CSE 431/531: Algorithm Analysis and Design (Spring 2022)

Graph Basics

Lecturer: Shi Li

Department of Computer Science and Engineering
University at Buffalo

Outline

Examples of Graphs

Figure: Road Networks

Figure: Internet

Figure: Social Networks

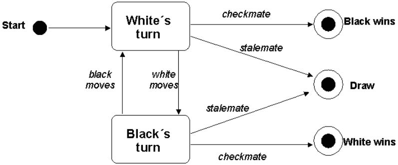
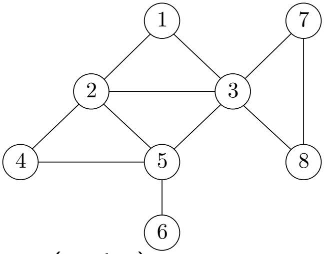


Figure: Transition Graphs

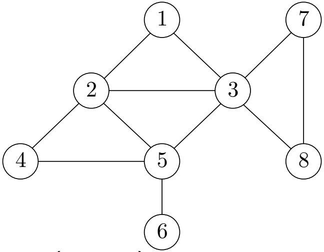
(Undirected) Graph $G = (V, E)$



- V: set of vertices (nodes);

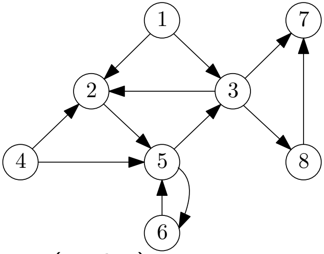
- E: pairwise relationships among V;
  - (undirected) graphs: relationship is symmetric, E contains subsets of size 2

(Undirected) Graph $G = (V, E)$



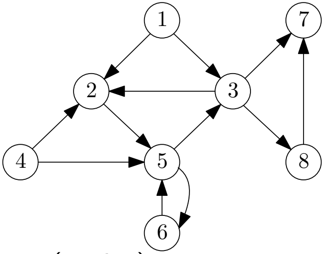
- V: set of vertices (nodes);
  - $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$
- E: pairwise relationships among V;
  - (undirected) graphs: relationship is symmetric, E contains subsets of size 2
  - $E = \{\{1, 2\}, \{1, 3\}, \{2, 3\}, \{2, 4\}, \{2, 5\}, \{3, 5\}, \{3, 7\}, \{3, 8\}, \{4, 5\}, \{5, 6\}, \{7, 8\}\}$

Directed Graph $G = (V, E)$



- V: set of vertices (nodes);
  - $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$
- E: pairwise relationships among V;
  - directed graphs: relationship is asymmetric, E contains ordered pairs

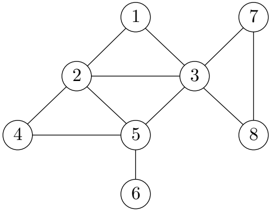
Directed Graph $G = (V, E)$



- V: set of vertices (nodes);
  - $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$
- E: pairwise relationships among V;
  - directed graphs: relationship is asymmetric, E contains ordered pairs
  - $E = \{(1, 2), (1, 3), (3, 2), (4, 2), (2, 5), (5, 3), (3, 7), (3, 8), (4, 5), (5, 6), (6, 5), (8, 7)\}$

Abuse of Notations

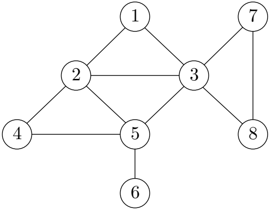
- For (undirected) graphs, we often use (i,j) to denote the set $\{i,j\}$.
- We call (i,j) an unordered pair; in this case $(i,j) = (j,i)$.



- $E = \{(1,2),(1,3),(2,3),(2,4),(2,5),(3,5),(3,7),(3,8),$
$(4,5),(5,6),(7,8)\}$

- Social Network : Undirected
- Transition Graph : Directed
- Road Network : Directed or Undirected
- Internet : Directed or Undirected

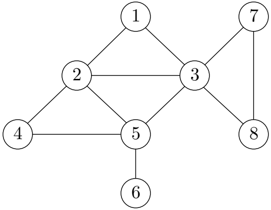
Representation of Graphs

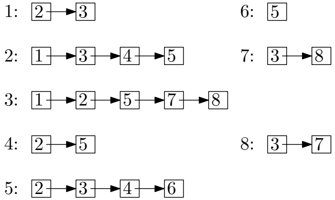


	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	1	0	0	0
3	1	1	0	0	1	0	1	1
4	0	1	0	0	1	0	0	0
5	0	1	1	1	0	1	0	0
6	0	0	0	0	1	0	0	0
7	0	0	1	0	0	0	0	1
8	0	0	1	0	0	0	1	0

- Adjacency matrix
  - $n \times n$ matrix, $A[u, v] = 1$ if $(u, v) \in E$ and $A[u, v] = 0$ otherwise
  - A is symmetric if graph is undirected

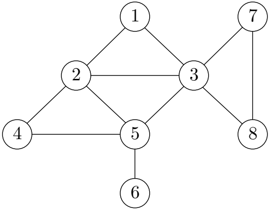
Representation of Graphs





- Adjacency matrix
  - $n \times n$ matrix, $A[u, v] = 1$ if $(u, v) \in E$ and $A[u, v] = 0$ otherwise
  - A is symmetric if graph is undirected
- Linked lists
  - For every vertex v, there is a linked list containing all neighbours of v.

Representation of Graphs



1: 2 3
2: 1 3 4 5
3: 1 2 5 7 8
4: 2 5
5: 2 3 4 6
6: 5
7: 3 8
8: 3 7

$d : (2, 4, 5, 2, 4, 1, 2, 2)$

- Adjacency matrix
  - $n \times n$ matrix, $A[u, v] = 1$ if $(u, v) \in E$ and $A[u, v] = 0$ otherwise
  - A is symmetric if graph is undirected
- Linked lists
  - For every vertex v, there is a linked list containing all neighbours of v.
  - When graph is static, can use array of variant-length arrays.

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n: number of vertices
- m: number of edges, assuming $n - 1 \le m \le n(n-1)/2$
- d_v: number of neighbors of v

	Matrix	Linked Lists
memory usage		
time to check $(u, v) \in E$		
time to list all neighbours of v		

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n: number of vertices
- m: number of edges, assuming $n-1 \leq m \leq n(n-1)/2$
- d_v: number of neighbors of v

	Matrix	Linked Lists
memory usage	$O(n^2)$	
time to check $(u,v) \in E$		
time to list all neighbours of v		

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n: number of vertices
- m: number of edges, assuming $n-1 \le m \le n(n-1)/2$
- d_v: number of neighbors of v

	Matrix	Linked Lists
memory usage	$O(n^2)$	$O(m)$
time to check $(u,v) \in E$		
time to list all neighbours of v		

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n: number of vertices
- m: number of edges, assuming $n - 1 \le m \le n(n-1)/2$
- d_v: number of neighbors of v

	Matrix	Linked Lists
memory usage	$O(n^2)$	$O(m)$
time to check $(u, v) \in E$	$O(1)$	
time to list all neighbours of v		

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n: number of vertices
- m: number of edges, assuming $n - 1 \leq m \leq n(n-1)/2$
- d_v: number of neighbors of v

	Matrix	Linked Lists
memory usage	$O(n^2)$	$O(m)$
time to check $(u, v) \in E$	$O(1)$	$O(d_u)$
time to list all neighbours of v		

