



# CSI 436/536

# Introduction to Machine Learning

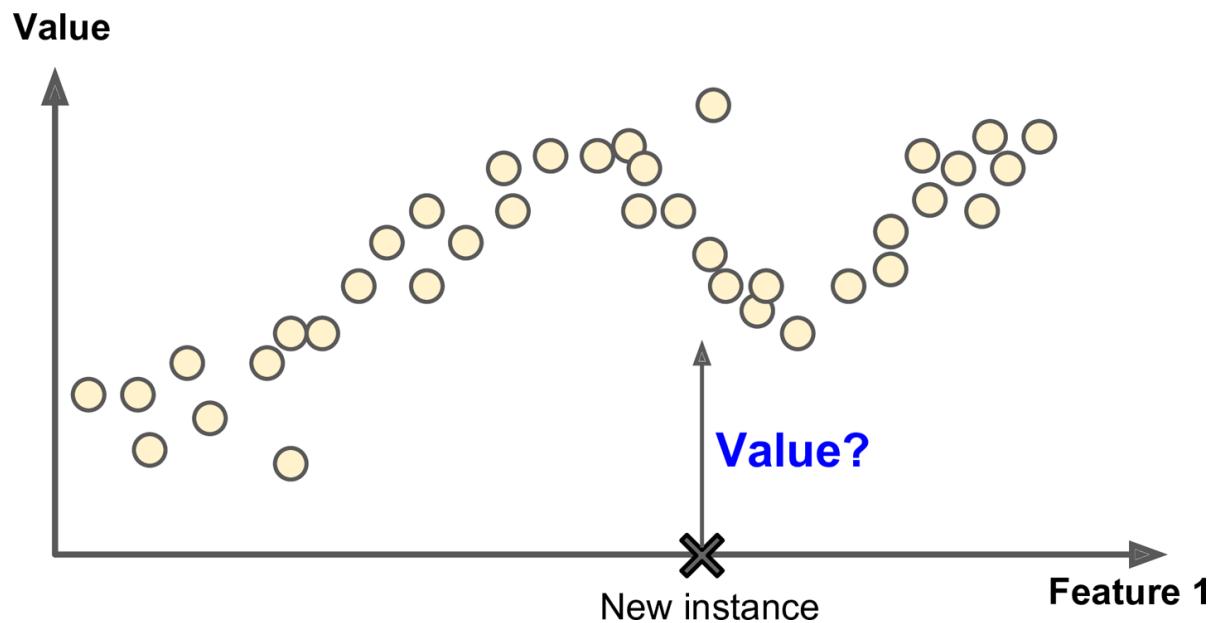
## Regression and LLSE

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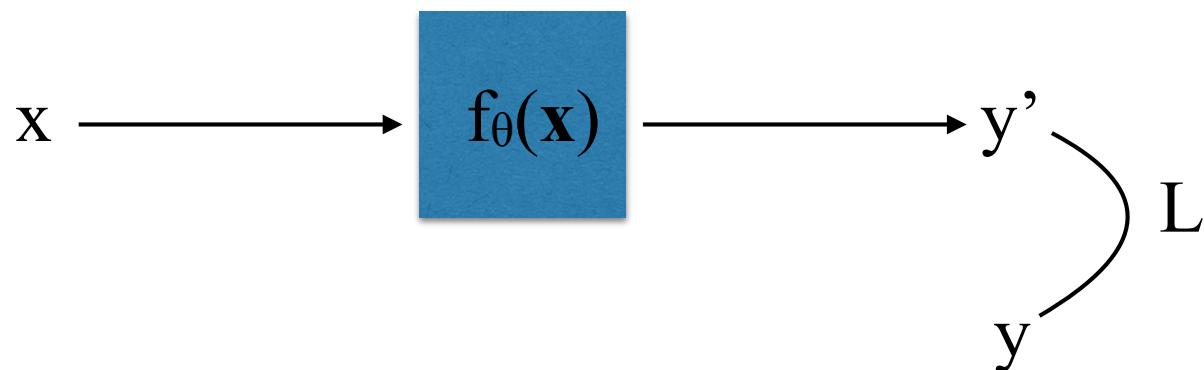
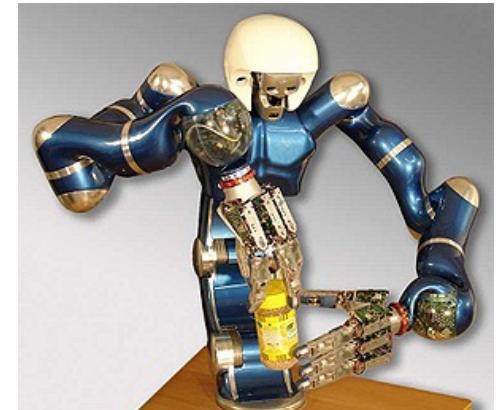
# Regression problem

