

CSE 431/531: Algorithm Analysis and Design (Spring 2021)

Graph Basics

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*Department of Computer Science and Engineering
University at Buffalo*

Outline

- 1 Graphs
- 2 Connectivity and Graph Traversal
 - Testing Bipartiteness
- 3 Topological Ordering

Examples of Graphs



Figure: Road Networks



Figure: Internet



Figure: Social Networks

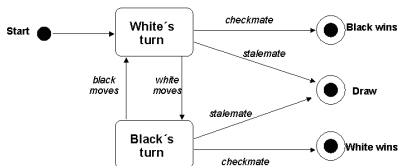
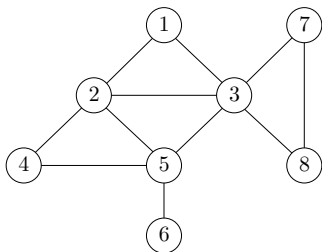


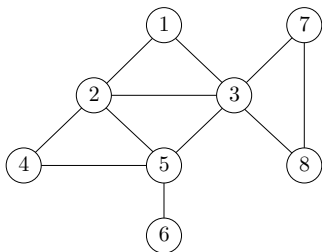
Figure: Transition Graphs

(Undirected) Graph $G = (V, E)$



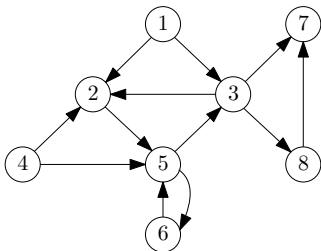
- V : set of vertices (nodes);
- E : pairwise relationships among V ;
 - (undirected) graphs: relationship is symmetric, E contains subsets of size 2

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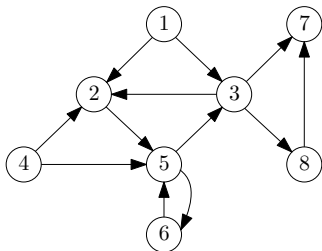
- V : set of vertices (nodes);
 - $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$
- E : pairwise relationships among V ;
 - (undirected) graphs: relationship is symmetric, E contains subsets of size 2
 - $E = \{\{1, 2\}, \{1, 3\}, \{2, 3\}, \{2, 4\}, \{2, 5\}, \{3, 5\}, \{3, 7\}, \{3, 8\}, \{4, 5\}, \{5, 6\}, \{7, 8\}\}$

Directed Graph $G = (V, E)$



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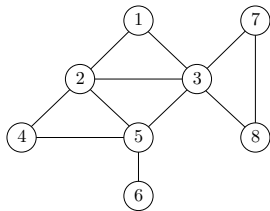
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Abuse of Notations

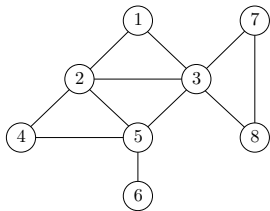
- For (undirected) graphs, we often use (i, j) to denote the set $\{i, j\}$.
- We call (i, j) an unordered pair; in this case $(i, j) = (j, i)$.



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- Social Network : Undirected
- Transition Graph : Directed
- Road Network : Directed or Undirected
- Internet : Directed or Undirected

Representation of Graphs

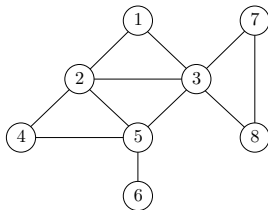


	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	1	0	0	0
3	1	1	0	0	1	0	1	1
4	0	1	0	0	1	0	0	0
5	0	1	1	1	0	1	0	0
6	0	0	0	0	1	0	0	0
7	0	0	1	0	0	0	0	1
8	0	0	1	0	0	0	1	0

- Adjacency matrix

- $n \times n$ matrix, $A[u, v] = 1$ if $(u, v) \in E$ and $A[u, v] = 0$ otherwise
- A is symmetric if graph is undirected

Representation of Graphs



1: [2] → [3]

6: [5]

2: [1] → [3] → [4] → [5]

7: [3] → [8]

3: [1] → [2] → [5] → [7] → [8]

4: [2] → [5]

8: [3] → [7]

5: [2] → [3] → [4] → [6]

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- Linked lists

- For every vertex v , there is a linked list containing all **neighbours** of v .

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n : number of vertices
- m : number of edges, assuming $n - 1 \leq m \leq n(n - 1)/2$
- d_v : number of neighbors of v

	Matrix	Linked Lists
memory usage		
time to check $(u, v) \in E$		
time to list all neighbours of v		

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memory usage	$O(n^2)$	$O(m)$
time to check $(u, v) \in E$	$O(1)$	
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time to list all neighbours of v	$O(n)$	

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Connectivity Problem

Input: graph $G = (V, E)$, (using linked lists)

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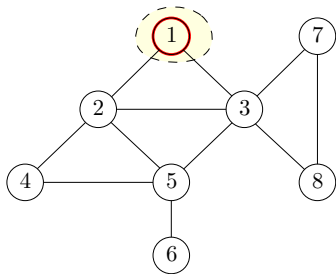
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 - Breadth-First Search (BFS)
 - Depth-First Search (DFS)

Breadth-First Search (BFS)

- Build layers $L_0, L_1, L_2, L_3, \dots$
- $L_0 = \{s\}$
- L_{j+1} contains all nodes that are not in $L_0 \cup L_1 \cup \dots \cup L_j$ and have an edge to a vertex in L_j

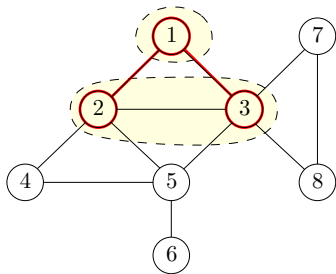
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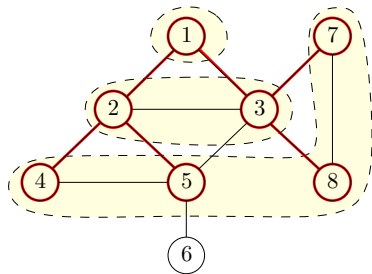
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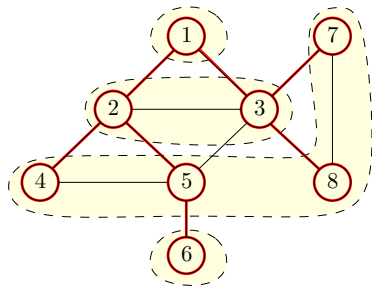
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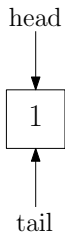
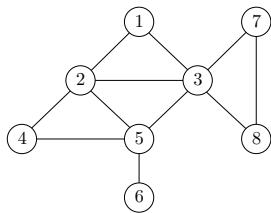
Implementing BFS using a Queue

