# CSE462/562: Database Systems (Spring 24) Lecture 9: Single-table query processing (Part 1) 4/1/2024



Last updated: 3/19/2024

## Reminders

- The next lecture on 4/8 will be remote due to the solar eclipse
  - Live streaming from Knox 104
  - Please join through Panopto
    - <u>https://ub.hosted.panopto.com/Panopto/Pages/Viewer.aspx?id=d5b61364-381a-4596-8f26-b0f20148c17a</u>
  - Project 3 is due today, 23:59 PM EDT
  - Project 4 to be released tomorrow, due on 4/15/2024, 23:59 PM EDT

## Single-table queries

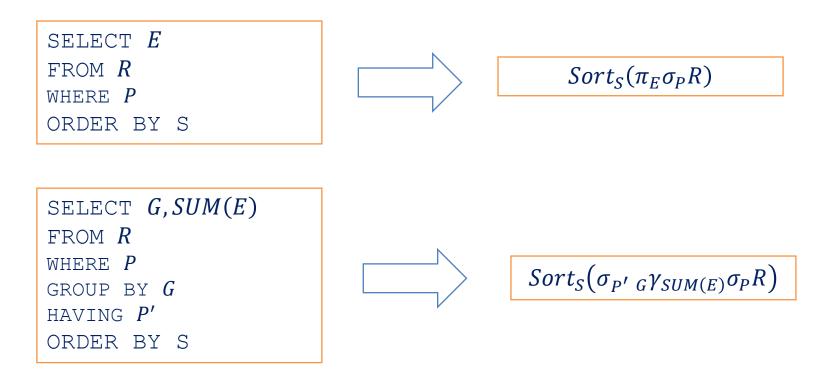
- We'll start with the simplest single-table queries w/o or w/ aggregations
  - How to translate it into a query plan?
  - How to implement each operator?
  - How to measure the cost of each operator?

SELECT <i>E</i>	
from <i>R</i>	
WHERE P	
ORDER BY	S

SELECT G,SUM(E)		
FROM R		
WHERE P		
GROUP BY $G$		
HAVING $P'$		
ORDER BY S		

# SQL -> logical plan

- We'll start with the simplest single-table queries w/o or w/ aggregations
  - How to translate it into a query plan?
  - How to implement each operator?
  - How to measure the cost of each operator?



# Logical plan -> physical plan

- We'll start with the simplest single-table queries w/o or w/ aggregations
  - How to translate it into a query plan?
  - How to implement each operator?
  - How to measure the cost of each operator?

- A few basic operators
  - Selection:  $\sigma$
  - Projection:  $\pi$  (w/ and w/o deduplication)
  - Aggregation:  $\gamma$  w/o or w/ group by
  - Set operators: U, −,∩
  - Sorting (later lectures)
  - Cartesian product: × or Join: ⋈ (later lectures)
- Question: what are the alternatives? How to evaluate their efficiency?

## Measuring cost

- We'll start with the simplest single-table queries w/o or w/ aggregations
  - How to translate it into a query plan?
  - How to implement each operator?
  - How to measure the cost of each operator?
- For disk-based systems, we mainly measure the number of I/Os
  - Differences between random I/O and sequential I/O
  - Faster storage -> also need to measure the CPU cost
- A simple cost model
  - $t_T$ : average time to transfer a page of data (data transfer time)
  - $t_S$ : average time to randomly seek data (seek time + rotation delay)
    - For SSD, time overhead for initiating an I/O request
  - Cost =  $B \times t_T + S \times t_S$ 
    - *B*: number of pages read/written; *S*: number of random I/O

Typical  $t_T$  and  $T_S$ 

	HDD*	SSD†
$t_T$ (ms)	0.1	0.01
<i>t<sub>s</sub></i> (ms)	4	0.09

Data from DB Concept book (Ch. 15.2). Assuming 4KB pages.

