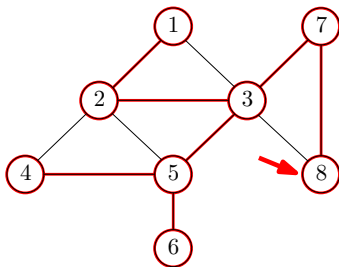
- Running time:  $O(n + m)$ .

# Example of BFS via Queue



# Depth-First Search (DFS)

- Starting from  $s$
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



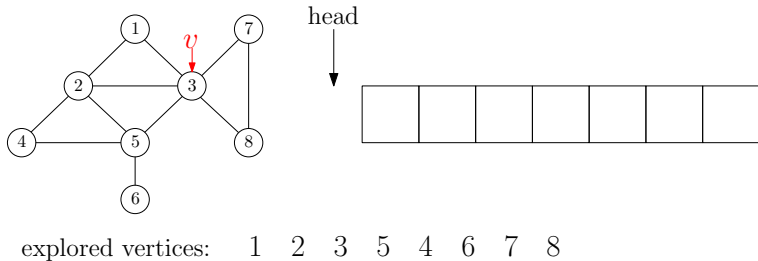
# Implementing DFS using a Stack

## DFS( $s$ )

- 1  $head \leftarrow 1, stack[1] \leftarrow s$
- 2 mark all vertices as “unexplored”
- 3 while  $head \geq 1$
- 4      $v \leftarrow stack[head], head \leftarrow head - 1$
- 5     if  $v$  is unexplored then
- 6         mark  $v$  as “explored”
- 7         for all neighbours  $u$  of  $v$
- 8             if  $u$  is not explored then
- 9                  $head \leftarrow head + 1, stack[head] = u$

- Running time:  $O(n + m)$ .

# Example of DFS using Stack





# Implementing DFS using Recursion

## DFS( $s$ )

- 1 mark all vertices as “unexplored”
- 2 recursive-DFS( $s$ )

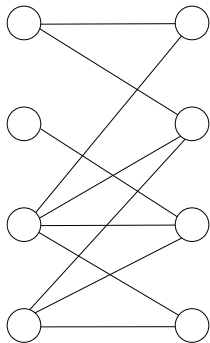
## recursive-DFS( $v$ )

- 1 if  $v$  is explored then return
- 2 mark  $v$  as “explored”
- 3 for all neighbours  $u$  of  $v$
- 4     recursive-DFS( $u$ )

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# Testing Bipartiteness: Applications of BFS

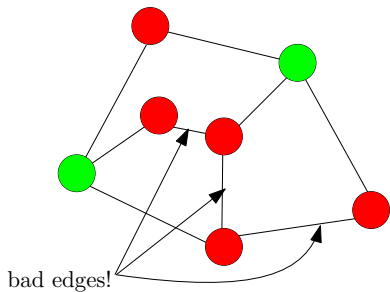
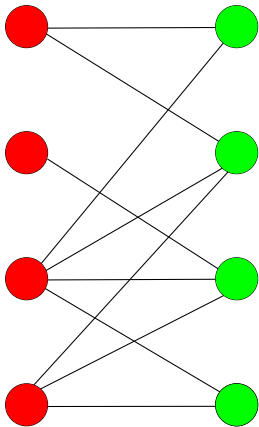
**Def.** A graph  $G = (V, E)$  is a **bipartite graph** if there is a partition of  $V$  into two sets  $L$  and  $R$  such that for every edge  $(u, v) \in E$ , we have either  $u \in L, v \in R$  or  $v \in L, u \in R$ .



