

CSE 431/531: Algorithm Analysis and Design (Fall 2021)

Greedy Algorithms

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Goals of algorithm design

- 1 Design efficient algorithms to solve problems
- 2 Design more efficient algorithms to solve problems

Common Paradigms for Algorithm Design

- Greedy Algorithms
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- Greedy algorithms are often for optimization problems.
- They often run in polynomial time due to their simplicity.

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- At each step, make an **irrevocable** decision using a “reasonable” strategy

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Analysis of Greedy Algorithm

- Prove that the reasonable strategy is “safe”
- Show that the remaining task after applying the strategy is to solve a (many) smaller instance(s) of the same problem

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Def. A strategy is safe: there is always an optimum solution that agrees with the decision made according to the strategy.

Outline

- 1 Toy Example: Box Packing
- 2 Interval Scheduling
- 3 Offline Caching
 - Heap: Concrete Data Structure for Priority Queue
- 4 Data Compression and Huffman Code
- 5 Summary

Box Packing

Input: n boxes of capacities c_1, c_2, \dots, c_n

m items of sizes s_1, s_2, \dots, s_m

Can put **at most 1** item in a box

Item j can be put into box i if $s_j \leq c_i$

Output: A way to put as many items as possible in the boxes.

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Example:

- Box capacities: 60, 40, 25, 15, 12
- Item sizes: 45, 42, 20, 19, 16
- Can put 3 items in boxes: 45 \rightarrow 60, 20 \rightarrow 40, 19 \rightarrow 25

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Designing a Reasonable Strategy for Box Packing

- Q: Take box 1. Which item should we put in box 1?

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Designing a Reasonable Strategy for Box Packing

- Q: Take box 1. Which item should we put in box 1?
- A: The item of the largest size that can be put into the box.

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- formal proof via exchanging argument:

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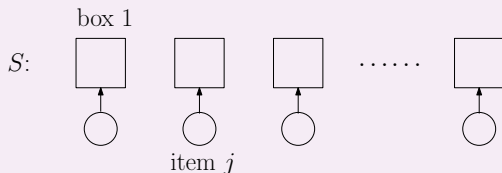
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- Let j = largest item that box 1 can hold.
- Take any optimum solution S . If j is put into Box 1 in S , done.

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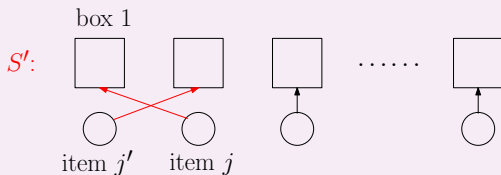
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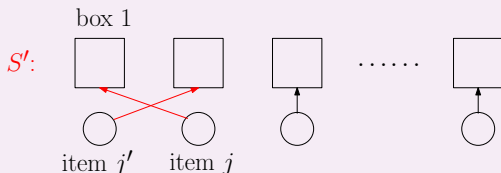


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- $s_{j'} \leq s_j$, and swapping gives another solution S'
- S' is also an optimum solution. In S' , j is put into Box 1. □

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- Trivial: we decided to put Item j into Box 1, and the remaining instance is obtained by removing Item j and Box 1.

Generic Greedy Algorithm

- 1: **while** the instance is non-trivial **do**
- 2: make the choice using the greedy strategy
- 3: reduce the instance

Greedy Algorithm for Box Packing

- 1: $T \leftarrow \{1, 2, 3, \dots, m\}$
- 2: **for** $i \leftarrow 1$ to n **do**
- 3: **if** some item in T can be put into box i **then**
- 4: $j \leftarrow$ the largest item in T that can be put into box i
- 5: print(“put item j in box i ”)
- 6: $T \leftarrow T \setminus \{j\}$

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Lemma Generic algorithm is correct **if and only if** the greedy strategy is safe.

- Greedy strategy is safe: we will not miss the optimum solution
- Greedy strategy is not safe: we will miss the optimum solution for some instance, since the choices we made are irrevocable.

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Def. A strategy is “safe” if there is always an optimum solution that is “consistent” with the decision made according to the strategy.

Exchange argument: Proof of Safety of a Strategy

- let S be an arbitrary optimum solution.
- if S is consistent with the greedy choice, done.
- otherwise, show that it can be modified to another optimum solution S' that is consistent with the choice.

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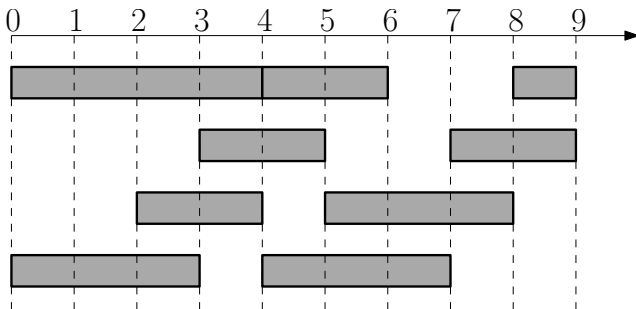
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Interval Scheduling

Input: n jobs, job i with start time s_i and finish time f_i

i and j are **compatible** if $[s_i, f_i)$ and $[s_j, f_j)$ are disjoint

Output: A maximum-size subset of mutually compatible jobs

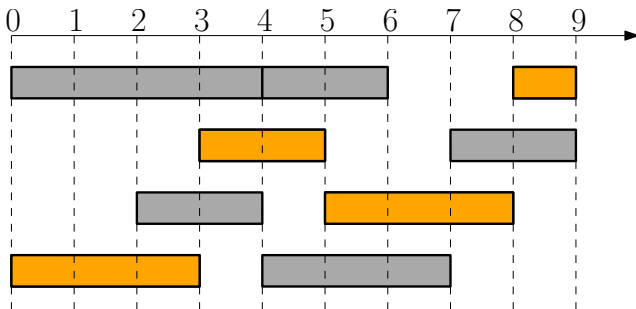


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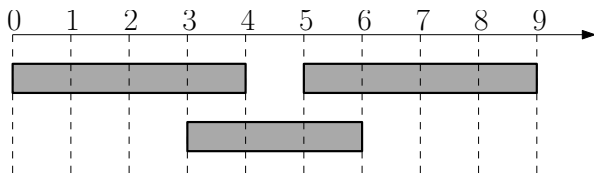
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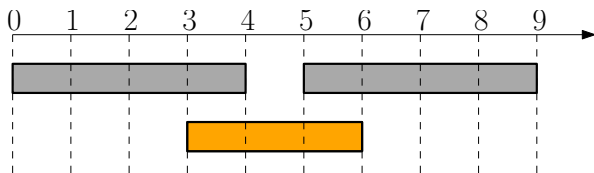
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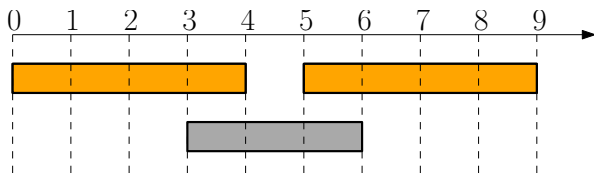
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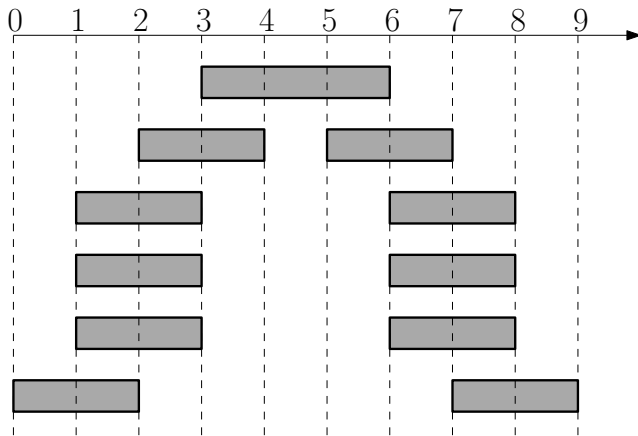
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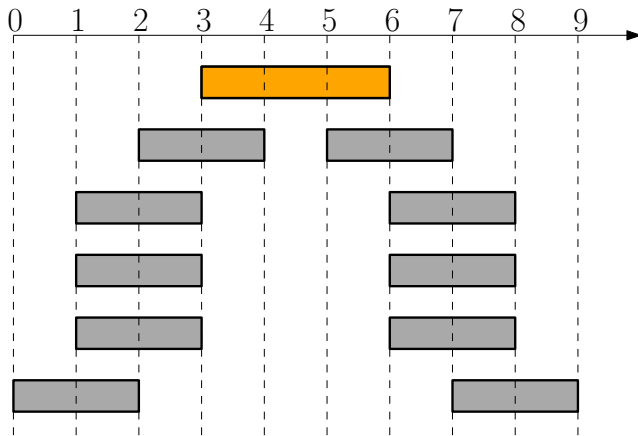
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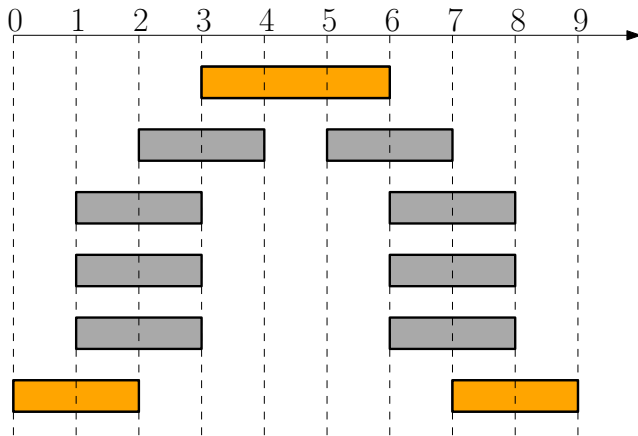
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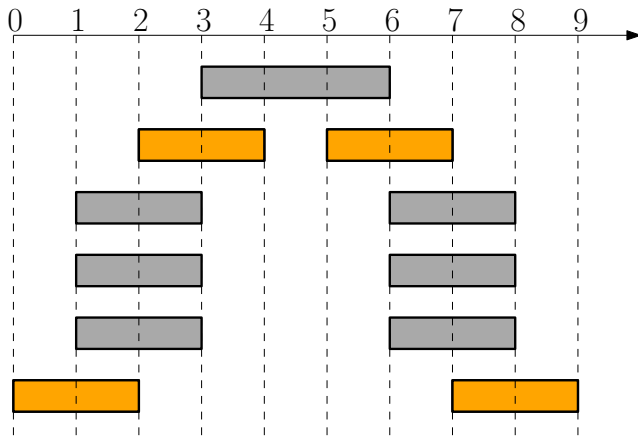
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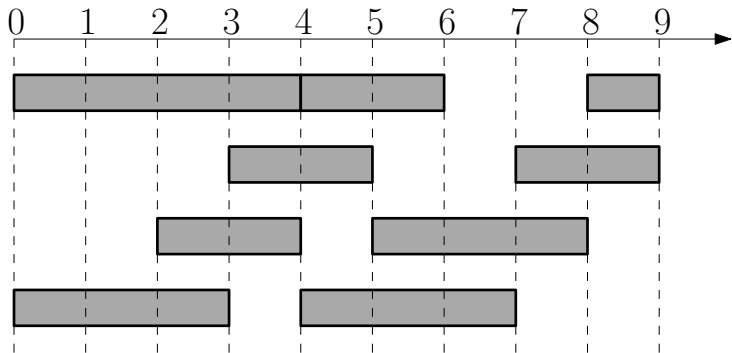
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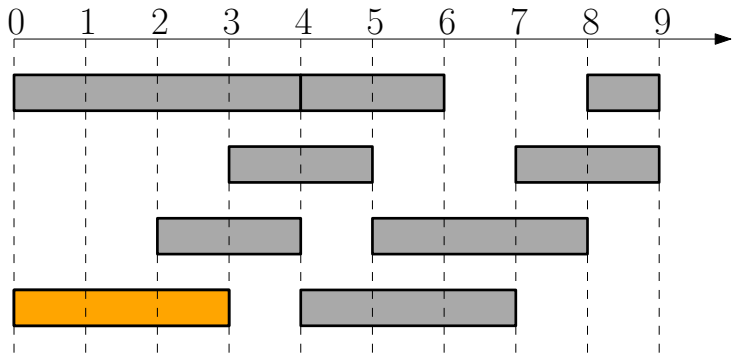
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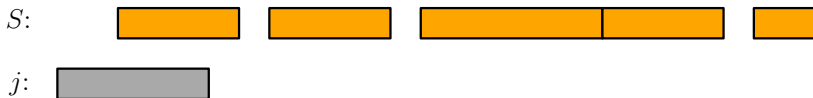


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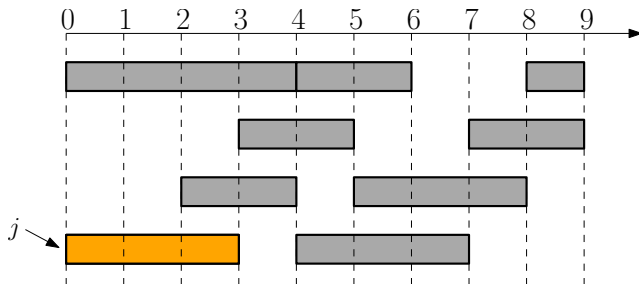
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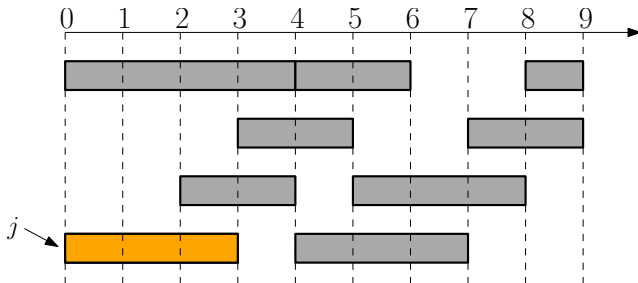
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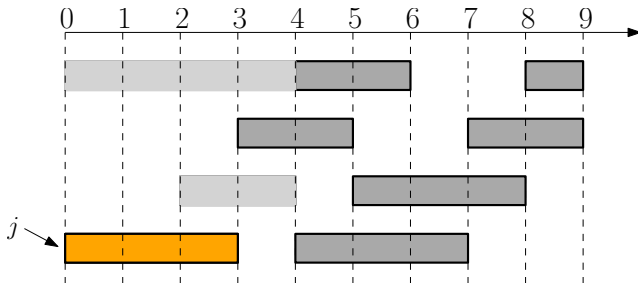
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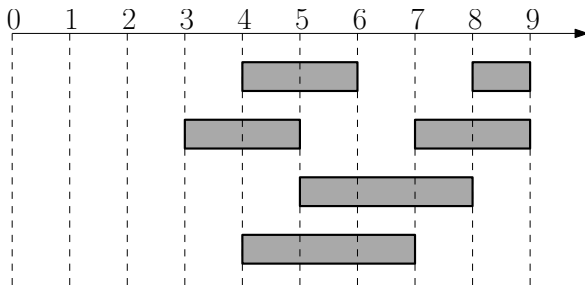
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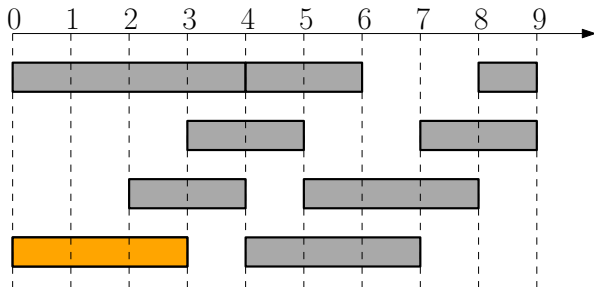
Schedule(s, f, n)

- 1: $A \leftarrow \{1, 2, \dots, n\}, S \leftarrow \emptyset$
- 2: **while** $A \neq \emptyset$ **do**
- 3: $j \leftarrow \arg \min_{j' \in A} f_{j'}$
- 4: $S \leftarrow S \cup \{j\}; A \leftarrow \{j' \in A : s_{j'} \geq f_j\}$
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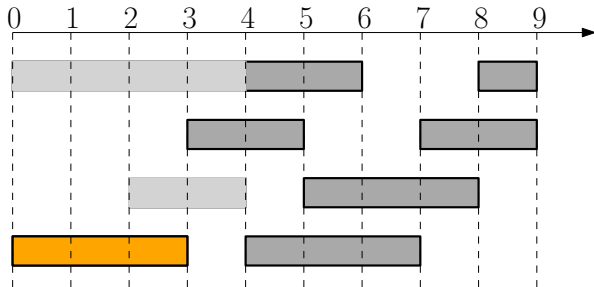
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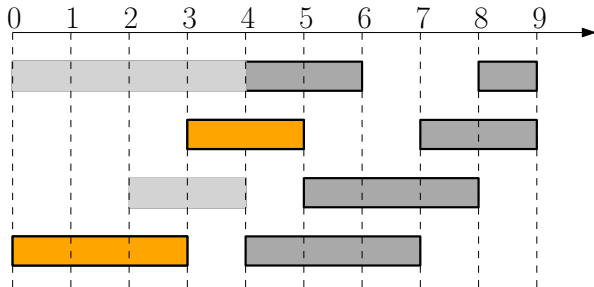
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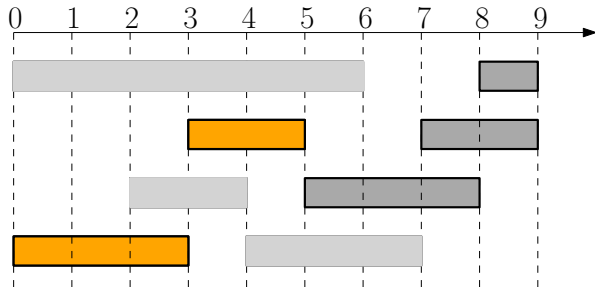
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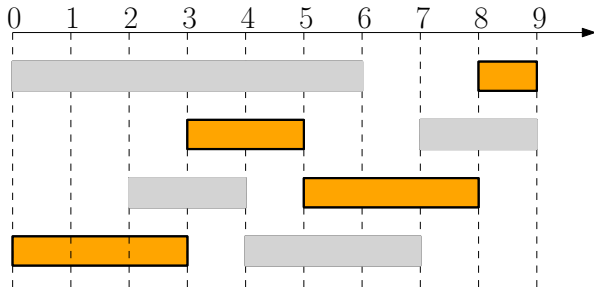
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Greedy Algorithm for Interval Scheduling

Schedule(s, f, n)

- 1: $A \leftarrow \{1, 2, \dots, n\}, S \leftarrow \emptyset$
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- Naive implementation: $O(n^2)$ time

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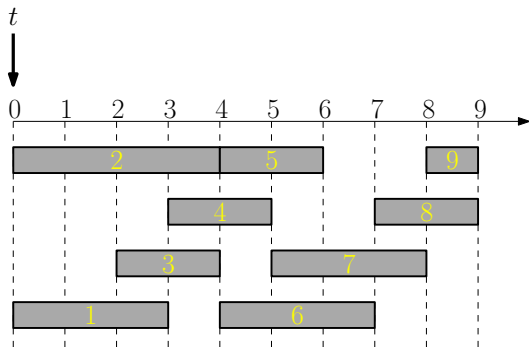
Running time of algorithm?