BFS(s)

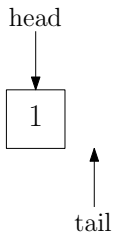
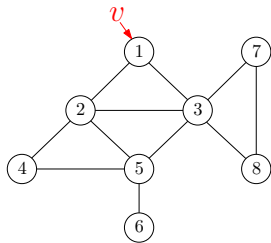
```
1:  $head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$ 
2: mark  $s$  as "visited" and all other vertices as "unvisited"
3: while  $head \geq tail$  do
4:    $v \leftarrow queue[tail], tail \leftarrow tail + 1$ 
5:   for all neighbours  $u$  of  $v$  do
6:     if  $u$  is "unvisited" then
7:        $head \leftarrow head + 1, queue[head] = u$ 
8:       mark  $u$  as "visited"
```

- Running time: $O(n + m)$.

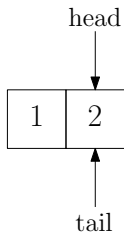
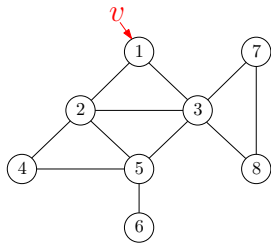
Example of BFS via Queue



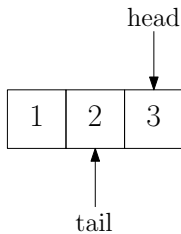
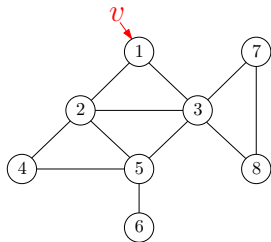
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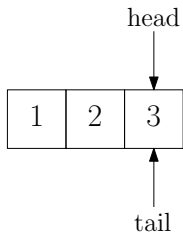
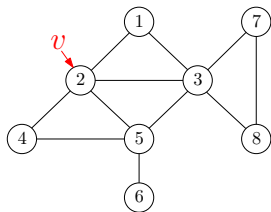
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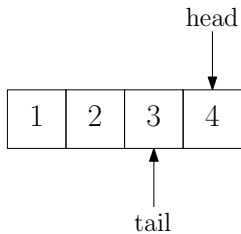
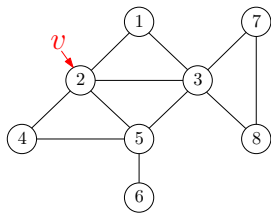
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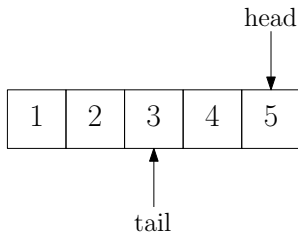
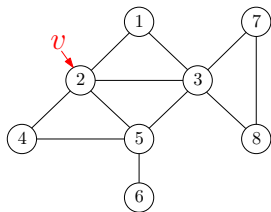
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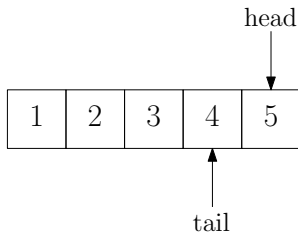
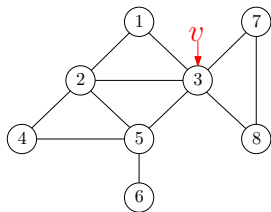
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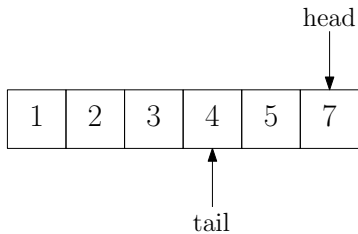
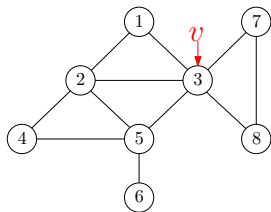
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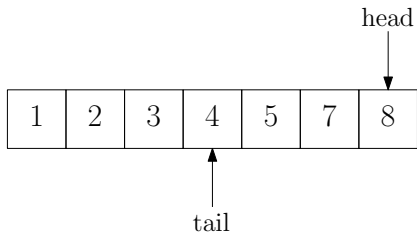
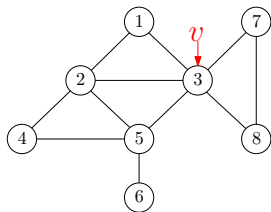
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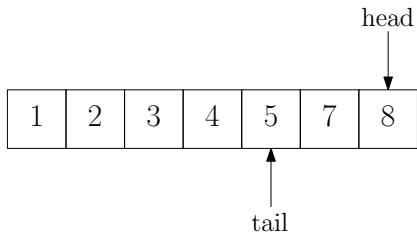
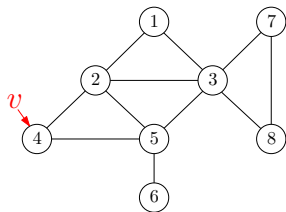
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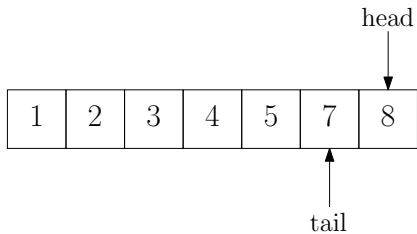
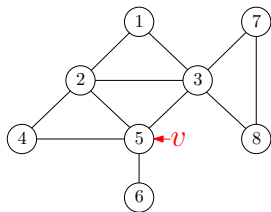
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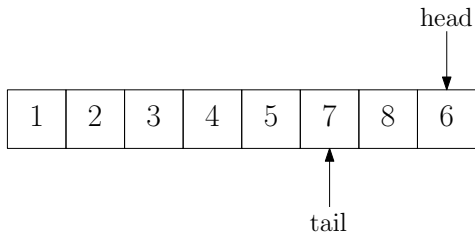
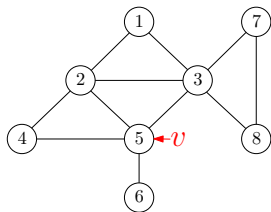
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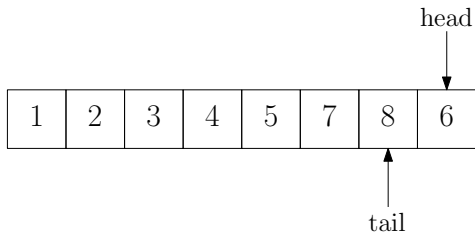
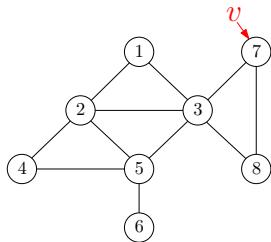
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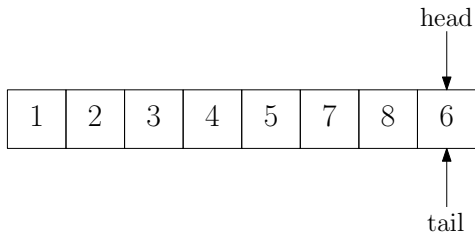
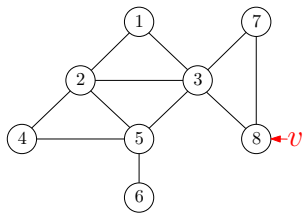
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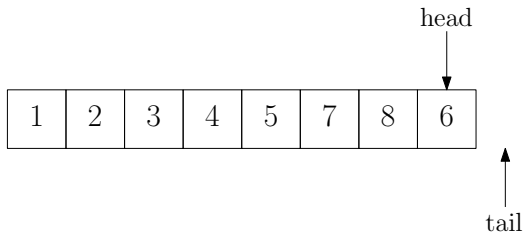
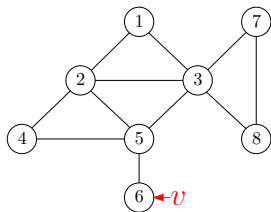
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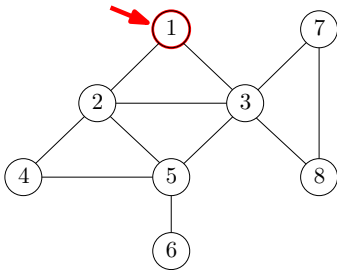


Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex (“dead-end”), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back

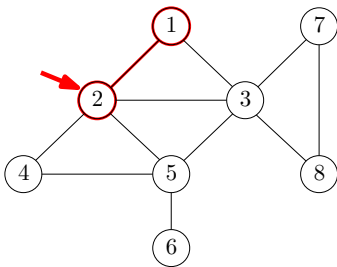
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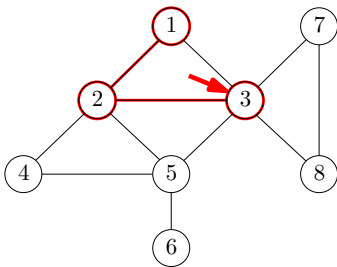
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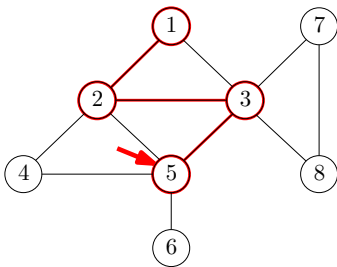
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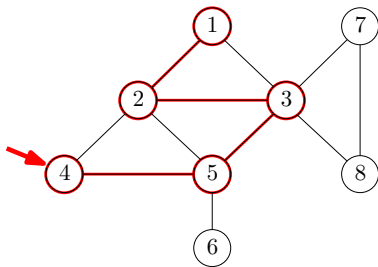
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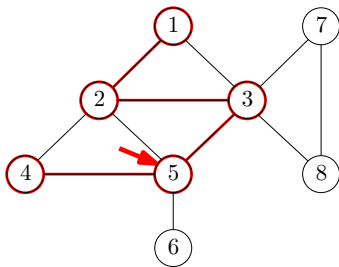
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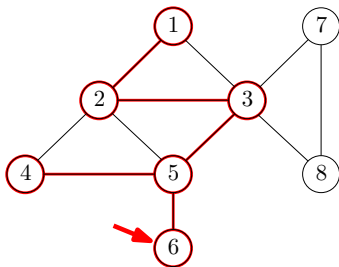
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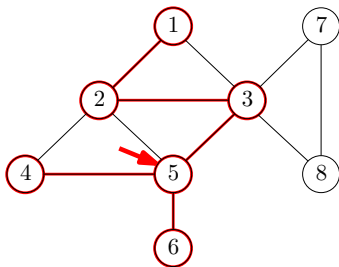
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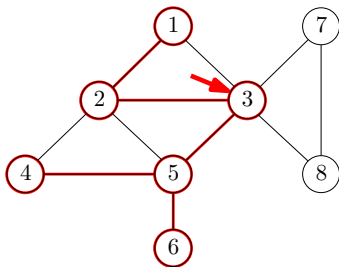
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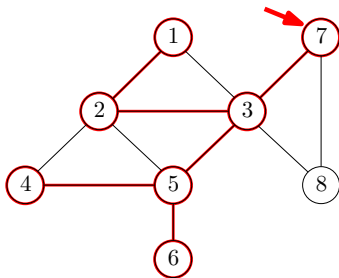
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex (“dead-end”), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



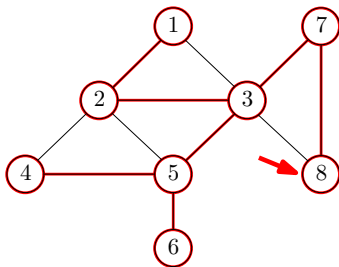
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Implementing DFS using Recursion

DFS(s)

- 1: mark all vertices as “unvisited”
- 2: recursive-DFS(s)

recursive-DFS(v)

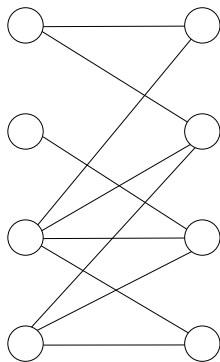
- 1: mark v as “visited”
- 2: **for** all neighbours u of v **do**
- 3: **if** u is unvisited **then** recursive-DFS(u)

Outline

- 1 Graphs
- 2 Connectivity and Graph Traversal
 - Testing Bipartiteness
- 3 Topological Ordering

Testing Bipartiteness: Applications of BFS

Def. A graph $G = (V, E)$ is a **bipartite graph** if there is a partition of V into two sets L and R such that for every edge $(u, v) \in E$, we have either $u \in L, v \in R$ or $v \in L, u \in R$.



Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$

Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g

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- Neighbors of s must be in R

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- ...

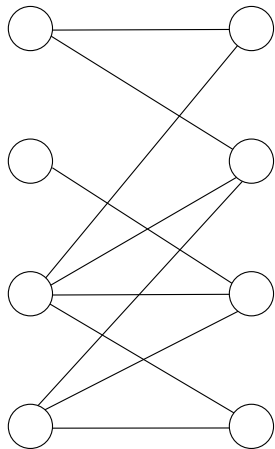
Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g
- Neighbors of s must be in R
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- ...
- Report “not a bipartite graph” if contradiction was found

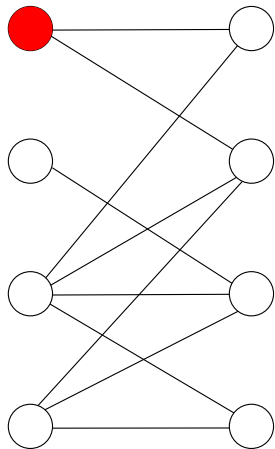
Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g
- Neighbors of s must be in R
- Neighbors of neighbors of s must be in L
- ...
- Report “not a bipartite graph” if contradiction was found
- If G contains multiple connected components, repeat above algorithm for each component

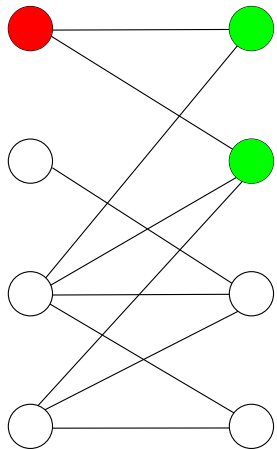
Test Bipartiteness



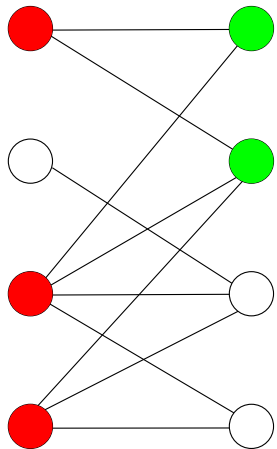
Test Bipartiteness



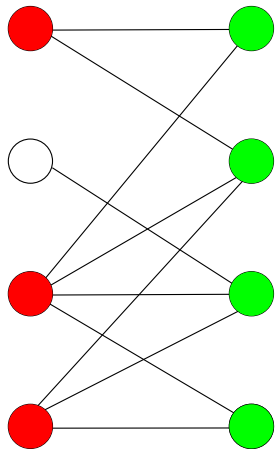
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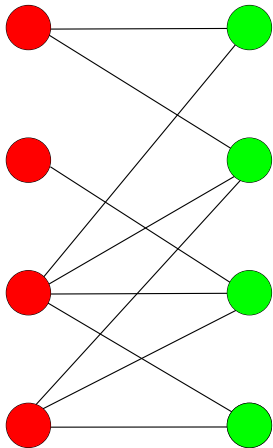
Test Bipartiteness



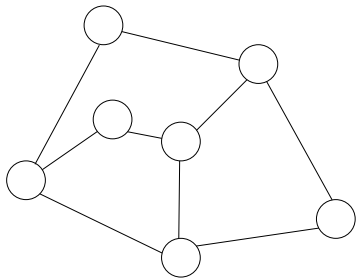
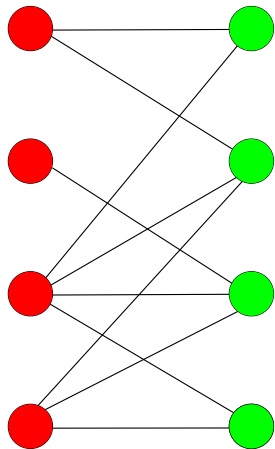
Test Bipartiteness



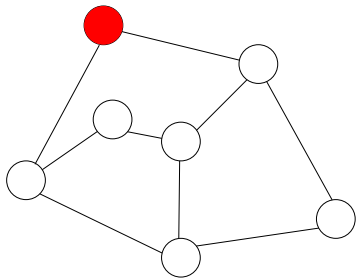
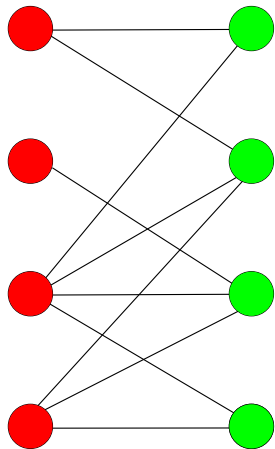
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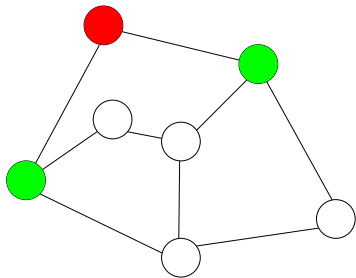
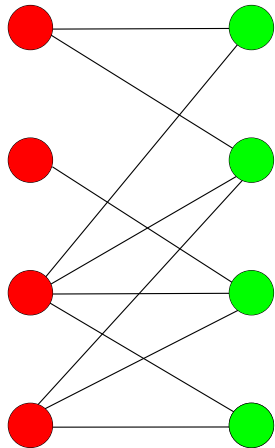
Test Bipartiteness



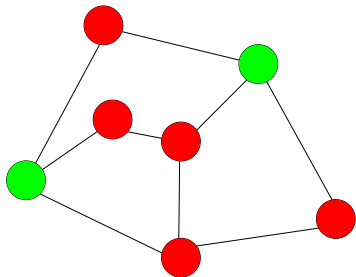
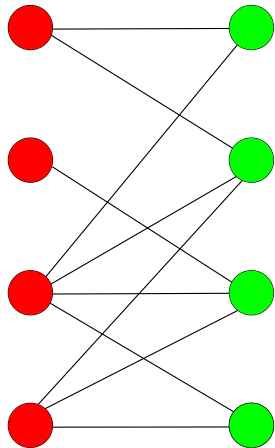
Test Bipartiteness



