



CSI 436/536

# Introduction to Machine Learning

## **Model selection for LLSE**

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# Model selection

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- Training a model (e.g., linear model using LLSE) from a training data can determine the *parameters* in the model
- There are *model families* that cannot be determined from data alone, such as
  - The degree of polynomial in polynomial fitting
  - The type of nonlinear models in regression
- *Model selection* decides the form of the model and the model parameter to be learned
- *Model training* decides the specific value of the model parameter for a model from the model family based on training data

# Model selection in LLSE

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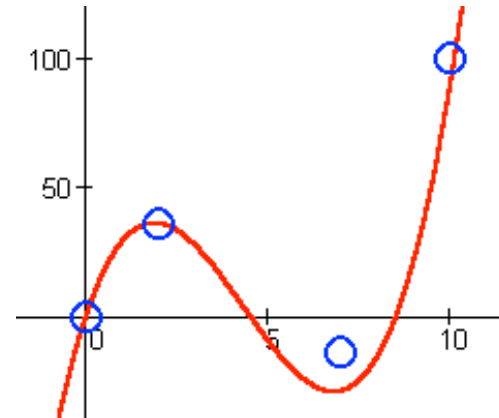
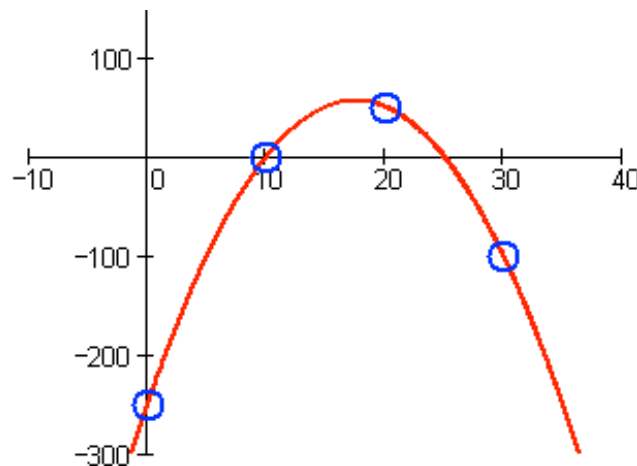
- find d-degree polynomial

$$f(x) = a_0 + a_1x + a_2x^2 + \dots + a_dx^d$$

as

$$\min_{w=(a_0, \dots, a_d)^T} \sum_{i=1}^N (y_i - f(x_i))^2$$

- What is the right d for a particular set of data?
  - This cannot be learned solely from data



# Overfitting and underfitting

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- If models are not chosen carefully, overfitting or underfitting will occur
- When a model has low error on training data but high error on testing data, it *overfits*. When it has high error on training data, it *underfits*
- Both are undesirable, but overfitting may be more harmful





# General procedure of model selection

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- Decide a candidate set of model families
  - For LLSE, corresponding to choosing polynomials of different degrees
- For each candidate model family
  - Obtain optimal parameter using the training set
  - Compute the error metric on the validation dataset
- Choose the model family that leads to the minimum error on the validation dataset
- Deploy the best model of the chosen family on the test dataset to report results

# Incremental LLSE

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- Idea: fitting data with polynomials of different degrees,
  - A simple idea is to try for a range of  $d = 1, \dots, D$ , to fit the training data using LLSE of each degree
    - problem: each time we have to solve the normal equation by inverting the correlation matrix, leading to complexity  $O(ND^4)$
- Better idea is to do this incrementally, using the result of previous step to bootstrap
- This is known as *incremental LLSE*, which can be solved similarly as recursive LLSE using dynamic programming and matrix inverse lemma

# Incremental LLSE

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- Old data matrix  $X$  and correlation matrix  $XX^T$
- New data matrix  $\tilde{X} = \begin{pmatrix} X \\ \tilde{x}^T \end{pmatrix}$ , where the new vector is  $N \times 1$  corresponding to the evaluation of additional degree monomial
- New correlation matrix
$$\tilde{X}\tilde{X}^T = \begin{pmatrix} X \\ \tilde{x}^T \end{pmatrix} \begin{pmatrix} X^T & \tilde{x} \end{pmatrix} = \begin{pmatrix} XX^T & X\tilde{x} \\ \tilde{x}^T X^T & \tilde{x}^T \tilde{x} \end{pmatrix}$$
- We need to compute  $(\tilde{X}\tilde{X}^T)^{-1}$ , can we use the result we already have for  $(XX^T)^{-1}$ ?