- Naive implementation: $O(n^2)$ time
- Clever implementation: $O(n \lg n)$ time

Clever Implementation of Greedy Algorithm

Schedule(s, f, n)

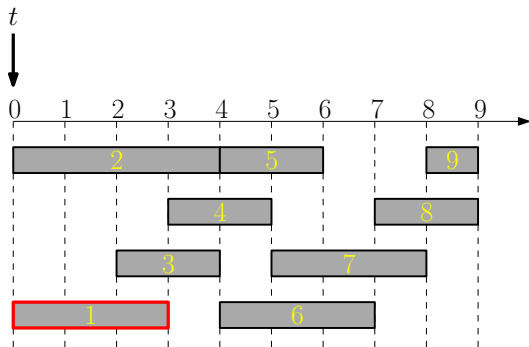
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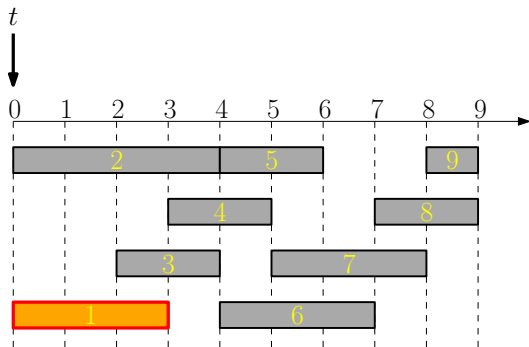
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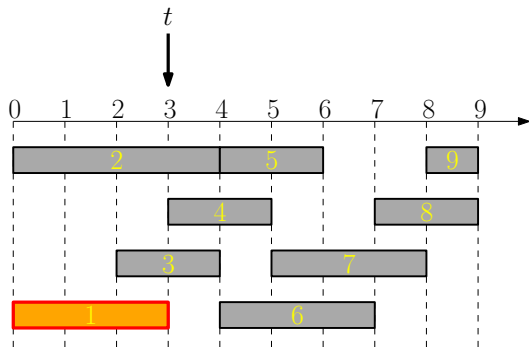
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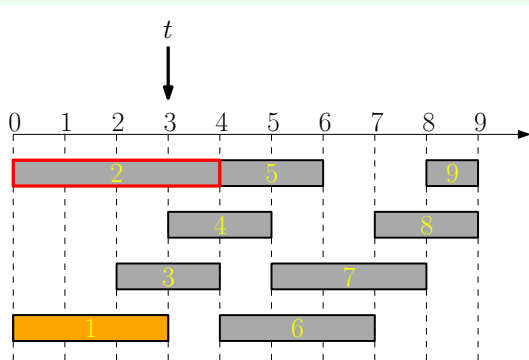
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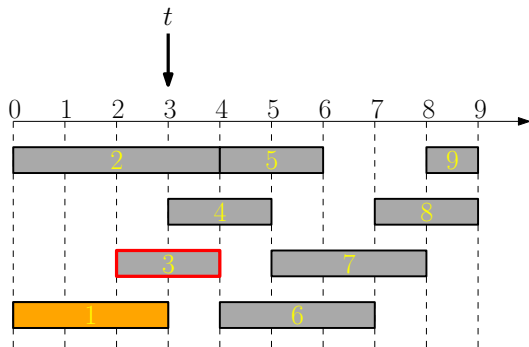
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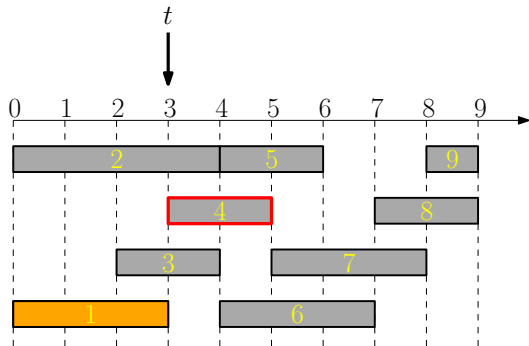
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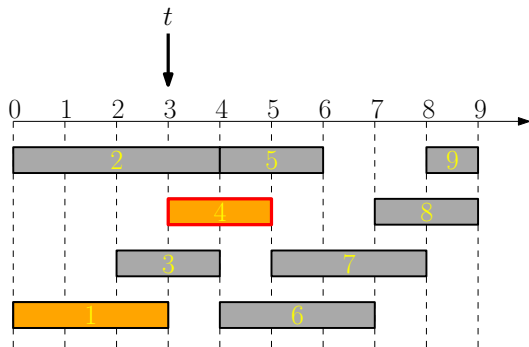
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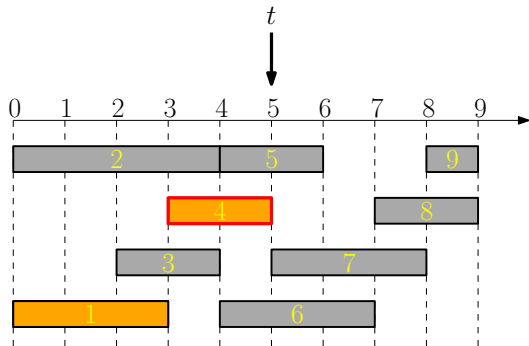
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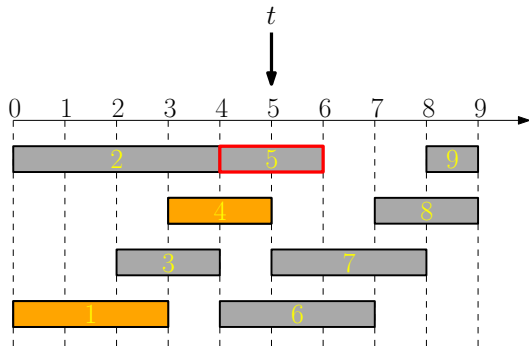
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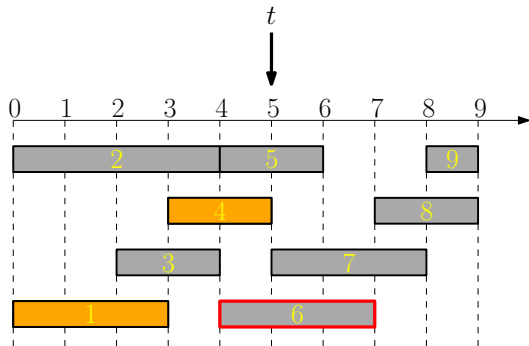
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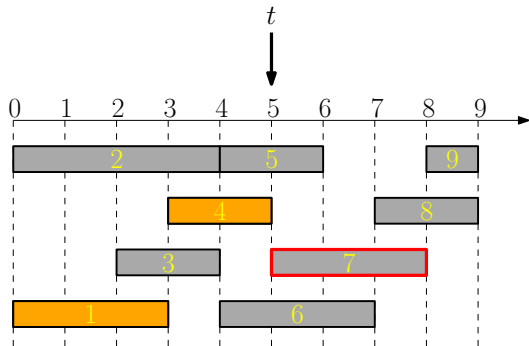
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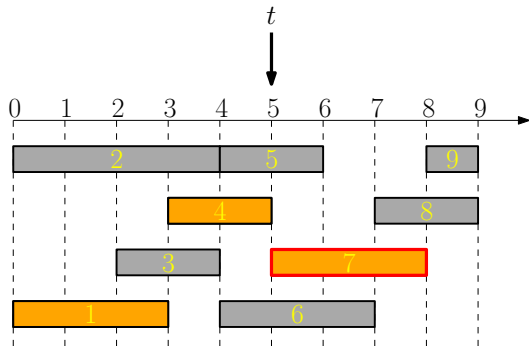
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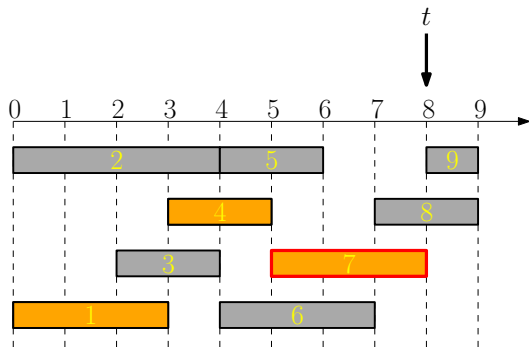
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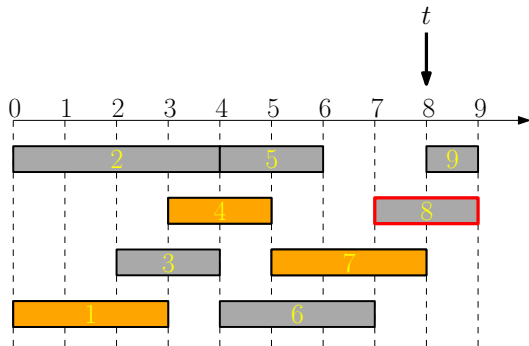
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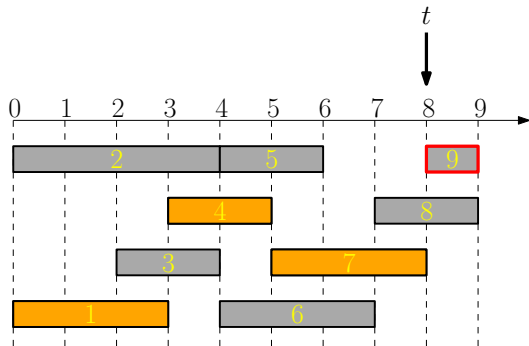
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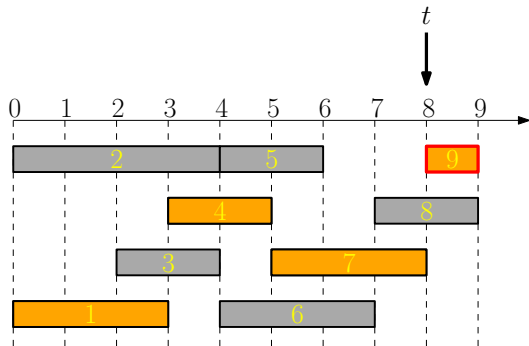
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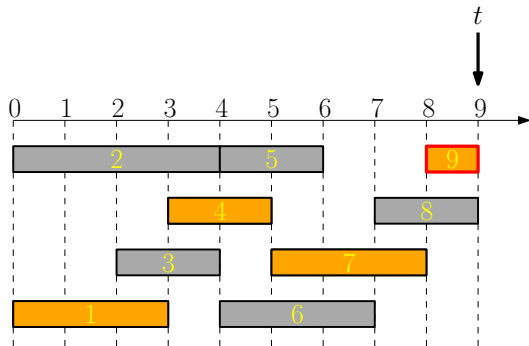
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Outline

- 1 Toy Example: Box Packing
- 2 Interval Scheduling
- 3 Offline Caching**
 - Heap: Concrete Data Structure for Priority Queue
- 4 Data Compression and Huffman Code
- 5 Summary

Offline Caching

- Cache that can store k pages
- Sequence of page requests

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page
sequence

1

5

4

2

5

3

2

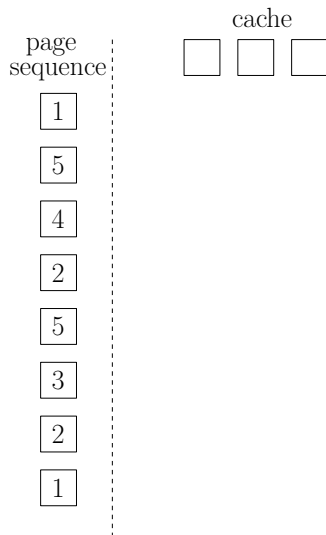
1

cache



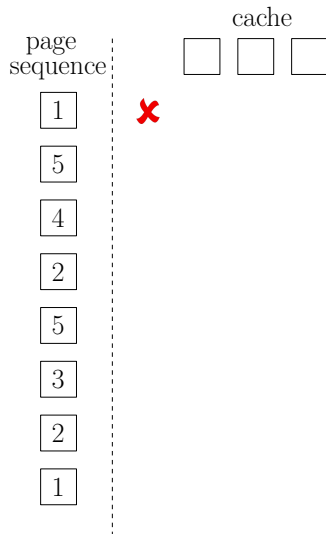
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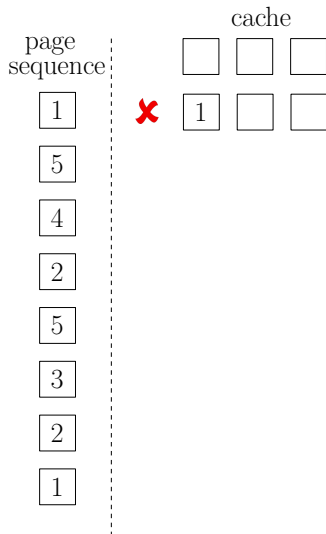
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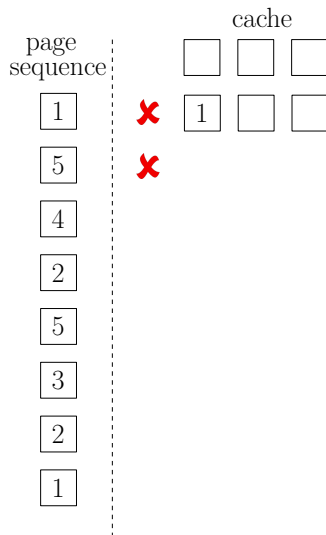
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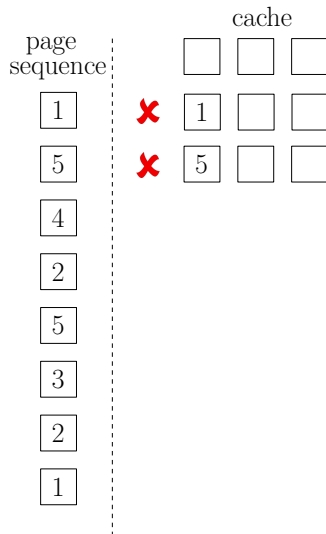
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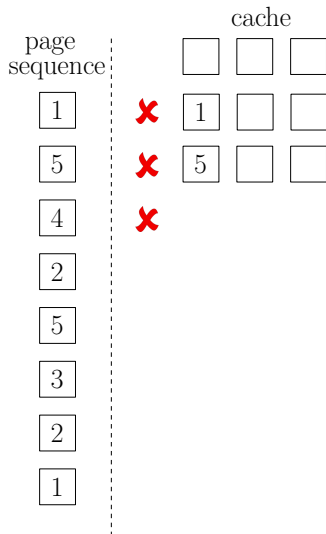
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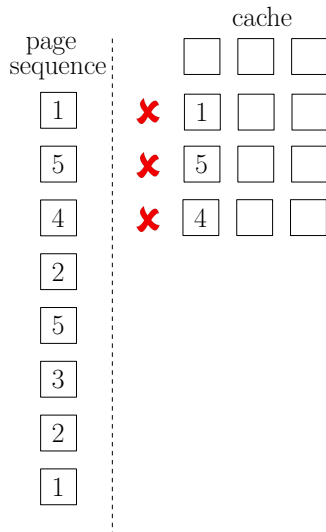
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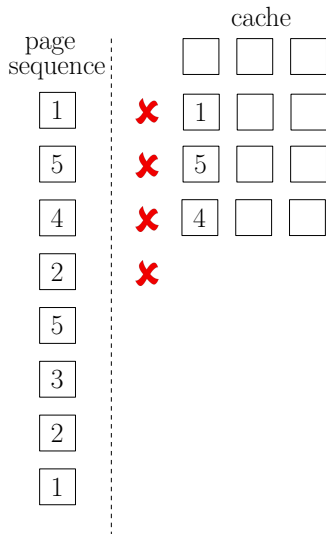
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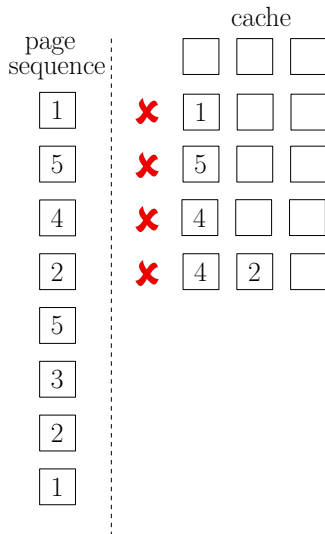
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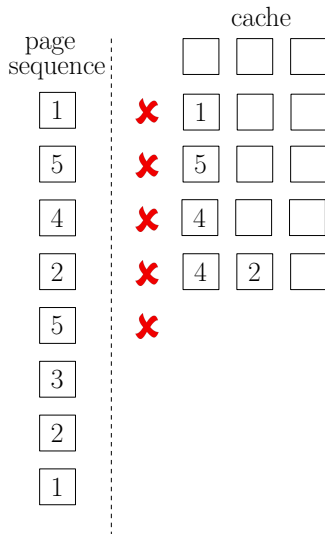
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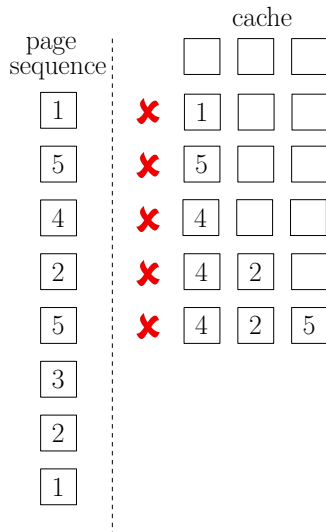
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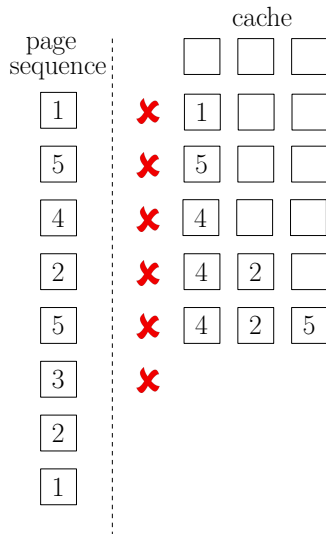
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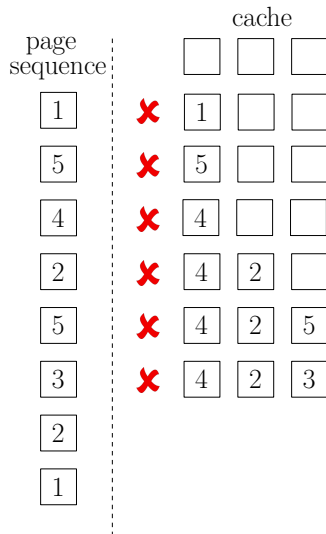
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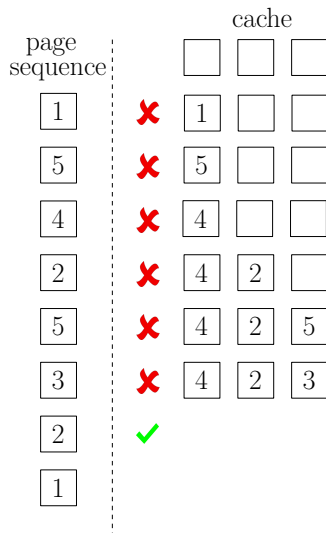
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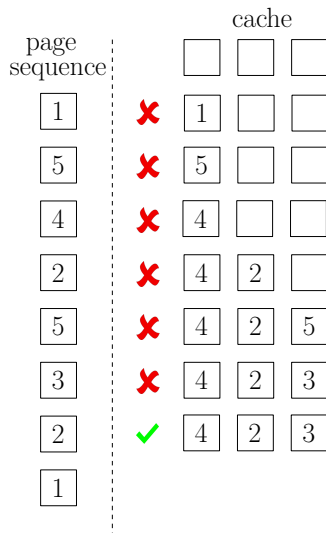
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		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
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5	✗	5	<input type="checkbox"/>	<input type="checkbox"/>
4	✗	4	<input type="checkbox"/>	<input type="checkbox"/>
2	✗	4	2	<input type="checkbox"/>
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3	✗	4	2	3
2	✓	4	2	3
1	✗			

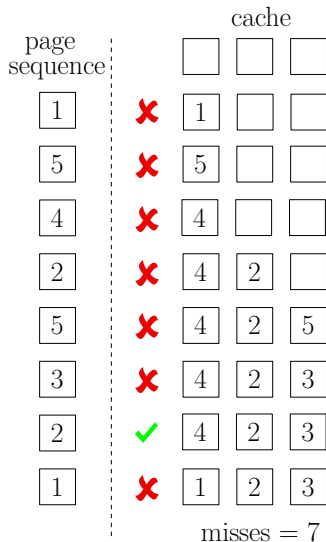
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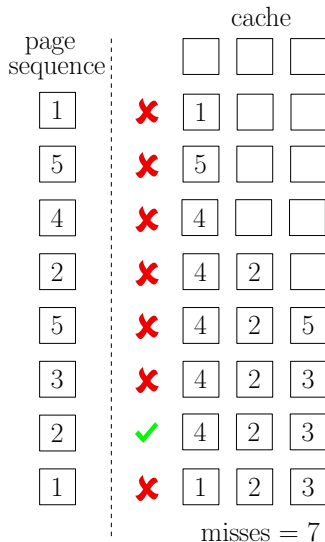
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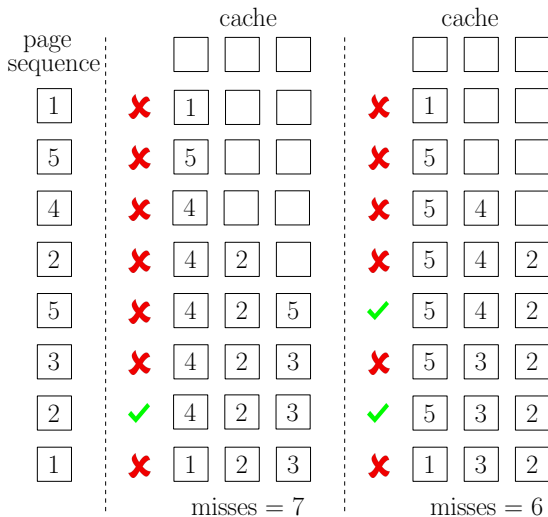


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- Goal: minimize the number of cache misses.