- \* typical HDD with 40 MB/s transfer rate,
- 15000 rpm disk in 2018
- <sup>+</sup> typical SATA SSD that supports 10K IOPS (QD-

1), 400 MB/s sequential read rate

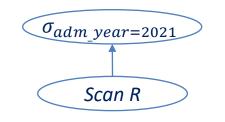
#### Measuring cost

- Other assumptions
  - Ignoring the buffer effect for random pages
    - Do consider the private workspace size *M* for the operators
  - Omitting the cost of transferring output to the user/disk
    - Common to any equivalent plan
- Notations: for relation *R* 
  - $T_R$ : number of records,  $N_R$ : number of pages in its heap file,  $B_R$ : (average) number of tuples per page
  - $h_I$ : height of a B-tree index I over the file
  - *M*: private workspace size in pages
- Running example
  - $t_S = 4 ms$ ,  $t_T = 0.1 ms$ , 4000-byte page
  - Student: R(sid: int, name: varchar(19), login: varchar(19), major: char(2), adm\_year: int)
    - 50 bytes/tuple,  $B_R = 80$ ,  $T_R = 40,000$ ,  $N_R = 500$
  - Enrollment: E(sid: int, semester: char(3), cno: int, grade: double)
    - 20 bytes/tuple,  $B_E = 200$ ,  $T_E = 200,000$ ,  $N_E = 1000$

#### Selection $\sigma$

- Scan is usually the leaf-level of logical plans
  - Represents reading an entire relation -- not really a relational operator
- Selection  $\sigma_P Q$ 
  - *P* is usually conjunctions or disjunctions *Q*. *attr op value* but can also be User-Defined Functions (UDF)
  - selects records satisfying some predicate from the child
  - Child may be a scan or some other operators
  - Many possible implementation of selection depending on
    - the predicate **P**
    - the available file/index for the scan

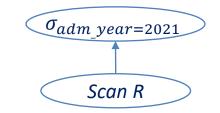
op is an operator: <, <=, =, <>, >, >=, ...





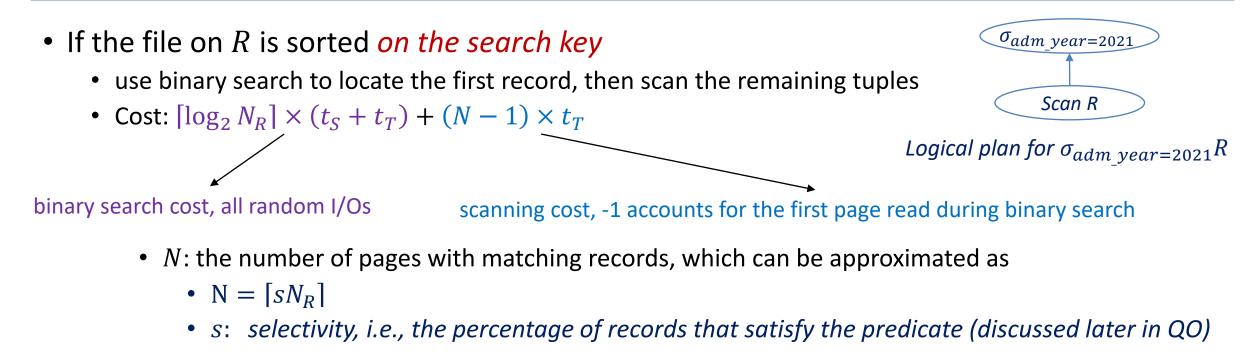
# Simple selection: linear scan

- Consider a simple selection  $\sigma_{R.attr op value} R$ 
  - Assume that the child is a relation stored in some disk file/index
- Most straight-forward implementation is linear scan
  - Scan each page and each record on the page
    - emits a record only if the predicate *R*. *attr op value* evaluates to true
  - Applies to any predicate *P* or file
  - Also works for pipelining -- can do selection on the fly without writing temporary files
- Cost:  $t_S + N_R \times t_T$ 
  - 1 seek to the start of the file and  $N_R$  pages to read
  - the "last resort" -- usually the slowest implementation
  - cost for  $\sigma_{adm\_year=2021} R: t_S + 500 \times t_T = 54 ms$



