CSE 486/586 Distributed Systems
Time and Synchronization

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Last Time

- Models of Distributed Systems
  - Synchronous systems
  - Asynchronous systems
- Failure detectors---why?
  - Because things do fail.
- Failure detectors---what?
  - Properties: completeness & accuracy
  - Cannot have a perfect failure detector
  - Metrics: bandwidth, detection time, scale, accuracy
- Failure detectors---how?
  - Two processes: Heartbeating and Ping
  - Multiple processes: Centralized, ring, all-to-all

Today's Question

- The topic of time
  - Today and next time
- Why?
  - Need to know when things happen
  - One of the fundamental challenges
- What?
  - Ideally, we'd like to know when exactly something happened.
- How?
  - Let's see!

Today's Question

- Servers in the cloud need to timestamp events
- Server A and server B in the cloud can have different clock values.
  - The cloud has server A and server B that service customers.
  - You try to purchase an airline ticket online via the cloud.
  - It's the last airline ticket available on that flight.
  - Server A timestamps your attempt at 9h:15m:32.45s.
  - Server B timestamps someone else's attempt at 9h:20m:22.76s.
  - Who should get the ticket?
  - What if Server A's clock was > 10 minutes ahead of server B's clock? Behind?
  - How would you know what the difference was at those times?

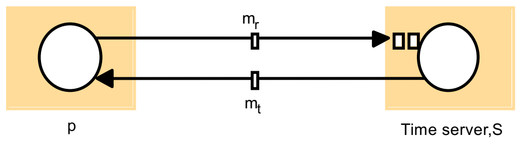
Physical Clocks & Synchronization

- Some definitions: Clock Skew versus Drift
  - Clock Skew = Relative Difference in clock *values* of two processes
  - Clock Drift = Relative Difference in clock *frequencies (rates)* of two processes
- *A non-zero clock drift will cause skew to continuously increase.*
- Real-life examples
  - Ever had "make: warning: Clock skew detected. Your build may be incomplete."?
  - It's reported that in the worst case, there's 1 sec/day drift in modern HW.
  - Almost all physical clocks experience this.

Synchronizing Physical Clocks

- $C_i(t)$: the reading of the software clock at process *i* when the real time is *t*.
- External synchronization: For a synchronization bound *D>0*, and for source S of UTC time,
  $$|S(t) - C_i(t)| < D,$$
  for *i=1,2,...,N* and for all real times *t*.
  Clocks C_i are accurate to within the bound *D*.
- Internal synchronization: For a synchronization bound *D>0*,
  $$|C_i(t) - C_j(t)| < D$$
  for *i, j=1,2,...,N* and for all real times *t*.
  Clocks C_i agree within the bound *D*.
- External synchronization with *D* $\Rightarrow$ Internal synchronization with *2D*
- Internal synchronization with D $\Rightarrow$ External synchronization with ??

Clock Synchronization Using a Time Server



- Client: “What time is it?”
- Server: “It’s *t*.”
- Any difficulty?

Cristian’s Algorithm

- Uses a *time server* to synchronize clocks
- Mainly designed for LAN
- Time server keeps the reference time (say UTC)
- A client asks the time server for time, the server responds with its current time *T*, and the client uses the received value T to set its clock
- But network round-trip time introduces an error.
- So what do we need to do?
  - Estimate one-way delay

Cristian’s Algorithm

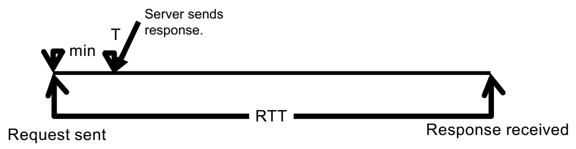
- Let *RTT* = *response-received-time – request-sent-time* (measurable at client)
- Also, suppose we know
  - The minimum value *min* of the client-server one-way transmission time [Depends on what?] (to simplify our discussion, let’s say there’s a single min)
  - That the server timestamped the message at the last possible instant before sending it back
- Ideally, the client should set its time to: T + (one-way latency from the server to the client)

Cristian’s Algorithm

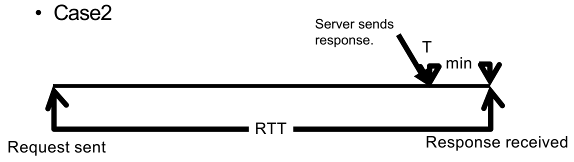
- But we don’t know the one-way latency from the server to the client.
- When the client receives the time (T) from the server, T can be in a range of possible values.
- Consider two extreme cases.

Cristian’s Algorithm

- Case 1

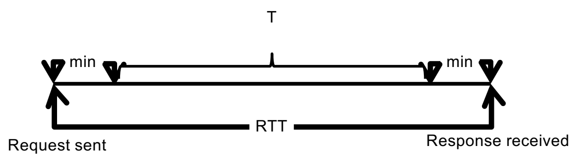


- Case2



Cristian’s Algorithm

- Server time T could be in the following range.