A Better Solution for Example



Offline Caching Problem

Input: k : the size of cache

n : number of pages

We use $[n]$ for $\{1, 2, 3, \dots, n\}$.

$\rho_1, \rho_2, \rho_3, \dots, \rho_T \in [n]$: sequence of requests

Output: $i_1, i_2, i_3, \dots, i_T \in \{\text{hit}, \text{empty}\} \cup [n]$: indices of pages to evict (“hit” means evicting no page, “empty” means evicting empty page)

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Q: Which one is more realistic?

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We use $[n]$ for $\{1, 2, 3, \dots, n\}$.

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Output: $i_1, i_2, i_3, \dots, i_T \in \{\text{hit}, \text{empty}\} \cup [n]$: indices of pages to evict (“hit” means evicting no page, “empty” means evicting empty page)

- Offline Caching: we know the whole sequence ahead of time.
- Online Caching: we have to make decisions on the fly, before seeing future requests.

Q: Which one is more realistic?

A: Online caching

- Offline Caching: we know the whole sequence ahead of time.
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Q: Which one is more realistic?

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Q: Why do we study the offline caching problem?

A: Use the offline solution as a benchmark to measure the “competitive ratio” of online algorithms

Offline Caching: Potential Greedy Algorithms

- FIFO(First-In-First-Out): always evict the first page in cache

Offline Caching: Potential Greedy Algorithms

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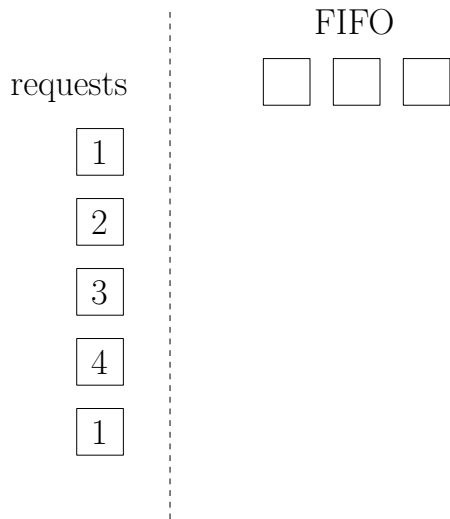
Offline Caching: Potential Greedy Algorithms

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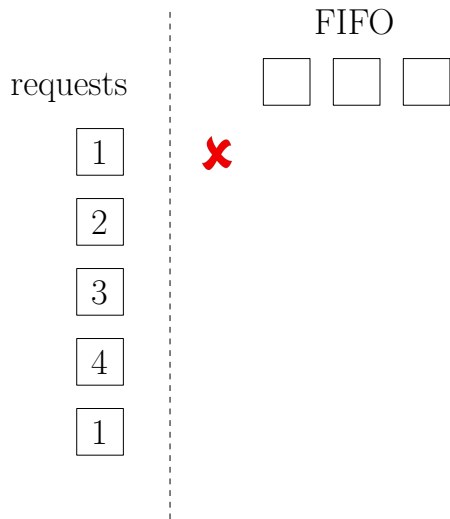
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- All the above algorithms are not optimum!
- Indeed all the algorithms are “online”, i.e, the decisions can be made without knowing future requests. Online algorithms can not be optimum.

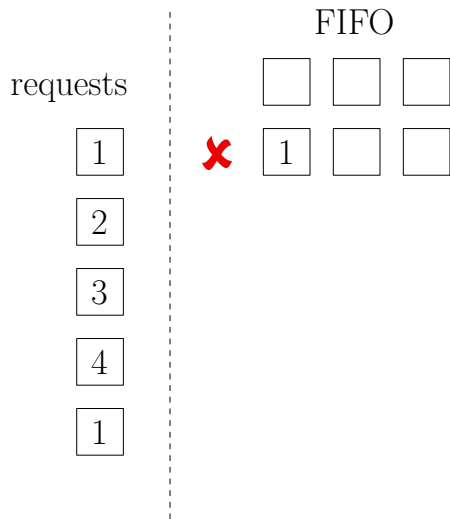
FIFO is not optimum



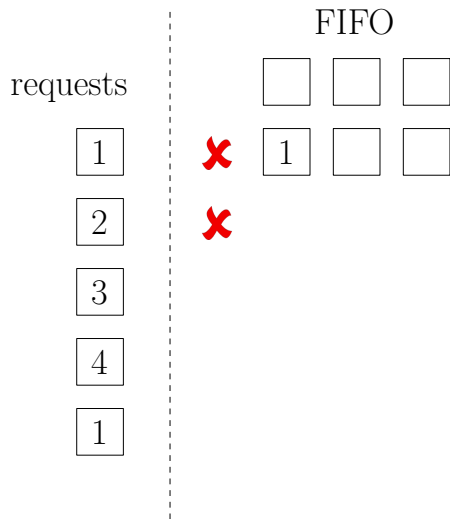
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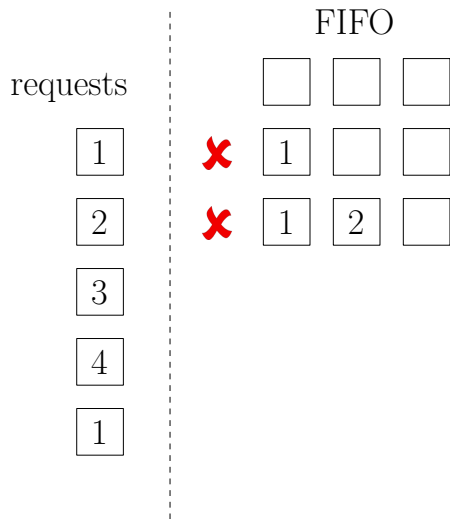
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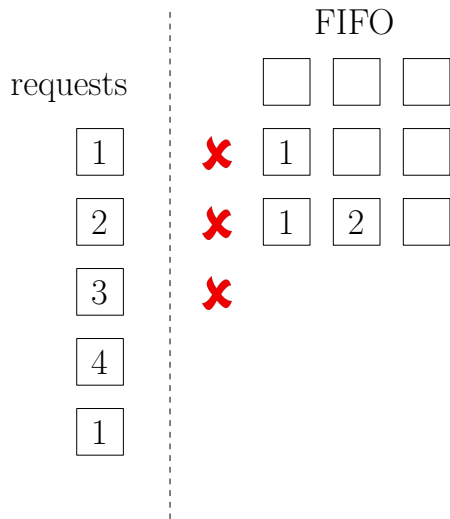
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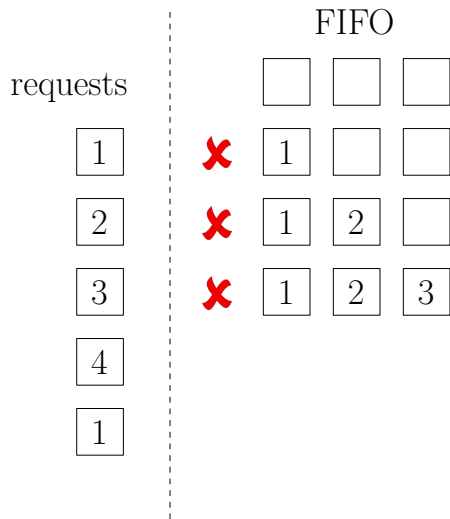
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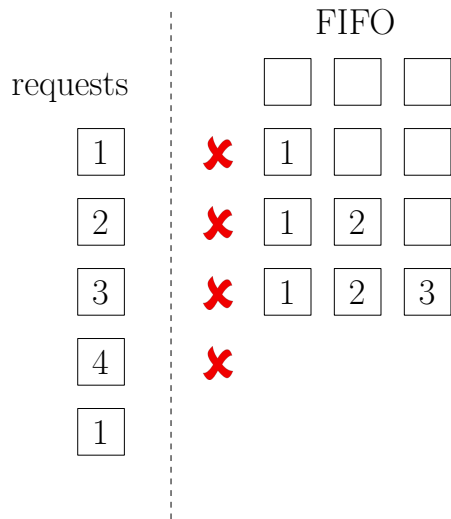
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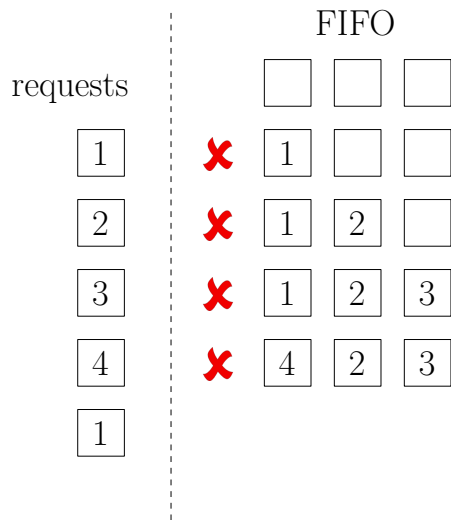
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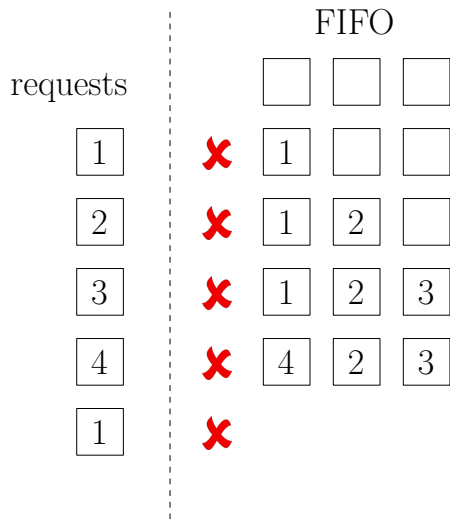
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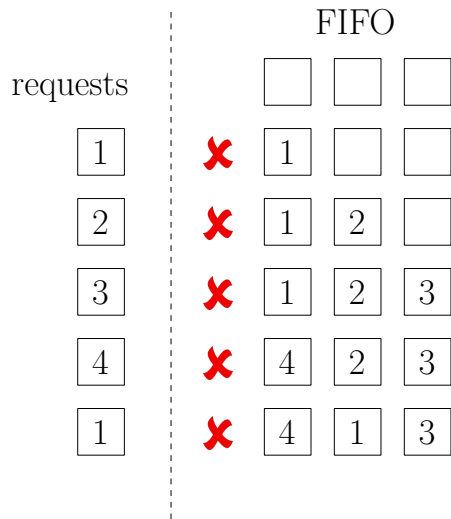
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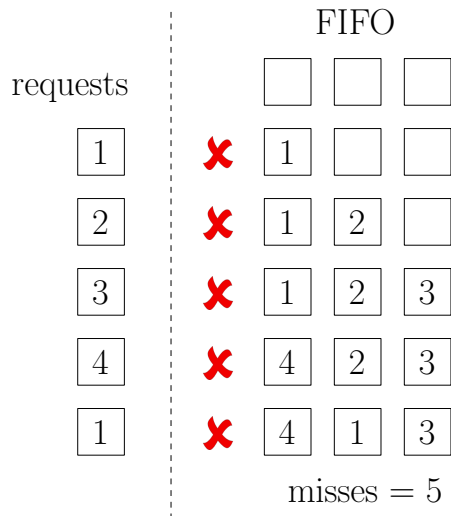
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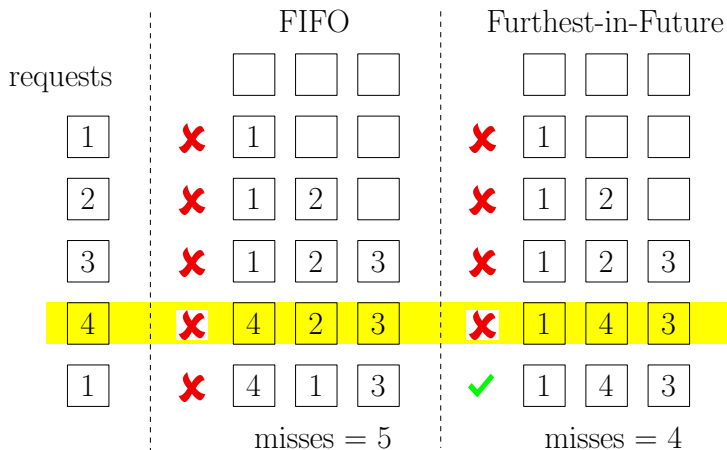
FIFO is not optimum

requests		FIFO				Furthest-in-Future		
		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
<input type="checkbox" value="1"/>	X	<input type="checkbox" value="1"/>	<input type="checkbox"/>	<input type="checkbox"/>	X	<input type="checkbox" value="1"/>	<input type="checkbox"/>	<input type="checkbox"/>
<input type="checkbox" value="2"/>	X	<input type="checkbox" value="1"/>	<input type="checkbox" value="2"/>	<input type="checkbox"/>	X	<input type="checkbox" value="1"/>	<input type="checkbox" value="2"/>	<input type="checkbox"/>
<input type="checkbox" value="3"/>	X	<input type="checkbox" value="1"/>	<input type="checkbox" value="2"/>	<input type="checkbox" value="3"/>	X	<input type="checkbox" value="1"/>	<input type="checkbox" value="2"/>	<input type="checkbox" value="3"/>
<input type="checkbox" value="4"/>	X	<input type="checkbox" value="4"/>	<input type="checkbox" value="2"/>	<input type="checkbox" value="3"/>	X	<input type="checkbox" value="1"/>	<input type="checkbox" value="4"/>	<input type="checkbox" value="3"/>
<input type="checkbox" value="1"/>	X	<input type="checkbox" value="4"/>	<input type="checkbox" value="1"/>	<input type="checkbox" value="3"/>	✓	<input type="checkbox" value="1"/>	<input type="checkbox" value="4"/>	<input type="checkbox" value="3"/>
		misses = 5				misses = 4		

Furthest-in-Future (FF)

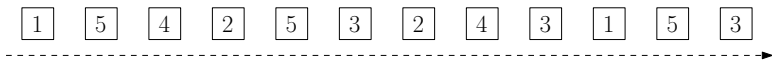
- Algorithm: every time, evict the item that is not requested until furthest in the future, if we need to evict one.
- The algorithm is **not** an online algorithm, since the decision at a step depends on the request sequence in the future.

Furthest-in-Future (FF)



Example

requests



Example

requests



X X X

1 1 1

5 5

4

Example

requests



✗ ✗ ✗

<input type="checkbox"/>	1	1	1
<input type="checkbox"/>	<input type="checkbox"/>	5	5
<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	4

Example

requests



✗ ✗ ✗ ✗

1 1 1 2

5 5 5

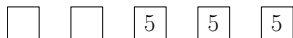
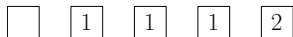
4 4

Example

requests



X X X X



Example

requests



	1	1	1	2	2
		5	5	5	5
			4	4	4

Example

requests



Example

requests



✗ ✗ ✗ ✗ ✓ ✗

1 1 1 2 2 2

5 5 5 5 3

4 4 4 4

Example

requests

1 5 4 2 5 3 2 4 3 1 5 3

✗ ✗ ✗ ✗ ✓ ✗

1 1 1 2 2 2

5 5 5 5 3

4 4 4 4

Example

requests

1 5 4 2 5 3 2 4 3 1 5 3

✗ ✗ ✗ ✗ ✓ ✗ ✓

	1	1	1	2	2	2	2
		5	5	5	5	3	3
			4	4	4	4	4

Example

requests

1 5 4 2 5 3 2 4 3 1 5 3

✗ ✗ ✗ ✗ ✓ ✗ ✓ ✓

1 1 1 2 2 2 2 2

5 5 5 5 3 3 3

4 4 4 4 4

Example

requests

1 5 4 2 5 3 2 4 3 1 5 3

✗ ✗ ✗ ✗ ✓ ✗ ✓ ✓ ✓

1 1 1 2 2 2 2 2 2

5 5 5 5 3 3 3 3

4 4 4 4 4 4 4

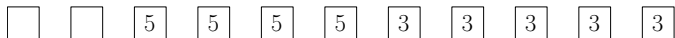
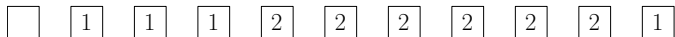
Example

requests



Example

requests



Example

requests



Example

requests



Recall: Designing and Analyzing Greedy Algorithms

Greedy Algorithm

- Build up the solutions in steps
- At each step, make an **irrevocable** decision using a “reasonable” strategy

Analysis of Greedy Algorithm

- Prove that the reasonable strategy is “safe” (key)
- Show that the remaining task after applying the strategy is to solve a (many) smaller instance(s) of the same problem (usually easy)

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Offline Caching Problem

Input: k : the size of cache

n : number of pages

$\rho_1, \rho_2, \rho_3, \dots, \rho_T \in [n]$: sequence of requests

Output: $i_1, i_2, i_3, \dots, i_t \in \{\text{hit}, \text{empty}\} \cup [n]$

- empty stands for an empty page
- “hit” means evicting no pages

Offline Caching Problem

Input: k : the size of cache

n : number of pages

$\rho_1, \rho_2, \rho_3, \dots, \rho_T \in [n]$: sequence of requests

$p_1, p_2, \dots, p_k \in \{\text{empty}\} \cup [n]$: initial set of pages in cache

Output: $i_1, i_2, i_3, \dots, i_t \in \{\text{hit}, \text{empty}\} \cup [n]$

- empty stands for an empty page
- “hit” means evicting no pages

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Analysis of Greedy Algorithm

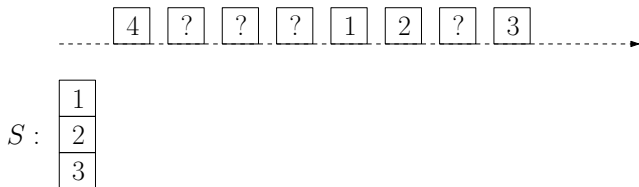
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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. It is safe to evict p^* at time 1.