Logical plan for  $\sigma_{adm \ year=2021}R$ 

## Simple selection: binary search on sorted file



- Running example: suppose R is sorted on  $adm_year$  and selectivity is s = 10%
  - $cost = [log_2 500] \times (t_S + t_T) + ([0.1 \times 500] 1) * t_T = 41.8 ms$

## Simple selection: index scan

T: # of matching recordsF: # of data entries per leaf pageN: # of pages with matching records

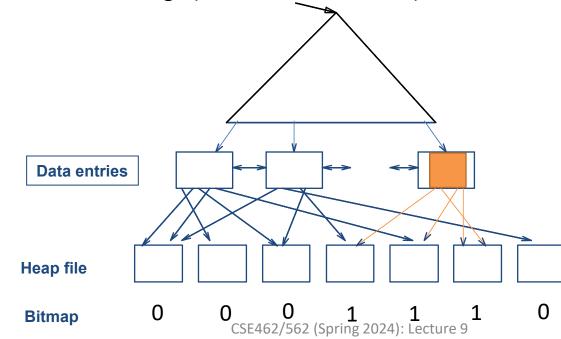
- If the file has a B-Tree index I over the search key, assuming alternative 2 for data entries
  - cost varies depending on whether it's clustered
- Assuming selectivity is s = 0.1, the number of matching records is T and the number of pages with matching records is N, assume h = 3
  cost =
  - $h_I \times (t_T + t_S)$  for finding qualifying data entries +
  - cost for retrieving the heap records
    - clustered:  $t_S + N \times t_T \approx t_S + [sN_R] \times t_T$  (total = 12.3 + 9 = 21.3 ms)

• unclustered: 
$$\left(\left[\frac{T}{F}\right] - 1\right) \times t_T + T \times (t_T + t_S)$$
  
=  $\left(\left[\frac{[sT_R]}{F}\right] - 1\right) \times t_T + [sT_R] \times (t_T + t_S)$  (total = 12.3 + 16401.3 = 16413.3 ms)

• can we do better?

# Simple selection: index scan (cont'd)

- Refinement for unclustered index scan: bitmap index scan
  - 1. Initialize a bitmap with one bit for each page in the file (usually fits in mem even for a large file)
  - 2. Find the first qualifying data entry
  - 3. Scan all the data entries and mark all the unique pages with the matching records in the bitmap
  - 4. Scan all the pages with bit 1 (linear scan on page)
- Alternative: collect all RID in memory in step 3, sort and fetch tuples in RID order
  - more expensive unless RIDs fit in memory
  - might make sense for faster storage (thus CPU cost matters)



# Simple selection: index scan (cont'd)

*T*: # of matching records *F*: # of data entries per leaf page N: # of pages with matching records