- Use input to estimate a target variable that takes continuous values
- It is an example of **supervised machine learning** problem: in training, the target variables together with the inputs are given
  - In testing, we only have input and need to estimate the target



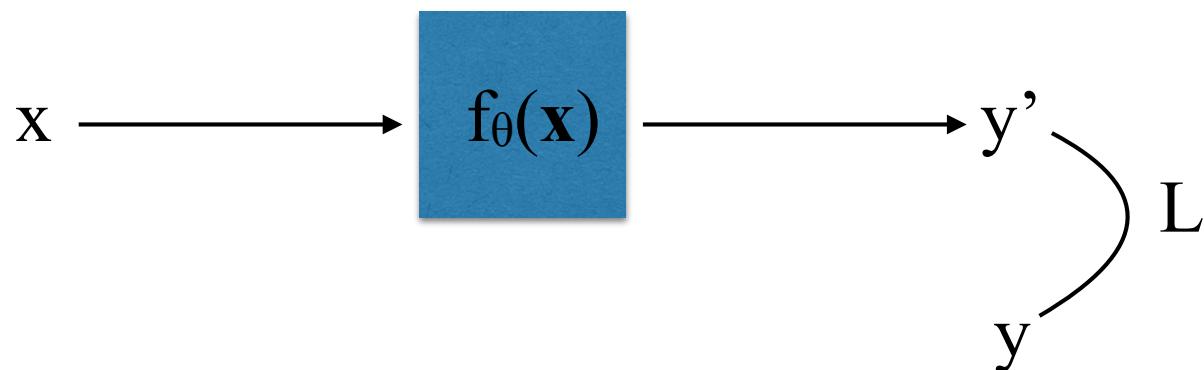
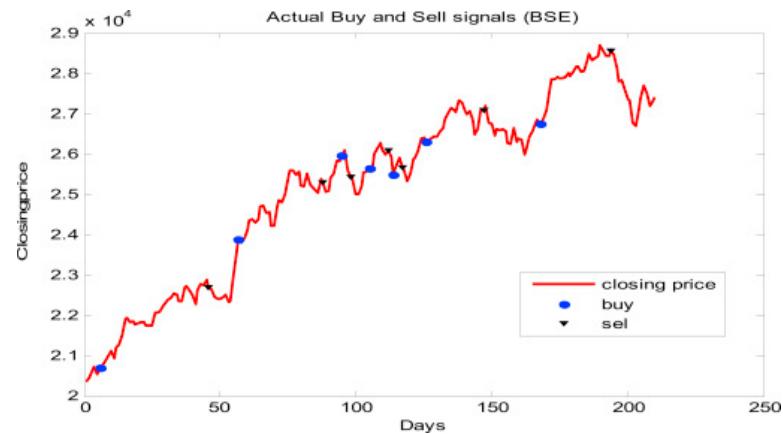
# Regression problem

- robotic control/automatic driving
  - input: internal parameters of robotic arm (force at angle)
  - output: end effector location
  - treat input-output as going through a black box transform
  - use training data to figure out best control function