Analysis of Greedy Algorithm

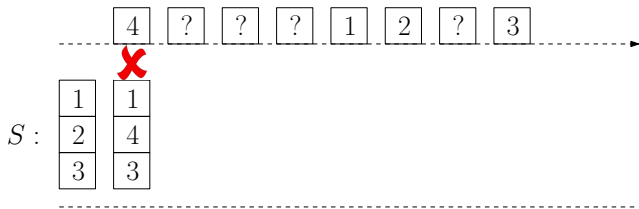
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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **There is an optimum solution in which p^* is evicted at time 1.**



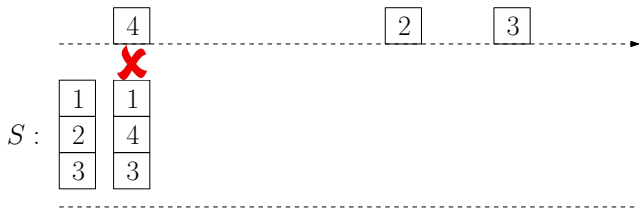
Proof.

- 1 S : any optimum solution
- 2 p^* : page in cache not requested until furthest in the future.
 - In the example, $p^* = 3$.



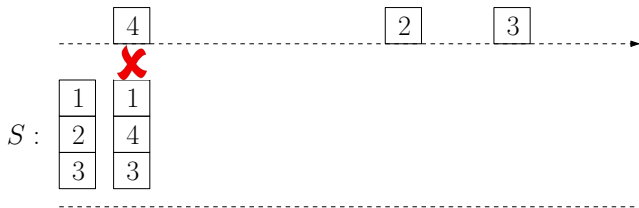
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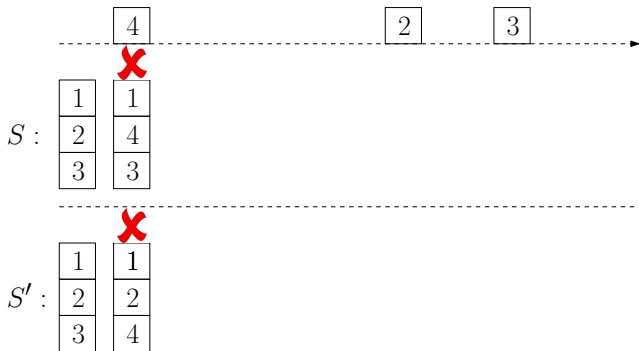


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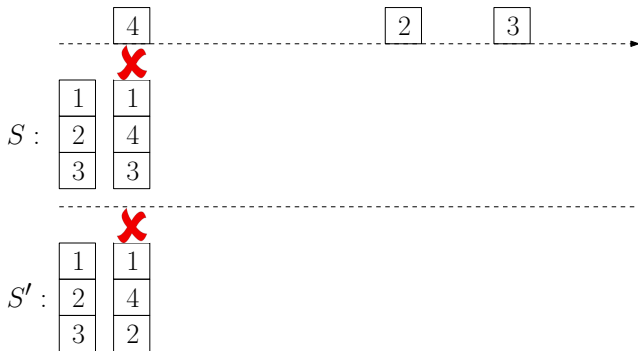


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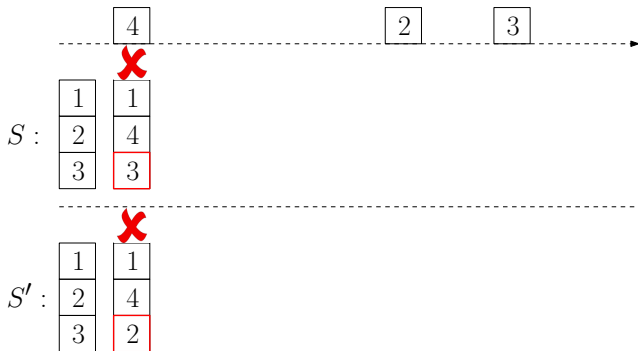
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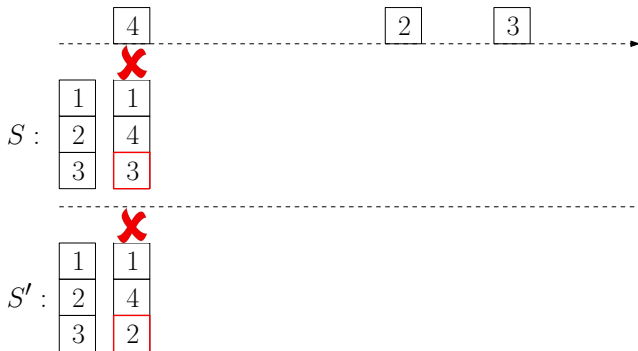
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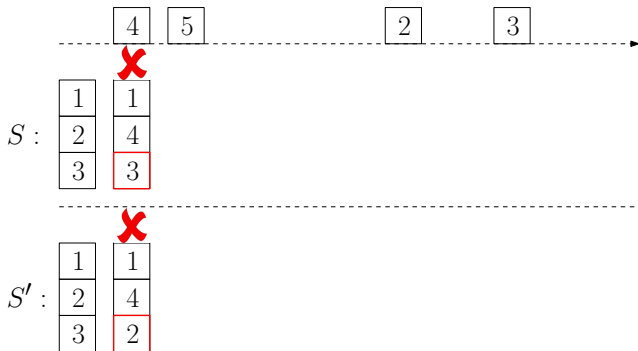
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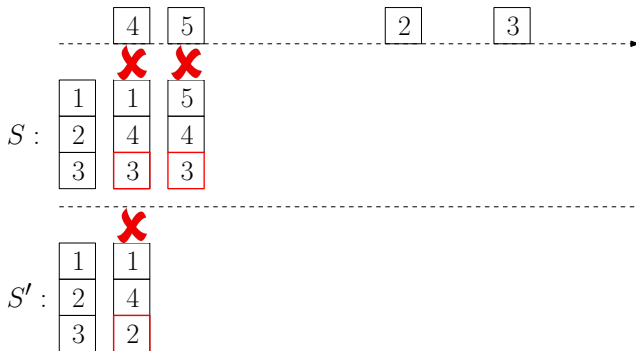
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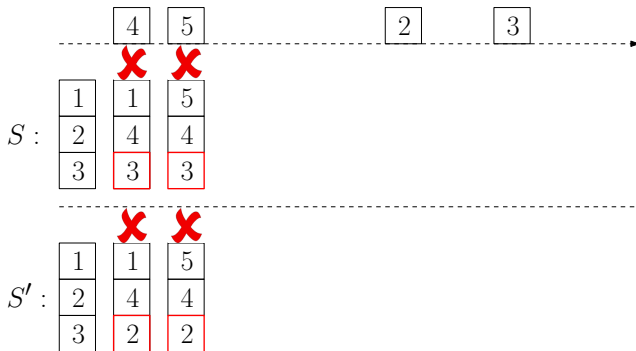
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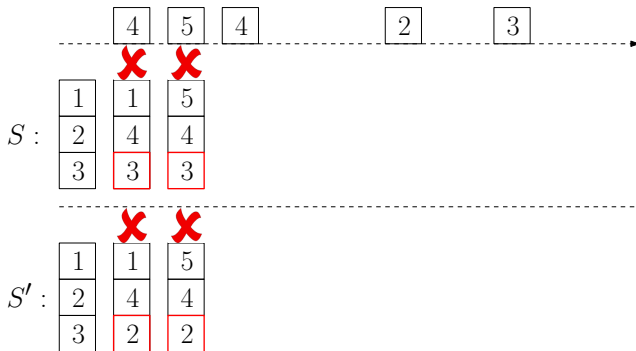
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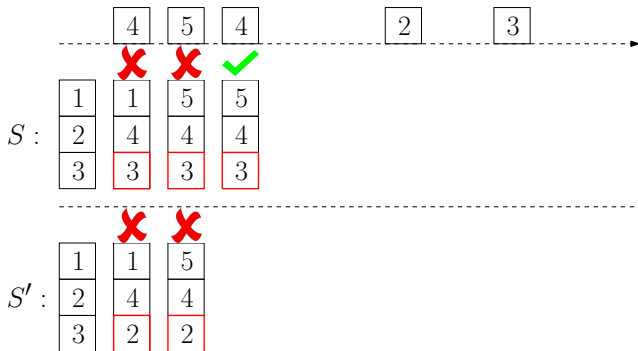
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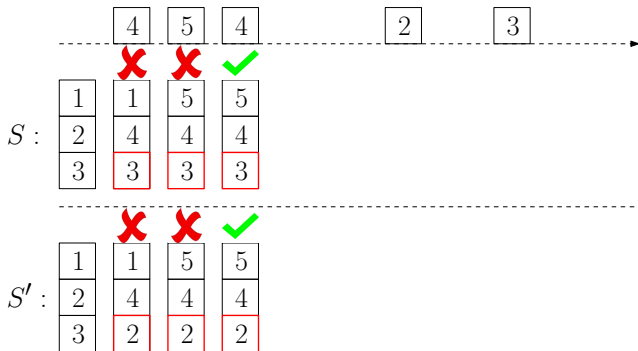
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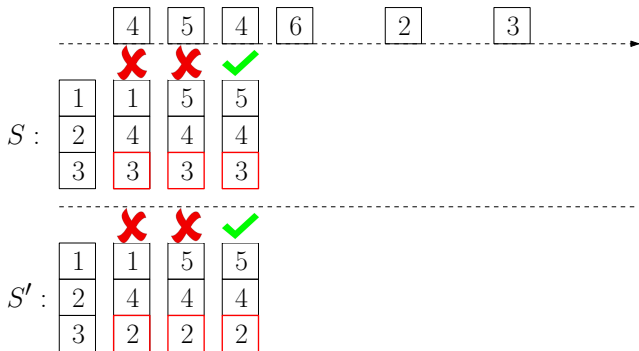
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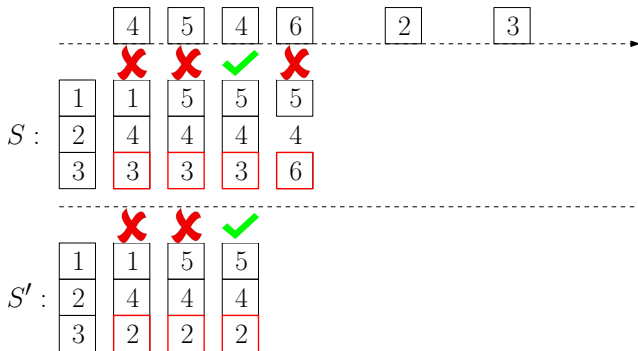
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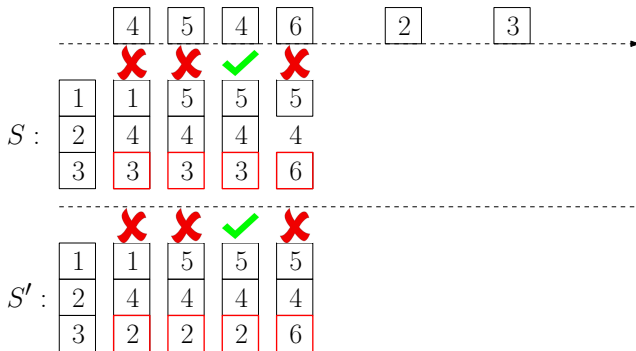
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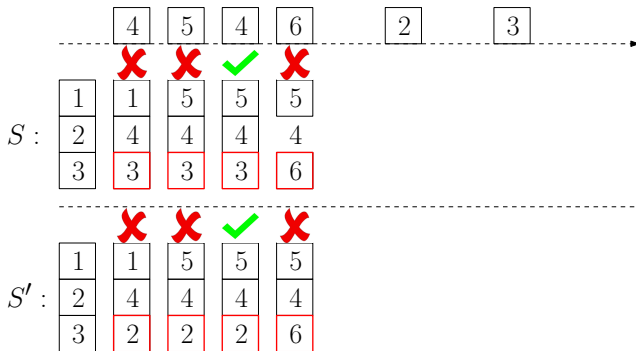
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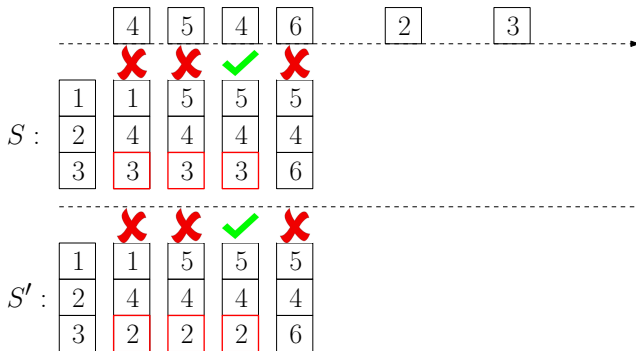


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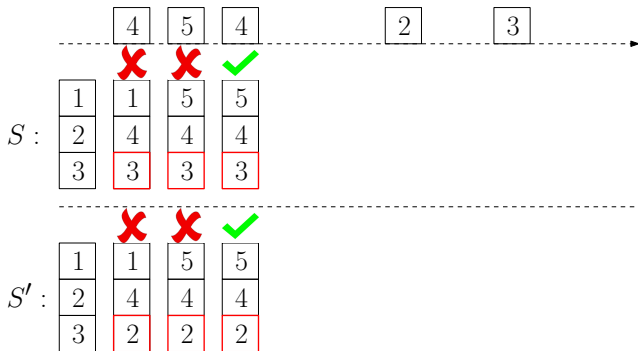


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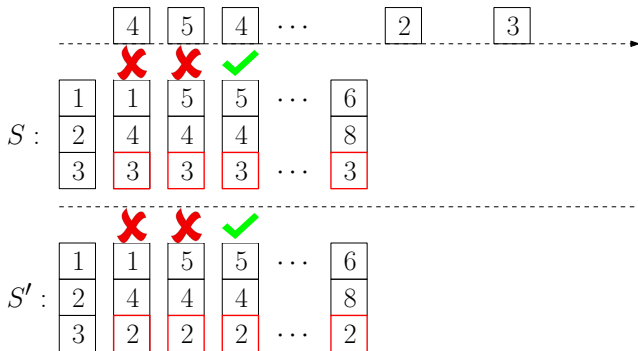
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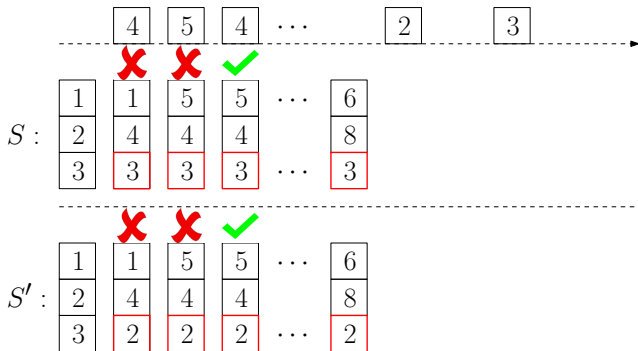
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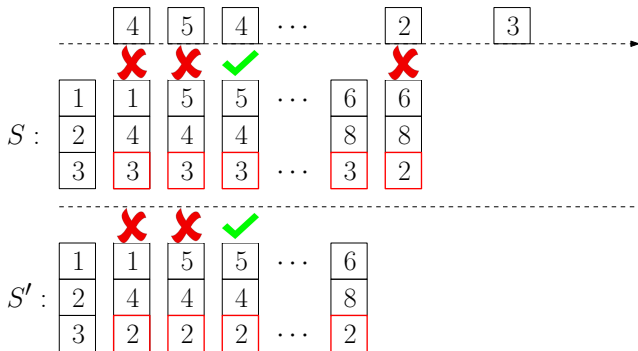


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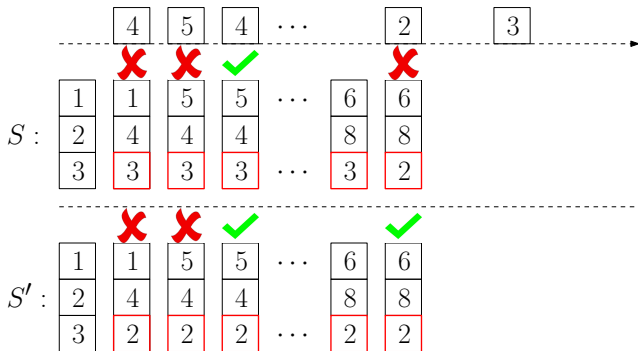
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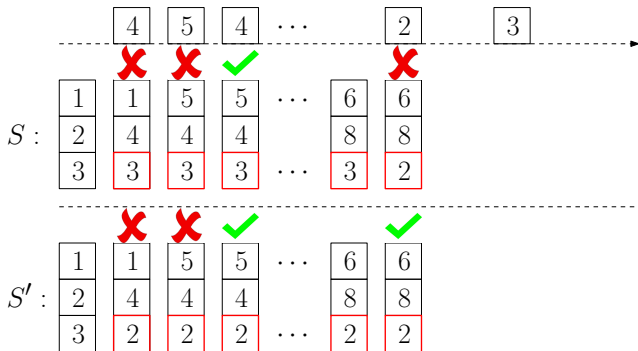
Proof.



Proof.