- Cost of bitmap index scan =
  - (tree search)  $h \times (t_{s} + t_{T}) +$
  - (scan of data entries)  $\left(\left[\frac{T}{r}\right] 1\right) \times t_T$  + (assuming leaf level is consecutive from bulk loading)
  - (scan of data pages)  $N \times (t_S + t_T)$  (when N is small and thus most involve random seeks) or  $t_S + N \times t_T$  (when N is close to  $N_R$  and it's close to sequential scan)
- Example 1 (large selectivity): s = 0.9, F = 300,  $T = [sT_R] = 36000$ ,  $N = 500 \Rightarrow$  $cost = 4.1 \times 3 + 0.1 \times \left( \left[ \frac{36000}{300} \right] - 1 \right) + 4 + 0.1 \times 500 = 78.2 \text{ ms (unclustered)} \\ vs 4.1 \times 3 + 4 + 0.1 \times [0.9 \times 500] = 61.3 \text{ ms (clustered)}$
- Example 2 (moderate selectivity): s = 0.1, F = 300,  $T = [sT_R] = 4000$ ,  $E[N] \approx 500$  (think: why?)  $cost = 4.1 \times 3 + 0.1 \times \left( \left[ \frac{4000}{300} \right] - 1 \right) + 4 + 0.1 \times 500 = 67.6 \text{ ms} \text{ (unclustered)}$ vs  $4.1 \times 3 + 4 + 0.1 \times [0.1 \times 500] = 21.3 ms$  (clustered)
- Example 3 (small selectivity): s = 0.0001, F = 300,  $T = [sT_R] = 4$ , N = 4 $cost = 4.1 \times 3 + 0.1 \times ([\frac{4}{200}] - 1) + 4.1 \times 4 = 28.7 ms$  (unclustered) vs  $4.1 \times 3 + 4 + 0.1 \times [0.0001 \times 500] = 16.4 ms$  (clustered)
- Trade-offs:
  - Only slightly more expensive than a linear scan when selectivity is close to 1
  - Only slightly more expensive than a regular secondary index scan when selectivity is close to 0 (<< linear scan)
  - Only works poorly when the selectivity is moderate -- better off with clustered index
    - To show that, let  $I_i = 1$  if page i has any matching record (an indicator variable) and assume uniform distribution in search key

• 
$$E[N] = \sum_{1 \le i \le N_R} E[I_i] = \sum_{1 \le i \le N_R} \Pr\{I_i = 1\} = N_R (1 - (1 - s)^{B_R})$$

## **General selection predicates**

- Atom predicate: *attr op value* or UDF
- General predicates:
  - Conjunction ∧ (and), disjunction ∨ (or), negation ¬ (not) of atoms or general predicates
  - e.g.,  $\sigma_{(adm_year \ge 2019 \lor major = 'CS') \land sid \ge 1000}R$
- Most general cases can always be handled by linear scans
  - Slow!
- Optimization for special cases:
  - Conjunction of simple selection predicates  $\theta_1 \wedge \theta_2 \wedge \cdots \wedge \theta_r$ 
    - where  $\theta_i$  is an atom
  - Disjunction of selection predicates  $\theta_1 \vee \theta_2 \vee \cdots \vee \theta_r$
  - Transforming a predicate *P* into *Conjunctive Normal Form (CNF)* or *Disjunction Normal Form (DNF)* for additional optimization opportunities
    - e.g.,  $(adm_year \ge 2019 \lor major =' CS') \land sid \ge 1000$  (CNF)  $\Leftrightarrow (adm_year \ge 2019 \land sid \ge 1000) \lor (major =' CS' \land sid \ge 1000)$  (DNF)

## Conjunctive selection with one index

- $\theta_1 \wedge \theta_2 \wedge \cdots \wedge \theta_r$ 
  - Choosing one or a prefix of predicates that can be answered using one index
    - Apply the rest of the predicates over the result on the fly
  - For instance, a B-Tree over  $(f_1, f_2)$  can select for predicates over a prefix of its index keys
    - $f_1 \text{ op value}$  (where  $op \in \{<, \le, =, >, \ge\}$ )
    - $f_1 = value \land f_2 op value$  (where  $op \in \{<, \leq, =, >, \geq\}$ )
    - If allow using skip scan (jump scan),  $f_2$  op value or  $f_1$  op value  $\land f_2$  op value
  - What if there're multiple choices?
    - Considerations: selectivity, type of indexes, actual cost (access path selection in QO)
  - Cost is the same as index scans/bitmap index scans