- When the client receives the time (T) from the server, the actual time that the client should set could be between [T + min, T + RTT - min]

Cristian's Algorithm

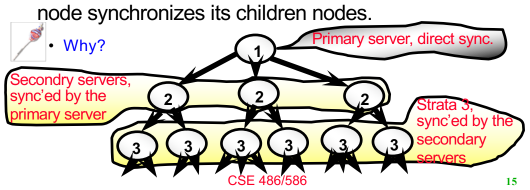
- (From the previous slide), the accuracy is: +-(RTT/2 – min)
- Cristian's algorithm
  - A client asks its time server.
  - The time server sends its time *T*.
  - The client estimates the one-way delay and sets its time.
    - » It uses T + RTT/2
- Want to improve accuracy?
  - Take multiple readings and use the minimum RTT → tighter bound
  - For unusually long RTTs, ignore them and repeat the request → removing outliers

CSE 486/586 Administrivia

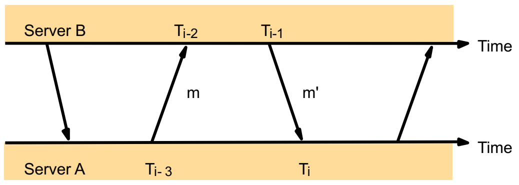
- Please start PA2-A.
- Grades will go to UBlearns. Will post grades for PA1 probably early next week.
- Please use Piazza; all announcements will go there.

The Network Time Protocol (NTP)

- Uses a network of time servers to synchronize all processes on a network.
- Designed for the Internet
  - Why not Christian's algo.?
- Time servers are connected by a synchronization subnet tree. The root is in touch with UTC. Each node synchronizes its children nodes.
  - Why?

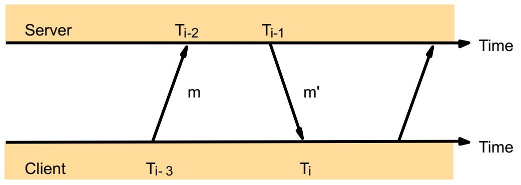

Primary server, direct sync.
1
Secondry servers, sync'ed by the primary server
2
2
2
Strata 3, sync'ed by the secondary servers
3
3
3
3
3
3

Messages Exchanged Between a Pair of NTP Peers ("Connected Servers")



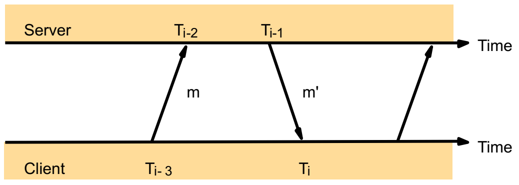
- Each message bears timestamps of recent message events: the local time when the previous NTP message was sent and received, and the local time when the current message was transmitted.

The Protocol



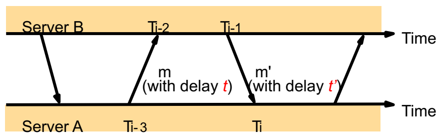
- Compute round-trip delay: $(T_i – T_{i-3}) – (T_{i-1} – T_{i-2})$
- Take the half of the round-trip delay as the one-way estimate: $((T_i – T_{i-3}) – (T_{i-1} – T_{i-2}))/2$

The Protocol



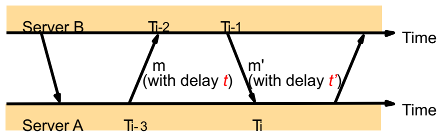
- Compute offset: T_{i-1} + (one-way estimate) - $T_i = ((T_{i-2} – T_{i-3}) + (T_{i-1} – T_i))/2$
- Get this offset with not just one server, but multiple servers.
- Do some statistical analysis, remove outliers, and apply a data filtering algorithm.

Theoretical Base for NTP



- o_i: estimate of the actual offset between the two clocks
- d_i: estimate of the bounds of o_i ; total transmission times for *m* and *m'*; $d_i=t+t'$

Theoretical Base for NTP



First, let's get o :

$$T_{i-2} = T_{i-3} + t + o$$

$$T_i = T_{i-1} + t' - o$$

$$\Rightarrow o = (T_{i-2} - T_{i-3} + T_{i-1} - T_i)/2 + (t' - t)/2$$

Then, get the bound for $(t' - t)/2$:

$$-t' - t \le t' - t \le t' + t \text{ (since } t', t \ge 0)$$

Finally, we set :

$$o_i = (T_{i-2} - T_{i-3} + T_{i-1} - T_i)/2$$

$$d_i = t + t' = T_{i-2} - T_{i-3} + T_i - T_{i-1}$$

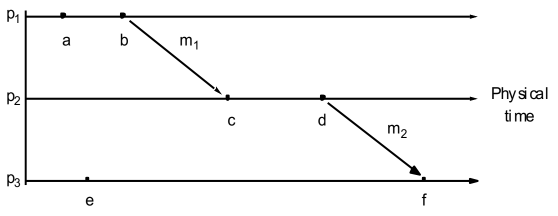
Then we get :

$$o_i - d_i/2 \le o \le o_i + d_i/2.$$

Then a Breakthrough…

- We cannot sync multiple clocks perfectly.
- Thus, if we want to order events happened at different processes (remember the ticket reservation example?), we cannot rely on physical clocks.
- Then came logical time.
  - First proposed by Leslie *Lamport* in the 70's
  - Based on causality of events
  - Defined relative time, not absolute time
- Critical observation: time (ordering) only matters if two or more processes interact, i.e., send/receive messages.

Events Occurring at Three Processes



Summary

- Time synchronization important for distributed systems
  - Cristian's algorithm
  - NTP
- Relative order of events enough for practical purposes
  - Lamport's logical clocks
- Next: continue on logical clocks

Acknowledgements

- These slides contain material developed and copyrighted by Indranil Gupta at UIUC.