# CSE 486/586 Distributed Systems Mutual Exclusion

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#### **Recap: Consensus**

- · On a synchronous system
  - There's an algorithm that works.
- On an asynchronous system
  - It's been shown (FLP) that it's impossible to guarantee.
- · Getting around the result
  - Masking faults
  - Using failure detectors
  - Still not perfect
- · Impossibility Result
  - Lemma 1: schedules are commutative
  - Lemma 2: some initial configuration is bivalent
  - Lemma 3: from a bivalent configuration, there is always another bivalent configuration that is reachable.

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# Why Mutual Exclusion?

- Bank's Servers in the Cloud: Think of two simultaneous deposits of \$10,000 into your bank account, each from one ATM connected to a different server
  - Both ATMs read initial amount of \$1000 concurrently from the bank's cloud server
  - Both ATMs add \$10,000 to this amount (locally at the ATM)
  - Both write the final amount to the server
  - What's wrong?

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# **Why Mutual Exclusion?**

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  - Both write the final amount to the server
  - What's wrong?
- The ATMs need mutually exclusive access to your account entry at the server (or, to executing the code that modifies the account entry)

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#### **Mutual Exclusion**

- Critical section problem
  - Piece of code (at all clients) for which we need to ensure there is at most one client executing it at any point of time.
- · Solutions:
  - Semaphores, mutexes, etc. in single-node OS
  - We'll see the solutions for distributed systems.
- Mutual exclusion requirements:
  - Safety At most one process/thread may execute in CS at any time
  - Liveness Every request for a CS is eventually granted
  - Ordering (desirable) Requests are granted in the order they were made

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#### **Mutexes**

• To synchronize access of multiple threads to common data structures

Allows two operations:

lock()

while true: // each iteration atomic

if lock not in use:

label lock in use

unlock()

label lock not in use

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# **Semaphores**

- · To synchronize access of multiple threads to common data structures
- · Semaphore S=1;
  - Allows two operations
  - wait(S) (or P(S)): while(1){ // each execution of the while loop is atomic if (S > 0) S--: break;
  - signal(S) (or V(S)):
    - S++
  - Each while loop execution and S++ are each atomic

#### **How Are Mutexes Used?**

mutex L= UNLOCKED;

unlock(L); // exit

extern mutex L;

lock(L); // enter

ATM2

ATM1

lock(L); // enter // critical section obtain bank amount: add in deposit;

update bank amount;

// critical section obtain bank amount: add in deposit; update bank amount; unlock(L); // exit

# **Assumptions/System Model**

- · For all the algorithms studied, we make the following assumptions:
  - Each pair of processes is connected by reliable channels (such as TCP)
  - Messages are eventually delivered to recipients' input buffer in FIFO order.
  - Processes do not fail
- · Four algorithms
  - Centralized control
  - Token ring
  - Ricart and Agrawala
  - Maekawa

# **Distributed Mutual Exclusion Performance Criteria**

- Bandwidth: the total number of messages sent in each entry and exit operation.
- Client delay: the delay incurred by a process at each entry and exit operation (when no other process is in, or waiting)
  - (We will look at mostly the entry operation as exit costs are typically lower.)
- Synchronization delay: the time interval between one process exiting the critical section and the next process entering it (when there is only one process
- These translate into throughput the rate at which the processes can access the critical section, i.e., x processes per second.
- · This is in addition to safety, liveness, and ordering.

#### 1. Centralized Control

- A central coordinator (master or leader)
  - Is elected (next lecture)
  - Grants permission to enter CS & keeps a queue of requests to
  - Ensures only one process at a time can access the CS
  - Has a special token per CS
- · Operations (token gives access to CS)
  - To enter a CS Send a request to the coord & wait for token.
  - On exiting the CS Send a message to the coord to release the
  - Upon receipt of a request, if no other process has the token, the coord replies with the token; otherwise, the coord queues the
  - Upon receipt of a release message, the coord removes the oldest entry in the queue (if any) and replies with a token.

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#### 1. Centralized Control

- · Safety, liveness, ordering?
- · Bandwidth?
  - Requires 3 messages per entry + exit operations combined.
- Client delay:
  - one round trip time (request + grant)
- Synchronization delay
  - one round trip time (release + grant)
- The coordinator becomes performance bottleneck and single point of failure.

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2

# 2. Token Ring Approach Processes are organized in a logical ring: pi has a communication channel to p(i+1)mod (n). Operations: Only the process holding the token can enter the CS. To enter the critical section, wait passively for the token. When in CS, hold on to the token. To exit the CS, the process sends the token onto its neighbor. If a process does not want to enter the CS when it receives the token, it forwards the token to the next neighbor. Features: Safety & liveness, ordering? Bandwidth, client delay, sync. delay? Bandwidth; 1 message per exit Client delay: 0 to N message transmissions. Synchronization delay between one process's exit from the CS and the next process's entry is between 1 and N-1 message transmissions.