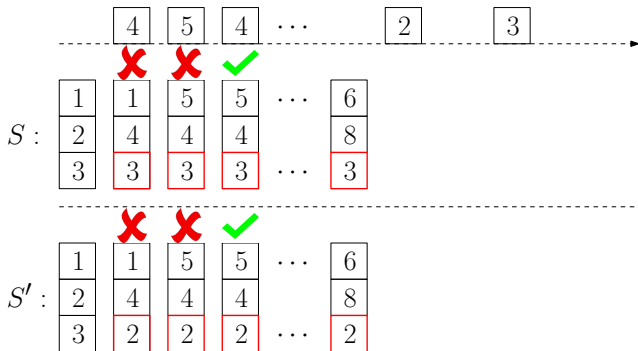


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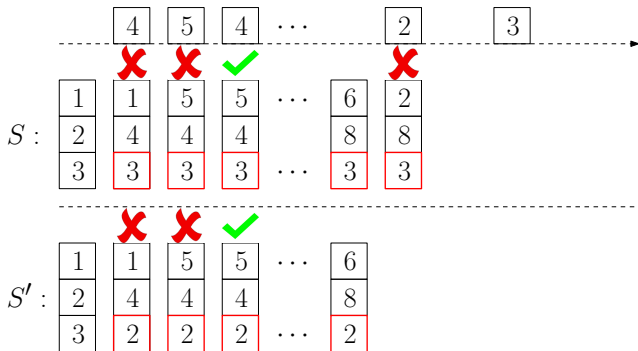
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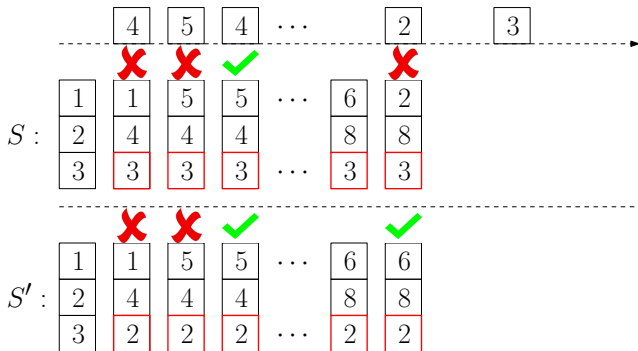
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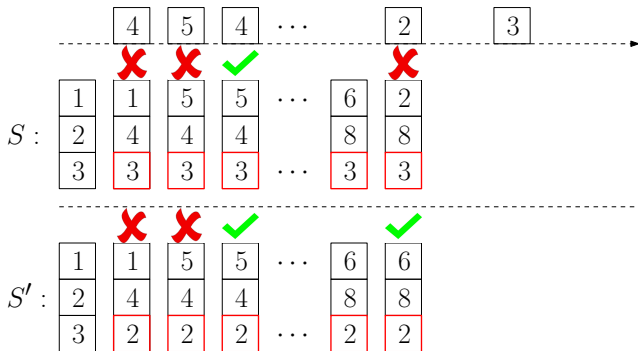
Proof.

- ⑨ If S evicts $p^*(=3)$ for $p' (=2)$, then S won't be optimum. Assume otherwise.



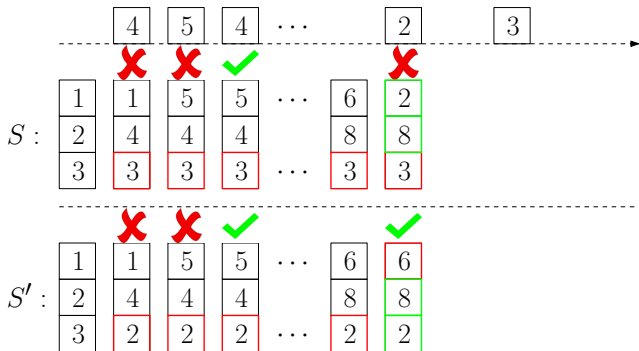
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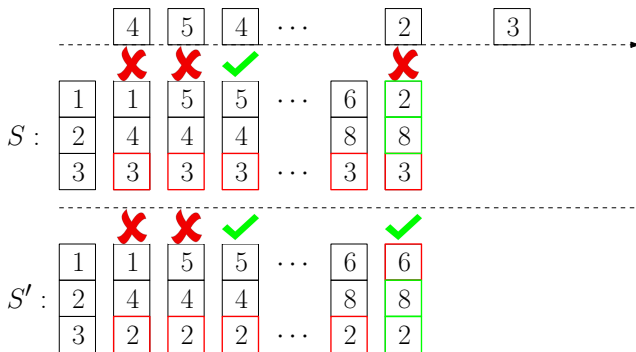
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- 9 If S evicts $p^*(=3)$ for $p' (=2)$, then S won't be optimum. Assume otherwise.
- 10 So far, S' has 1 less page-miss than S does.

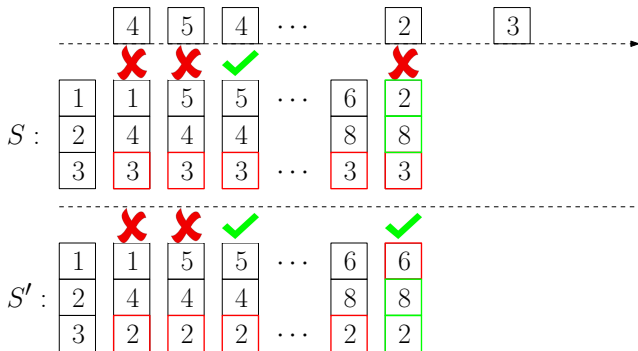


Proof.

- 9 If S evicts $p^*(=3)$ for $p'(=2)$, then S won't be optimum. Assume otherwise.
- 10 So far, S' has 1 less page-miss than S does.
- 11 The status of S' and that of S only differ by 1 page.

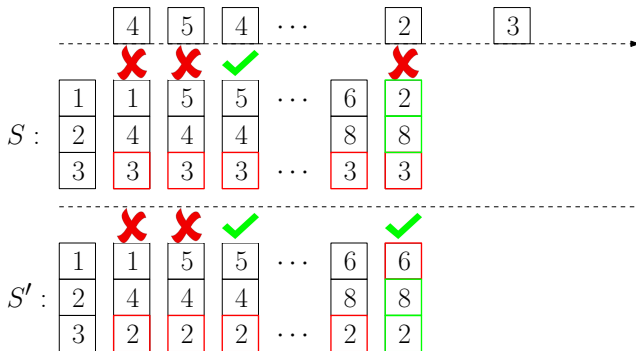


Proof.



Proof.

- 12 We can then guarantee that S' make at most the same number of page-misses as S does.



Proof.

12 We can then guarantee that S' make at most the same number of page-misses as S does.

- Idea: if S has a page-hit and S' has a page-miss, we use the opportunity to make the status of S' the same as that of S . □

- Thus, we have shown how to create another solution S' with the same number of page-misses as that of the optimum solution S . Thus, we proved

Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **There is an optimum solution in which p^* is evicted at time 1.**

- Thus, we have shown how to create another solution S' with the same number of page-misses as that of the optimum solution S . Thus, we proved

Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **It is safe to evict p^* at time 1.**

- Thus, we have shown how to create another solution S' with the same number of page-misses as that of the optimum solution S . Thus, we proved

Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. **It is safe to evict p^* at time 1.**

Theorem The furthest-in-future strategy is optimum.

```
1: for  $t \leftarrow 1$  to  $T$  do  
2:   if  $\rho_t$  is in cache then do nothing  
3:   else if there is an empty page in cache then  
4:     evict the empty page and load  $\rho_t$  in cache  
5:   else  
6:      $p^* \leftarrow$  page in cache that is not used furthest in the future  
7:     evict  $p^*$  and load  $\rho_t$  in cache
```

Q: How can we make the algorithm as fast as possible?

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- For each page p , use a linked list (or an array with dynamic size) to store the time steps in which p is requested.
 - We can find the next time a page is requested easily.
- Use a priority queue data structure to hold all the pages in cache, so that we can easily find the page that is requested furthest in the future.

time	0	1	2	3	4	5	6	7	8	9	10	11	12
pages		P1	P5	P4	P2	P5	P3	P2	P4	P3	P1	P5	P3

P1:

1	10
---	----

P2:

4	7
---	---

P3:

6	9	12
---	---	----

P4:


3	8
---	---

P5:

2	5	11
---	---	----

priority queue

pages	priority values



time	0	1	2	3	4	5	6	7	8	9	10	11	12
pages		P1	P5	P4	P2	P5	P3	P2	P4	P3	P1	P5	P3

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priority queue

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P1:

1	10
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priority queue

pages	priority values



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pages		P1	P5	P4	P2	P5	P3	P2	P4	P3	P1	P5	P3

P1: 1 10

P2: 4 7

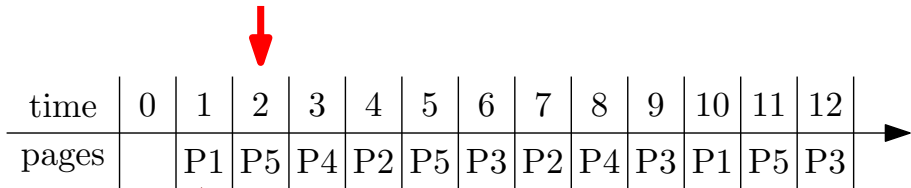
P3: 6 9 12

P4: 3 8

P5: 2 5 11

priority queue

pages	priority values
P1	10



X

P1: [1 | 10]

P2: [4 | 7]

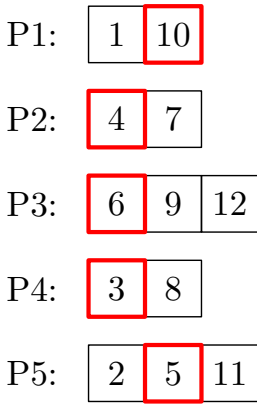
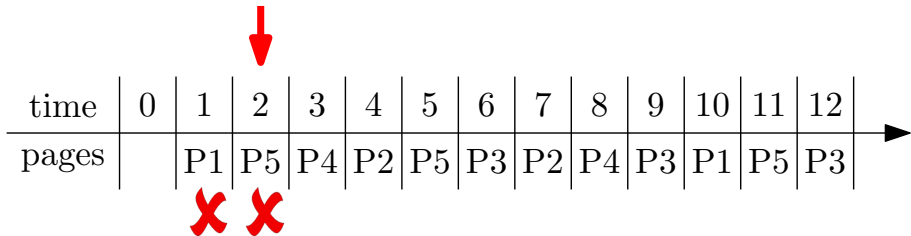
P3: [6 | 9 | 12]

P4: [3 | 8]

P5: [2 | 5 | 11]

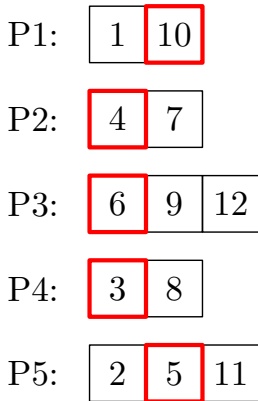
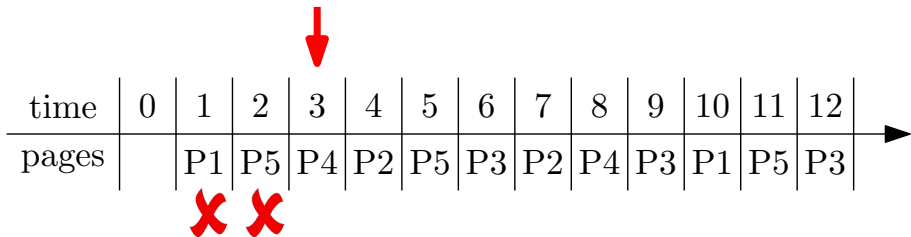
priority queue

pages	priority values
P1	10



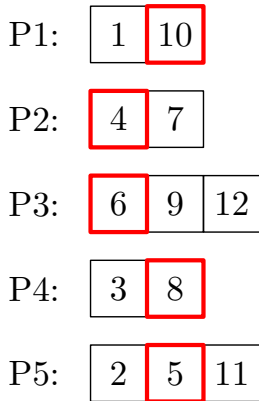
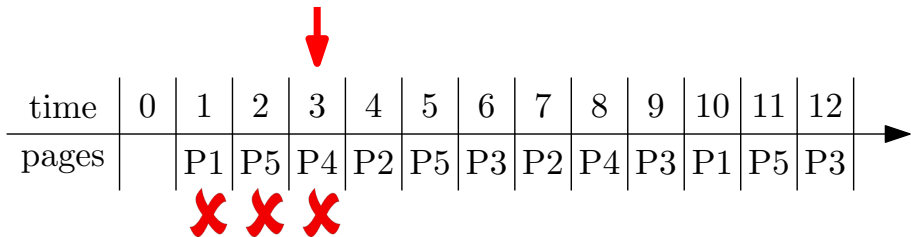
priority queue

pages	priority values
P1	10
P5	5



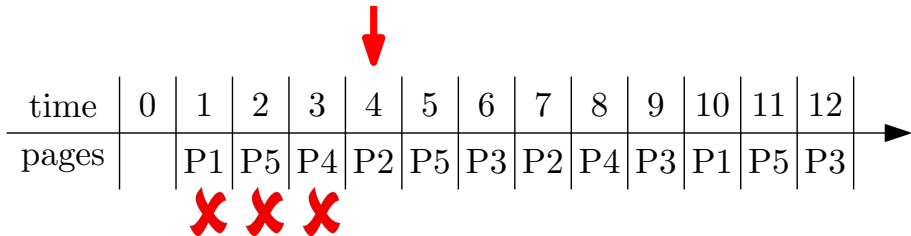
priority queue

pages	priority values
P1	10
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priority queue

pages	priority values
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- P1:

1	10
---	----
- P2:

4	7
---	---
- P3:

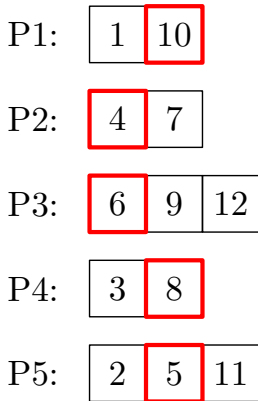
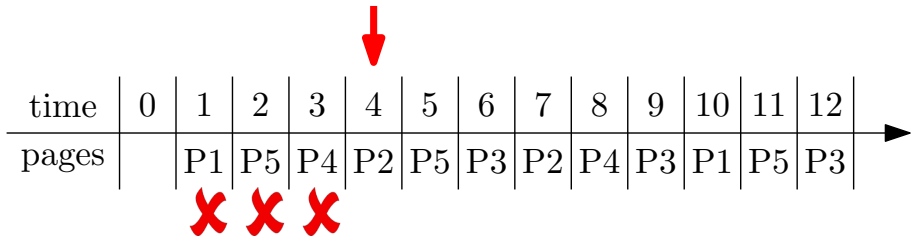
6	9	12
---	---	----
- P4:

3	8
---	---
- P5:

2	5	11
---	---	----

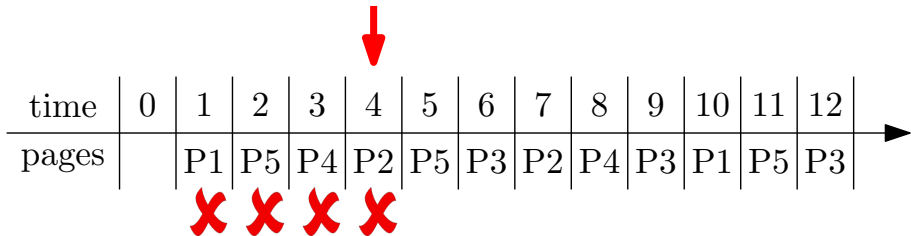
priority queue

pages	priority values
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P5	5
P4	8



priority queue

pages	priority values
P5	5
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P1:

1	10
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P2:

4	7
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P3:

6	9	12
---	---	----

P4:

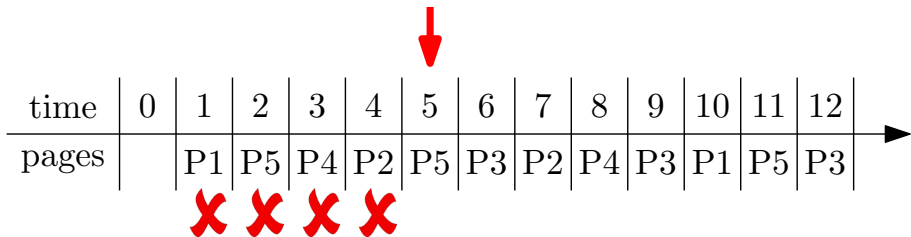
3	8
---	---

P5:

2	5	11
---	---	----

priority queue

pages	priority values
P2	7
P5	5
P4	8



P1:

1	10
---	----

P2:

4	7
---	---

P3:

6	9	12
---	---	----

P4:

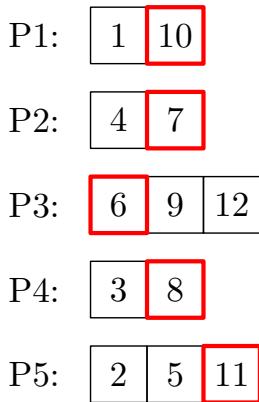
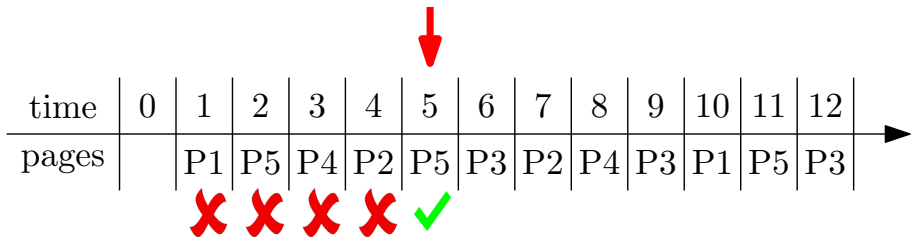
3	8
---	---

P5:

2	5	11
---	---	----

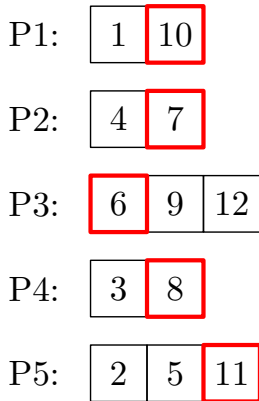
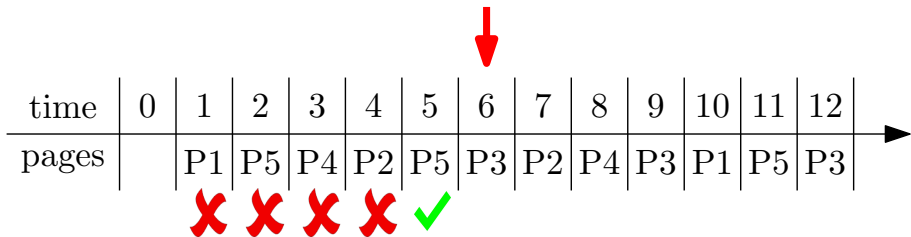
priority queue

pages	priority values
P2	7
P5	5
P4	8



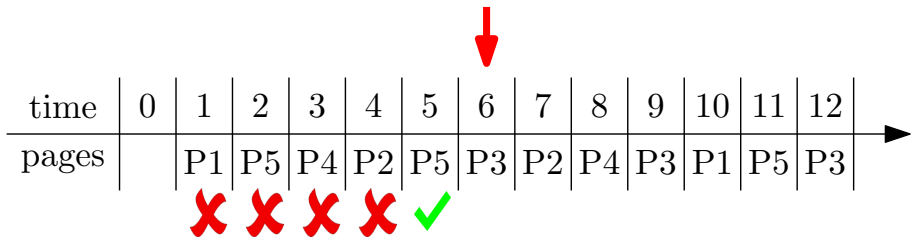
priority queue

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priority queue

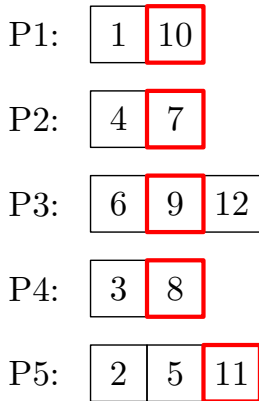
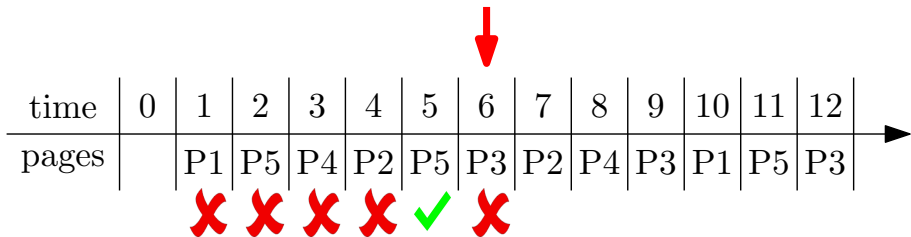
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- P1: 1 10
- P2: 4 7
- P3: 6 9 12
- P4: 3 8
- P5: 2 5 11

