Complex Pipelining: Motivation

Pipelining becomes complex when we want high performance in the presence of:

- Long latency or partially pipelined floating-point units
- Memory systems with variable access time
- Multiple arithmetic and memory units

Floating-Point Unit (FPU)

Much more hardware than an integer unit

Single-cycle FPU is a bad idea - why?

- it is common to have several FPU's
- it is common to have different types of FPU's
  
- an FPU may be pipelined, partially pipelined or not pipelined

To operate several FPU's concurrently the FP register file needs to have more read and write ports

Functional Unit Characteristics

<table>
<thead>
<tr>
<th></th>
<th>Fully Pipelined</th>
<th>Partially Pipelined</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cycles per Instruction</td>
<td>1 cycle</td>
<td>2 cycles</td>
</tr>
</tbody>
</table>

Functional units have internal pipeline registers

- operands are latched when an instruction enters a functional unit
- inputs to a functional unit (e.g., register file) can change during a long latency operation

Floating-Point ISA

Interaction between the floating-point datapath and the integer datapath is determined largely by the ISA

MIPS ISA

- separate register files for FP and Integer instructions
  - the only interaction is via a set of move instructions (some ISA's don't even permit this)
  - separate load/store for FPR's and GPR's but both use GPR's for address calculation
  - separate conditions for branches
  - FP branches are defined in terms of condition codes
Realistic Memory Systems

Common approaches to improving memory performance:
- Caches: single cycle except in case of a miss → stall
- Interleaved memory: multiple memory accesses → bank conflicts
- Split-phase memory operations (separate memory request from response) → out-of-order responses

Latency of access to the main memory is usually much greater than one cycle and often unpredictable.

Solving this problem is a central issue in computer architecture.

Complex Pipeline Control Issues

- Structural conflicts at the execution stage if some FPU or memory unit is not pipelined and takes more than one cycle
- Structural conflicts at the write-back stage due to variable latencies of different functional units
- Out-of-order write hazards due to variable latencies of different functional units
- How to handle exceptions?

In-Order Superscalar Pipeline

- Fetch two instructions per cycle; issue both simultaneously if one is integer/memory and other is floating point
- Inexpensive way of increasing throughput, examples include Alpha 21064 (1992) & MIPS R5000 series (1996)
- Same idea can be extended to wider issue by duplicating functional units (e.g. 4-issue UltraSPARC) but regfile ports and bypassing costs grow quickly

Types of Data Hazards

Consider executing a sequence of

<table>
<thead>
<tr>
<th>Type of Hazards</th>
<th>Operands</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data-dependence</td>
<td>$r_3 \leftarrow r_1 \text{ op } r_2$</td>
<td>Read-after-Write (RAW) hazard</td>
</tr>
<tr>
<td>Anti-dependence</td>
<td>$r_1 \leftarrow r_3 \text{ op } r_4$</td>
<td>Write-after-Read (WAR) hazard</td>
</tr>
<tr>
<td>Output-dependence</td>
<td>$r_5 \leftarrow r_1 \text{ op } r_2$</td>
<td>Write-after-Write (WAW) hazard</td>
</tr>
</tbody>
</table>
Register vs. Memory Dependence

Data hazards due to register operands can be determined at the decode stage but data hazards due to memory operands can be determined only after computing the effective address

\[
\text{store} \quad M[r_1 + \text{disp1}] \leftarrow r_2 \\
\text{load} \quad r_3 \leftarrow M[r_4 + \text{disp2}] 
\]

Does \((r_1 + \text{disp1}) = (r_4 + \text{disp2})\) ?

Data Hazards: An Example

<table>
<thead>
<tr>
<th>I</th>
<th>DIVD</th>
<th>f6, f6, f4</th>
<th>Latency</th>
</tr>
</thead>
<tbody>
<tr>
<td>I1</td>
<td>DIVD</td>
<td>f6, f6, f4</td>
<td>4</td>
</tr>
<tr>
<td>I2</td>
<td>LD</td>
<td>f2, 45(r3)</td>
<td>1</td>
</tr>
<tr>
<td>I3</td>
<td>MULTD</td>
<td>f0, f2, f4</td>
<td>3</td>
</tr>
<tr>
<td>I4</td>
<td>DIVD</td>
<td>f8, f6, f2</td>
<td>4</td>
</tr>
<tr>
<td>I5</td>
<td>SUBD</td>
<td>f10, f0, f6</td>
<td>1</td>
</tr>
<tr>
<td>I6</td>
<td>ADDD</td>
<td>f6, f8, f2</td>
<td>1</td>
</tr>
</tbody>
</table>

Valid orderings: 
in-order \(I_1, I_2, I_3, I_4, I_5, I_6\) 
out-of-order \(I_2, I_3, I_4, I_5, I_6\)