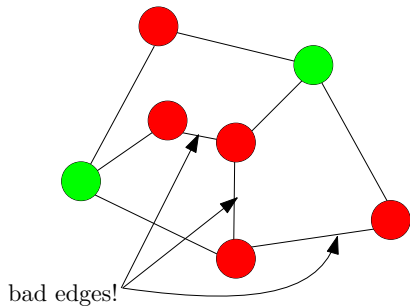
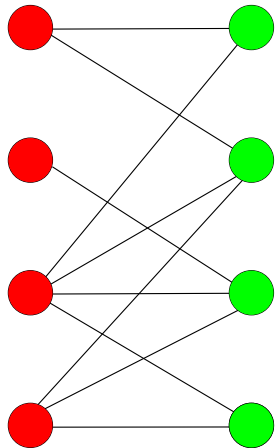
Test Bipartiteness



Test Bipartiteness



Test Bipartiteness



Testing Bipartiteness using BFS

BFS(s)

```
1:  $head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$ 
2: mark  $s$  as "visited" and all other vertices as "unvisited"
3: while  $head \geq tail$  do
4:    $v \leftarrow queue[tail], tail \leftarrow tail + 1$ 
5:   for all neighbours  $u$  of  $v$  do
6:     if  $u$  is "unvisited" then
7:        $head \leftarrow head + 1, queue[head] = u$ 
8:       mark  $u$  as "visited"
```

Testing Bipartiteness using BFS

test-bipartiteness(s)

```
1:  $head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$ 
2: mark  $s$  as "visited" and all other vertices as "unvisited"
3:  $color[s] \leftarrow 0$ 
4: while  $head \geq tail$  do
5:    $v \leftarrow queue[tail], tail \leftarrow tail + 1$ 
6:   for all neighbours  $u$  of  $v$  do
7:     if  $u$  is "unvisited" then
8:        $head \leftarrow head + 1, queue[head] = u$ 
9:       mark  $u$  as "visited"
10:       $color[u] \leftarrow 1 - color[v]$ 
11:     else if  $color[u] = color[v]$  then
12:       print("G is not bipartite") and exit
```


Testing Bipartiteness using BFS

```
1: mark all vertices as "unvisited"  
2: for each vertex  $v \in V$  do  
3:   if  $v$  is "unvisited" then  
4:     test-bipartiteness( $v$ )  
5: print("G is bipartite")
```

Testing Bipartiteness using BFS

```
1: mark all vertices as "unvisited"  
2: for each vertex  $v \in V$  do  
3:   if  $v$  is "unvisited" then  
4:     test-bipartiteness( $v$ )  
5: print("G is bipartite")
```

Obs. Running time of algorithm = $O(n + m)$

Outline

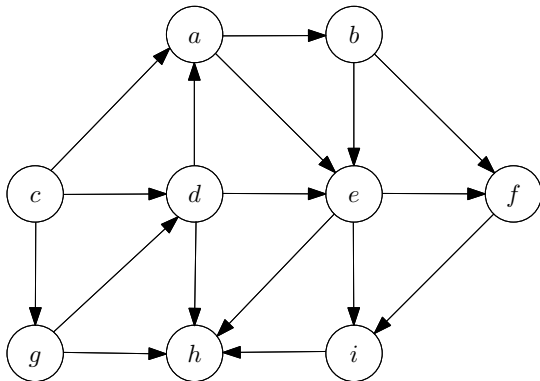
- 1 Graphs
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Topological Ordering Problem

Input: a directed acyclic graph (DAG) $G = (V, E)$

Output: 1-to-1 function $\pi : V \rightarrow \{1, 2, 3 \dots, n\}$, so that

- if $(u, v) \in E$ then $\pi(u) < \pi(v)$

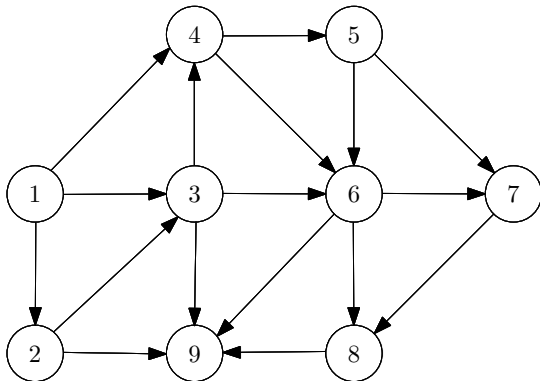


Topological Ordering Problem

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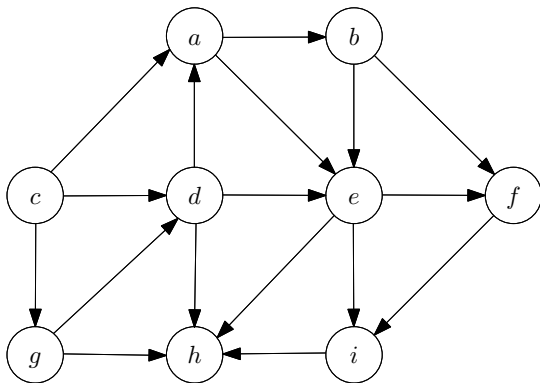
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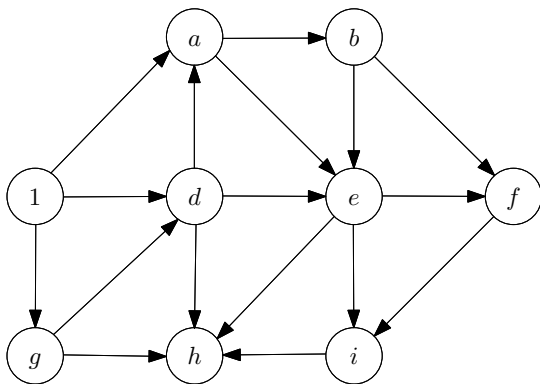
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