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n: number of vertices
- m: number of edges, assuming $n-1 \le m \le n(n-1)/2$
- d_v: number of neighbors of v

	Matrix	Linked Lists
memory usage	$O(n^2)$	$O(m)$
time to check $(u,v) \in E$	$O(1)$	$O(d_u)$
time to list all neighbours of v	$O(n)$	

Comparison of Two Representations

- Assuming we are dealing with undirected graphs
- n: number of vertices
- m: number of edges, assuming $n-1 \le m \le n(n-1)/2$
- d_v: number of neighbors of v

	Matrix	Linked Lists
memory usage	$O(n^2)$	$O(m)$
time to check $(u,v) \in E$	$O(1)$	$O(d_u)$
time to list all neighbours of v	$O(n)$	$O(d_v)$

Outline

1. Graphs
2. Connectivity and Graph Traversal
   - Testing Bipartiteness
3. Topological Ordering

Connectivity Problem

Input: graph $G = (V, E)$, (using linked lists)
two vertices $s, t \in V$

Output: whether there is a path connecting s to t in G

Connectivity Problem

Input: graph $G = (V, E)$, (using linked lists)
two vertices $s, t \in V$

Output: whether there is a path connecting s to t in G

- Algorithm: starting from s, search for all vertices that are reachable from s and check if the set contains t

Connectivity Problem

Input: graph $G = (V, E)$, (using linked lists)
two vertices $s, t \in V$

Output: whether there is a path connecting s to t in G

- Algorithm: starting from s, search for all vertices that are reachable from s and check if the set contains t
  - Breadth-First Search (BFS)

Connectivity Problem

Input: graph $G = (V, E)$, (using linked lists)

two vertices $s, t \in V$

Output: whether there is a path connecting s to t in G

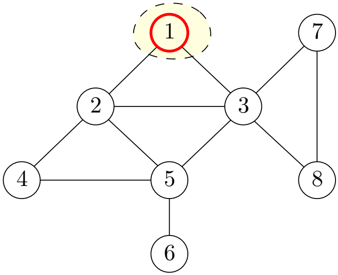
- Algorithm: starting from s, search for all vertices that are reachable from s and check if the set contains t
  - Breadth-First Search (BFS)
  - Depth-First Search (DFS)

Breadth-First Search (BFS)

- Build layers $L_0, L_1, L_2, L_3, \cdots$
- $L_0 = \{s\}$
- L_{j+1} contains all nodes that are not in $L_0 \cup L_1 \cup \cdots \cup L_j$ and have an edge to a vertex in L_j

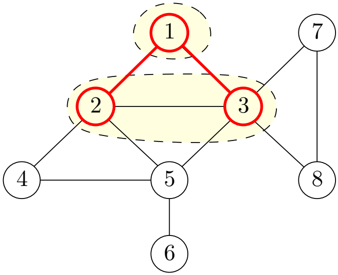
Breadth-First Search (BFS)

- Build layers $L_0, L_1, L_2, L_3, \cdots$
- $L_0 = \{s\}$
- L_{j+1} contains all nodes that are not in $L_0 \cup L_1 \cup \cdots \cup L_j$ and have an edge to a vertex in L_j



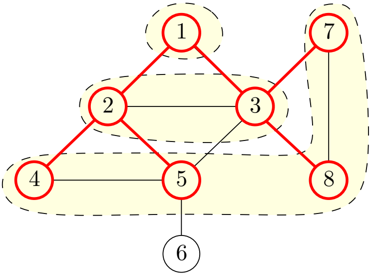
Breadth-First Search (BFS)

- Build layers $L_0, L_1, L_2, L_3, \cdots$
- $L_0 = \{s\}$
- L_{j+1} contains all nodes that are not in $L_0 \cup L_1 \cup \cdots \cup L_j$ and have an edge to a vertex in L_j



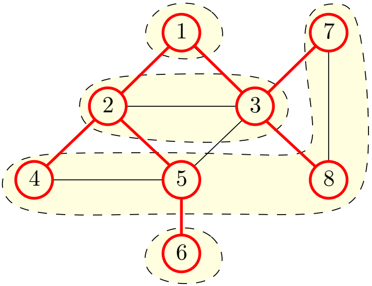
Breadth-First Search (BFS)

- Build layers $L_0, L_1, L_2, L_3, \cdots$
- $L_0 = \{s\}$
- L_{j+1} contains all nodes that are not in $L_0 \cup L_1 \cup \cdots \cup L_j$ and have an edge to a vertex in L_j



Breadth-First Search (BFS)

- Build layers $L_0, L_1, L_2, L_3, \cdots$
- $L_0 = \{s\}$
- L_{j+1} contains all nodes that are not in $L_0 \cup L_1 \cup \cdots \cup L_j$ and have an edge to a vertex in L_j



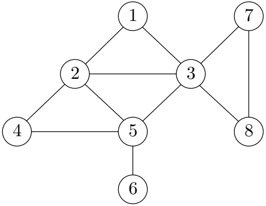
Implementing BFS using a Queue

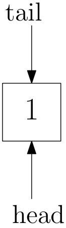
BFS(s)

$head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$
mark s as "visited" and all other vertices as "unvisited"
while $head \leq tail$ **do**
    $v \leftarrow queue[head], head \leftarrow head + 1$
    for all neighbours u of v **do**
        if u is "unvisited" **then**
            $tail \leftarrow tail + 1, queue[tail] = u$
            mark u as "visited"

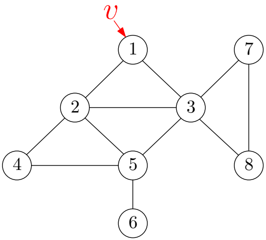
- Running time: $O(n + m)$.