# Regression problem

- High-frequency stock trading (algorithmic trading)
  - input: historic stock prices & trading records
  - output: new trading action
  - treat input-output as going through a black box transform
  - use training data to figure out best control function



# Notations

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- Data matrix can include processed data, i.e.,  $g$  is a function on raw  $x$

$$X = \begin{pmatrix} | & | & & | \\ g(x_1) & g(x_2) & \cdots & g(x_N) \\ | & | & & | \end{pmatrix}$$

- Mean and centering
  - introduce  $N$ -dim all one vectors  $1_N$ , the (arithmetic) mean of data is computed as  $m = \frac{1}{N} X 1_N$
  - The (column) centering operation is expressed as
$$\tilde{X} = X - m 1_N^T = X - \frac{1}{N} X 1_N 1_N^T = X \left( I - \frac{1}{N} 1_N 1_N^T \right)$$
the final matrix is the column centering operation
- **Correlation** and **covariance** matrices are defined as  $XX^T$  and  $\tilde{X}\tilde{X}^T$ , respectively

# Kernel matrix

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- Definition:  $G = X^T X \succeq 0$ ,  $G_{ij} = x_i^T x_j$ ,  
element is the pairwise inner product of two points
  - This matrix is known as the inner product matrix, the Gram matrix, or the *kernel* matrix
  - It is in a sense the *dual* of the correlation matrix  $XX^T$ , when  $X$  is full ranked, then at least one of them is invertible
  - Kernel matrix plays a central role in the subsequent nonlinear extension of linear machine learning algorithms

# General regression

- Training
  - Training data matrix  
data points are column vectors
  - Training targets, assuming scalar
  - parametric function  $f_w(\cdot) : R^d \mapsto R$
  - **loss function**  $L(y - f_w(x)) \geq 0$
  - Numerical procedure to find optimal  $w$  to minimize the learning objective  $\sum_{i=1}^n L(y_i - f_w(x_i))$
- In testing, for input  $x$  and generate prediction  $f_w(x)$ 
  - **metric function**  $m(y - f_w(x)) \geq 0$  on a validation dataset, may be different from the loss

$$X = \begin{pmatrix} | & | & & | \\ x_1 & x_2 & \cdots & x_N \\ | & | & & | \end{pmatrix}$$

$$y = (y_1, y_2, \dots, y_N)^T$$

# Linear least squares regression

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- Training
  - Training data matrix  
data points are column vectors
  - Training targets, assuming scalar
  - **Linear** function  $f_w(x) = w^T \phi(x)$
  - **Least squares loss function**  
$$L(y, f_w(x)) = \|y - f_w(x)\|^2$$
  - Optimal solution to the learning objective  
$$\sum_{i=1}^n L(y_i - f_w(x_i))$$
 satisfies the normal equation
- Testing
  - Metric function is also the least squares loss

$$X = \begin{pmatrix} | & | & \cdots & | \\ x_1 & x_2 & \cdots & x_N \\ | & | & \cdots & | \end{pmatrix}$$
$$y = (y_1, y_2, \dots, y_N)^T$$

# LLSE: the Swiss army knife in ML

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- Learning tasks
  - Supervised learning
    - Regression: basic LLSE and weighted LLSE
    - Classification: discriminative LLSE
  - Unsupervised learning
    - Clustering: multi-modal LLSE
    - Dimension reduction: total LLSE
- Learning paradigms
  - Batch learning: all other LLSE methods
  - Online learning: recursive LLSE
  - Dynamic programming: segmented LLSE
- Control of overfitting
  - Model selection: model selection LLSE
  - cross-validation: LOO LLSE
  - Regularization: ridge LLSE & LASSO