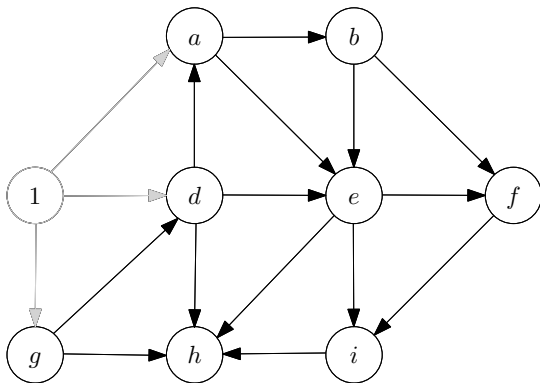
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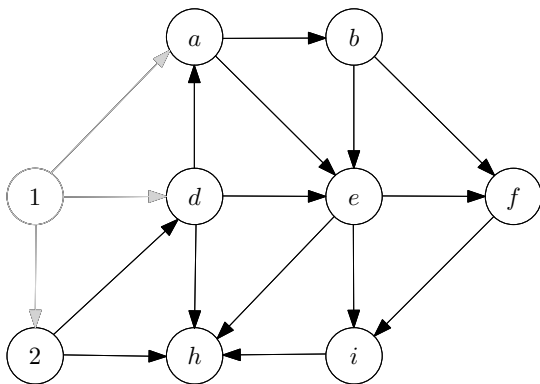
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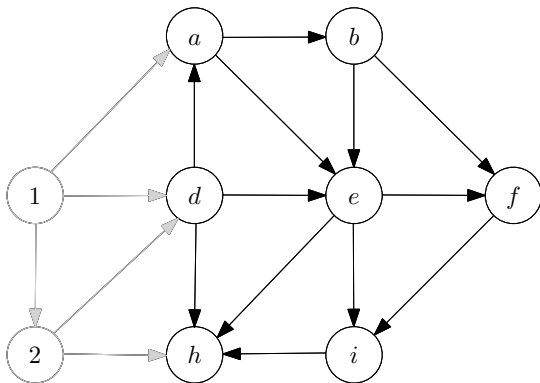
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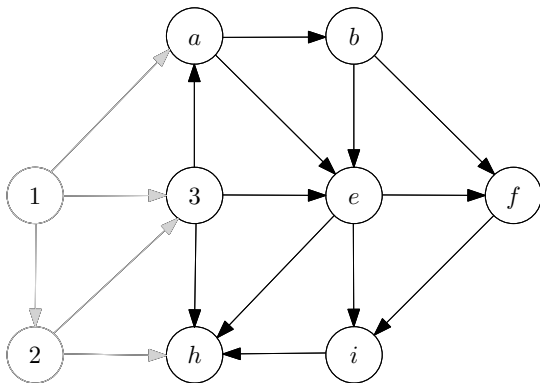
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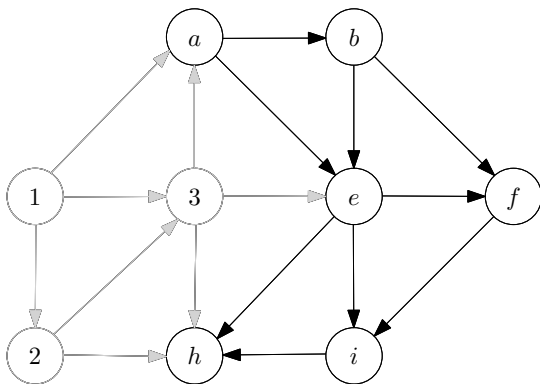
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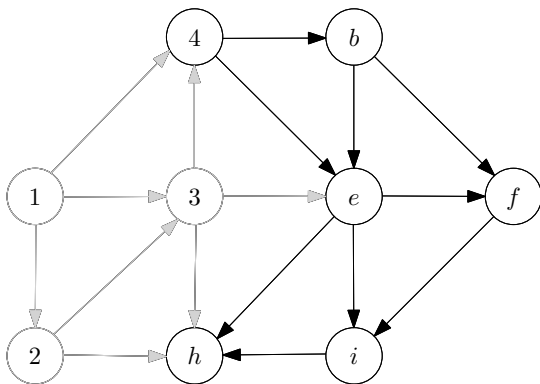
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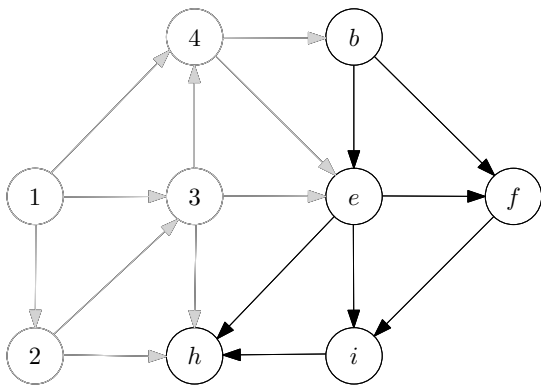
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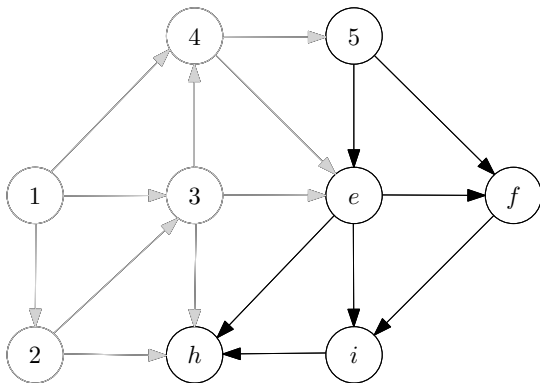
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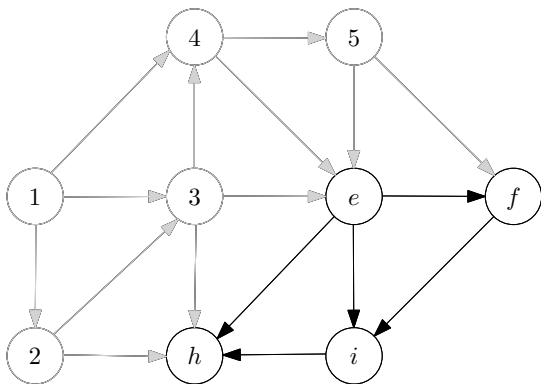
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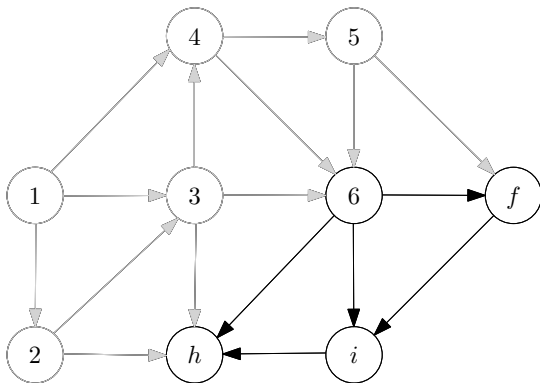
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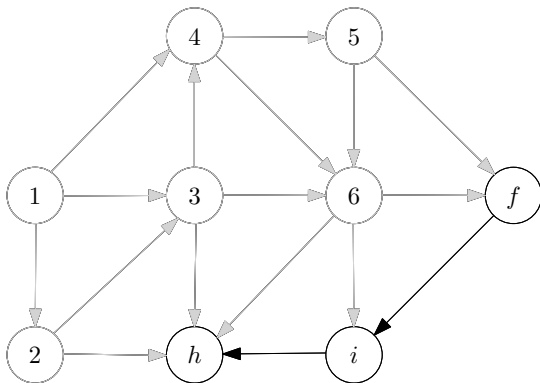
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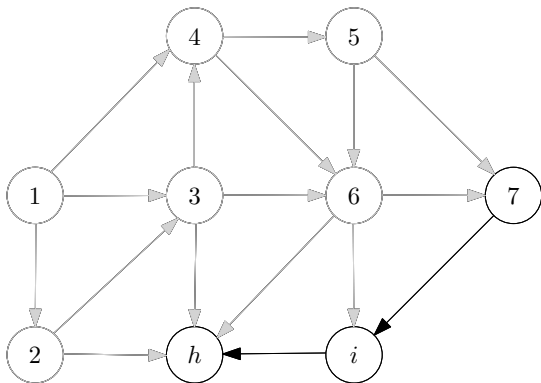
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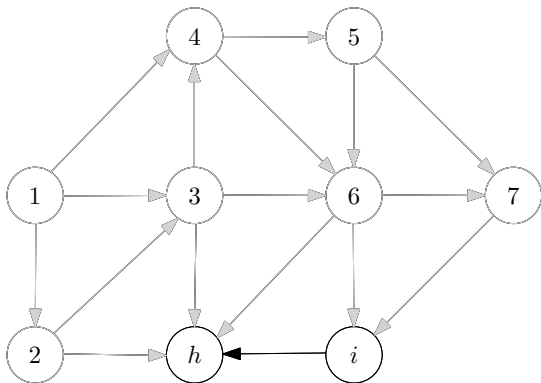
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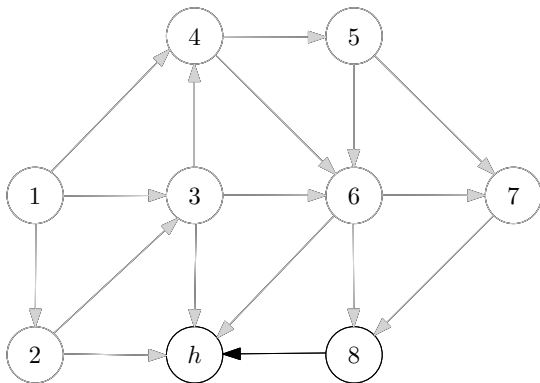
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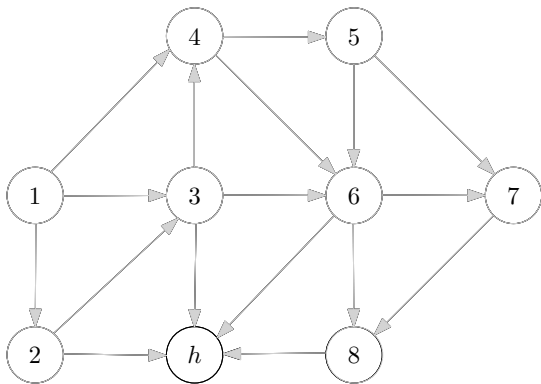
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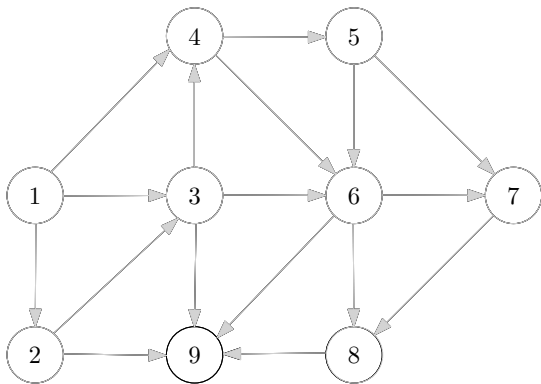
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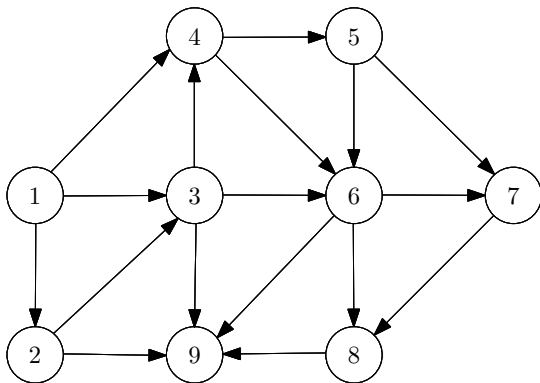
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Q: How to make the algorithm as efficient as possible?

Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.

Q: How to make the algorithm as efficient as possible?

A:

- Use linked-lists of outgoing edges
- Maintain the in-degree d_v of vertices
- Maintain a queue (or stack) of vertices v with $d_v = 0$

topological-sort(G)

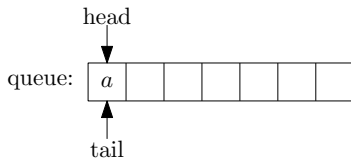
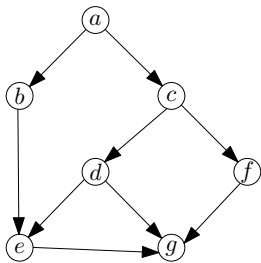
```
1: let  $d_v \leftarrow 0$  for every  $v \in V$ 
2: for every  $v \in V$  do
3:     for every  $u$  such that  $(v, u) \in E$  do
4:          $d_u \leftarrow d_u + 1$ 
5:  $S \leftarrow \{v : d_v = 0\}, i \leftarrow 0$ 
6: while  $S \neq \emptyset$  do
7:      $v \leftarrow$  arbitrary vertex in  $S, S \leftarrow S \setminus \{v\}$ 
8:      $i \leftarrow i + 1, \pi(v) \leftarrow i$ 
9:     for every  $u$  such that  $(v, u) \in E$  do
10:         $d_u \leftarrow d_u - 1$ 
11:        if  $d_u = 0$  then add  $u$  to  $S$ 
12: if  $i < n$  then output "not a DAG"
```