# Testing Bipartiteness

- Taking an arbitrary vertex  $s \in V$
- Assuming  $s \in L$  w.l.o.g
- Neighbors of  $s$  must be in  $R$
- Neighbors of neighbors of  $s$  must be in  $L$
- ...
- Report “not a bipartite graph” if contradiction was found
- If  $G$  contains multiple connected components, repeat above algorithm for each component

# Test Bipartiteness



# Testing Bipartiteness using BFS

## BFS( $s$ )

- 1  $head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$
- 2 mark  $s$  as “visited” and all other vertices as “unvisited”
- 3  $color[s] \leftarrow 0$
- 4 while  $head \geq tail$
- 5      $v \leftarrow queue[tail], tail \leftarrow tail + 1$
- 6     for all neighbours  $u$  of  $v$
- 7         if  $u$  is “unvisited” then
- 8              $head \leftarrow head + 1, queue[head] = u$
- 9             mark  $u$  as “visited”
- 10              $color[u] \leftarrow 1 - color[v]$
- 11         elseif  $color[u] = color[v]$  then
- 12             print(“ $G$  is not bipartite”) and exit

# Testing Bipartiteness using BFS

- 1 mark all vertices as “unvisited”
- 2 for each vertex  $v \in V$
- 3     if  $v$  is “unvisited” then
- 4         test-bipartiteness( $v$ )
- 5 print(“ $G$  is bipartite”)

**Obs.** Running time of algorithm =  $O(n + m)$

Homework problem: using DFS to implement test-bipartiteness.

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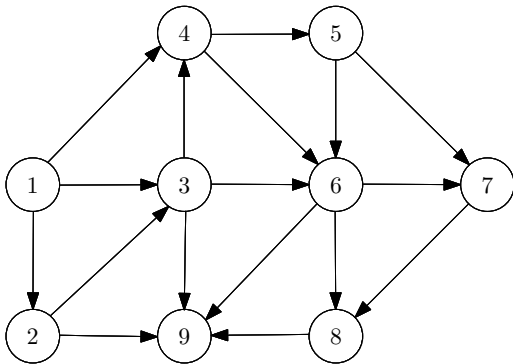


## Topological Ordering Problem

**Input:** a directed acyclic graph (DAG)  $G = (V, E)$

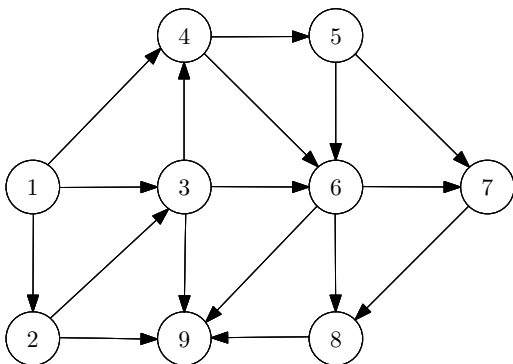
**Output:** 1-to-1 function  $\pi : V \rightarrow \{1, 2, 3 \dots, n\}$ , so that

- if  $(u, v) \in E$  then  $\pi(u) < \pi(v)$



# Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



# Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.

**Q:** How to make the algorithm as efficient as possible?

**A:**

- Use linked-lists of outgoing edges
- Maintain the in-degree  $d_v$  of vertices
- Maintain a queue (or stack) of vertices  $v$  with  $d_v = 0$

## topological-sort( $G$ )

- 1 let  $d_v \leftarrow 0$  for every  $v \in V$
- 2 for every  $v \in V$
- 3     for every  $u$  such that  $(v, u) \in E$
- 4          $d_u \leftarrow d_u + 1$
- 5  $S \leftarrow \{v : d_v = 0\}, i \leftarrow 0$
- 6 while  $S \neq \emptyset$
- 7      $v \leftarrow$  arbitrary vertex in  $S, S \leftarrow S \setminus \{v\}$
- 8      $i \leftarrow i + 1, \pi(v) \leftarrow i$
- 9     for every  $u$  such that  $(v, u) \in E$
- 10          $d_u \leftarrow d_u - 1$
- 11         if  $d_u = 0$  then add  $u$  to  $S$
- 12 if  $i < n$  then output "not a DAG"

- $S$  can be represented using a queue or a stack
- Running time =  $O(n + m)$