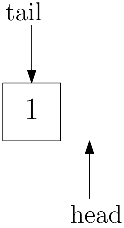
Example of BFS via Queue



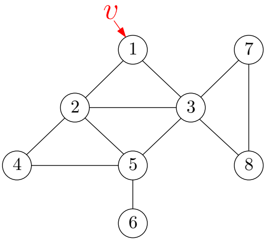


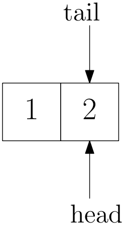
Example of BFS via Queue



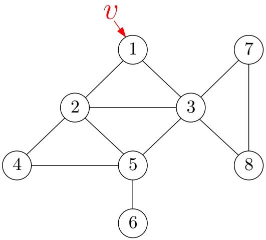


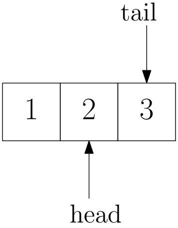
Example of BFS via Queue



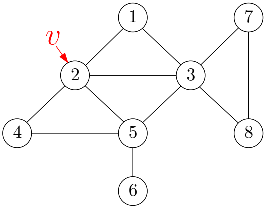


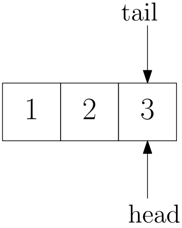
Example of BFS via Queue



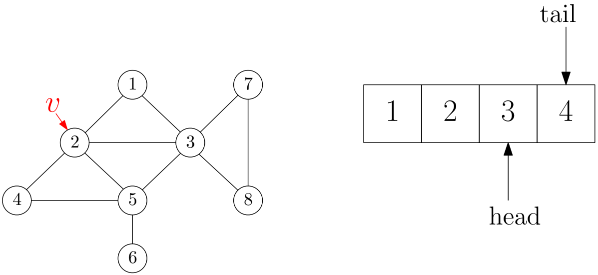


Example of BFS via Queue

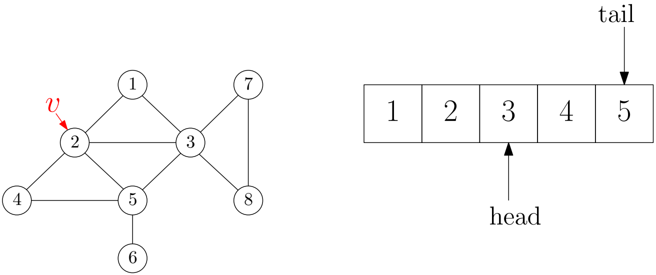




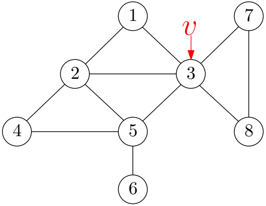
Example of BFS via Queue

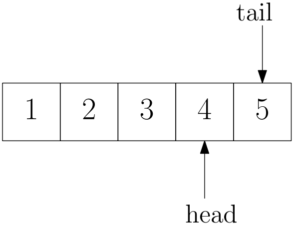


Example of BFS via Queue

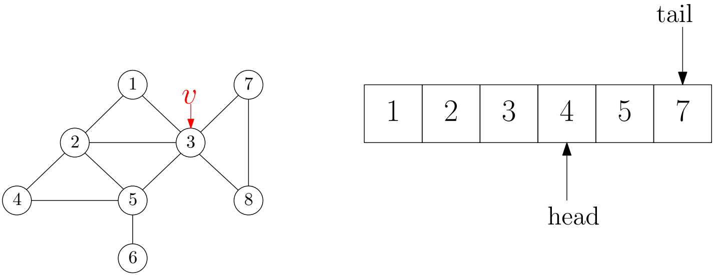


Example of BFS via Queue

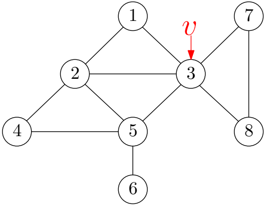


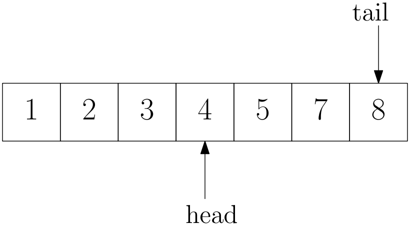


Example of BFS via Queue

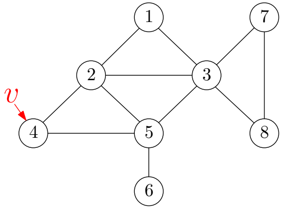


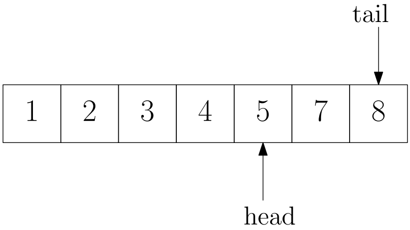
Example of BFS via Queue



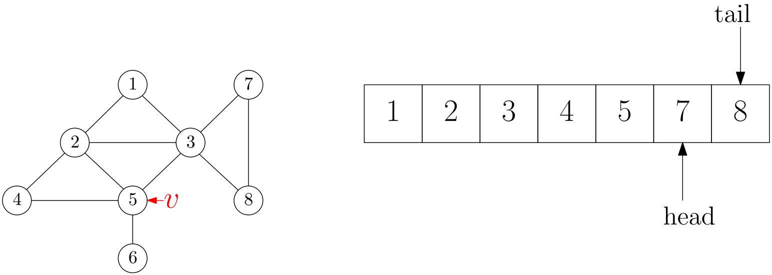


Example of BFS via Queue

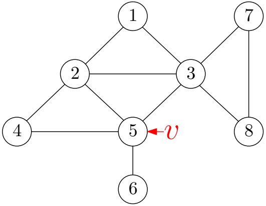


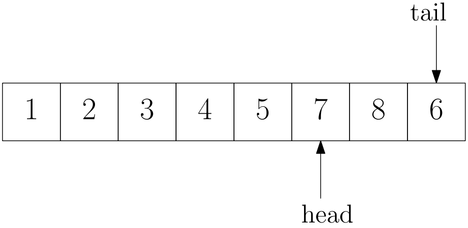


Example of BFS via Queue

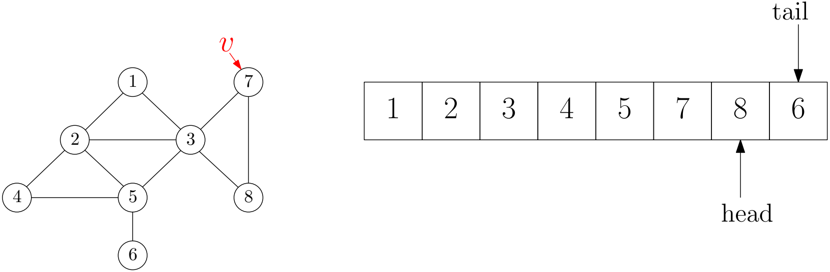


Example of BFS via Queue

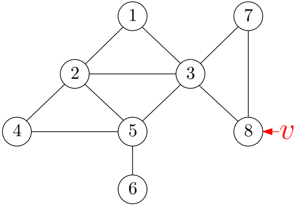


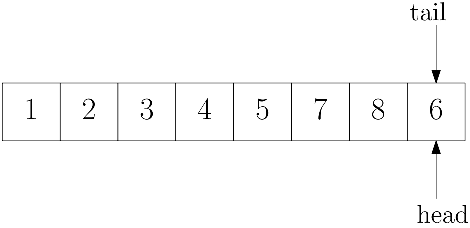


Example of BFS via Queue

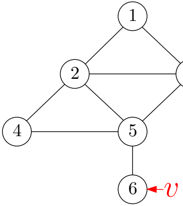


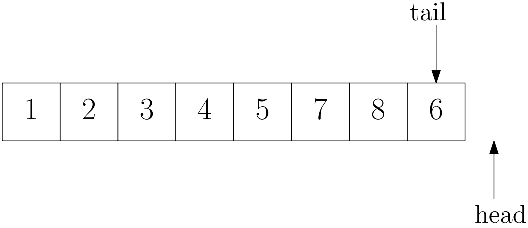
Example of BFS via Queue





Example of BFS via Queue



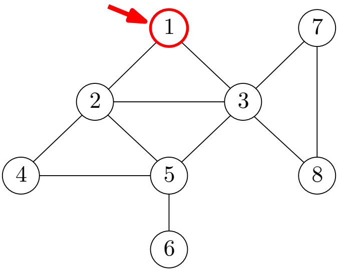


Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back

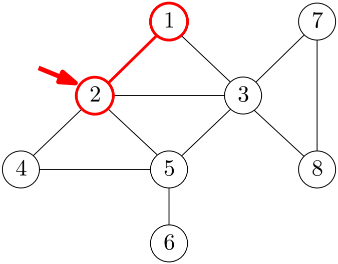
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



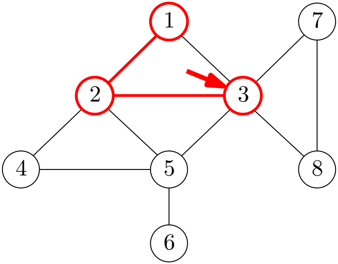
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