# Block matrix inversion lemma

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- Given a block matrix  $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$ , if  $D$  is invertible, define  $D$ 's Schur complement as  $\hat{D} = A - BD^{-1}C$ , then we can show that

$$M = \begin{pmatrix} I & BD^{-1} \\ 0 & I \end{pmatrix} \begin{pmatrix} \hat{D} & 0 \\ 0 & D \end{pmatrix} \begin{pmatrix} I & 0 \\ D^{-1} & I \end{pmatrix}$$

- Then it is easy to show that

$$M^{-1} = \begin{pmatrix} I & 0 \\ -D^{-1}C & I \end{pmatrix} \begin{pmatrix} \hat{D}^{-1} & 0 \\ 0 & D^{-1} \end{pmatrix} \begin{pmatrix} I & -BD^{-1} \\ 0 & I \end{pmatrix}$$

- Special case, when  $D = d$ ,  $B = x$ ,  $C = x^T$ , we have

$$M^{-1} = \begin{pmatrix} I & 0 \\ -x^T/d & I \end{pmatrix} \begin{pmatrix} (A - xx^T/d)^{-1} & 0 \\ 0 & 1/d \end{pmatrix} \begin{pmatrix} I & -x/d \\ 0 & I \end{pmatrix}$$

# Block matrix inversion lemma

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- Using matrix inversion lemma,

$$(A - xx^T/d)^{-1} = A^{-1} + \frac{A^{-1}xx^T A^{-1}}{d - x^T A^{-1}x}$$

then

$$\begin{aligned} M^{-1} &= \begin{pmatrix} I & 0 \\ -x^T/d & I \end{pmatrix} \begin{pmatrix} A^{-1} + \frac{A^{-1}xx^T A^{-1}}{d - x^T A^{-1}x} & 0 \\ 0 & 1/d \end{pmatrix} \begin{pmatrix} I & -x/d \\ 0 & I \end{pmatrix} \\ &= \begin{pmatrix} A^{-1} + \frac{A^{-1}xx^T A^{-1}}{d - x^T A^{-1}x} & 0 \\ \frac{-x^T A^{-1}}{(d - x^T A^{-1}x)} & 1/d \end{pmatrix} \begin{pmatrix} I & -x/d \\ 0 & I \end{pmatrix} \\ &= \begin{pmatrix} A^{-1} + \frac{A^{-1}xx^T A^{-1}}{d - x^T A^{-1}x} & \frac{-A^{-1}x}{(d - x^T A^{-1}x)} \\ \frac{-x^T A^{-1}}{(d - x^T A^{-1}x)} & \frac{1}{d - x^T A^{-1}x} \end{pmatrix} \end{aligned}$$

# Incremental LLSE

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- Computing

$$\hat{w} = \begin{pmatrix} (XX^T)^{-1} + \frac{(XX^T)^{-1}xx^T(XX^T)^{-1}}{d - x^T(XX^T)^{-1}x} & \frac{-(XX^T)^{-1}x}{(d - x^T(XX^T)^{-1}x)} \\ \frac{-x^T(XX^T)^{-1}}{(d - x^T(XX^T)^{-1}x)} & \frac{1}{d - x^T(XX^T)^{-1}x} \end{pmatrix} \begin{pmatrix} Xy \\ \tilde{x}^T y \end{pmatrix}$$

- After simplification we have  $\hat{w} = \begin{pmatrix} w + w_0(XX^T)^{-1}X\tilde{x} \\ w_0 \end{pmatrix}$ ,

$$\text{where } w_0 = \frac{\tilde{x}^T(X^T w - y)}{\tilde{x}^T \tilde{x} - \tilde{x}^T X^T(XX^T)^{-1}X\tilde{x}}$$

- interpretation:  $w_0 = 0$  if  $X^T w - y = 0$ , i.e., the previous model is enough to get perfect prediction on the data, so no need to add any further new components

# Cross-validation

- Cross-validation is used to avoid any potential bias in the training-validation segmentation
- k-fold cross-validation: equally segment training dataset to k parts, then train on any k-1 parts and test the error on the remaining part



5-fold cross-validation

- For training single model, choose the best model out of the k-fold estimates
- For model selection, find a model family that gives the smallest average k-fold training losses
- Special case:  $k = N$ , known as the *leave-one-out* (LOO) cross-validation
- In the case of LLSE, LOO can be computed in closed form