- S can be represented using a queue or a stack
- Running time = $O(n + m)$

S as a Queue or a Stack

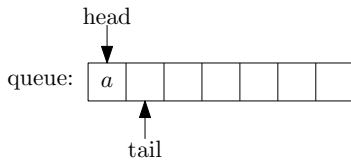
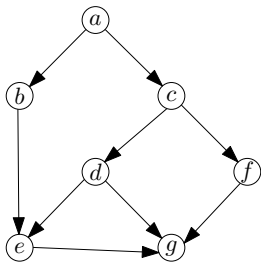
DS	Queue	Stack
Initialization	$head \leftarrow 0, tail \leftarrow 1$	$top \leftarrow 0$
Non-Empty?	$head \geq tail$	$top > 0$
Add(v)	$head \leftarrow head + 1$ $S[head] \leftarrow v$	$top \leftarrow top + 1$ $S[top] \leftarrow v$
Retrieve v	$v \leftarrow S[tail]$ $tail \leftarrow tail + 1$	$v \leftarrow S[top]$ $top \leftarrow top - 1$

Example



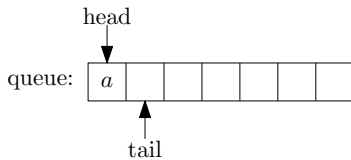
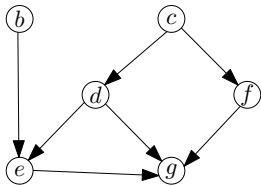
	a	b	c	d	e	f	g
degree	0	1	1	1	2	1	3

Example



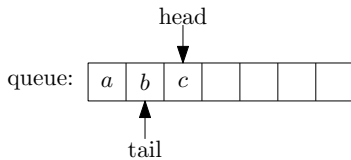
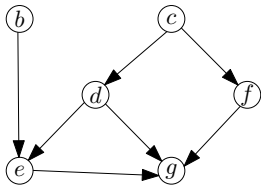
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Example



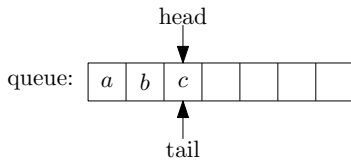
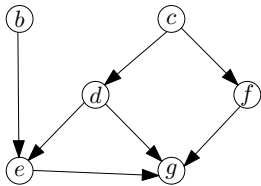
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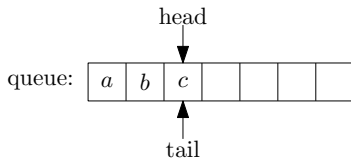
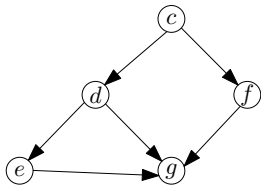
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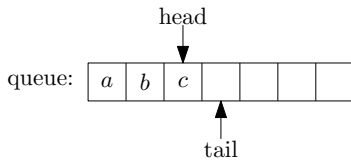
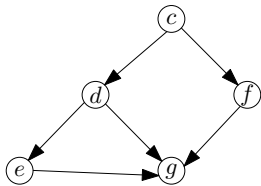
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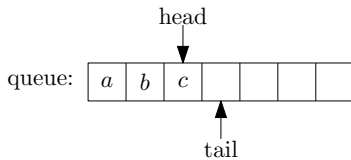
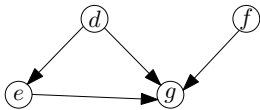
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Example



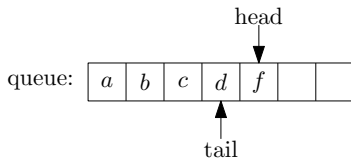
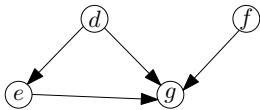
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degree	0	0	0	1	1	1	3

Example



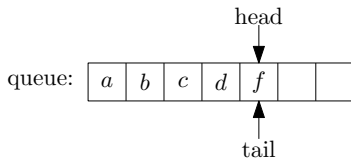
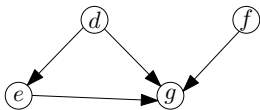
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	1	0	3

Example



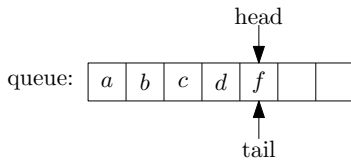
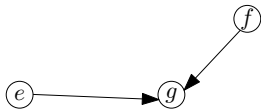
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	1	0	3

Example



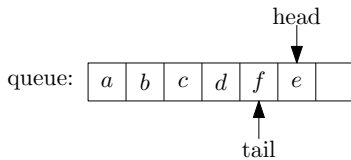
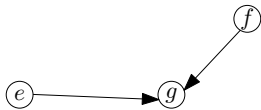
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	1	0	3

Example



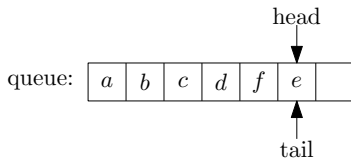
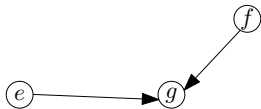
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	2

Example



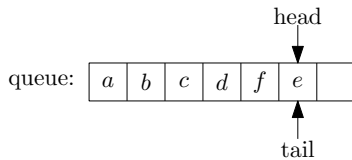
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	2

Example



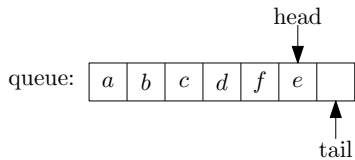
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	2

Example



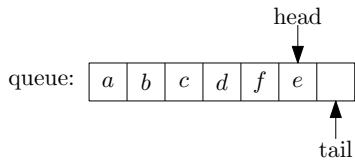
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	1

Example



	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	1

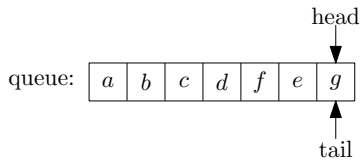
Example



⑨

	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	0

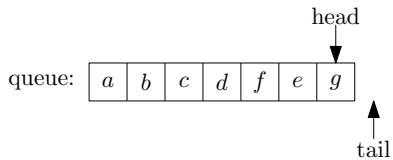
Example



⑨

	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	0

Example



⑨

	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>
degree	0	0	0	0	0	0	0