#### CSE 486/586 Administrivia

- PA2-B due on Friday next week (3/15)
  - Please do not use someone else's code!
- Midterm on Wednesday (3/13)
  - Cheat sheet allowed (letter-sized, front-and-back, 1-page)
  - Multiple choices

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36

# 3. Ricart & Agrawala's Algorithm

- Processes requiring entry to critical section multicast a request, and can enter it only when all other processes have replied positively.
- · Use the Lamport clock and process id for ordering
  - Messages requesting entry are of the form <T,pi>, where T is the sender's timestamp (Lamport clock) and pi the sender's identity (used to break ties in T).

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15

# 3. Ricart & Agrawala's Algorithm

- · To enter the CS
  - set state to wanted
  - multicast "request" to all processes (including timestamp)
  - wait until all processes send back "reply"
  - change state to held and enter the CS
- On receipt of a request <Ti, pi> at pj:
  - if (state = held) or (state = wanted & (Tj, pj)<(Ti,pi)), enqueue request
  - else "reply" to pi
- · On exiting the CS
  - change state to release and "reply" to all queued requests.

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36

3

# 3. Ricart & Agrawala's Algorithm

On initialization state := RELEASED; To enter the section state := WANTED; Multicast request to all processes; T := request's timestamp; Wait until (number of replies received = (N-1)); state := HELD; On receipt of a request < T,  $p_i > at p_i (i \neq j)$  if  $(state = \text{HELD or } (state = \text{WANTED } and (T, p_i) < (T_i, p_i)))$  then queue request from  $p_i$  without replying; else reply immediately to  $p_i$ ; end if To exit the critical section state := RELEASED; reply to any queued requests;

3. Ricart & Agrawala's Algorithm

Algorithm

Reply

Reply

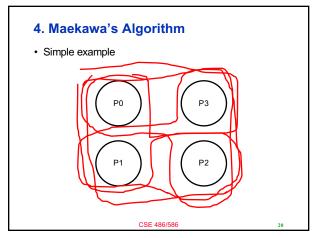
Algorithm

# Analysis: Ricart & Agrawala

- · Safety, liveness, and ordering?
- · Bandwidth:
  - 2(N-1) messages per entry operation
  - N-1 unicasts for the multicast request + N-1 replies
  - N-1 unicast messages per exit operation
- · Client delay
  - One round-trip time
- · Synchronization delay
  - One message transmission time

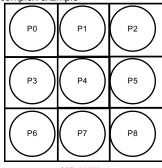
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19



# 4. Maekawa's Algorithm

· A more complex example



6

# 4. Maekawa's Algorithm

- · Observation: no need to have all peers reply
- Only need to have a subset of peers as long as all subsets overlap.
- Voting set: a subset of processes that grant permission to enter a CS
- Voting sets are chosen so that for any two processes, p<sub>i</sub> and p<sub>j</sub>, their corresponding voting sets have at least one common process.
  - Each process p<sub>i</sub> is associated with a voting set v<sub>i</sub> (of processes)
  - Each process belongs to its own voting set
  - The intersection of any two voting sets is non-empty
  - Each voting set is of size K
  - Each process belongs to M other voting sets

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#### 4. Maekawa's Algorithm

- Multicasts messages to a (voting) subset of processes
  - To access a critical section,  $\textbf{p}_i$  requests permission from all other processes in its own voting set  $\textbf{v}_i$
  - Voting set member gives permission to only one requestor at a time, and queues all other requests
  - Guarantees safety
  - Maekawa showed that K=M= $\sqrt{N}$  works best
  - One way of doing this is to put N processes in a  $\sqrt{N}$  by  $\sqrt{N}$  matrix and take union of row & column containing  $p_i$  as its voting set.

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23

# Maekawa's Algorithm - Part 1

```
On initialization
state := RELEASED;
voted := FALSE;
For p. to enter the critical section
state := WANTED;
Multicast request to all processes in V;
Wait until (number of replies received = K);
state := HELD;
On receipt of a request from p: at p;
if (state = HELD or voted = TRUE)
then
queue request from p: without replying;
else
send reply to p;
voted := TRUE;
end if
Continues on
next slide
```

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# Maekawa's Algorithm - Part 2

```
For p, to exit the critical section
state := RELEASED;
Multicast release to all processes in V;
On receipt of a release from p; at p;
if (queue of requests is non-empty)
then
remove head of queue – from pk, say;
send reply to pk;
woted := TRUE;
else
woted := FALSE;
end if
```

# Maekawa's Algorithm - Analysis

- Bandwidth:  $2\sqrt{N}$  messages per entry,  $\sqrt{N}$  messages per exit
  - Better than Ricart and Agrawala's (2(N-1) and N-1 messages)
- · Client delay: One round trip time
  - Same as Ricart and Agrawala
- Synchronization delay: One round-trip time
  - Worse than Ricart and Agrawala
- May not guarantee liveness (may deadlock)
  - How?

P1 P2

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# **Summary**

- Mutual exclusion
  - Coordinator-based token
  - Token ring
  - Ricart and Agrawala's timestamp algorithm
  - Maekawa's algorithm

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# **Acknowledgements**

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C 5