# LLSE — linear function

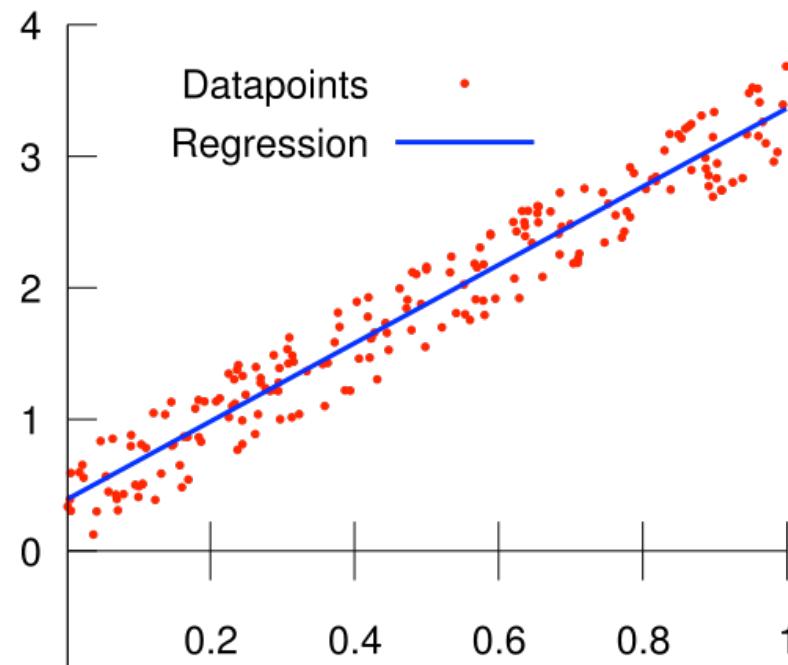
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- finding linear relation between input/output

$$f(x) = ax + b$$

- solving an optimization problem

$$\min_{w=(a,b)^T} \sum_{i=1}^N (y_i - ax_i - b)^2$$



# LLSE — quadratic function

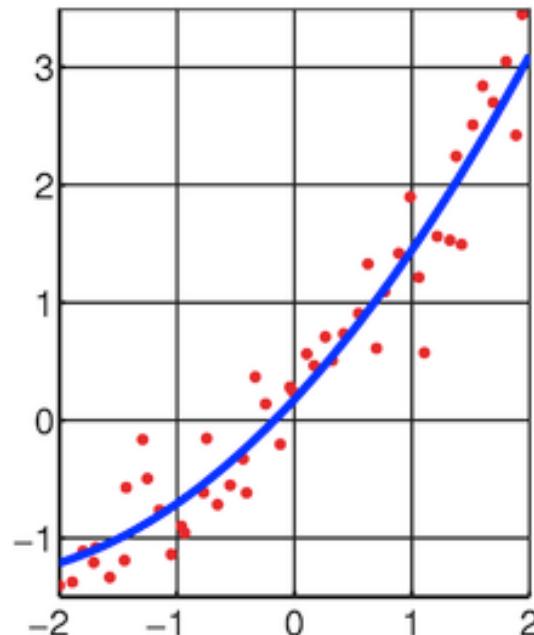
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- finding quadratic relation between input/output