Out-of-order Completion

<table>
<thead>
<tr>
<th></th>
<th>DIVD</th>
<th>f6, f6, f4</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>I1</td>
<td>DIVD</td>
<td>f6, f6, f4</td>
<td>Latency</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I2</td>
<td>LD</td>
<td>f2, 45(r3)</td>
<td>4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I3</td>
<td>MULTD</td>
<td>f0, f2, f4</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I4</td>
<td>DIVD</td>
<td>f8, f6, f2</td>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I5</td>
<td>SUBD</td>
<td>f10, f0, f6</td>
<td>4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I6</td>
<td>ADDD</td>
<td>f6, f8, f2</td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

in-order comp \(1, 2, 3, 4, 5, 6\) 
out-of-order comp \(1, 2, 3, 4, 5, 6, 7\)

CSE 490/590 Administrivia

- Midterm on Friday, 3/4
- Review on Wednesday, 3/2
- Project 1 deadline: Friday, 3/11
- CSE machines are available for projects
  - Thin clients & SSH only for simulation
  - Linux & Windows machines @ 216 Bell for board
- Office hours will be posted again.
  - At least next week, it'll be Wed after class until 2pm.

CDC 6600

- Seymour Cray, 1963
- A fast pipelined machine with 60-bit words
- 128 Kword main memory capacity, 32 banks
- Ten functional units (parallel, unpipelined)
- Floating Point: adder, 2 multipliers, divider
- Integer: adder, 2 incrementers, ...
- Hardwired control (no microcoding)
- scoreboard for dynamic scheduling of instructions
- Ten Peripheral Processors for Input/Output
  - a fast multi-threaded 12-bit integer ALU
- Very fast clock, 10 MHz (FP add in 4 clocks)
- >400,000 transistors, 750 sq. ft., 5 tons, 150 kW, novel freon-based technology for cooling
- Fastest machine in world for 5 years (until 7600)
  - over 100 sold ($7-10M each)
IBM Memo on CDC6600

Thomas Watson Jr., IBM CEO, August 1963:

“Last week, Control Data ... announced the 6600 system. I understand that in the laboratory developing the system there are only 34 people including the janitor. Of these, 14 are engineers and 4 are programmers... Contrasting this modest effort with our vast development activities, I fail to understand why we have lost our industry leadership position by letting someone else offer the world’s most powerful computer.”

To which Cray replied: “It seems like Mr. Watson has answered his own question.”

CDC 6600: Datapath

- 128K words, 32 banks, 1 µs cycle
- 10 Functional Units
- Central Memory
- Instruction Stack
- Operator Registers
- Address Registers
- Index Registers

CDC6600 ISA designed to simplify high-performance implementation

- Use of three-address, register-register ALU instructions simplifies pipelined implementation
  - No implicit dependencies between inputs and outputs
- Decoupling setting of address register (Ar) from retrieving value from data register (Xr) simplifies providing multiple outstanding memory accesses
  - Software can schedule load of address register before use of value
  - Can interleave independent instructions inbetween
- CDC6600 has multiple parallel but unpipelined functional units
  - E.g., 2 separate multipliers
- Follow-on machine CDC7600 used pipelined functional units
  - Foreshadows later RISC designs

When is it Safe to Issue an Instruction?

Suppose a data structure keeps track of all the instructions in all the functional units

- Can we solve write hazards without equalizing all pipeline depths and without bypassing?

Complex Pipeline

- IF
- ID
- Issue
- GPR’s
- FPR’s
- ALU
- Mem
- Fadd
- Fmul
- Fdiv
- WB

CDC 6600: A Load/Store Architecture

- Separate instructions to manipulate three types of reg.
  - 60-bit data registers (X)
  - 18-bit address registers (A)
  - 18-bit index registers (B)
- All arithmetic and logic instructions are reg-to-reg
  - opcode [i] [j] [k] Ri ← (Rj) op (Rk)
- Only Load and Store instructions refer to memory!
  - opcode [i] [j] disp Ri ← M[(Rj) + disp]

Touching address registers 1 to 5 initiates a load
6 to 7 initiates a store
- very useful for vector operations
A Data Structure for Correct Issues
Keeps track of the status of Functional Units

<table>
<thead>
<tr>
<th>Name</th>
<th>Busy</th>
<th>Op</th>
<th>Dest</th>
<th>Src1</th>
<th>Src2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Int</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mem</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Add1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Add2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Add3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mult1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mult2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The instruction i at the Issue stage consults this table:
- FU available?: check the busy column
- RAW?: search the dest column for i’s sources
- WAR?: search the source columns for i’s destination
- WAW?: search the dest column for i’s destination

An entry is added to the table if no hazard is detected;
An entry is removed from the table after Write-Back

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