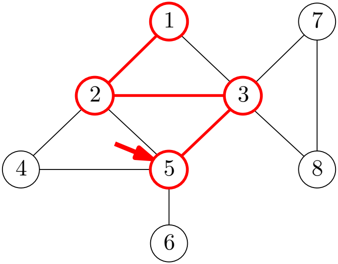
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



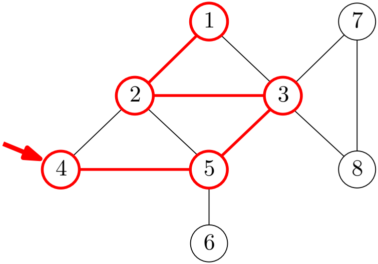
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



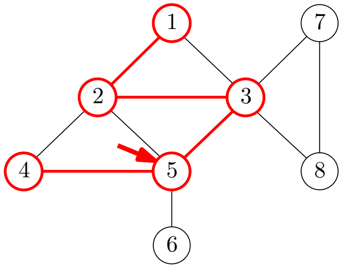
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



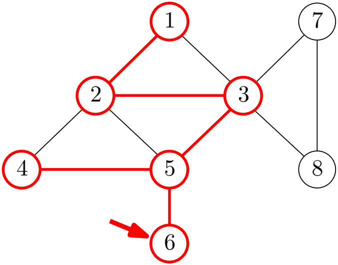
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



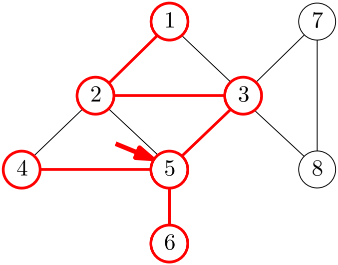
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex (“dead-end”), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



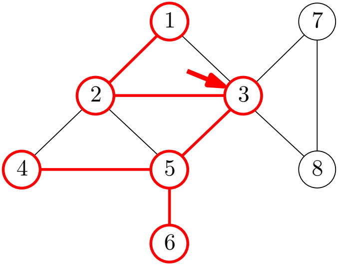
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



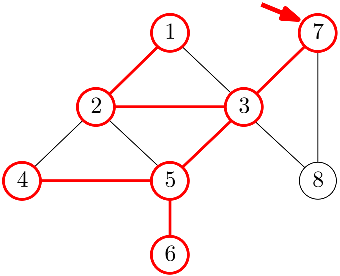
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



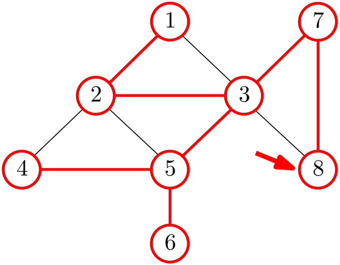
Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



Depth-First Search (DFS)

- Starting from s
- Travel through the first edge leading out of the current vertex
- When reach an already-visited vertex ("dead-end"), go back
- Travel through the next edge
- If tried all edges leading out of the current vertex, go back



Implementing DFS using Recurrsion

DFS(s)

1: mark all vertices as "unvisited"
2: recursive-DFS(s)

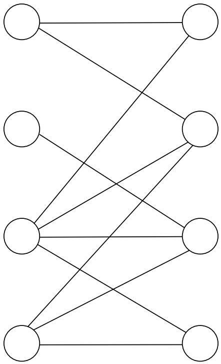
recursive-DFS(v)

1: mark v as "visited"
2: **for** all neighbours u of v **do**
3:     **if** u is unvisited **then** recursive-DFS(u)

Outline

Testing Bipartiteness: Applications of BFS

Def. A graph $G = (V, E)$ is a bipartite graph if there is a partition of V into two sets L and R such that for every edge $(u, v) \in E$, we have either $u \in L, v \in R$ or $v \in L, u \in R$.



Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$

Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g

Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g
- Neighbors of s must be in R

Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g
- Neighbors of s must be in R
- Neighbors of neighbors of s must be in L

Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g
- Neighbors of s must be in R
- Neighbors of neighbors of s must be in L
- $\cdots$

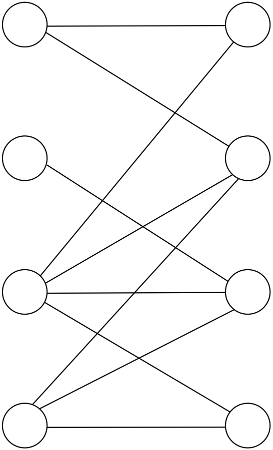
Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g
- Neighbors of s must be in R
- Neighbors of neighbors of s must be in L
- $\cdots$
- Report "not a bipartite graph" if contradiction was found

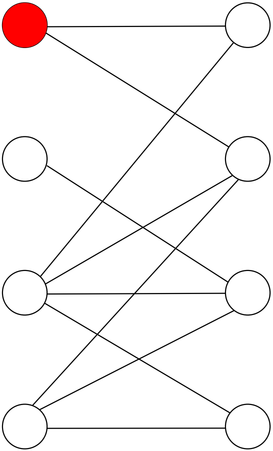
Testing Bipartiteness

- Taking an arbitrary vertex $s \in V$
- Assuming $s \in L$ w.l.o.g
- Neighbors of s must be in R
- Neighbors of neighbors of s must be in L
- $\cdots$
- Report "not a bipartite graph" if contradiction was found
- If G contains multiple connected components, repeat above algorithm for each component