$$f(x) = ax^2 + bx + c$$

- solving an optimization problem

$$\min_{w=(a,b,c)^T} \sum_{i=1}^N (y_i - ax_i^2 - bx_i^2 - c)^2$$



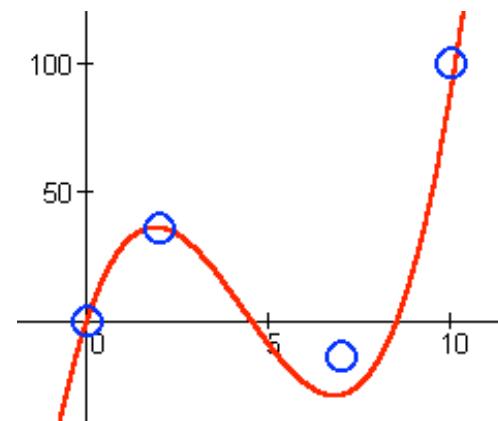
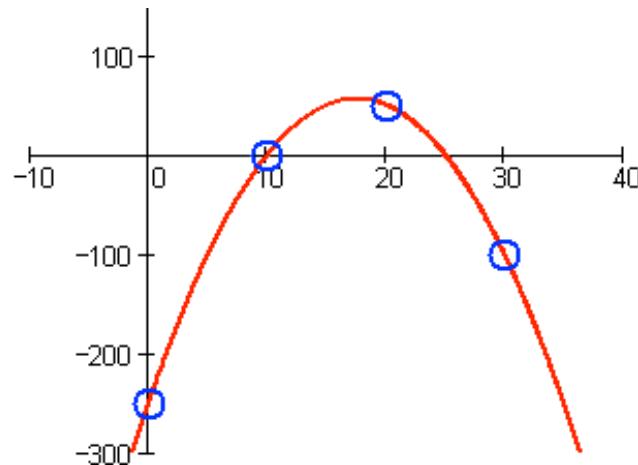
# LLSE — polynomial function

- find d-degree polynomial

$$f(x) = a_0 + a_1x + a_2x^2 + \cdots + a_dx^d$$

as

$$\min_{w=(a_0, \dots, a_d)^T} \sum_{i=1}^N (y_i - f(x_i))^2$$



# LLSE — arbitrary basis functions

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- find linear combinations of basis functions

$$f(x) = a_0 + a_1 g_1(x) + a_2 g_2(x) + \cdots + a_d g_d(x)$$

to  $\min_{w=(a_0, \dots, a_d)^T} \sum_{i=1}^N (y_i - f(x_i))^2$

- monomials:  $g_i(x) = x^i$  (polynomial fitting)
- Chebychev (orthogonal) polynomials

- Hermite polynomials:  $g_i(x) = e^{x^2} \frac{d^i e^{-x^2}}{dx^i}$

- complex exponentials (Fourier transform):  
 $g_i(x) = e^{-i\omega x}$

- radial basis functions (RBFs):  $g_i(x) = e^{-a_i(x-b_i)^2}$

# LLSE — general case

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- Define the general problem as fitting  $\sum_{i=1}^m a_i g_i(x_j)$  to target  $y$  by minimizing  $\sum_{j=1}^n (y_j - \sum_{i=1}^m a_i g_i(x_j))^2$
- Rewrite using linear algebra notations

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_N \end{pmatrix}, w = \begin{pmatrix} a_1 \\ a_2 \\ \dots \\ a_m \end{pmatrix}, \text{ objective is } \min_w \|y - X^T w\|^2 \text{ data}$$
$$\text{matrix } X = \begin{pmatrix} g_1(x_1) & g_1(x_2) & \dots & g_1(x_N) \\ g_2(x_1) & g_2(x_2) & \dots & g_2(x_N) \\ \vdots & \vdots & \ddots & \vdots \\ g_m(x_1) & g_m(x_2) & \dots & g_m(x_N) \end{pmatrix}$$

# Solving LLSE

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- Expand the terms

$$\|y - X^T w\|^2 = y^T y - 2y^T X^T w + w^T X X^T w$$

- Taking derivative on both sides w.r.t.  $w$

$$\nabla_w \|y - X^T w\|^2 = 2(X X^T w - X y) = 0$$

- The solution is given by  $X X^T w = X y$ , which is known as the **normal equation**

- Check Hessian matrix  $\nabla \nabla_w^T \|y - X^T w\|^2 = 2 X X^T \succeq 0$  (why?)

so the solution is a minimum

- We will assume the data matrix is full ranked (no linearly dependent rows or columns)

# Weighted LLSE

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- Introducing a weight matrix  $W$ , usually diagonal with  $W_{ii} \geq 0$ , and to solve

$$\min_w (y - X^T w)^T W (y - X^T w)$$

- This is known as weighted LLSE
  - When  $W = I$ , WLLSE reduces to LLSE

$$(y - X^T w)^T W (y - X^T w) = \sum_{i=1}^n W_{ii} \left( y_i - \sum_{j=1}^m a_j g_j(x_i) \right)^2$$