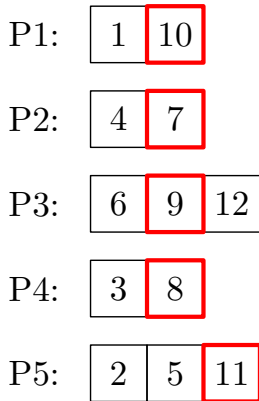
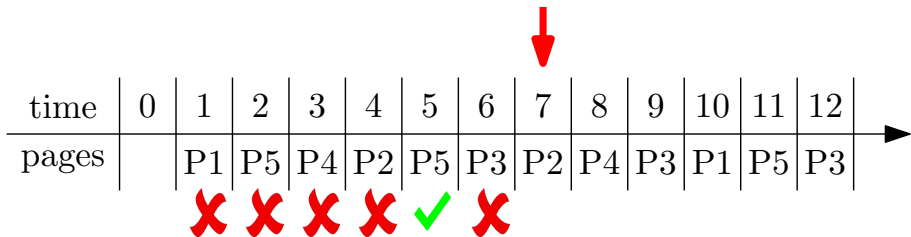
priority queue

pages	priority values
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P4	8



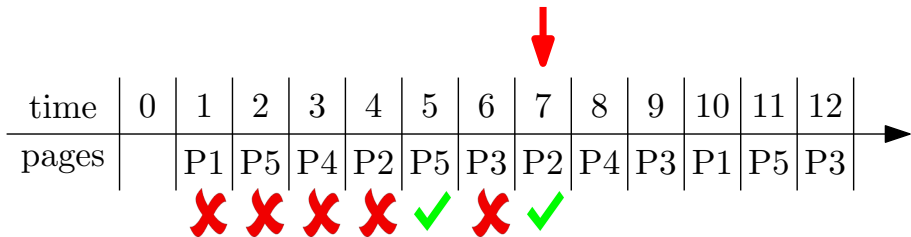
priority queue

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priority queue

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P1:

1	10
---	----

P2:

4	7	
---	---	--

P3:

6	9	12
---	---	----

P4:

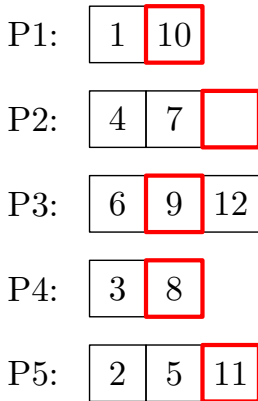
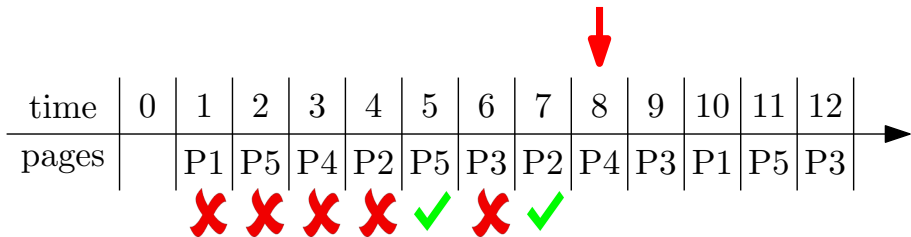
3	8
---	---

P5:

2	5	11
---	---	----

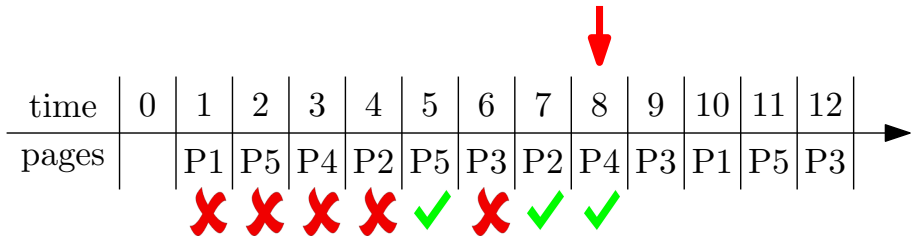
priority queue

pages	priority values
P2	∞
P3	9
P4	8



priority queue

pages	priority values
P2	∞
P3	9
P4	8



P1:

1	10
---	----

P2:

4	7	
---	---	--

P3:

6	9	12
---	---	----

P4:

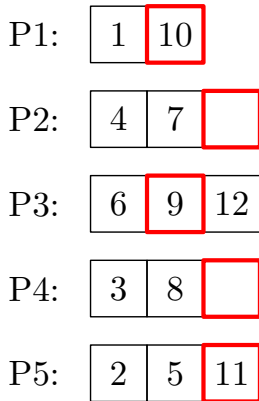
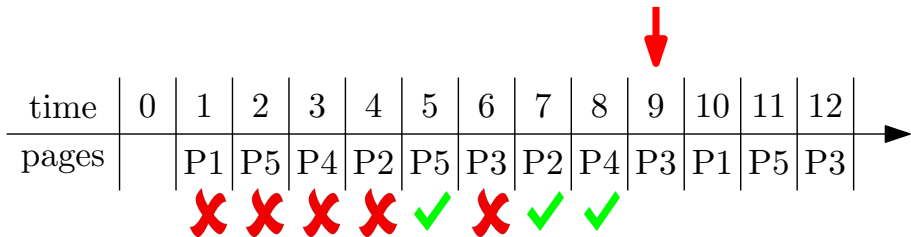
3	8	
---	---	--

P5:

2	5	11
---	---	----

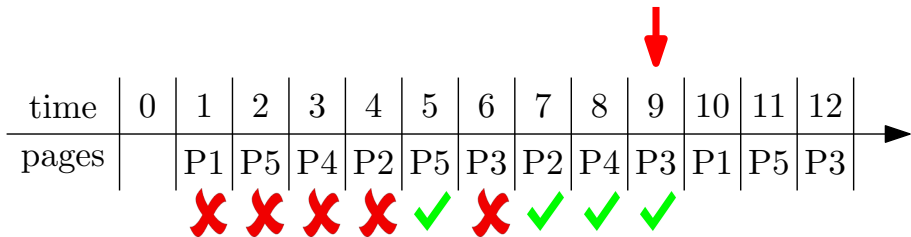
priority queue

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P4	∞



priority queue

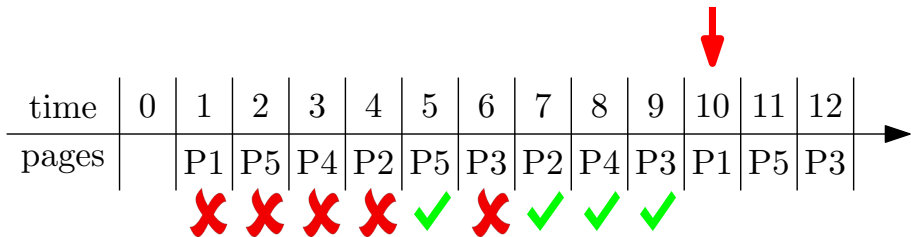
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P2:	4	7	
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priority queue

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1	10
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P2:

4	7	
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P3:

6	9	12
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P4:

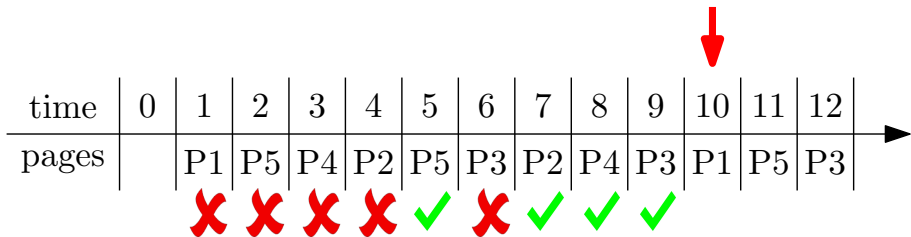
3	8	
---	---	--

P5:

2	5	11
---	---	----

priority queue

pages	priority values
P2	∞
P3	12
P4	∞



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1	10
---	----

P2:

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P3:

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P4:

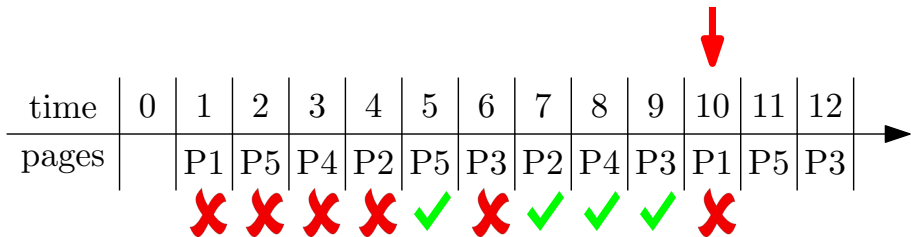
3	8	
---	---	--

P5:

2	5	11
---	---	----

priority queue

pages	priority values
P3	12
P4	∞



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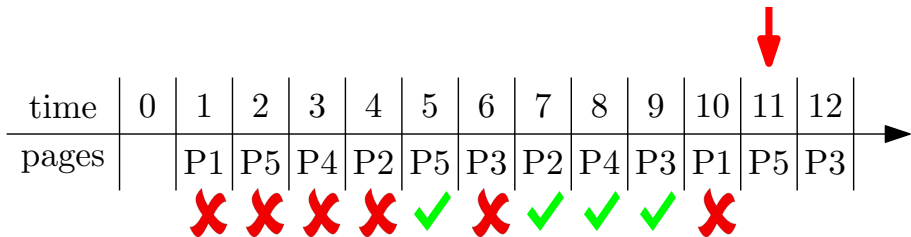
P3: 6 9 12

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priority queue

pages	priority values
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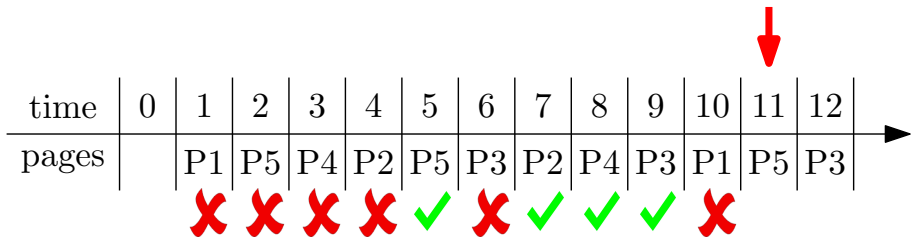
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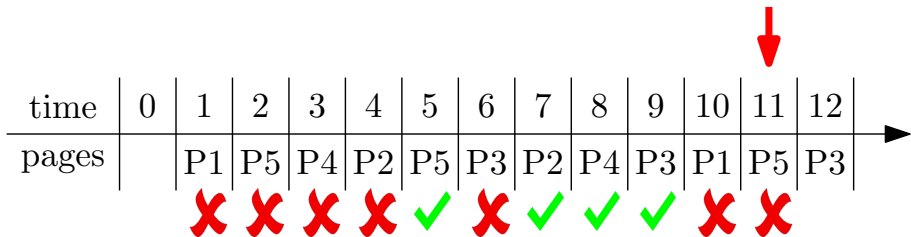
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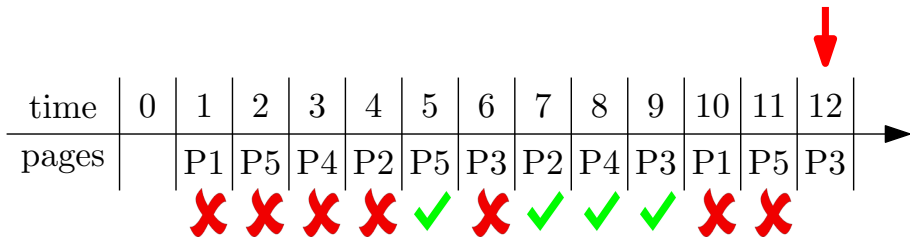
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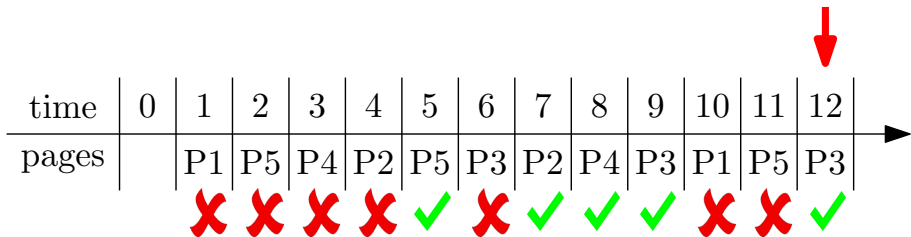
P3: 6 9 12

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priority queue

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P5: 2 5 11

priority queue

pages	priority values
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P3	∞
P4	∞

```

1: for every  $p \leftarrow 1$  to  $n$  do
2:    $times[p] \leftarrow$  array of times in which  $p$  is requested, in
   increasing order                                ▷ put  $\infty$  at the end of array
3:    $pointer[p] \leftarrow 1$ 
4:  $Q \leftarrow$  empty priority queue
5: for every  $t \leftarrow 1$  to  $T$  do
6:    $pointer[\rho_t] \leftarrow pointer[\rho_t] + 1$ 
7:    $nexttime[\rho_t] \leftarrow times[\rho_t, pointer[\rho_t]]$ 
8:   if  $\rho_t \in Q$  then
9:      $Q.increase\text{-}key(\rho_t, nexttime[\rho_t])$ , print “hit”, continue
10:  if  $Q.size() < k$  then
11:    print “load  $\rho_t$  to an empty page ”
12:  else
13:     $p \leftarrow Q.extract\text{-}max()$ , print “evict  $p$  and load  $\rho_t$ ”
14:     $Q.insert(\rho_t, nexttime[\rho_t])$            ▷ add  $\rho_t$  to  $Q$  with key value
 $nexttime[\rho_t]$ 

```

Outline

- 1 Toy Example: Box Packing
- 2 Interval Scheduling
- 3 Offline Caching**
 - Heap: Concrete Data Structure for Priority Queue
- 4 Data Compression and Huffman Code
- 5 Summary

- Let V be a ground set of size n .

Def. A **priority queue** is an **abstract** data structure that maintains a set $U \subseteq V$ of elements, each with an associated key value, and supports the following operations:

- $\text{insert}(v, \text{key_value})$: insert an element $v \in V \setminus U$, with associated key value key_value .
- $\text{decrease_key}(v, \text{new_key_value})$: decrease the key value of an element $v \in U$ to new_key_value
- $\text{extract_min}()$: return and remove the element in U with the smallest key value
- ...

Simple Implementations for Priority Queue

- n = size of ground set V

data structures	insert	extract_min	decrease_key
array			
sorted array			

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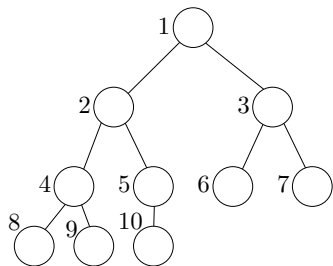
Simple Implementations for Priority Queue

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data structures	insert	extract_min	decrease_key
array	$O(1)$	$O(n)$	$O(1)$
sorted array	$O(n)$	$O(1)$	$O(n)$
heap	$O(\lg n)$	$O(\lg n)$	$O(\lg n)$

Heap

The elements in a heap is organized using a complete binary tree:

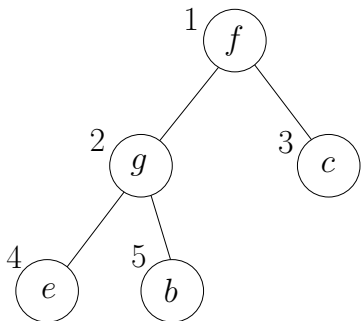


- Nodes are indexed as $\{1, 2, 3, \dots, s\}$
- Parent of node i : $\lfloor i/2 \rfloor$
- Left child of node i : $2i$
- Right child of node i : $2i + 1$

Heap

A heap H contains the following fields

- s : size of U (number of elements in the heap)
- $A[i], 1 \leq i \leq s$: the element at node i of the tree
- $p[v], v \in U$: the index of node containing v
- $key[v], v \in U$: the key value of element v

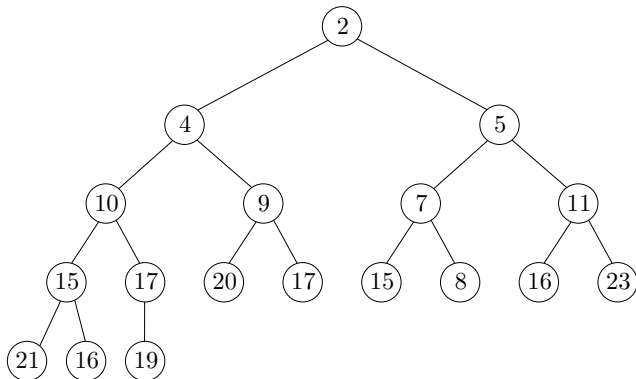


- $s = 5$
- $A = ('f', 'g', 'c', 'e', 'b')$
- $p['f'] = 1, p['g'] = 2, p['c'] = 3,$
 $p['e'] = 4, p['b'] = 5$

Heap

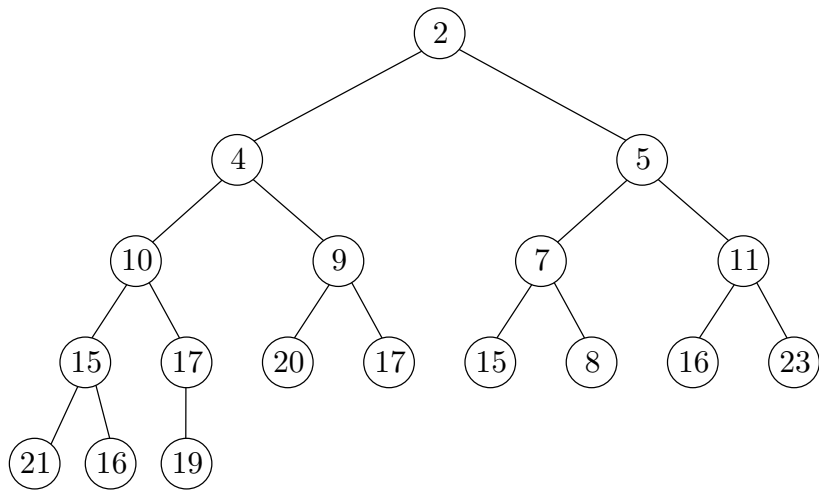
The following **heap property** is satisfied:

- for any two nodes i, j such that i is the parent of j , we have $key[A[i]] \leq key[A[j]]$.