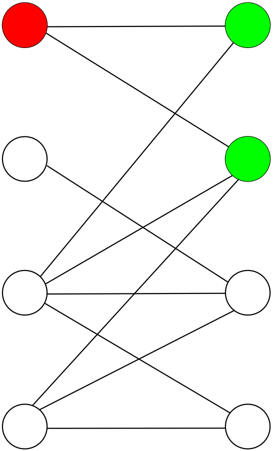
Test Bipartiteness



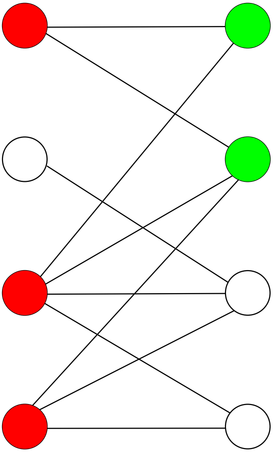
Test Bipartiteness



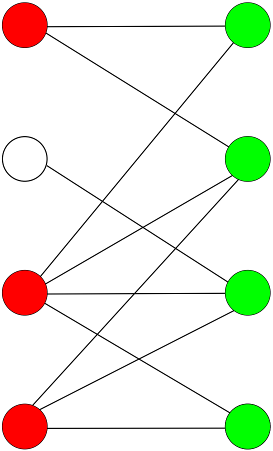
Test Bipartiteness



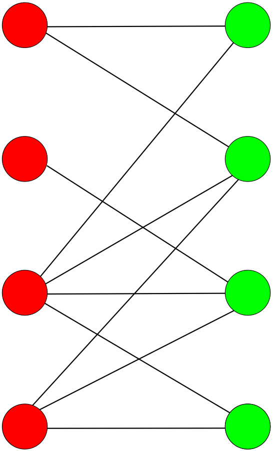
Test Bipartiteness



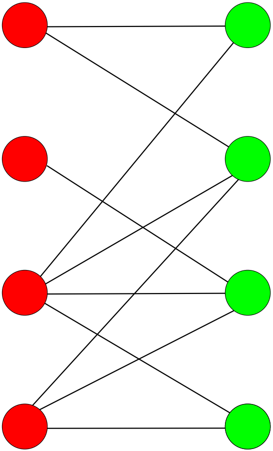
Test Bipartiteness

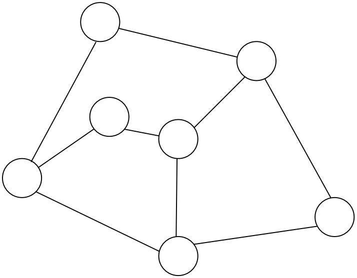


Test Bipartiteness

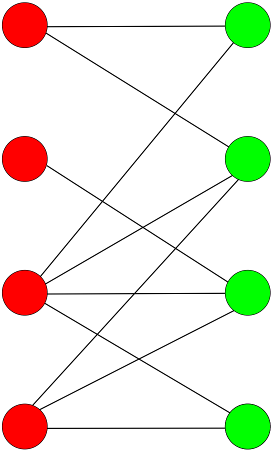


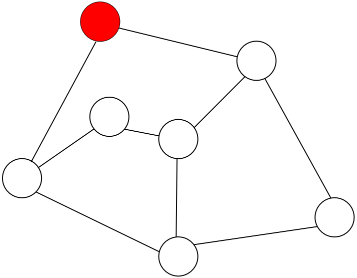
Test Bipartiteness



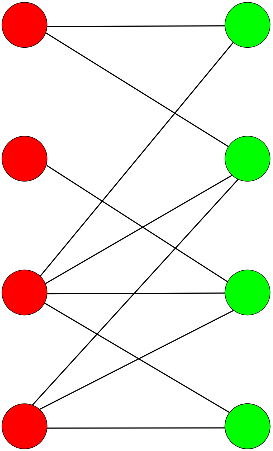


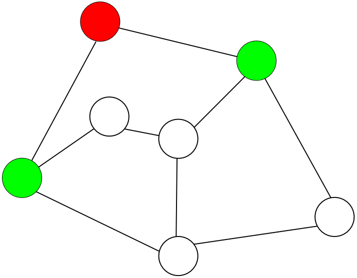
Test Bipartiteness



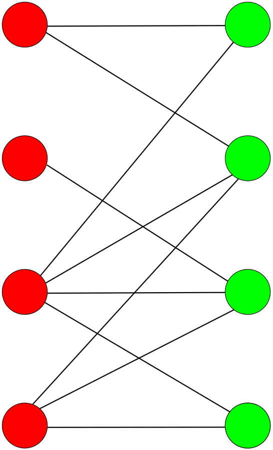


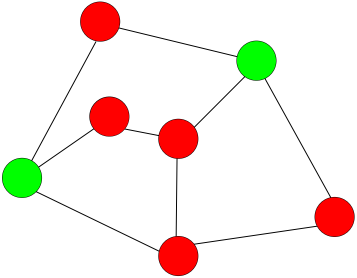
Test Bipartiteness



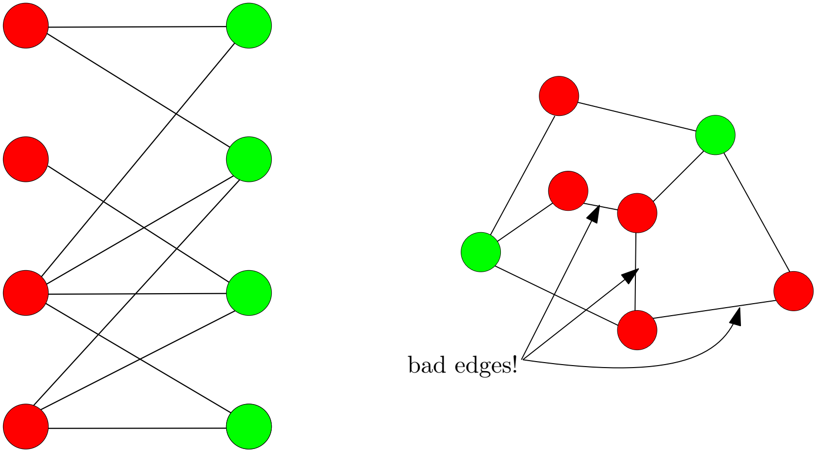


Test Bipartiteness





Test Bipartiteness



Testing Bipartiteness using BFS

BFS(s)

$head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$
mark s as "visited" and all other vertices as "unvisited"
while $head \leq tail$ **do**
    $v \leftarrow queue[head], head \leftarrow head + 1$
    for all neighbours u of v **do**
        if u is "unvisited" **then**
            $tail \leftarrow tail + 1, queue[tail] = u$
            mark u as "visited"

Testing Bipartiteness using BFS

test-bipartiteness(s)

$head \leftarrow 1, tail \leftarrow 1, queue[1] \leftarrow s$
mark s as “visited” and all other vertices as “unvisited”
$color[s] \leftarrow 0$
while $head \leq tail$ **do**
    $v \leftarrow queue[head], head \leftarrow head + 1$
    for all neighbours u of v **do**
        if u is “unvisited” **then**
            $tail \leftarrow tail + 1, queue[tail] = u$
            mark u as “visited”
            $color[u] \leftarrow 1 - color[v]$
        else if $color[u] = color[v]$ **then**
            print(“G is not bipartite”) and exit

Testing Bipartiteness using BFS

```
mark all vertices as "unvisited"
for each vertex v ∈ V do
    if v is "unvisited" then
        test-bipartiteness(v)
print("G is bipartite")
```

Testing Bipartiteness using BFS

mark all vertices as "unvisited"
for each vertex $v \in V$ **do**
    if v is "unvisited" **then**
        test-bipartiteness(v)
print("G is bipartite")

Obs. Running time of algorithm $= O(n+m)$

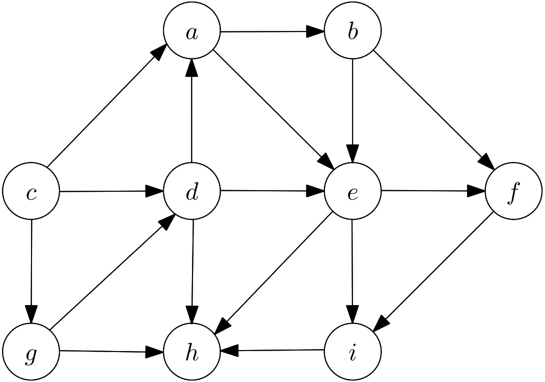
Outline

Topological Ordering Problem

Input: a directed acyclic graph (DAG) $G = (V, E)$

Output: 1-to-1 function $\pi : V \to \{1, 2, 3 \cdots, n\}$, so that

- if $(u, v) \in E$ then $\pi(u) < \pi(v)$

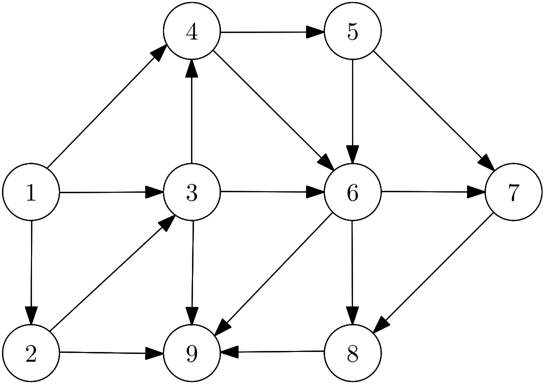


Topological Ordering Problem

Input: a directed acyclic graph (DAG) $G = (V, E)$

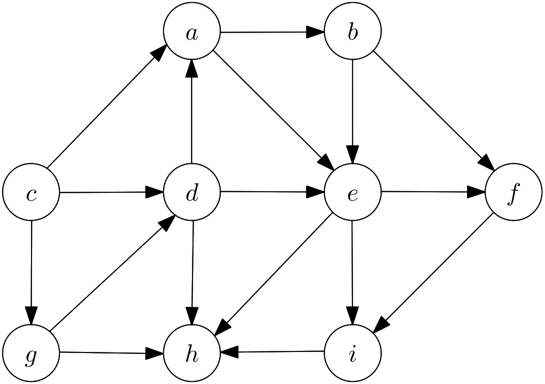
Output: 1-to-1 function $\pi : V \to \{1, 2, 3 \cdots, n\}$, so that