- Solution

$$\nabla_w (y - X^T w)^T W (y - X^T w) = 2(XW X^T w - XW y) = 0$$

so  $XW X^T w = XW y \Rightarrow w = (XW X^T)^{-1} XW y$

# Weighted LLSE

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- How to determine the weight
  - Larger weight => error has to be small
  - Smaller weight => more relaxed error
- Relation with the variance of the error
  - $W_{ii} = \frac{1}{\sigma_i^2}$ , where  $\sigma_i^2$  is the variance of the error in the corresponding component
  - Larger variance => less reliable estimation => smaller weight => more relaxed error
  - smaller variance => more reliable estimation => larger weight => error has to be small

# Solving normal equation

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- case 1: complete problem  
 $N = m$ , i.e., # of data = # of parameters  
 $\Rightarrow$  matrix  $X$  is square  
 $\Rightarrow$  correlation matrix  $XX^T$ ,  $X$  and  $X^T$  are all invertible
- case 2: over-complete problem  
 $N > m$ , i.e., # of data > # of parameters  
 $\Rightarrow$  matrix  $X$  is short & fat  
 $\Rightarrow$  correlation matrix  $XX^T$  is  $N \times N$  and invertible
- case 3: under-complete problem  
 $N < m$ , i.e., # of data < # of parameters  
 $\Rightarrow$  matrix  $X$  is tall & thin  
 $\Rightarrow$  correlation matrix  $XX^T$  is  $m \times m$  and **not** invertible,  
but the Gram matrix  $X^T X$  is invertible

# Complete case

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- We can solve directly by matrix inversion

$$XX^T w = Xy \Rightarrow X^T w = y \Rightarrow w = X^{-T} y$$

- Prediction error is zero:  $y - X^T w = y - X^T X^{-T} y = 0$ 
  - Direct matrix inversion is usually not a good option
  - Solving  $Xp = y$  becomes  $LDU p = y$ , then two steps  $Lx = y$  (forward elimination),  $DUp = x$  (backward elimination)
    - This is known as Gaussian elimination
    - Solution time is  $O(n^2)$ , and numerically it is very stable (caveat: if the pivots are chosen right)
    - It is numerically stable (only divide by pivot)

# over-complete problem

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- Correlation matrix  $XX^T$  is invertible and positive definite so LLSE objective function has unique global optimal solution, as  $XX^T w = Xy \Rightarrow w = (XX^T)^{-1}Xy$ 
  - interpretation: projection of  $y$  in row space of  $X$
  - Prediction is  $X^T w = X^T(XX^T)^{-1}Xy$
  - Prediction error is
$$y - X^T w = y - X^T(XX^T)^{-1}Xy = (I_N - X^T(XX^T)^{-1}X)y$$
- $(XX^T)^{-1}X$  is known as the **left Penrose-Moore** pseudo inverse of general matrix  $X^T$ , as  $(XX^T)^{-1}XX^T = I_N$

# under-complete problem

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- $X$  is not invertible,  $X^T X$  is invertible and p.d.
- Define the right Penrose-Moore pseudo inverse of general matrix  $X$ ,  $X^T (X X^T)^{-1}$ , then  $w = X^T (X X^T)^{-1} y$  is a solution to the normal equation
- solution is not unique
  - for any vector in the null space of  $X$ ,  $Xh = 0$ ,  $p+h$  is also a solution
  - $p$  is a solution, we have  $X(p+h) = Xp = y$
- there are infinite number of solutions that lead to zero least squares error (**ill-posed problem**)