## Conjunctive selection with multiple indexes

- $\theta_1 \wedge \theta_2 \wedge \cdots \wedge \theta_r$ 
  - What if the atoms or several conjunctions of atoms can be answered by different indexes?
  - Example:  $\sigma_{major='CS' \land adm \ year=2021}R$  when we have two indexes  $I_1(major)$  and  $I_2(adm_year)$
- Algorithm:
  - 1. Collect all the RIDs using both indexes
  - 2. Compute the intersection of the RIDs
  - 3. Fetch the heap records of the RIDs in the result set
- Cost: index search + collecting data entries+ sort + intersection + fetching heap records

## Partial matches for conjunctive selection

- $\bullet \ \theta_1 \wedge \theta_2 \wedge \cdots \wedge \theta_r$ 
  - What if only part of the predicates can be optimized with indexes
    - Apply the remaining predicates over the result and discard those that do not satisfy
    - e.g.,  $\sigma_{major='CS' \land adm\_year=2021}$  with a hash index I(major)
      - Index Scan for all CS majors using I(major)
      - Apply the predicate  $adm_year = 2021$  over the heap records on the fly
    - Note the remaining predicates do not need to be in conjunctive normal form!
      - Can be arbitrary predicates (e.g., UDF)

## Disjunction selection with multiple indexes

- $\theta_1 \vee \theta_2 \vee \cdots \vee \theta_r$ 
  - Only optimizable if all clauses  $\theta_i$  can be optimized using some index
  - Otherwise, fall back to linear scan
- Algorithm:
  - 1. Collect all the RIDs using both indexes
  - 2. Compute the union of the RIDs
  - 3. Fetch the heap records of the RIDs in the result set
- Cost: index search + collecting data entries + sort + union + fetching heap records

#### An excursion: expression evaluation

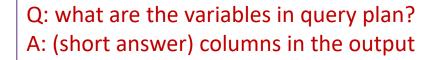
- So far, we assume expression evaluation is a black box
  - Does the predicate evaluate to true in selection?
  - Projection list evaluation?

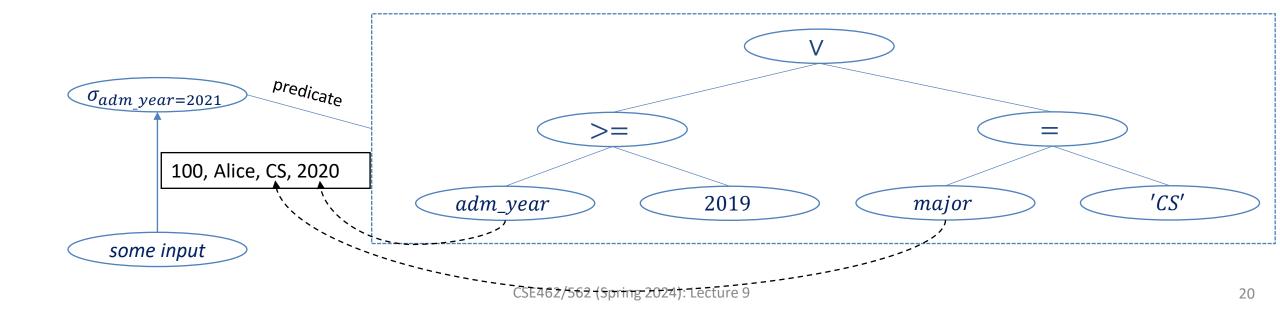
• ...

- How does it work?
  - How costly are they?