- if $(u, v) \in E$ then $\pi(u) < \pi(v)$



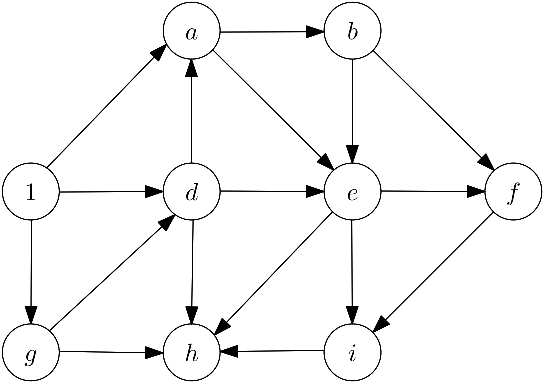
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



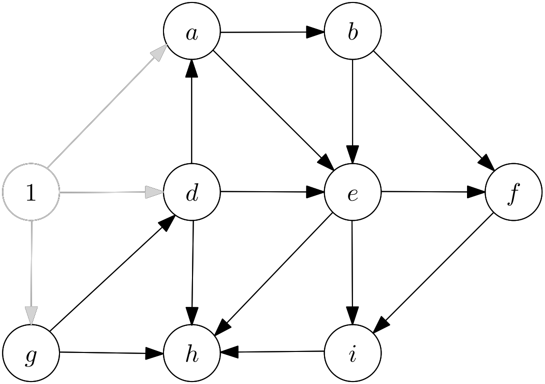
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



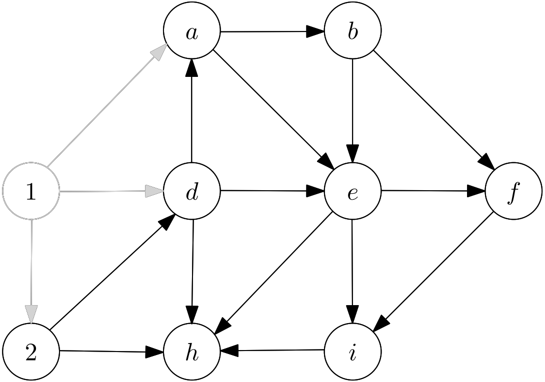
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



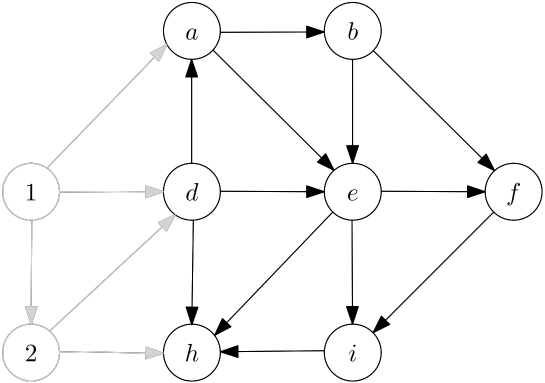
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



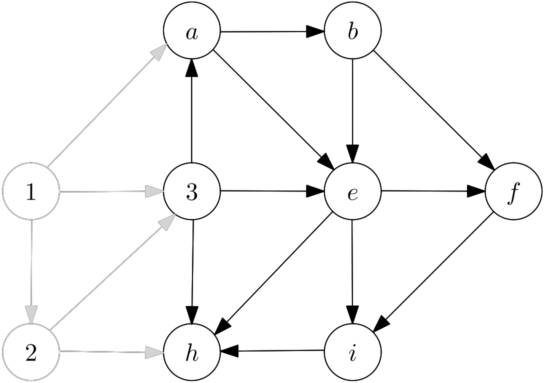
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



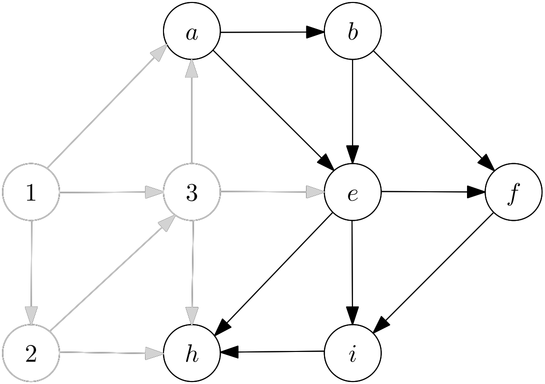
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



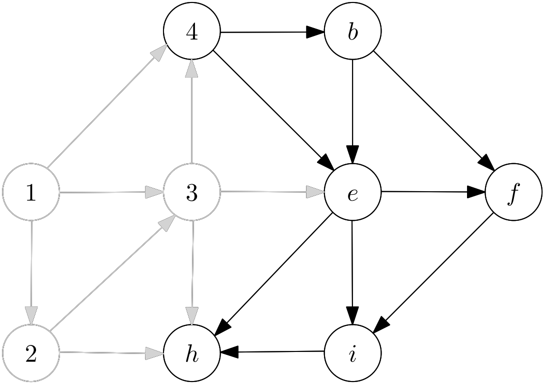
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



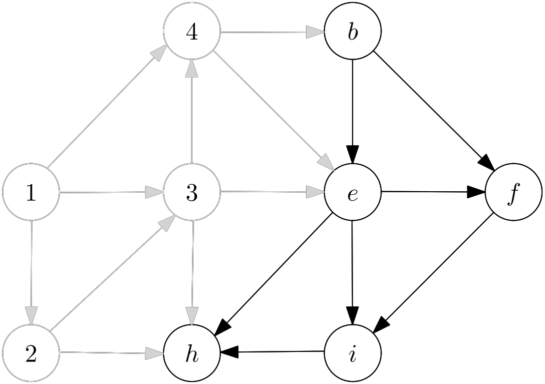
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



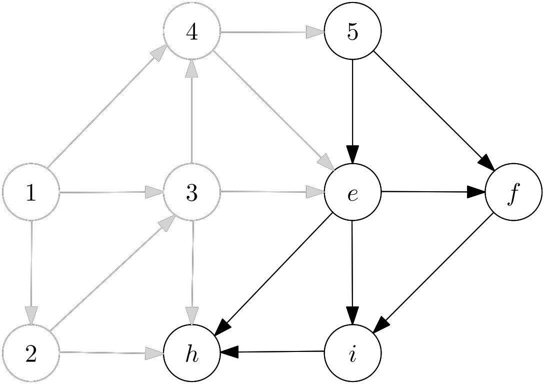
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