# Matrix inversion lemma

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- Woodsbury identity: when A and D are invertible
$$(A + BDC^T)^{-1} = A^{-1} - A^{-1}C(D^{-1} + CA^{-1}B^T)^{-1}B^T A^{-1}$$
- Proof: multiply the matrix on both sides
- important special case
  - B=C=z, a vector, D=I
$$(A + zz^T)^{-1} = A^{-1} - (A^{-1}zz^T A^{-1})/(1 + z^T A^{-1}z)$$
  - B=-C=z, a vector, D=I
$$(A - zz^T)^{-1} = A^{-1} + (A^{-1}zz^T A^{-1})/(1 - z^T A^{-1}z)$$
- caching A<sup>-1</sup> and computing the inversion recursively, typical inversion will take O(n<sup>3</sup>), while this special case it is O(n)

# Correlation matrix

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- Data matrix

$$X = \begin{pmatrix} | & | & & | \\ x_1 & x_2 & \cdots & x_N \\ | & | & & | \end{pmatrix}$$

- Correlation matrix  $XX^T = x_1x_1^T + x_2x_2^T + \cdots + x_Nx_N^T$
- Inverse of correlation matrix when adding  $x$

$$(XX^T + xx^T)^{-1} = (XX^T)^{-1} - \frac{(XX^T)^{-1}xx^T(XX^T)^{-1}}{1 + x^T(XX^T)^{-1}x}$$

- Inverse of correlation matrix when removing  $x$

$$(XX^T - xx^T)^{-1} = (XX^T)^{-1} + \frac{(XX^T)^{-1}xx^T(XX^T)^{-1}}{1 - x^T(XX^T)^{-1}x}$$

# Review of over-complete LLSE

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- LLSE objective  $\min_w \|y - X^T w\|^2$
- Solution (over-complete)  $w = (XX^T)^{-1}Xy$
- LS Error at optimum  $y^T y - (Xy)^T (XX^T)^{-1}Xy$
- To prove: the prediction matrix  $A = (I_N - X^T (XX^T)^{-1}X)y$  is idempotent, i.e.,  $AA = A$ , so the LS error  $y^T (I_N - X^T (XX^T)^{-1}X)^T (I_N - X^T (XX^T)^{-1}X)y$  becomes  $y^T y - (Xy)^T (XX^T)^{-1}Xy$

# LOO for LLSE

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- Each LOO pass corresponds to the removal of a particular data point from the data matrix, so correspondingly we can compute the updated parameter and error using matrix inversion lemma
- Parameter

$$\begin{aligned}\hat{w} &= (XX^T - x_i x_i^T)^{-1} (Xy - y_i x_i) \\ &= \left( (XX^T)^{-1} + \frac{(XX^T)^{-1} x_i x_i^T (XX^T)^{-1}}{1 - x_i^T (XX^T)^{-1} x_i} \right) (Xy - y_i x_i) \\ &= w + \frac{x_i^T w - y_i}{1 - x_i^T (XX^T)^{-1} x_i} (XX^T)^{-1} x_i\end{aligned}$$



# LOO for LLSE

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- The prediction on the single data point that is left out is

$$\begin{aligned}y_i - x_i^T \hat{w} &= y_i - x_i^T \left( w + \frac{x_i^T w - y_i}{1 - x_i^T (XX^T)^{-1} x_i} (XX^T)^{-1} x_i \right) \\&= y_i - x_i^T w - \frac{x_i^T w - y_i}{1 - x_i^T (XX^T)^{-1} x_i} x_i^T (XX^T)^{-1} x_i \\&= \frac{y_i - x_i^T w}{1 - x_i^T (XX^T)^{-1} x_i}\end{aligned}$$

- So LSE loss on the single data point that is left out is

$$\frac{(y_i - x_i^T w)^2}{(1 - x_i^T (XX^T)^{-1} x_i)^2}$$

# Overall computation complexity

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- Instead of inverting  $N$  matrices of dimension  $m \times m$ , which will have a time complexity of  $O(Nm^3)$ , the LOO algorithm can compute the inverse of the overall correlation matrix once and reuse it for all LOO objective computation, which leaves a time complexity of  $O(Nm+m^3)$
- Averaging LOO LSE loss can be used to choose from different model families, e.g., when fitting data, this will be polynomials of different degrees

# Summary

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- Incremental LLSE model selection based on LOO error
  - For each degree  $d = 1, \dots, D$ :
    - Compute optimal parameter using incremental LLSE  $w_d$
    - Compute LOO error using  $w_d$
  - Select the optimal model with the minimum LOO error