#### **Expression tree**

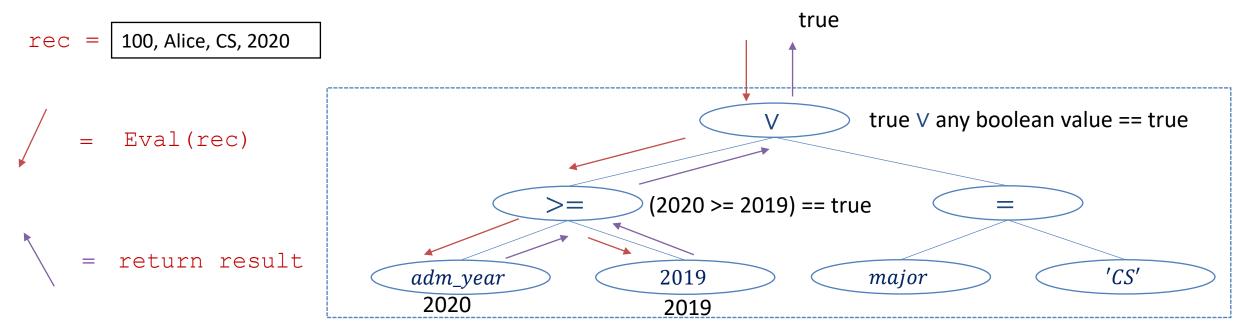
- A tree that represents an expression
  - Leaf nodes: literals, variables
  - Internal nodes: operators (+, -, \*, /, ...), function calls, ...
- Expressions in QP are attached to a plan node
  - Variables refers to columns in the output of some plan node
    - usually output from child, but could be intermediate outputs within certain operators
- Example: predicate *adm\_year* >= 2019 ∨ *major* = 'CS'





#### **Expression evaluation**

- Interpretation vs Compilation
  - type checking?
- In the course project Taco-DB, we use interpretation (for ease of implementation)
  - recursive evaluation through  ${\tt Eval}$  ( ) calls



## Projection $\pi$

- Without deduplication
  - evaluate projection list for the records on the fly
  - cost: no additional I/O
  - sometimes baked into other operators (i.e., all operators can be followed by an implicit projection)
- With deduplication
  - Requires materialization (blocking)
  - Hash or Sort
    - Hash -> build a hash table where duplicates are dropped
    - Sort -> emit a record only if it is the first record or it is different from the previous one
  - Result set fits in memory => easy to implement (does not add I/O cost)
  - When result sets exceed configured workspace size *M*,
    - Need to use external hashing and sorting algorithms (next lecture)
    - Optimization opportunities
    - Will come back to this later after we discuss external hashing and sorting

## Projection over selection: Index only scan

- For  $\pi_{E_1,E_2,\ldots,E_k}\sigma_P R$ 
  - Let Var(E) be the set of attributes in the expression E
    - e.g.,  $Var(R.sid > 100) = \{R.sid\}$  $Var(length(R.name) + length(R.login)) = \{R.name, R.login\}$
  - Suppose there's an index I over R whose index key is  $K_I$ , such that
    - $\bigcup_{1 \le i \le k} Var(E_i) \cup Var(P) \subseteq K_I$
    - we can perform an index scan without fetching the heap records (index-only scan)
    - Note: attributes that only appear in the projection list can be non-key columns in index
    - Might be useful even if search key does not match the index key
      - Cheaper than heap scan due to high fan-out
  - Cost = tree search cost + cost for scanning all matching data entries

 $= h \times (t_S + t_T) + \left( \left[ \frac{T}{F} \right] - 1 \right) \times t_T$  (assuming leaf level is consecutive on disk due to bulk loading)

- Example:  $\pi_{adm\_year,sid}\sigma_{adm\_year=2021}R$ , B-Tree index on  $R(adm\_year,sid)$ h = 3, s = 0.1, T =  $[sT_R] = 4000, F = 300$ 
  - cost of index-only scan =  $3 \times 4.1 + \left(\left[\frac{4000}{300}\right] 1\right) \times 0.1 = 13.6 \text{ ms}$ vs cost of index scan (clustered) =  $3 \times 4.1 + 4 + 0.1 \times [0.1 \times 500] = 21.3 \text{ ms}$

# Summary

- This lecture:
  - Operators for single-table queries
    - Scan, Selection, Projection
  - Expression evaluation
- Next lecture:
  - Aggregation, Sorting, External sorting
- Reminders:
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