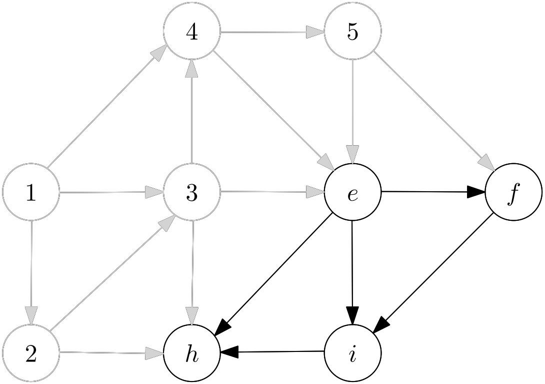
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



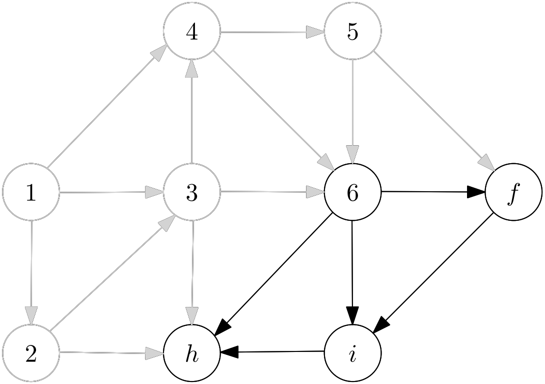
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



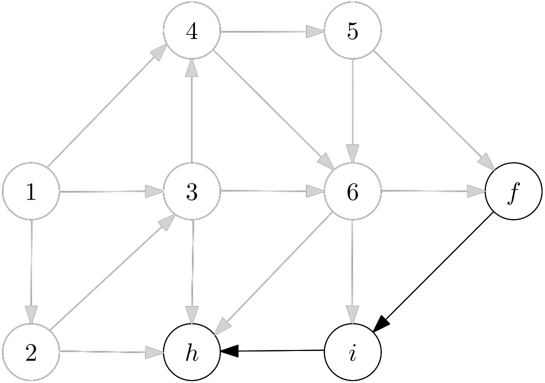
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



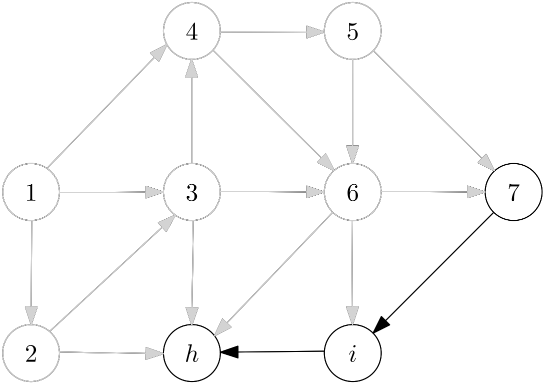
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



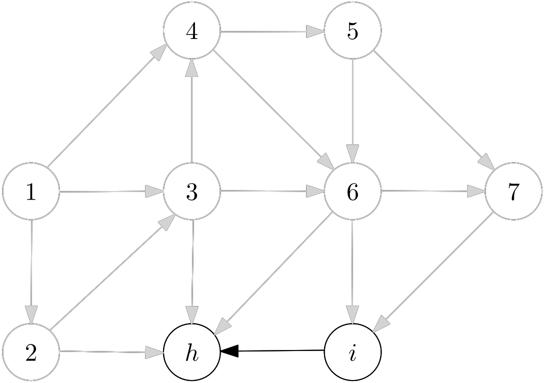
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



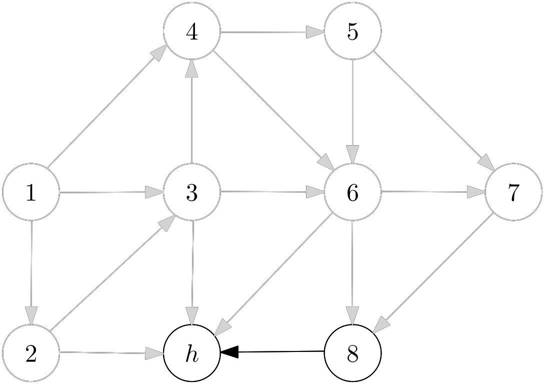
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



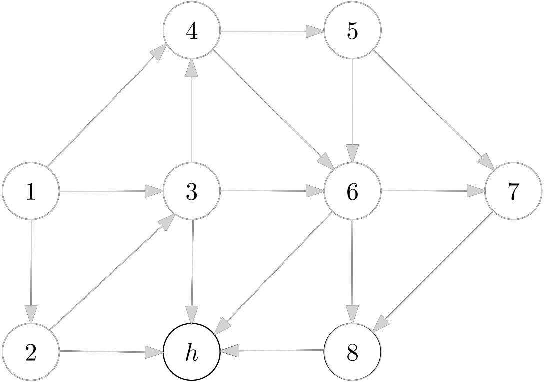
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



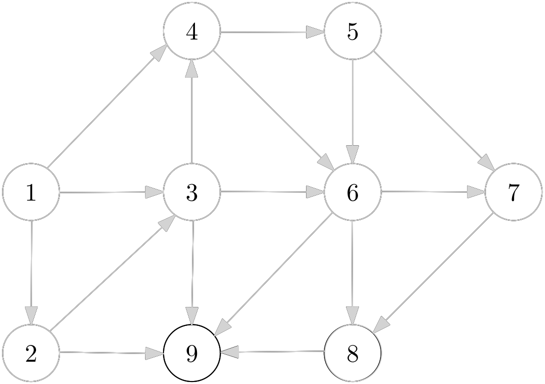
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



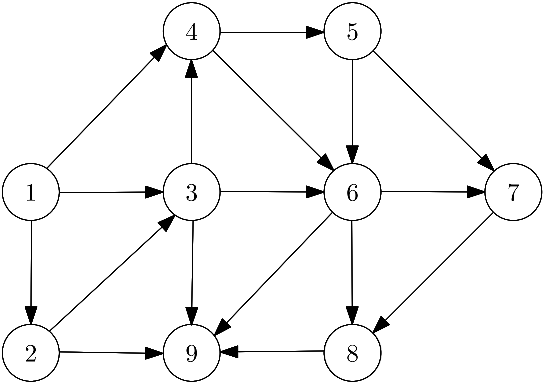
Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.



Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.

Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.

Q: How to make the algorithm as efficient as possible?

Topological Ordering

- Algorithm: each time take a vertex without incoming edges, then remove the vertex and all its outgoing edges.

Q: How to make the algorithm as efficient as possible?