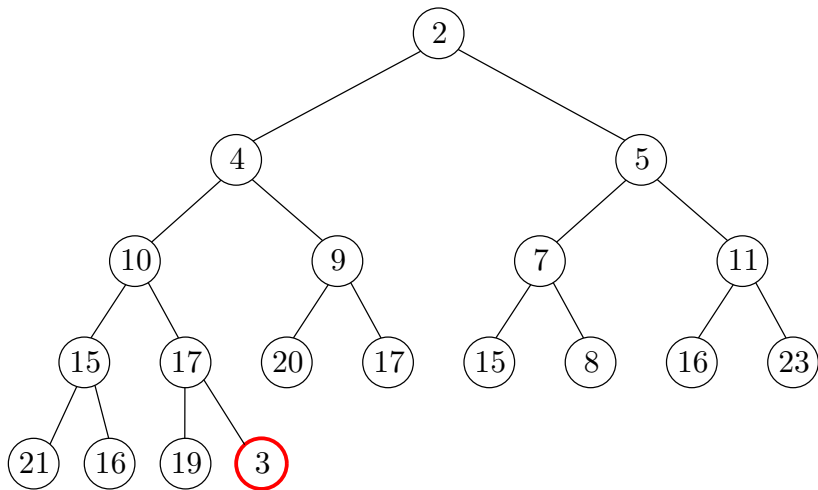


A heap. Numbers in the circles denote key values of elements.

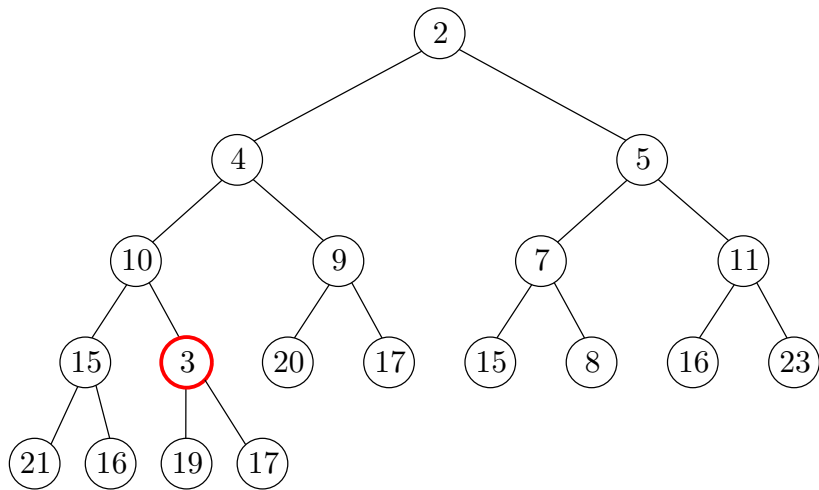
`insert(v , key_value)`



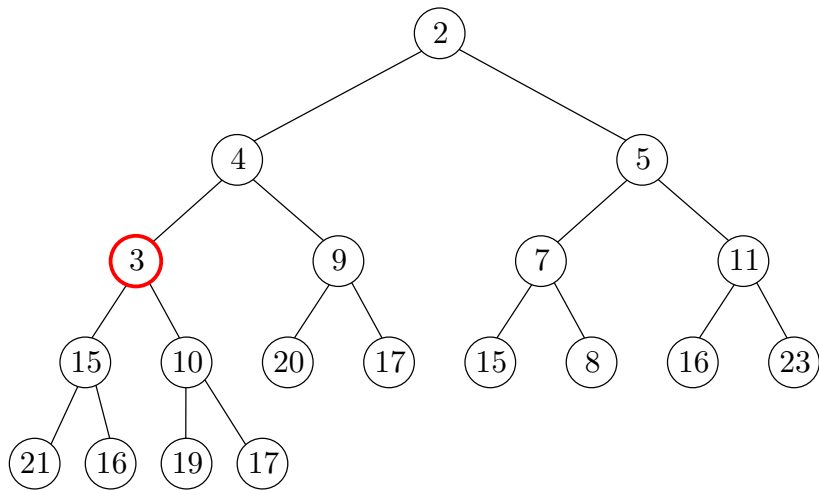
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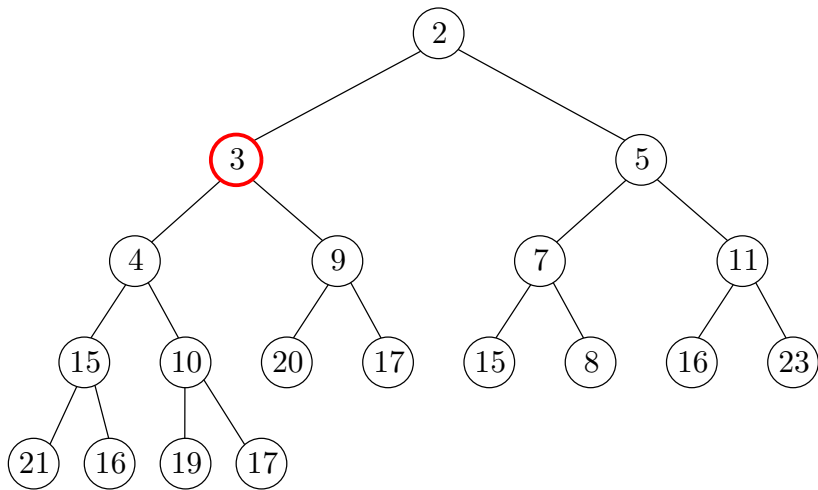
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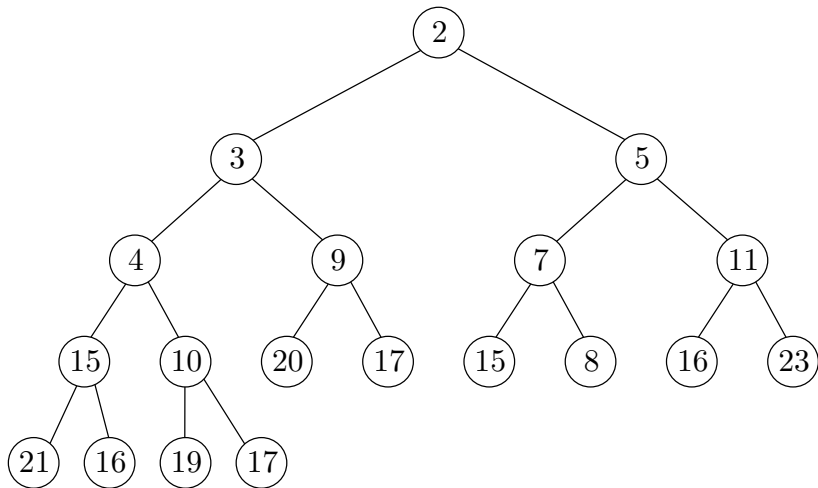
insert(v , key_value)

```
1:  $s \leftarrow s + 1$   
2:  $A[s] \leftarrow v$   
3:  $p[v] \leftarrow s$   
4:  $key[v] \leftarrow key\_value$   
5: heapify-up( $s$ )
```

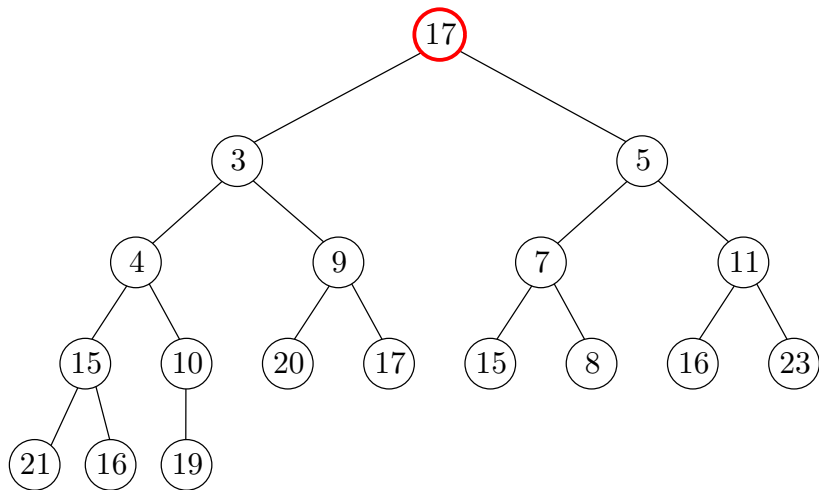
heapify-up(i)

```
1: while  $i > 1$  do  
2:    $j \leftarrow \lfloor i/2 \rfloor$   
3:   if  $key[A[i]] < key[A[j]]$  then  
4:     swap  $A[i]$  and  $A[j]$   
5:      $p[A[i]] \leftarrow i, p[A[j]] \leftarrow j$   
6:      $i \leftarrow j$   
7:   else break
```

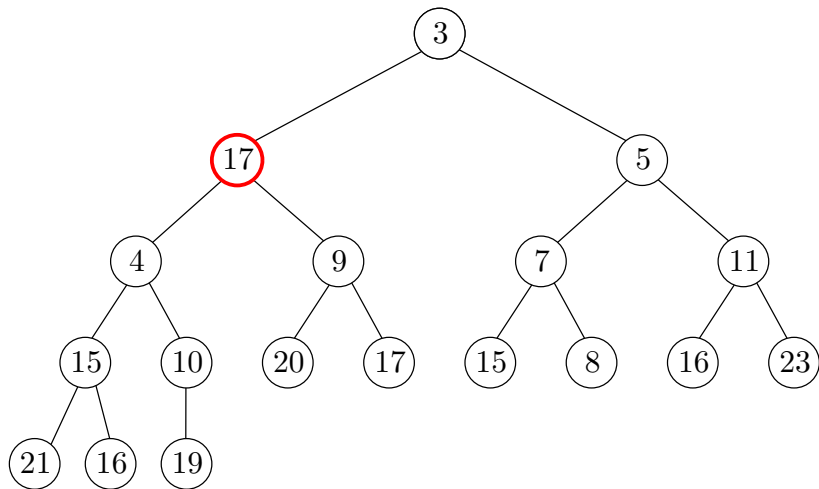
`extract_min()`



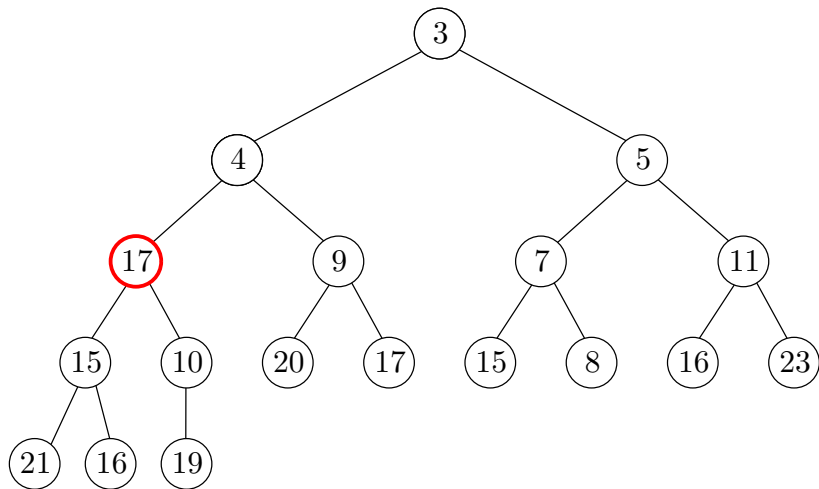
`extract_min()`



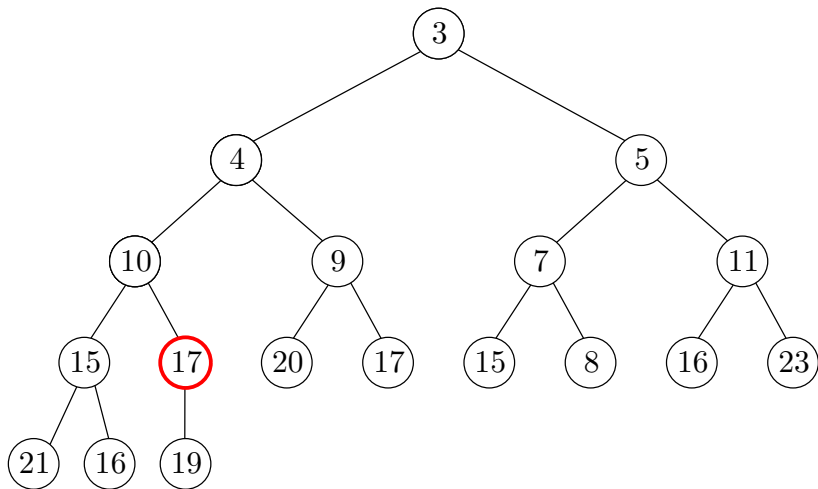
`extract_min()`



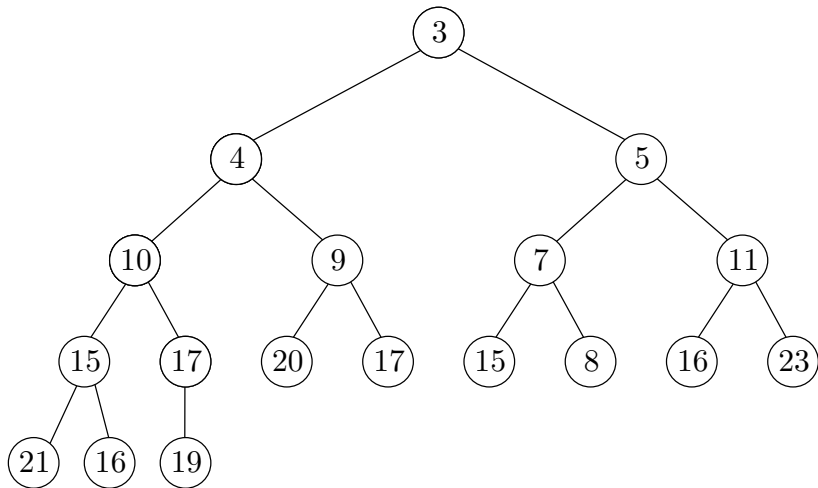
`extract_min()`



`extract_min()`



`extract_min()`



extract_min()

```
1: ret ← A[1]
2: A[1] ← A[s]
3: p[A[1]] ← 1
4: s ← s - 1
5: if s ≥ 1 then
6:     heapify_down(1)
7: return ret
```

decrease_key(*v*, *key_val*)

```
1: key[v] ← key_value
2: heapify-up(p[v])
```

heapify-down(*i*)

```
1: while 2i ≤ s do
2:     if 2i = s or
       key[A[2i]] ≤ key[A[2i + 1]] then
3:         j ← 2i
4:     else
5:         j ← 2i + 1
6:     if key[A[j]] < key[A[i]] then
7:         swap A[i] and A[j]
8:         p[A[i]] ← i, p[A[j]] ← j
9:         i ← j
10:    else break
```

- Running time of `heapify_up` and `heapify_down`: $O(\lg n)$

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- Running time of `insert`, `extract_min` and `decrease_key`: $O(\lg n)$

data structures	insert	extract_min	decrease_key
array	$O(1)$	$O(n)$	$O(1)$
sorted array	$O(n)$	$O(1)$	$O(n)$
heap	$O(\lg n)$	$O(\lg n)$	$O(\lg n)$

Two Definitions Needed to Prove that the Procedures Maintain **Heap Property**

Def. We say that H is almost a heap except that $key[A[i]]$ is too small if we can increase $key[A[i]]$ to make H a heap.

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Outline

- 1 Toy Example: Box Packing
- 2 Interval Scheduling
- 3 Offline Caching
 - Heap: Concrete Data Structure for Priority Queue
- 4 Data Compression and Huffman Code**
- 5 Summary

Encoding Letters Using Bits

- 8 letters a, b, c, d, e, f, g, h in a language
- need to encode a message using bits
- idea: use 3 bits per letter

a	b	c	d	e	f	g	h
000	001	010	011	100	101	110	111

$deacfg \rightarrow 011100000010101110$

Q: Can we have a better encoding scheme?

- Seems unlikely: must use 3 bits per letter

Q: What if some letters appear more frequently than the others?

Q: If some letters appear more frequently than the others, can we have a better encoding scheme?

A: Using **variable-length encoding scheme** might be more efficient.

Idea

- using fewer bits for letters that are more frequently used, and more bits for letters that are less frequently used.

Q: What is the issue with the following encoding scheme?

- $a: 0$ $b: 1$ $c: 00$

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Solution

Use **prefix codes** to guarantee a unique decoding.

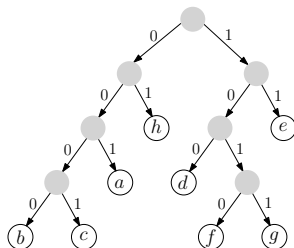
Prefix Codes

Def. A prefix code for a set S of letters is a function $\gamma : S \rightarrow \{0, 1\}^*$ such that for two distinct $x, y \in S$, $\gamma(x)$ is not a prefix of $\gamma(y)$.