# under-complete problem

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- Correlation matrix  $XX^T$  is not invertible, but Gram matrix  $X^TX$  is invertible and p.d.
- Define the right Penrose-Moore pseudo inverse of general matrix  $X$ ,  $X(X^TX)^{-1}$ , then  $w = X(X^TX)^{-1}y$  is a solution to the normal equation
- solution is not unique
  - for any vector in the row null space of  $X$ ,  $X^T\mathbf{h} = 0$ ,  $w+\mathbf{h}$  is also a solution
  - $w$  is a solution, we have  $X^T(w+\mathbf{h}) = X^Tw = y$
- there are infinite number of solutions that lead to zero least squares error (**ill-posed problem**)

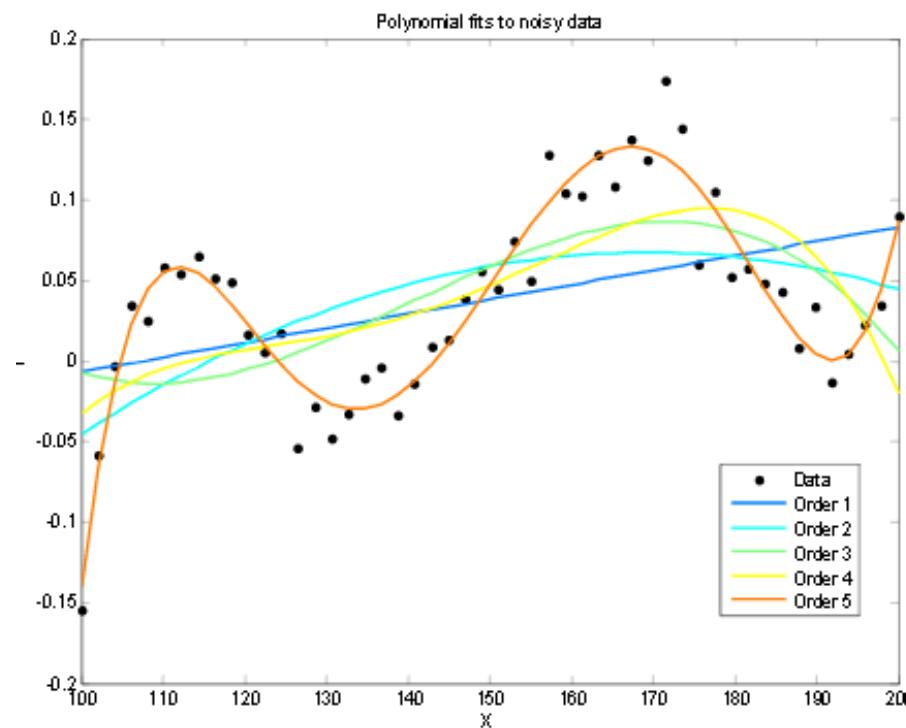
# Solving normal equation

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- case 1: complete problem  
 $N = m$ , i.e., # of data = # of parameters  
 $\Rightarrow$  matrix  $X$  is square  
 $\Rightarrow$  **unique** solution with **zero prediction error**
- case 2: over-complete problem  
 $N > m$ , i.e., # of data > # of parameters  
 $\Rightarrow$  matrix  $X$  is short & fat  
 $\Rightarrow$  **unique** solution with **non-zero prediction error**
- case 3: under-complete problem  
 $N < m$ , i.e., # of data < # of parameters  
 $\Rightarrow$  matrix  $X$  is tall & thin  
 $\Rightarrow$  **non-unique** solution with **zero prediction error**

# LLSE — general procedure

- Obtain training data  $X$
- Decide number of base functions to use
- Choose a proper weight matrix  $W$
- Form LSE objective function, and solve the normal equation for optimal solution



# Issues

- Squared L2 loss is sensitive to **outliers** in training data
  - Using L1 loss is more **robust** to outliers in training data
- Data points may not come at the same time, we need to handle the data in an **online** manner
- Using a high degree of polynomial may **overfit** the data, how do we control that from occurring
- The number of base functions (degree of polynomials) is a **hyper-parameter**, how do we select it