A:

- Use linked-lists of outgoing edges
- Maintain the in-degree d_v of vertices
- Maintain a queue (or stack) of vertices v with $d_v = 0$

topological-sort(G)

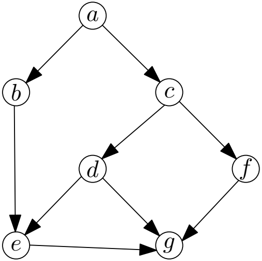
let $d_v \leftarrow 0$ for every $v \in V$
for every $v \in V$ **do**
    for every u such that $(v, u) \in E$ **do**
        $d_u \leftarrow d_u + 1$
$S \leftarrow \{v : d_v = 0\}, i \leftarrow 0$
while $S \neq \emptyset$ **do**
    $v \leftarrow$ arbitrary vertex in S, $S \leftarrow S \setminus \{v\}$
    $i \leftarrow i + 1$, $\pi(v) \leftarrow i$
    for every u such that $(v, u) \in E$ **do**
        $d_u \leftarrow d_u - 1$
        if $d_u = 0$ **then** add u to S
if $i < n$ then output "not a DAG"

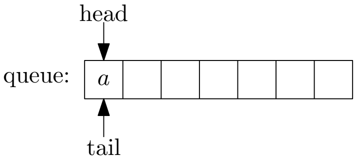
- S can be represented using a queue or a stack
- Running time $= O(n + m)$

S as a Queue or a Stack

DS	Queue	Stack
Initialization	$head \leftarrow 1$, $tail \leftarrow 0$	$top \leftarrow 0$
Non-Empty?	$head \leq tail$	$top > 0$
Add(v)	$tail \leftarrow tail + 1$ $S[tail] \leftarrow v$	$top \leftarrow top + 1$ $S[top] \leftarrow v$
Retrieve v	$v \leftarrow S[head]$ $head \leftarrow head + 1$	$v \leftarrow S[top]$ $top \leftarrow top - 1$

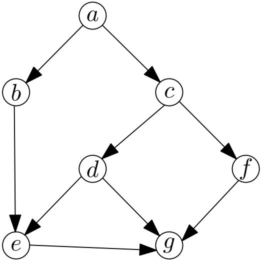
Example

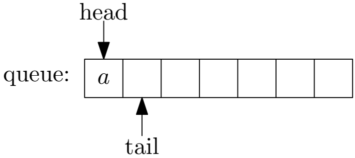




	a	b	c	d	e	f	g
degree	0	1	1	1	2	1	3

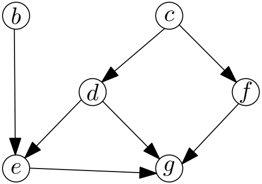
Example

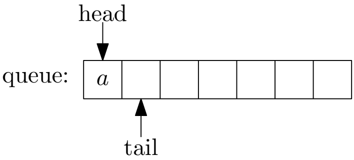




	a	b	c	d	e	f	g
degree	0	1	1	1	2	1	3

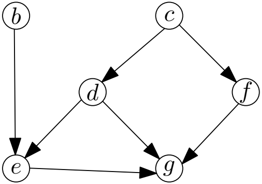
Example

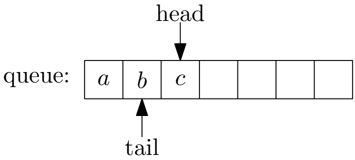




	a	b	c	d	e	f	g
degree	0	0	0	1	2	1	3

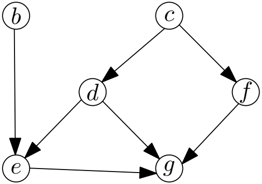
Example

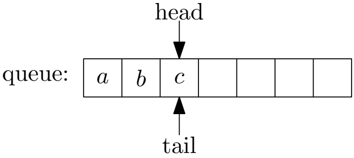




	a	b	c	d	e	f	g
degree	0	0	0	1	2	1	3

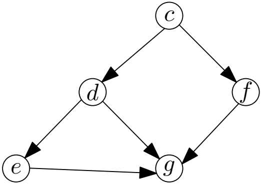
Example

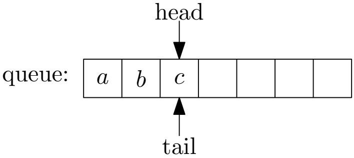




	a	b	c	d	e	f	g
degree	0	0	0	1	2	1	3

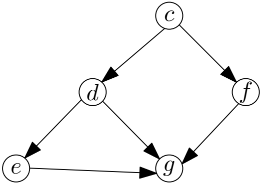
Example

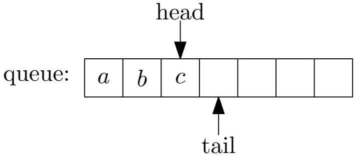




	a	b	c	d	e	f	g
degree	0	0	0	1	1	1	3

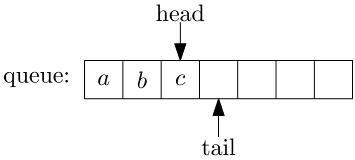
Example

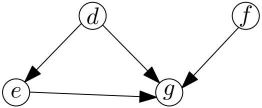




	a	b	c	d	e	f	g
degree	0	0	0	1	1	1	3

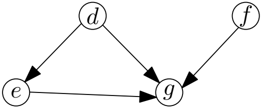
Example

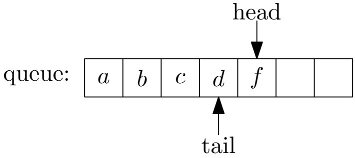




	a	b	c	d	e	f	g
degree	0	0	0	0	1	0	3

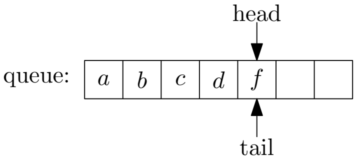
Example

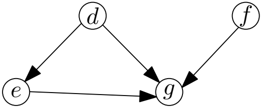




	a	b	c	d	e	f	g
degree	0	0	0	0	1	0	3

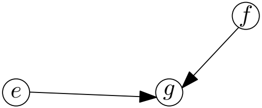
Example

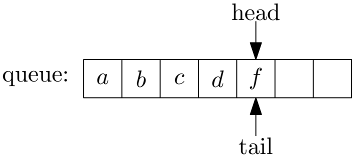




	a	b	c	d	e	f	g
degree	0	0	0	0	1	0	3

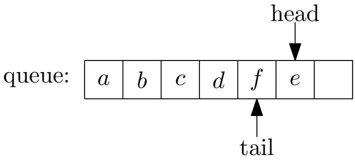
Example

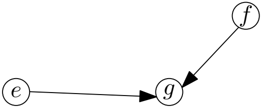




	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	2

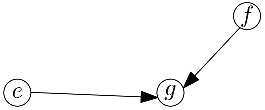
Example

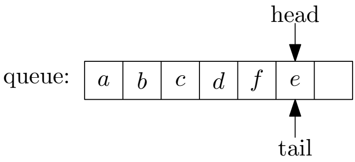




	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	2

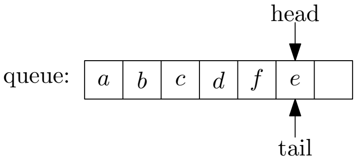
Example

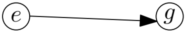




	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	2

Example





	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	1

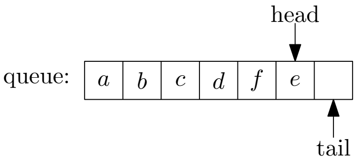
Example

queue: | a | b | c | d | f | e | |

head → e; tail → (empty cell after e)

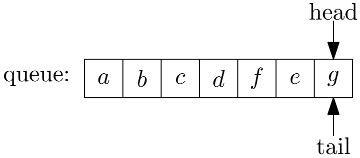
	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	1

Example



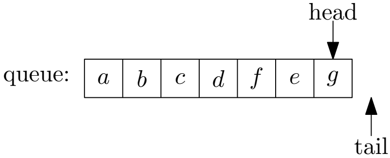
	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	0

Example



	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	0

Example



	a	b	c	d	e	f	g
degree	0	0	0	0	0	0	0