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a	b	c	d
001	0000	0001	100
e	f	g	h
11	1010	1011	01



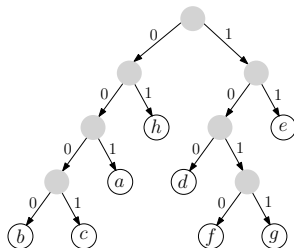
Prefix Codes Guarantee Unique Decoding

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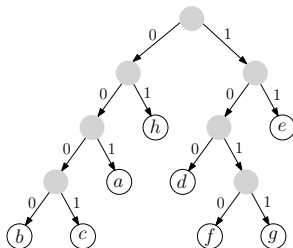
<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
001	0000	0001	100
<i>e</i>	<i>f</i>	<i>g</i>	<i>h</i>
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11	1010	1011	01

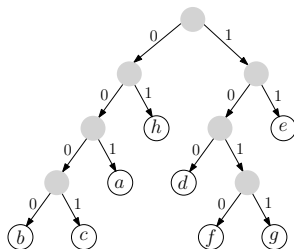


- 0001001100000001011110100001001

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<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
001	0000	0001	100
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11	1010	1011	01

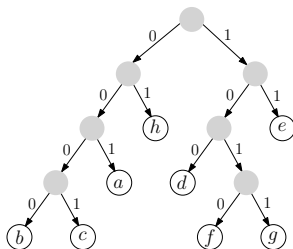


- 0001/001100000001011110100001001
- c

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<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
001	0000	0001	100
<i>e</i>	<i>f</i>	<i>g</i>	<i>h</i>
11	1010	1011	01

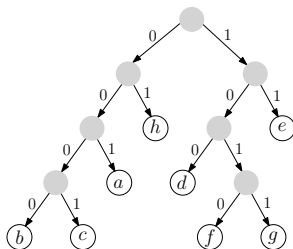


- 0001/001/100000001011110100001001
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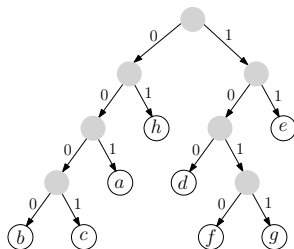


- 0001/001/100/000001011110100001001
- cad

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001	0000	0001	100
<i>e</i>	<i>f</i>	<i>g</i>	<i>h</i>
11	1010	1011	01

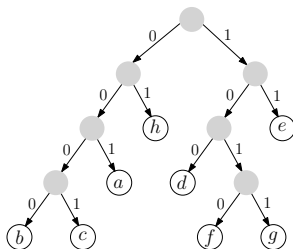


- 0001/001/100/0000/01011110100001001
- cad**b**

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11	1010	1011	01

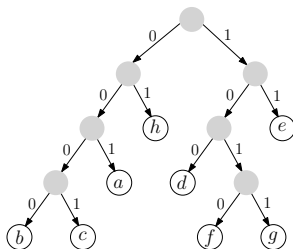


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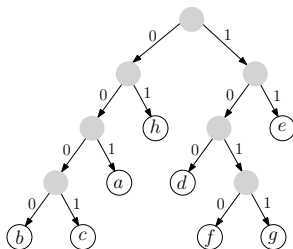


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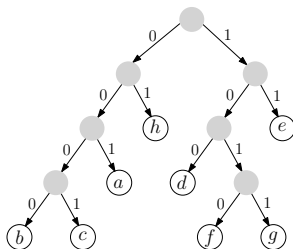


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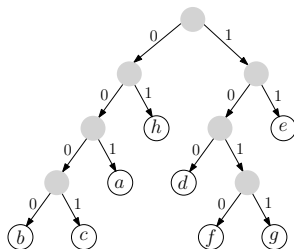


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- cadbhhef

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001	0000	0001	100
<i>e</i>	<i>f</i>	<i>g</i>	<i>h</i>
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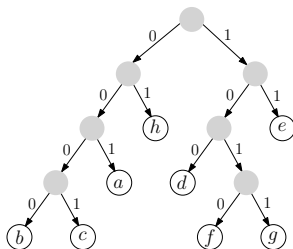


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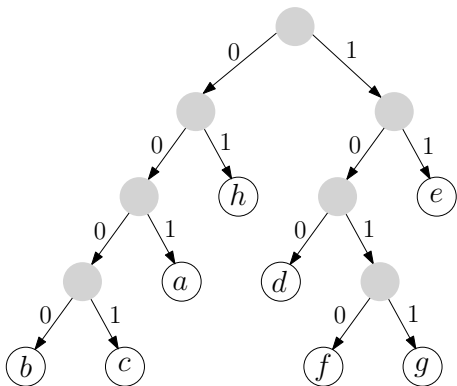
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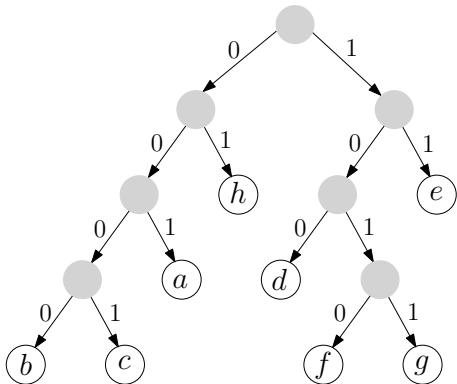
- 0001/001/100/0000/01/01/11/1010/0001/001/
- cadbhhefca

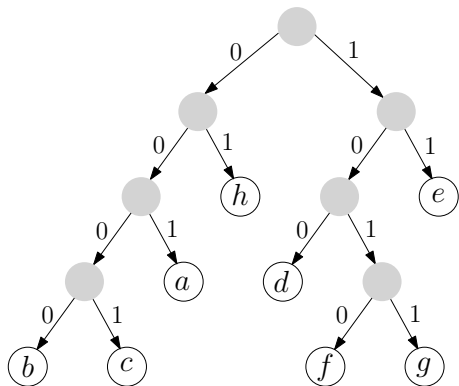
Properties of Encoding Tree



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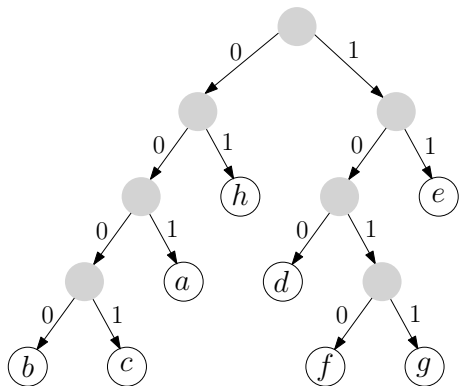
- Rooted binary tree





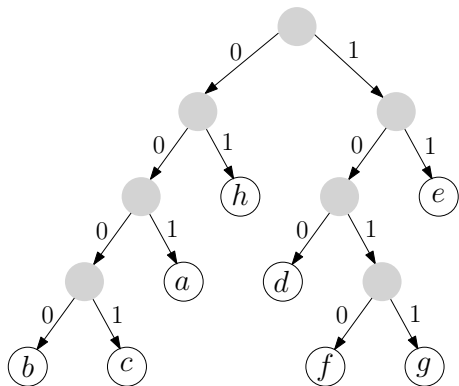
Properties of Encoding Tree

- Rooted binary tree
- Left edges labelled 0 and right edges labelled 1



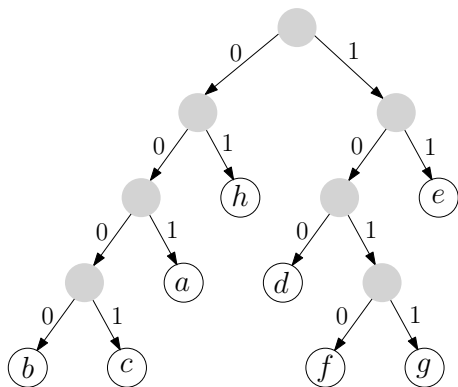
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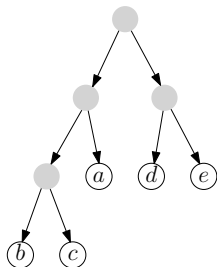
Best Prefix Codes

Input: frequencies of letters in a message

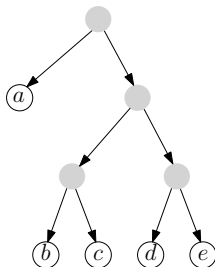
Output: prefix coding scheme with the shortest encoding for the message

example

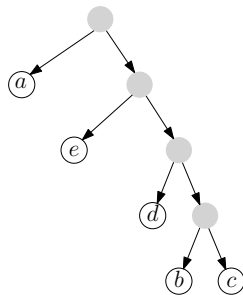
letters	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>
frequencies	18	3	4	6	10



scheme 1



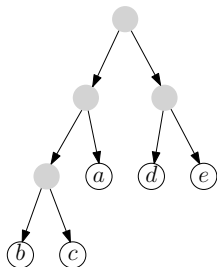
scheme 2



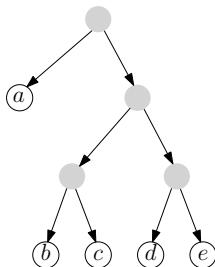
scheme 3

example

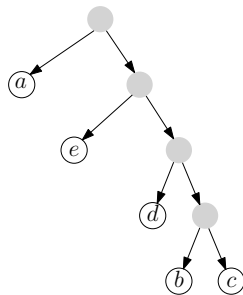
letters	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	
frequencies	18	3	4	6	10	
scheme 1 length	2	3	3	2	2	total = 89
scheme 2 length	1	3	3	3	3	total = 87
scheme 3 length	1	4	4	3	2	total = 84



scheme 1



scheme 2



scheme 3

- Example Input: (a : 18, b : 3, c : 4, d : 6, e : 10)

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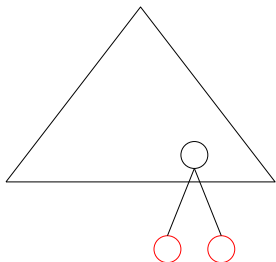
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- Can we directly give a code for some letter?
- Hard to design a strategy; residual problem is complicated.
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- Not clear how to design the greedy algorithm

A: We can choose two letters and make them brothers in the tree.

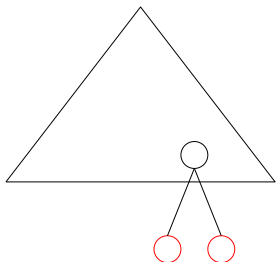
Which Two Letters Can Be Safely Put Together As Brothers?

- Focus on the “structure” of the optimum encoding tree



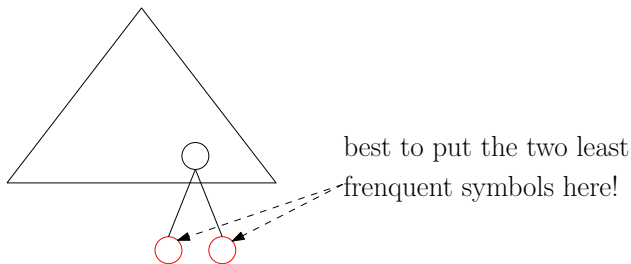
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- Focus on the “structure” of the optimum encoding tree
- There are two deepest leaves that are brothers



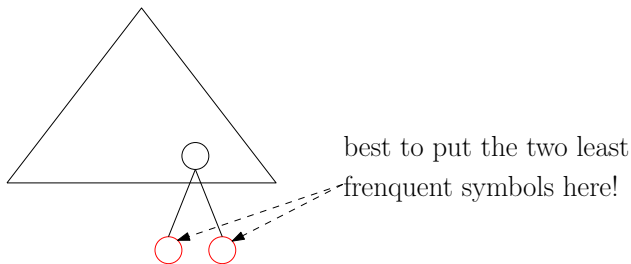
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Lemma It is safe to make the two least frequent letters brothers.

Lemma There is an optimum encoding tree, where the two least frequent letters are brothers.

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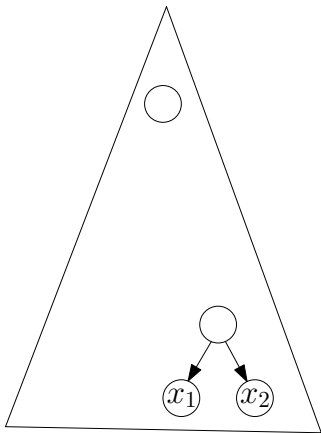
Lemma There is an optimum encoding tree, where the two least frequent letters are brothers.

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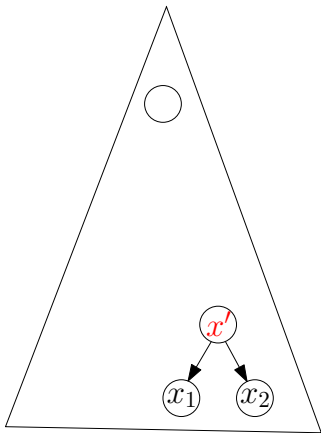
A: Yes, though it is not immediate to see why.

- f_x : the frequency of the letter x in the support.
- x_1 and x_2 : the two letters we decided to put together.
- d_x the depth of letter x in our output encoding tree.



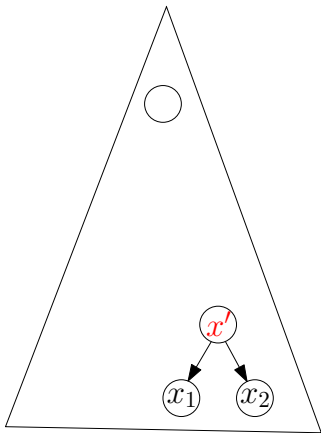
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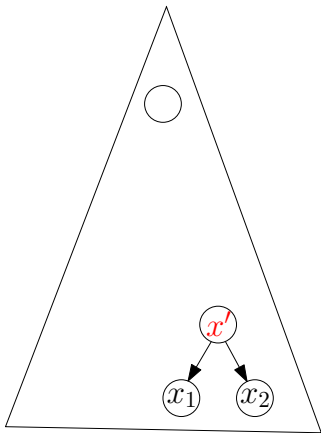
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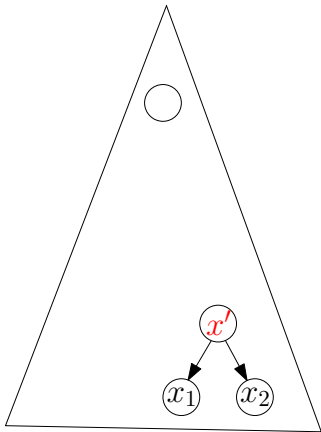
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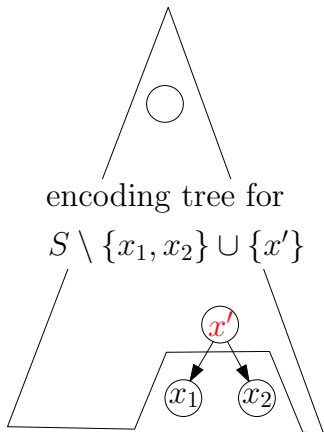
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$$\sum_{x \in S} f_x d_x,$$

we need to minimize

$$\sum_{x \in S \setminus \{x_1, x_2\} \cup \{x'\}} f_x d_x,$$

subject to that d is the depth function for an encoding tree of $S \setminus \{x_1, x_2\}$.

- This is exactly the best prefix codes problem, with letters $S \setminus \{x_1, x_2\} \cup \{x'\}$ and frequency vector f !

Example

A 27

B 15

C 11

D 9

E 8

F 5

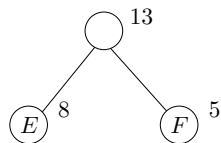
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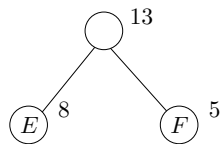
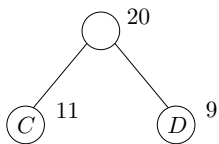
D 9



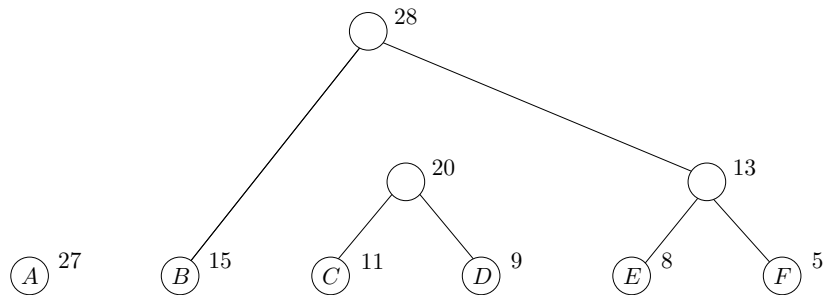
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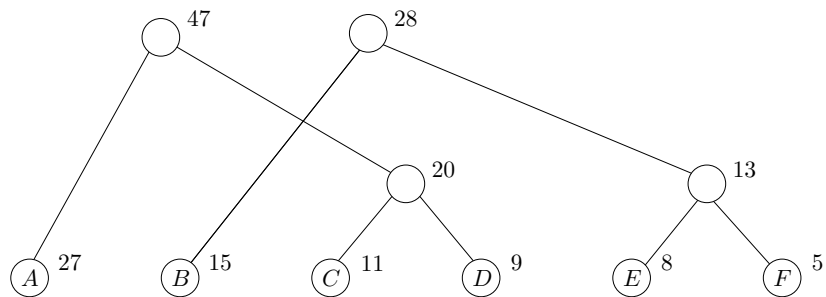
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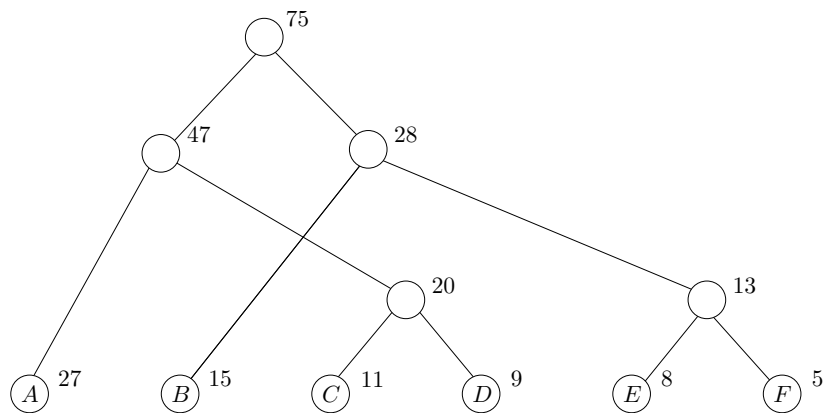
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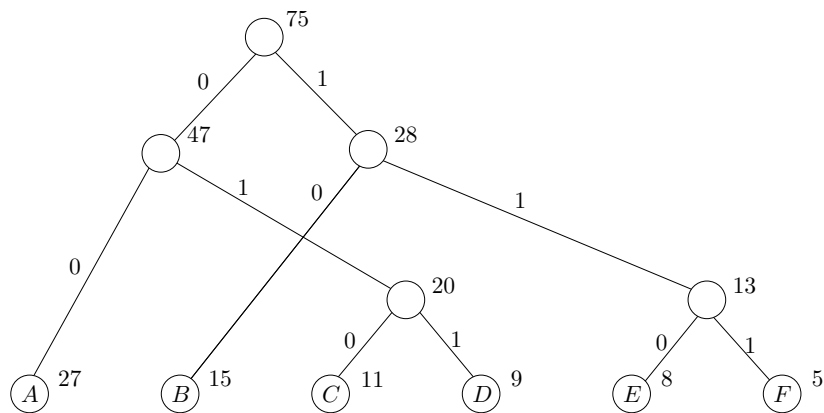
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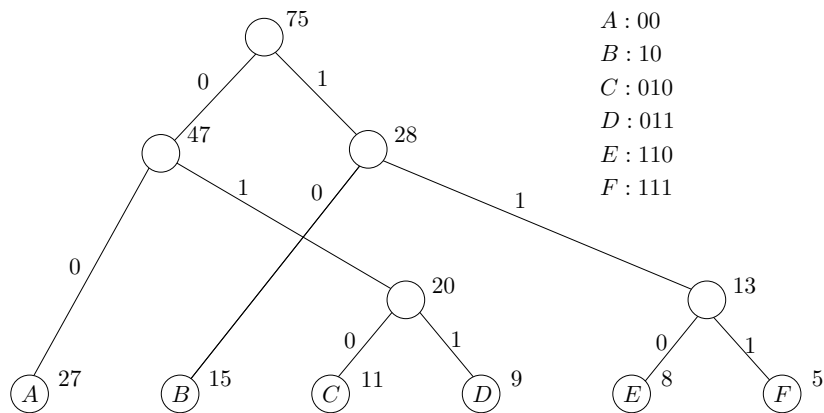
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Huffman(S, f)

- 1: **while** $|S| > 1$ **do**
- 2: let x_1, x_2 be the two letters with the smallest f values
- 3: introduce a new letter x' and let $f_{x'} = f_{x_1} + f_{x_2}$
- 4: let x_1 and x_2 be the two children of x'
- 5: $S \leftarrow S \setminus \{x_1, x_2\} \cup \{x'\}$
- 6: **return** the tree constructed

Algorithm using Priority Queue

Huffman(S, f)

- 1: $Q \leftarrow \text{build-priority-queue}(S)$
- 2: **while** $Q.\text{size} > 1$ **do**
- 3: $x_1 \leftarrow Q.\text{extract-min}()$
- 4: $x_2 \leftarrow Q.\text{extract-min}()$
- 5: introduce a new letter x' and let $f_{x'} = f_{x_1} + f_{x_2}$
- 6: let x_1 and x_2 be the two children of x'
- 7: $Q.\text{insert}(x', f_{x'})$
- 8: **return** the tree constructed

Outline

- 1 Toy Example: Box Packing
- 2 Interval Scheduling
- 3 Offline Caching
 - Heap: Concrete Data Structure for Priority Queue
- 4 Data Compression and Huffman Code
- 5 Summary

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Greedy Algorithm

- Build up the solutions in steps
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- Huffman codes: merge two letters into one